

crl::loco::GeneralizedCoordinates  
RobotRepresentation::getQAndQDotFrom  
ReducedState

crl::loco::GeneralizedCoordinates  
RobotRepresentation::getQFromReducedState

crl::loco::IK\_Solver  
::solve

crl::loco::testGeneralized  
CoordinateRepresentation

crl::loco::GeneralizedCoordinates  
RobotRepresentation::getQ

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graph LR; A[crl::loco::GeneralizedCoordinates<br/>RobotRepresentation::getQAndQDotFrom<br/>ReducedState] --> D[crl::loco::GeneralizedCoordinates<br/>RobotRepresentation::getQ]; B[crl::loco::GeneralizedCoordinates<br/>RobotRepresentation::getQFromReducedState] --> D; C[crl::loco::IK_Solver<br/>::solve] --> D; E[crl::loco::testGeneralized<br/>CoordinateRepresentation] --> D;
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