crl::loco::GeneralizedCoordinates
RobotRepresentation::GeneralizedCoordinates
RobotRepresentation

crl::loco::GeneralizedCoordinates
RobotRepresentation::getQAndQDotFrom
ReducedState

crl::loco::GeneralizedCoordinates RobotRepresentation::getQFromReducedState

> crl::loco::testGeneralized CoordinateRepresentation

crl::loco::BodyFrame ::BodyFrame crl::loco::computeRotation AngleFromQuaternion crl::computeEulerAnglesFrom crl::loco::GeneralizedCoordinates Quaternion RobotRepresentation::syncGeneralized CoordinatesWithRobotState crl::loco::computeEulerAngles FromQuaternion crl::loco::getHeadingAngle crl::loco::estimateAngular crl::loco::testQuaternion Velocity Decomposition crl::loco::RBJoint crl::getRotationAngle crl::loco::LocomotionTrajectory ::fixJointConstraints Planner::getTargetTrunkAngularVelocityAtTime crl::loco::RBJoint ::getCurrentJointAngle crl::loco::Robot::saveReduced crl::loco::RobotState crl::loco::RobotState StateToFile ::writeToFile ::getHeading crl::loco::Robot::getHeading Angle crl::getRotationAngle