

crl::Ray::getDistanceToPlane



```
graph LR; Ray[crl::Ray::getDistanceToPlane] --> Plane[crl::Plane::getSignedDistanceToPoint];
```

A diagram illustrating a function call. On the left, a gray rectangular box contains the text 'crl::Ray::getDistanceToPlane'. A blue arrow points from the right side of this box to the left side of a white rectangular box on the right. The white box contains the text 'crl::Plane::getSignedDistanceToPoint'.

crl::Plane::getSignedDistance
ToPoint