


cr1::loco::LocomotionTrajectory
Planner::appendPeriodicGaitIfNeeded



```
graph LR; A["cr1::loco::LocomotionTrajectory  
Planner::appendPeriodicGaitIfNeeded"] --> B["cr1::loco::ContactPlanManager  
::timeUntilEndOfPlanningHorizon"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains two lines of text. The right box is gray with a black border and also contains two lines of text.

cr1::loco::ContactPlanManager
::timeUntilEndOfPlanningHorizon