

crl::loco::Robot::Robot



```
graph LR; A[crl::loco::Robot::Robot] --> B[crl::loco::RBLoader::populateRobot];
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box is white with a black border and contains the text 'crl::loco::Robot::Robot'. The right box is gray with a black border and contains the text 'crl::loco::RBLoader::populateRobot' on two lines. The blue arrow originates from the right side of the first box and points to the left side of the second box.

crl::loco::RBLoader
::populateRobot