

crl::loco::RBJoint
::fixJointConstraints

crl::loco::RBJoint
::getCurrentJointAngle

crl::loco::RBJoint
::computeRelativeOrientation

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graph LR; A[crl::loco::RBJoint::fixJointConstraints] --> C[crl::loco::RBJoint::computeRelativeOrientation]; B[crl::loco::RBJoint::getCurrentJointAngle] --> C;
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The diagram illustrates a dependency or call relationship. Two source functions, 'crl::loco::RBJoint::fixJointConstraints' and 'crl::loco::RBJoint::getCurrentJointAngle', are shown in white boxes on the left. Blue arrows point from each of these source functions to a single target function, 'crl::loco::RBJoint::computeRelativeOrientation', which is shown in a gray box on the right.