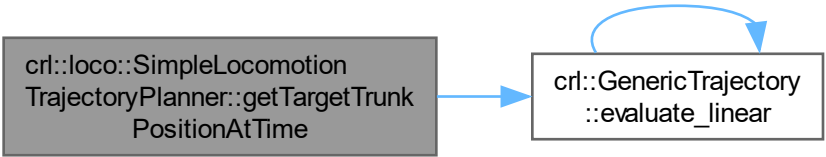


crl::loco::SimpleLocomotion  
TrajectoryPlanner::getTargetTrunk  
PositionAtTime



```
graph LR; A[crl::loco::SimpleLocomotionTrajectoryPlanner::getTargetTrunkPositionAtTime] --> B[crl::GenericTrajectory::evaluate_linear]; B --> B;
```

The diagram consists of two rectangular boxes. The left box is gray and contains the text 'crl::loco::SimpleLocomotionTrajectoryPlanner::getTargetTrunkPositionAtTime'. The right box is white and contains the text 'crl::GenericTrajectory::evaluate\_linear'. A straight blue arrow points from the right side of the gray box to the left side of the white box. A curved blue arrow starts from the top right of the white box and points back to the top left of the white box, indicating a self-call or loop.

crl::GenericTrajectory  
::evaluate\_linear