

crl::loco::GeneralizedCoordinates  
RobotRepresentation::getOffsetFromParentToQ



```
graph LR; A["crl::loco::GeneralizedCoordinates  
RobotRepresentation::getOffsetFromParentToQ"] --> B["crl::loco::GeneralizedCoordinates  
RobotRepresentation::getPivotPointLocal  
Position"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a gray background and contains two lines of text. The right box has a white background and contains three lines of text.

crl::loco::GeneralizedCoordinates  
RobotRepresentation::getPivotPointLocal  
Position