

McMASTER UNIVERSITY

SMARTSERVE

SOFTWARE & MECHATRONICS CAPSTONE

Verification and Validation

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Date	Revision	Comments	Author(s)
Feb 1, 2018	1.0	Document structure and Headings	Christopher McDonald
Feb 10, 2018	1.1	Philosophy and Intro section	Christopher McDonald
Feb 13, 2018	1.2	UI and DS Tests	Sharon Platkin
Feb 15, 2018	1.3	SM, SMC, SS, CV and SR	Christopher McDonald & Harit Patel & Sam Hamel
Feb 16-17, 2018	1.4	Executive Summary and Testing	Christopher McDonald & Sharon Platkin
Apr 6, 2018	2.0	Added integration tests, fixed grammar and added test instructions	Christopher McDonald

Figure 1: Revision History

1 Executive Summary of Testing

The testing completed on February 17th, 2018 has yielded 44 passes, 10 failures, and 3 pending. Pending tests have not been executed due to lack of relevance at this stage. The failures in their entirety can be attributed to features that are in progress or that have not yet been implemented including; automated roll and pitch as well as the machine learning model. Given that the failure rate is roughly 17%, the team does not recommend operation of the project at this time.

An important note to consider is that most errors are localized in the Shooting Mechanism and ShotRecommender subsystems. The team would also like to expand testing further to have higher coverage of the system and increase their confidence in its reliability.

The team will continue developing the system until March 9th where tests will be re-defined and added to satisfy the team's ideals. After which, the second round of testing will commence.

2 Introduction

2.1 Project Overview

SmartServe is an autonomous table tennis training system for table tennis players with various skill levels. SmartServe aids in diagnosing and improving a player's performance over time. The system trains table tennis players by shooting table tennis balls towards the player and detects successful returns from the player. The system can further adapt to the player's weaknesses and help them overcome it through further training. Importantly, SmartServe alleviates the problems of finding and working with a coach for players, as well as coaches trying to train multiple players simultaneously. The system will be deemed a success if the table tennis players and coaches can enjoy and see some value added by using SmartServe.

The project started at the beginning of the Fall 2017 academic term and will conclude at the end of the Winter 2018 term. In addition, the core project team consists of final year Software and Mechatronics Engineering students who are enrolled in the MECHTRON 4TB6/SFWRENG 4G06 capstone project course.

2.2 Document Overview

This document will provide details of all formal testing methods and results performed on the SmartServe system. The first part of testing includes detailing how it will be performed and the details of the system on which it is run. This matters due to details which can

affect the testing outcomes like operating system, lighting or performance of hardware. The schedule for the test will also be detailed alongside the major deliverables to have clear outcomes to explain to stakeholders. The testing will be performed off of the *master* branch as it stands during the beginning of the testing phase.

The actual testing will then be detailed as test cases based on what subsystem they are testing. As needed, the communication will be tested in between the subsystems to ensure communication is working as intended. Lastly, a test case-requirement matrix will be provided which maps what test cases test which requirement. This will give the reader a simple way to check if a requirement is fully satisfied. Supporting documents include the requirements which can be found [here](#).

2.3 Naming Conventions and Terminology

The following terms and definitions will be used throughout this document:

- **ACID**: a database transaction which is atomic, consistent, isolated and durable
- **CV**: computer vision
- **FPS**: frames per second
- **FSM**: finite state machine, shows transitions between states
- **GUI**: graphical user interface
- **IPO**: input process output
- **Pitch**: rotation along the y-axis; this rotation angle primarily dictates the range of the ball from the net to the edge of the table on the user side
- **Roll**: rotation along the x-axis
- **Shooting Mechanism**: refers to the part of the system that shoots the table tennis balls towards the user side (player) Please refer to Figure ?? for visual illustration
- **System**: encompasses both the hardware and software parts of SmartServe
- **System Side**: the side of the table where the electromechanical system is placed; it is the opposite side of the User Side Please refer to Figure ?? for visual illustration
- **TCP**: transmission control protocol
- **Team**: all team members of the core capstone project, as noted in the list of Authors
- **User Side**: the side of the table where the user (player) is standing

- **Yaw:** rotation along the z-axis; this rotation angle primarily dictates the panning functionality of the shooting mechanism from the right side to the left side of the table

3 Testing Philosophy

3.1 Approach

The approach to testing will be to separate the subsystems as much as possible and test them accordingly. Every subsystem will be unit tested in JUnit or PyUnit if implemented in Java or Python respectively. The shooting mechanism will be tested manually to ensure it is functioning properly. Stubbing a service or dependancy can be done to return consistent, reliable and predictable results. For instance, the SmartServe system may use a stub for the CV subsystem to return a predefined sequence of pass/fail flags.

When performing the tests, every test will be run three times unless specified otherwise. The test must be satisfied at least two of the three attempts to be determined successful.

3.2 Schedule

Task	Date	Notes
Complete Test Cases	February 13, 2018	N/A
Run Tests (First)	February 16, 2018	N/A
Edit Test Cases	March 9, 2018	N/A
Run Tests (Second)	March 16, 2018	N/A

Table 1: Testing Schedule

3.3 Environment

The SmartServe system uses heavy computation power due to the CV and ML models, so the system which runs the test will have the following details. The system will be a 15-inch Macbook Pro (Late 2016) running macOS High Sierra (10.13). The Macbook Pro has an 2.6 GHz Intel Core i7 CPU and a Radeon Pro 450 2GB GPU. The location will be in Thode Makerspace where the CV will be adjusted as necessary for those lighting conditions.

3.4 Code Reviews

As per the Development Plan document, the team will be using branches on GitHub to control additions into the source code. The list of Pull Requests can be found here [here](#). Although it is impossible to test whether it is better that they were made as opposed to

all members contributing to the same branch, few commits have had to be made directly to the develop branch, and 0 to the master branch, which indicates the system is working as expected.

3.5 Setup Instructions

The following items should be preformed in succession to set up the system for testing.

- Data Storage: delete the *smartserve* database if it exists, and dump the only SQL file in `src/Database` into a new *smartserve* database
- Arduino: add the .cpp and .h files for `AutomaticPanning`, `AutomaticRoll`, `Pitch` and `FeedAndShoot`, then load the `FeedPitchAndShoot` sketch onto the top Arduino, and `PanAndRoll` sketch onto the bottom Arduino
- ComputerVision: connect the webcam over USB, and run `src/ComputerVision/cv.py` using Python 3.6
- ShotRecommender: run the `src/ShotRecommender/shotRecommender.py` using Python 3.6
- SmartServe: replace the port strings in the `Controller.java` with the associated ports using the Arduino desktop application for both arduinos

4 Test Cases

4.1 Electromechanical Subsystems

4.1.1 Shooting Mechanism

Test ID: SMC1	Feeding Mechanism Rotation Test		Status: PASS
Description: The feeding mechanism rotates by given amount in degrees.			
Pass/Fail Condition: The feeding mechanism rotates by given amount of degrees within a tolerance of 2 degrees.			
Pre-Conditions: The feeding mechanism is ready/powerd on.			
Input: Integer indicating the amount of degrees to be rotated.			
Expected Results: Feeding mechanism rotates to the required position.		Actual Results: One ball is shot at a time	
Post-Conditions: N/A			

Table 2: Feeding Mechanism Rotation Test

Test ID: SMC2	Shooting Control Test		Status: PASS
Description: The shooting control shoots the ball using a rotating wheel at the requested power level to achieve the desired speed.			
Pass/Fail Condition: The system must reach the same distance each time for the same amount of power, within 0.1 metres of error.			
Pre-Conditions: The Shooting Control motor is powered on, and connected to the system.			
Input: Integer between 0-100 indicating the power level of the shot.			
Expected Results: 2 successive shots land in the same spot		Actual Results: 2 successive shots land in the same spot	
Post-Conditions: N/A			

Table 3: Shooting Control Test

Test ID: SMC3	Four Position Roll Test	Status: FAIL
Description: The system rotates the Shooting Control to one of the four default positions.		
Pass/Fail Condition: Rotates to the indicated position.		
Pre-Conditions: The Shooting Control motor is powered on, and connected to the system.		
Input: Integer between 0-3 indicating the desired default position.		
Expected Results: The shooting control rotates to the requested default position.		Actual Results: Not implemented
Post-Conditions: N/A		

Table 4: Four Position Roll Test

Test ID: SMC4	Adjustable Pitch Control Test	Status: FAIL
Description: The pitch control angles the shooting mechanism at the desired pitch level.		
Pass/Fail Condition: Rotate to the desired pitch level with a tolerance of 5 degrees.		
Pre-Conditions: N/A		
Input: Integer between -15 deg to 45 deg indicating pitch angle.		
Expected Results: Rotate to the desired pitch level with a tolerance of 5 degrees.		Actual Results: Not implemented
Post-Conditions: N/A		

Table 5: Adjustable Pitch Control Test

Test ID: SMC5 Panning Shooting Mechanism Across the Table Status: PASS	
Description: Move the system to face the direction specified in degrees.	
Pass/Fail Condition: System moved to desired position.	
Pre-Conditions: Panning stage is homed correctly before moving to the first location.	
Input: Integer between 60 deg to 120 deg indicating where to point the shooter.	
Expected Results: Moves to the desired position without going out of bounds.	Actual Results: Moves to desired positions
Post-Conditions: When powered down, the system rotates to the home (0 degrees) position.	

Table 6: Panning Shooting Mechanism Test

Test ID: SMC6 Shut Off Power Switch Test Status: PENDING	
Description: Switch on the machine cuts power to the system in case of an emergent situation	
Pass/Fail Condition: Systems shuts off when flicking the switch	
Pre-Conditions: Machine must be on	
Input: N/A	
Expected Results: Power shuts off when the switch is used	Actual Results: N/A
Post-Conditions: System is off	

Table 7: Shut Off Power Switch Test

4.2 Software Subsystems

4.2.1 Computer Vision

Test ID: CV1	Ball Detection Test	Status: PASS
Description: Tests if CV subsystem can detect a table tennis ball		
Pass/Fail Condition: N/A		
Pre-Conditions: CV subsystem successfully connects to camera		
Input: Ball is placed in frame		
Expected Results: CV subsystem detects ball		Actual Results: As expected
Post-Conditions: N/A		

Table 8: Ball Detection Test

Test ID: CV2	Ball Upward Detection Test	Status: PASS
Description: Tests if CV Subsystem can detect upward motion of the ball		
Pass/Fail Condition: N/A		
Pre-Conditions: CV Subsystem successfully connects to camera, ball is being detected		
Input: Ball is lifted upwards		
Expected Results: CV tracks the ball in motion		Actual Results: As expected
Post-Conditions: N/A		

Table 9: Ball Upward Detection Test

Test ID: CV3	Ball Downward Detection Test		Status: PASS
Description: Tests if CV Subsystem can detect downward motion of the ball			
Pass/Fail Condition: N/A			
Pre-Conditions: CV Subsystem successfully connects to camera, ball is being detected			
Input: Ball is moved downward			
Expected Results: CV tracks the ball in motion		Actual Results: As expected	
Post-Conditions: N/A			

Table 10: Ball Downward Detection Test

Test ID: CV4	Ball Rightward Detection Test	Status: PASS
Description: Tests if CV Subsystem can detect rightward motion of the ball		
Pass/Fail Condition: N/A		
Pre-Conditions: CV Subsystem successfully connects to camera, ball is being detected		
Input: Ball is moved rightwards		
Expected Results: CV tracks the ball in motion	Actual Results: As expected	
Post-Conditions: N/A		

Table 11: Ball Rightward Detection Test

Test ID: CV5	Ball Leftward Detection Test	Status: PASS
Description: Tests if CV Subsystem can detect leftward motion of the ball		
Pass/Fail Condition: N/A		
Pre-Conditions: CV Subsystem successfully connects to camera, ball is being detected		
Input: Ball is moved leftward		
Expected Results: CV tracks the ball in motion	Actual Results: As expected	
Post-Conditions: N/A		

Table 12: Ball Leftward Detection Test

Test ID: CV6	CV Timeout Test	Status: PASS
Description: Tests if CV subsystem times out		
Pass/Fail Condition: Times out within 1 second of initiation		
Pre-Conditions: CV is in state 1		
Input: N/A		
Expected Results: Times out in 8 seconds		Actual Results: As expected
Post-Conditions: cvmodule is closed		

Table 13: CV Timeout Test

Test ID: CV7	CV Transition: State 1 to 2	Status: PASS
Description: Tests that the CV state transitions from state 1 to 2 when ball is moving away from player		
Pass/Fail Condition: State changes within 0.5 seconds of real-time		
Pre-Conditions: CV is in state 1		
Input: Ball is moving towards system-side		
Expected Results: CV moves to state 2		Actual Results: As expected
Post-Conditions: CV is in state 2		

Table 14: CV Transition: State 1 to 2

Test ID: CV8	CV Transition: State 2 to 3	Status: PASS
Description: Tests that the CV state transitions from state 2 to 3 when ball is descending		
Pass/Fail Condition: State changes within 0.5 seconds of real-time		
Pre-Conditions: CV is in state 2		
Input: Ball is moved downward in frame		
Expected Results: CV moves to state 3		Actual Results: As expected
Post-Conditions: CV is in state 3		

Table 15: CV Transition: State 2 to 3

Test ID: CV9	CV Transition: State 3 to 0	Status: PASS
Description: Tests that the CV state transitions from state 3 to 0 when ball is ascending		
Pass/Fail Condition: State changes within 0.5 seconds of real-time		
Pre-Conditions: CV is in state 3		
Input: Ball is moved upward in frame		
Expected Results: CV moves to state 0		Actual Results: As expected
Post-Conditions: CV is in state 0		

Table 16: CV Transition: State 3 to 0

Test ID: CV10	Hit Signal to SmartServe Test	Status: PASS
Description: Tests that the CV Subsystem sends a “GOOD” signal to SmartServe		
Pass/Fail Condition: N/A		
Pre-Conditions: CV is in state 3		
Input: Ball is moved upward in frame		
Expected Results: “GOOD” signal sent to SmartServe		Actual Results: As expected
Post-Conditions: CV is in state 0		

Table 17: Hit Signal to SmartServe Test

Test ID: CV11	CV Accuracy Test	Status: ???
Description: CV should detect successful hits and misses		
Pass/Fail Condition: 80% accuracy rate		
Pre-Conditions: N/A		
Input: 10 bounces and 10 misses will be thrown in front of the camera		
Expected Results: CV subsystem detects each throw correctly		Actual Results: ???
Post-Conditions: N/A		

Table 18: CV Accuracy Test

4.2.2 ShotRecommender

Test ID: SR1	ShotRecommender Listen Test	Status: PASS
Description: The ShotRecommender service responds to HTTP calls on port 8080.		
Pass/Fail Condition: The system waits until a request.		
Pre-Conditions: N/A		
Input: None		
Expected Results: N/A		Actual Results: As expected
Post-Conditions: N/A		

Table 19: ShotRecommender Listen Test

Test ID: SR2	ShotRecommender Query Test	Status: FAIL
Description: The ShotRecommender calls the “query” method for user data.		
Pass/Fail Condition: The call returns a table of user performance data.		
Pre-Conditions: The SQL database is running on port 3306.		
Input: a valid user id for the “performance” procedure		
Expected Results: table of data	Actual Results: Procedure not found	
Post-Conditions: N/A		

Table 20: ShotRecommender Query Test

Test ID: SR3	ShotRecommender Random Shot Test	Status: PASS
Description: The ShotRecommender receives a request for a shot.		
Pass/Fail Condition: The service generates a random shot.		
Pre-Conditions: The service is running on port 8080.		
Input: an HTTP request with “Random” as the mode parameter		
Expected Results: a random shot which adheres to requirements	Actual Results: As expected	
Post-Conditions: N/A		

Table 21: ShotRecommender Random Shot Test

Test ID: SR4	ShotRecommender Training Shot Test	Status: FAIL
Description: The ShotRecommender receives a request for a shot.		
Pass/Fail Condition: The service generates a shot.		
Pre-Conditions: The service is running on port 8080.		
Input: an HTTP request with “Train” as the mode parameter		
Expected Results: a random shot which adheres to requirements		Actual Results: Model not found
Post-Conditions: N/A		

Table 22: ShotRecommender Training Shot Test

Test ID: SR5	ShotRecommender UpdateModel Test	Status: FAIL
Description: The ShotRecommender receives a status update for a shot.		
Pass/Fail Condition: The service changes the model in response.		
Pre-Conditions: The service is running on port 8080.		
Input: an HTTP request with the shot id and returned boolean as parameters.		
Expected Results: the model is updated		Actual Results: Model not found
Post-Conditions: N/A		

Table 23: ShotRecommender UpdateModel Test

4.2.3 Shooting Model

Test ID: SM1	ShootingModel calculateYawAngle Test	Status: PASS
Description: The calculateYawAngle method returns an accurate yaw angle in degrees.		
Pass/Fail Condition: The method returns an angle in degrees accurate to a whole number.		
Pre-Conditions: N/A		
Input: xDist, yDist; distance to desired shot's x-coordinate and y-coordinate.		
Expected Results: A yaw angle in degrees, accurate to a whole number.		Actual Results: As expected
Post-Conditions: N/A		

Table 24: ShootingModel calculateYawAngle Test

Test ID: SM2	ShootingModel calculateVelocity Test	Status: PASS
Description: The calculateVelocity method returns an accurate velocity in meters/second.		
Pass/Fail Condition: The method returns the velocity accurate to a whole number.		
Pre-Conditions: N/A		
Input: N/A		
Expected Results: Velocity in m/s, accurate to a whole number.		Actual Results: As expected
Post-Conditions: N/A		

Table 25: ShootingModel calculateVelocity Test

Test ID: SM3	ShootingModel netHeightChecker Test	Status: PASS
Description: ThenetHeightChecker method checks whether the desired shot will pass over the net.		
Pass/Fail Condition: The method returns the correct boolean indicating if the shot will pass over the net.		
Pre-Conditions: N/A		
Input: N/A.		
Expected Results: A boolean; True is shot will pass over the net, False otherwise.		Actual Results: As expected
Post-Conditions: N/A		

Table 26: ShootingModel netHeightChecker Test

4.2.4 Data Storage

Test ID: DS1	Data Storage Sign Up Test	Status: PASS
Description: Data Storage receives user name and password to sign up		
Pass/Fail Condition: User table updates with correct parameters		
Pre-Conditions: The SQL database is running on port 3306.		
Input: User name and user password		
Expected Results: User table updated		Actual Results: As expected
Post-Conditions: N/A		

Table 27: Data Storage Sign Up Test

Test ID: DS2	Data Storage Next Shot Test	Status: PASS
Description: Data Storage returns a shot type for the system to execute		
Pass/Fail Condition: a specified desired zone the system must aim for is returned		
Pre-Conditions: The SQL database is running on port 3306.		
Input: Desired zone id as an integer		
Expected Results: Return valid shot parameters, speed and angular velocity		Actual Results: As expected
Post-Conditions: N/A		

Table 28: Data Storage Next Shot Test

Test ID: DS3	Data Storage Returned Test	Status: PASS
Description: Data Storage received parameters for a successful or missed shot		
Pass/Fail Condition: Returnrate table updates with correct parameters		
Pre-Conditions: The SQL database is running on port 3306.		
Input: Timestamp, user and shot ids		
Expected Results: Returnrate table updated		Actual Results: As expected
Post-Conditions: N/A		

Table 29: Data Storage Returned Test

Test ID: DS4	Data Storage Sign In Test	Status: PASS
Description: Data Storage receives user name and password and authenticates it		
Pass/Fail Condition: Returns accurate boolean value according to matching of user name and password		
Pre-Conditions: The SQL database is running on port 3306.		
Input: User name and user password		
Expected Results: True is returned if the password matches the user name, false if they do not match	Actual Results: As expected	
Post-Conditions: N/A		

Table 30: Data Storage Sign In Test

Test ID: DS5	Data Storage Statistics Test	Status: PENDING
Description: Data Storage provides return rate given a time frame		
Pass/Fail Condition: Returns return information given a range of time stamp inputs		
Pre-Conditions: The SQL database is running on port 3306.		
Input: Time stamp range		
Expected Results: Return stats within the inputted range	Actual Results: N/A	
Post-Conditions: N/A		

Table 31: Data Storage Statistics Test

4.2.5 User Interface

Test ID: UI1	User Interface Display Test	Status: PASS
Description: All elements of UI are displayed in a window		
Pass/Fail Condition: UI displays when program is run		
Pre-Conditions:N/A		
Input: N/A		
Expected Results: Window opens with Welcome Screen		Actual Results: As expected
Post-Conditions: Application running		

Table 32: User Interface Display Test

Test ID: UI2	User Interface Button Test	Status: PASS
Description: All buttons should do some action when pressed		
Pass/Fail Condition: When pressed, buttons change the state of the application and return		
Pre-Conditions: Application UI is running		
Input: N/A		
Expected Results: Return true when button is pressed		Actual Results: As expected
Post-Conditions: N/A		

Table 33: User Interface Button Test

Test ID: UI3	User Interface Mode Test	Status: PASS
Description: Mode should be assigned when it is picked in a dropdown		
Pass/Fail Condition: Mode variable assigned selected value		
Pre-Conditions: Application UI is running		
Input: N/A		
Expected Results: Return value selected		Actual Results: As expected
Post-Conditions: N/A		

Table 34: User Interface Mode Test

Test ID: UI4	User Interface Sign up Test	Status: FAIL
Description: When signup button is pressed, user is added with given parameters		
Pass/Fail Condition: User inputs are sent to Data Storage		
Pre-Conditions: Application UI is running		
Input: User name and user password		
Expected Results: Return user parameters		Actual Results: Page not implemented
Post-Conditions: N/A		

Table 35: User Interface Sign up Test

Test ID: UI4	User Interface Sign up Test	Status: FAIL
Description: When signup button is pressed, user is added with given parameters		
Pass/Fail Condition: User inputs are sent to Data Storage		
Pre-Conditions: Application UI is running		
Input: User name and user password		
Expected Results: Return user parameters		Actual Results: Page not implemented
Post-Conditions: N/A		

Table 36: User Interface Sign up Test

Test ID: UI5	User Interface Log In Test	Status: FAIL
Description: When login button is pressed, user is authenticated		
Pass/Fail Condition: User inputs are sent to Data Storage		
Pre-Conditions: Application UI is running		
Input: User name and user password		
Expected Results: Return true if password matches user name		Actual Results: Page not implemented
Post-Conditions: N/A		

Table 37: User Interface Log In Test

Test ID: UI6	User Interface Statistics Test	Status: PENDING
Description: Statistics show on page		
Pass/Fail Condition: Relevant page shows when statistics tab is pressed		
Pre-Conditions: Application UI is running		
Input: N/A		
Expected Results: Statistics page displays		Actual Results: N/A
Post-Conditions: N/A		

Table 38: User Interface Statistics Test

4.2.6 SmartServe

Test ID: SS1	ShotRecommendation Connection Test - Pass	Status: PASS
Description: The ShotRecommendation class will call the <i>connect</i> method with port 8080 as a parameter.		
Pass/Fail Condition: The method should return true.		
Pre-Conditions: The ShotRecommendation server is running on port 8080.		
Input: 8080		
Expected Results: true		Actual Results: As expected
Post-Conditions: N/A		

Table 39: ShotRecommendation Connection Test - Pass

Test ID: SS2 ShotRecommendation Connection Test - Fail Status: PASS	
Description: The ShotRecommendation class will call the <i>connect</i> method with port 8090 as a parameter.	
Pass/Fail Condition: The method should return false.	
Pre-Conditions: The ShotRecommendation server is running on port 8080.	
Input: 8090	
Expected Results: false	Actual Results: As expected
Post-Conditions: N/A	

Table 40: ShotRecommendation Connection Test - Fail

Test ID: SS3 ShotRecommendation Request Shot - Random Status: PASS	
Description: The ShotRecommendation class will call the <i>getRecommendation</i> method with Random mode as a parameter.	
Pass/Fail Condition: The method should a random shot of the form “X=A.BC,Y=A.BC,V=A.BC,W=A.BC” where the values are within the requirements of the system.	
Pre-Conditions: The ShotRecommendation server is running on port 8080.	
Input: Mode.Random	
Expected Results: A valid shot, in string form.	Actual Results: As expected
Post-Conditions: N/A	

Table 41: ShotRecommendation Request Shot - Random

Test ID: SS4	ShotRecommendation Request Shot - Train	Status: FAIL
Description: The ShotRecommendation class will call the <i>getRecommendation</i> method with Training mode as a parameter.		
Pass/Fail Condition: The method should a shot of the form “X=A.BC,Y=A.BC,V=A.BC,W=A.BC” where the values are within the requirements of the system.		
Pre-Conditions: The ShotRecommendation server is running on port 8080.		
Input: Mode.Train		
Expected Results: A valid shot, in string form.		Actual Results: Model not found
Post-Conditions: N/A		

Table 42: ShotRecommendation Request Shot - Train

Test ID: SS5	ShotRecommendation Request Shot - One-shot	Status: PASS
Description: The ShotRecommendation class will call the <i>getRecommendation</i> method with One-shot mode as a parameter.		
Pass/Fail Condition: The method should a shot of the form “X=A.BC,Y=A.BC,V=A.BC,W=A.BC” where the values are within the requirements of the system. Repeated requests should return the same shot.		
Pre-Conditions: The ShotRecommendation server is running on port 8080.		
Input: Mode.OneShot		
Expected Results: A valid shot, in string form.		Actual Results: As expected
Post-Conditions: N/A		

Table 43: ShotRecommendation Request Shot - One-shot

Test ID: SS6	ShotRecommendation Model Update	Status: FAIL
Description: The ShotRecommendation class will call the <i>updateModel</i> method.		
Pass/Fail Condition: The ShotRecommender does not throw an error and the model is updated.		
Pre-Conditions: The ShotRecommendation server is running on port 8080.		
Input: a previously request shot and false		
Expected Results: N/A	Actual Results: Model not found	
Post-Conditions: N/A		

Table 44: ShotRecommendation Model Update

Test ID: SS7	ShotRecommendation Model Update	Status: FAIL
Description: The ShotRecommendation class will call the <i>updateModel</i> method.		
Pass/Fail Condition: The ShotRecommender does not throw an error and the model is updated.		
Pre-Conditions: The ShotRecommendation server is running on port 8080.		
Input: a previously request shot and true		
Expected Results: N/A	Actual Results: Model not found	
Post-Conditions: N/A		

Table 45: ShotRecommendation Request Shot - One-shot

Test ID: SS8 ComputerVisionController Connection Test - Pass Status: PASS	
Description: The CV class will call the <i>connection</i> method.	
Pass/Fail Condition: The method returns true.	
Pre-Conditions: The CV server is running on port 8000.	
Input: 8000	
Expected Results: true	Actual Results: As expected
Post-Conditions: N/A	

Table 46: ComputerVisionController Connection Test - Pass

Test ID: SS9 ComputerVisionController Connection Test - Fail Status: PASS	
Description: The CV class will call the <i>connection</i> method.	
Pass/Fail Condition: The method returns false.	
Pre-Conditions: The CV server is running on port 8001.	
Input: 8000	
Expected Results: false	Actual Results: As expected
Post-Conditions: N/A	

Table 47: ComputerVisionController Connection Test - Fail

Test ID: SS10 ComputerVisionController Detect Test - Timeout Status: PASS	
Description: The CV class will call the <i>start</i> method and no ball is introduced into the frame.	
Pass/Fail Condition: The method returns false.	
Pre-Conditions: The CV server is running on port 8000.	
Input: N/A	
Expected Results: false	Actual Results: As expected
Post-Conditions: N/A	

Table 48: ComputerVisionController Detect Test - Timeout

Test ID: SS11 ComputerVisionController Detect Test - Detect Status: PASS	
Description: The CV class will call the <i>start</i> method and a ball is introduced into the frame, emulating a successful shot.	
Pass/Fail Condition: The method returns true.	
Pre-Conditions: The CV server is running on port 8000.	
Input: N/A	
Expected Results: true	Actual Results: As expected
Post-Conditions: N/A	

Table 49: ComputerVisionController Detect Test - Detect

Test ID: SS12	SQLConnector Connection Test - Pass		Status: PASS
Description: The SQLConnector class will call the <i>connect</i> method.			
Pass/Fail Condition: The method returns true.			
Pre-Conditions: The SQL server is running on port 3306.			
Input: 3306			
Expected Results: true		Actual Results: As expected	
Post-Conditions: N/A			

Table 50: SQLConnector Connection Test - Pass

Test ID: SS13	SQLConnector Connection Test - Fail		Status: PASS
Description: The SQLConnector class will call the <i>connect</i> method.			
Pass/Fail Condition: The method returns false.			
Pre-Conditions: The SQL server is not running.			
Input: 3306			
Expected Results: false		Actual Results: As expected	
Post-Conditions: N/A			

Table 51: SQLConnector Connection Test - Pass

Test ID: SS14	SQLConnector Query Test - Signup	Status: PASS
Description: The SQLConnector class will call the <i>save</i> method.		
Pass/Fail Condition: The user is saved in the database.		
Pre-Conditions: The SQL server is running on port 3306.		
Input: Object[] with “Chris” and “password123” for the “sign_up” procedure		
Expected Results: true	Actual Results: As expected	
Post-Conditions: N/A		

Table 52: SQLConnector Query Test - Signup

Test ID: SS15	SQLConnector Query Test - Returned	Status: PASS
Description: The SQLConnector class will call the <i>save</i> method.		
Pass/Fail Condition: The shot is saved in the database correctly.		
Pre-Conditions: The SQL server is running on port 3306.		
Input: Object[] with 25, 1, 1 and the current time for the “returned” procedure		
Expected Results: true	Actual Results: As expected	
Post-Conditions: N/A		

Table 53: SQLConnector Query Test - Returned

Test ID: SS16	SQLConnector Query Test - Login	Status: PASS
Description: The SQLConnector class will call the <i>save</i> method.		
Pass/Fail Condition: The shot is saved in the database correctly.		
Pre-Conditions: The SQL server is running on port 3306.		
Input: Object[] with “Chris” and “password123” for the “login” procedure		
Expected Results: true	Actual Results: As expected	
Post-Conditions: N/A		

Table 54: SQLConnector Query Test - Returned

Test ID: SS17	ArduinoController Connection Test - Pass	Status: PASS
Description: The ArduinoController class will call the <i>test</i> method, repeat for all arduinos.		
Pass/Fail Condition: The method returns true.		
Pre-Conditions: The Arduinos are plugged in via USB and loaded with the correct code.		
Input: the port for the Arduino(s)		
Expected Results: true	Actual Results: As expected	
Post-Conditions: N/A		

Table 55: ArduinoController Connection Test - Pass

Test ID: SS18	ArduinoController Connection Test - Fail	Status: PASS
Description: The ArduinoController class will call the <i>test</i> method, repeat for all arduinos.		
Pass/Fail Condition: The method returns false.		
Pre-Conditions: The Arduinos are plugged in via USB and loaded with the correct code.		
Input: “some-test-string”		
Expected Results: false	Actual Results: As expected	
Post-Conditions: N/A		

Table 56: ArduinoController Connection Test - Fail

Test ID: SS19	ArduinoController Test - Pan	Status: PASS
Description: The ArduinoController class will call the <i>shoot</i> method.		
Pass/Fail Condition: The system pans to 75 degrees.		
Pre-Conditions: The Arduinos are plugged in via USB and loaded with the correct code.		
Input: a ShotDetail object with pan of 75 degrees		
Expected Results: true	Actual Results: As expected	
Post-Conditions: N/A		

Table 57: ArduinoController Test - Pan

Test ID: SS20	ArduinoController Test - Pan	Status: PASS
Description: The ArduinoController class will call the <i>shoot</i> method.		
Pass/Fail Condition: The system pans to 120 degrees.		
Pre-Conditions: The Arduinos are plugged in via USB and loaded with the correct code.		
Input: a ShotDetail object with pan of 120 degrees		
Expected Results: true	Actual Results: As expected	
Post-Conditions: N/A		

Table 58: ArduinoController Test - Pan

Test ID: SS21	ArduinoController Test - Shoot	Status: PASS
Description: The ArduinoController class will call the <i>shoot</i> method.		
Pass/Fail Condition: The system shoots at 75% power.		
Pre-Conditions: The Arduinos are plugged in via USB and loaded with the correct code.		
Input: 75		
Expected Results: true	Actual Results: As expected	
Post-Conditions: N/A		

Table 59: ArduinoController Test - Shoot

Test ID: SS22	ArduinoController Test - Shoot		Status: PASS
Description: The ArduinoController class will call the <i>shoot</i> method.			
Pass/Fail Condition: The system shoots at 100% power.			
Pre-Conditions: The Arduinos are plugged in via USB and loaded with the correct code.			
Input: 100			
Expected Results: true		Actual Results: As expected	
Post-Conditions: N/A			

Table 60: ArduinoController Test - Shoot

4.3 Hardware Integration Testing

4.3.1 Shooting Testing

Test ID: HI1	Shooting Test - Shot 1		Status: ???
Description: The system can fetch a shot with ID: 48 and shoot it			
Pass/Fail Condition: N/A			
Pre-Conditions: The system is in the home position.			
Input: one-shot mode set at ID 48.			
Expected Results: The shot hits zone 17, with a pitch of 20 and roll angle of 0.		Actual Results: ???	
Post-Conditions: N/A			

Table 61: Shooting Test - Shot 1

Test ID: HI2	Shooting Test - Shot 2	Status: ???
Description: The system can fetch a shot with ID: 91 and shoot it		
Pass/Fail Condition: N/A		
Pre-Conditions: The system is in the home position.		
Input: one-shot mode set at ID 91.		
Expected Results: The shot hits zone 12, with a pitch of 10 and roll angle of 90.		Actual Results: ???
Post-Conditions: N/A		

Table 62: Shooting Test - Shot 2

Test ID: HI3	Shooting Test - Consecutive Shots	Status: ???
Description: The system can shoot two shots consecutively with IDs 148 and 193.		
Pass/Fail Condition: N/A		
Pre-Conditions: The system is in the home position.		
Input: one-shot mode set at ID 148 and then 193.		
Expected Results: The shot hits zone 5, with a pitch of 10 and roll angle of 180, which is followed by another shot that hits zone 2 with a pitch of 0 and roll angle of 270.		Actual Results: ???
Post-Conditions: N/A		

Table 63: Shooting Test - Consecutive Shots

Test ID: HI4	Shooting Test - Repeatability	Status: ???
Description: The system can shoot three shots consecutively with IDs 148, 193 and 148.		
Pass/Fail Condition: The same zone is hit for the first and third shot, at the same pitch and roll angles.		
Pre-Conditions: The system is in the home position.		
Input: one-shot mode set at ID 148, 193 and then 148.		
Expected Results: the first and third shot should be identical		Actual Results: ???
Post-Conditions: N/A		

Table 64: Shooting Test - Repeatability

5 Test Case-Requirement Traceability Matrix

Table 65: Matrix to Match Tests to Functional Requirements [1]

Functional Requirement-Test Matrix																		
	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13	F14	F15	F16	F17	F18
SMC1	X	X	X	X	X													X
SMC2	X	X			X													X
SMC3	X			X														
SMC4	X																	
SMC5	X		X															
SMC6																		
CV1					X													X
CV2					X													
CV3					X													
CV4					X													X
CV5					X													X
CV6						X												X
CV7					X													
CV8					X													
CV9					X													
CV10						X												
CV11					X													
SR1														X	X			
SR2							X							X	X			
SR3																		
SR4														X				
SR5														X				
SM1	X		X		X													
SM2	X	X			X													X
SM3																		
DS1								X										
DS2	X	X	X	X	X	X												X
DS3						X												
DS4									X									
DS5					X	X	X	X					X					

Table 66: Matrix to Match Tests to Functional Requirements [2]

Functional Requirement-Test Matrix																		
	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13	F14	F15	F16	F17	F18
UI1								X	X	X	X	X	X			X	X	
UI2								X	X	X	X	X	X			X	X	
UI3																X		
UI4								X										
UI5								X	X									
UI6					X	X	X						X	X				
SS1							X							X	X			
SS2							X							X	X			
SS3																		
SS4														X				
SS5															X			
SS6														X				
SS7														X				
SS8					X	X												X
SS9					X	X												X
SS10					X	X												X
SS11					X	X												X
SS12						X		X	X				X					X
SS13						X		X	X				X					X
SS14								X										
SS15						X												
SS16									X									
SS17	X	X	X	X	X													X
SS18	X	X	X	X	X													X
SS19	X		X															
SS20	X		X															
SS21	X	X			X													X
SS22	X	X			X													X
HI1	X	X	X	X											X			
HI2	X	X	X	X											X			
HI3	X	X	X	X											X			
HI4	X	X	X	X											X			

Table 67: Matrix to Match Tests to Non-Functional Requirements [1]

Non-Functional Requirement-Test Matrix																		
	LF1	UH1	UH2	P1	P2	P4	P5	OE2	MS2	S1	S2	P1	LC1	HS1	HS2	HS3	HS4	HS5
SMC1														X	X			
SMC2														X	X			
SMC3														X				
SMC4														X				
SMC5														X				
SMC6																		X
CV1								X										
CV2																		
CV3																		
CV4																		
CV5																		
CV6																		
CV7																		
CV8																		
CV9																		
CV10																		
CV11																		
SR1														X	X			
SR2														X				
SR3														X				
SR4																		
SR5																		
SM1														X				
SM2														X	X			
SM3														X				
DS1						X				X								
DS2														X	X			
DS3					X													
DS4																		
DS5									X		X							

Table 68: Matrix to Match Tests to Non-Functional Requirements [2]

Non-Functional Requirement-Test Matrix																		
	LF1	UH1	UH2	P1	P2	P4	P5	OE2	MS2	S1	S2	P1	LC1	HS1	HS2	HS3	HS4	HS5
UI1	X	X	X		X	X	X		X	X		X						
UI2	X	X	X	X														
UI3			X	X														
UI4			X			X				X								
UI5	X	X	X	X														
UI6	X	X	X	X					X									
SS1															X			
SS2															X			
SS3															X			
SS4															X			
SS5															X			
SS6																		
SS7																		
SS8																		
SS9																		
SS10																		
SS11																		
SS12					X	X				X								
SS13					X	X				X				X	X			
SS14						X				X				X	X			
SS15					X													
SS16																		
SS17														X	X			
SS18														X	X			
SS19														X				
SS20														X				
SS21														X	X			
SS22														X	X			
HI1														X	X			
HI2														X	X			
HI3														X	X			
HI4														X	X			

6 Appendix

Shot ID	Zone ID	Roll (degrees, x-axis)	Pitch (degrees, y-axis)
48	17	0	20
91	12	90	10
148	5	180	10
193	2	270	0

Figure 2: Shot details for tested shots