crl::loco::LocomotionTrajectory
Planner::appendPeriodicGaitIfNeeded

crl::loco::LocomotionTrajectory
Planner::appendPeriodicGait

crl::loco::LocomotionTrajectory
Planner::appendPeriodicGait

crl::loco::ContactPlanManager
::appendPeriodicGaitToPlanningHorizon