

crl::loco::RB::getRayIntersection
Point

crl::loco::RB::getVelocity
ForPoint_local

crl::loco::RB::getWorldCoordinates

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graph LR; A[crl::loco::RB::getRayIntersectionPoint] --> C[crl::loco::RB::getWorldCoordinates]; B[crl::loco::RB::getVelocityForPoint_local] --> C;
```

The diagram illustrates a dependency or relationship between three function calls. On the left, there are two white rectangular boxes with black borders. The top box contains the text 'crl::loco::RB::getRayIntersectionPoint' and the bottom box contains 'crl::loco::RB::getVelocityForPoint_local'. On the right, there is a single gray rectangular box with a black border containing the text 'crl::loco::RB::getWorldCoordinates'. Two blue arrows originate from the right side of the two white boxes and point towards the left side of the gray box, indicating that both functions on the left depend on or call the function on the right.