

PGD IN NUCLEAR REACTOR PHYSICS

An Investigation of A Priori Model Reduction for Nuclear Reactor Physics Calculations

Proper Generalized Decomposition

- Assume separable solution
- Flexibility -> can be physical dimensions, material constants, boundary and initial conditions, etc

$$u(x_1, x_2, \dots, x_D) = \sum_{i=1}^n \prod_{k=1}^D X_{i,k}(x_k)$$

- “Curse of dimensionality” is overcome by linear relationship!**

Test Problems: Transient Neutron Diffusion

- Assume separated solution in space and time.

$$\phi(x, t) \approx \sum_{j=1}^n X_j(x) T_j(t) = \sum_{j=1}^{n-1} X_j(x) T_j(t) + \mathcal{X}(x) \mathcal{T}(t)$$

- Solution is enriched by constructing a nonlinear problem.
- Invoke variational formulation, insert assumed separated solution, and integrate over respective dimensions resulting in a 1D BVP and 1D IVP.

BVP – CFEM

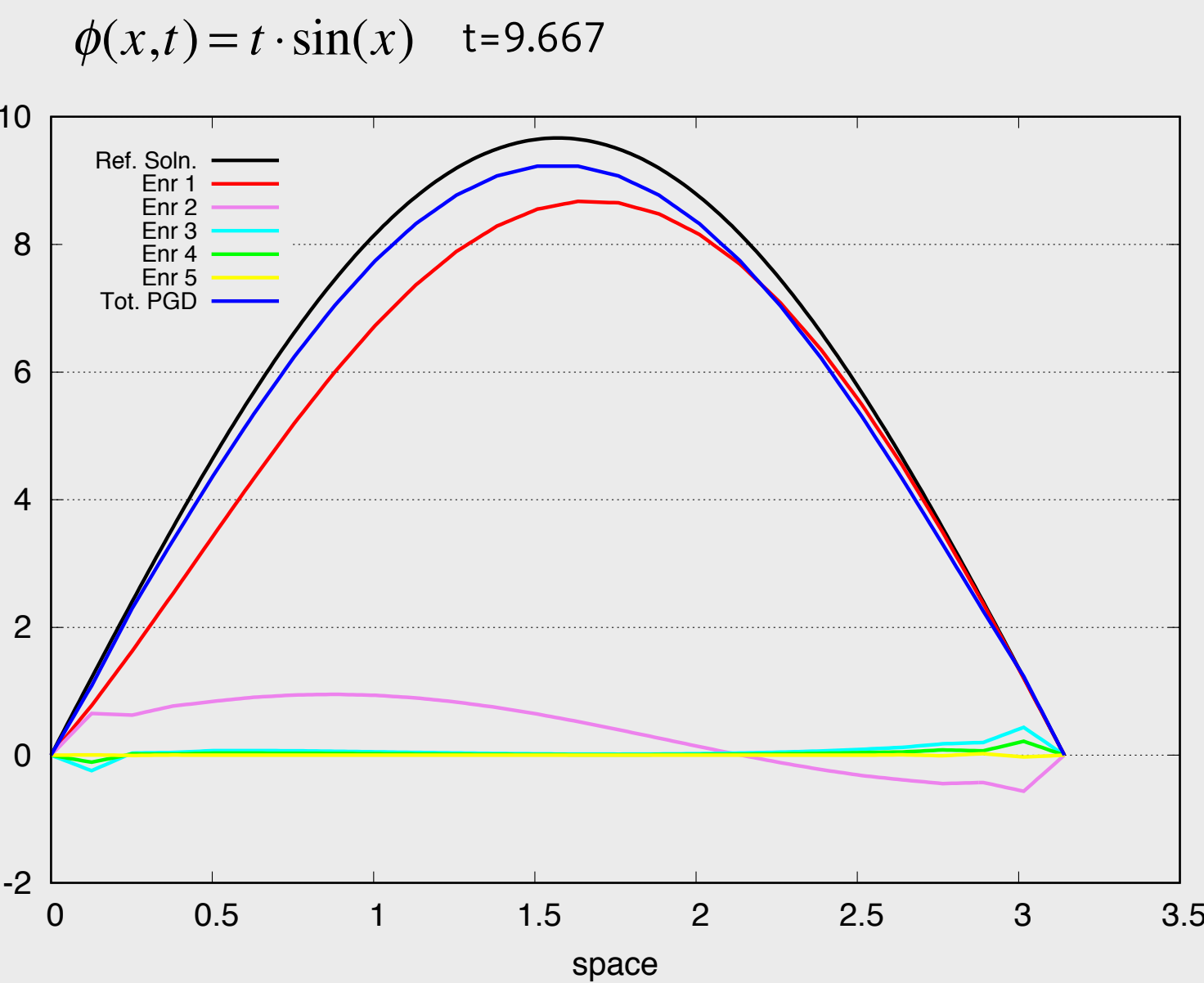
$$\int_{\Omega_x} (t_1 + t_2) u \mathcal{X}(x) dx + \int_{\Omega_x} t_1 \frac{du}{dx} \frac{d\mathcal{X}}{dx} dx$$
$$= - \sum_{j=1}^n \left[\int_{\Omega_x} u X_i(x) (t_{3,i} + t_{4,i}) dx + \int_{\Omega_x} t_{3,i} \left(\frac{du}{dx} \frac{dX_i}{dx} dx \right) \right] + S_x$$

Complications with Neutron Transport

- Consider transient neutron transport equation:

$$\frac{1}{v(E)} \frac{\partial \psi}{\partial t} + \boldsymbol{\Omega} \cdot \boldsymbol{\nabla} \psi + \Sigma_t(\mathbf{r}, E) \psi(\mathbf{r}, E, \boldsymbol{\Omega}, t)$$
$$= \int_{4\pi} d\boldsymbol{\Omega}' \int_0^\infty \Sigma_s(\mathbf{r}, E' \rightarrow E, \boldsymbol{\Omega}' \rightarrow \boldsymbol{\Omega}, t) \psi(\mathbf{r}, E', \boldsymbol{\Omega}', t) dE' + S$$

- 7 degrees of freedom quickly lead to intractability!
- Simplifying assumptions required



IVP – DFEM

$$\int_{\Omega_t} x_1 \left(w \mathcal{T}(t) \Big|_{bndry} - \int_{\Omega_t} \mathcal{T}(t) \frac{dw}{dt} dt \right) + \int_{\Omega_t} (x_2 + x_3) w \mathcal{T}(t) dt$$
$$= - \sum_{j=1}^n \left[\int_{\Omega_t} \frac{1}{v} x_{4,i} w \frac{dT_i}{dt} dt + \int_{\Omega_t} (x_{5,i} - x_{6,i}) w T_i(t) dt \right] + S_t$$

Monoenergetic Transient Neutron Diffusion

- Remove spatial dependence in neutron transport by assuming linearly anisotropic scattering – i.e. scattering physics are *weakly* dependent upon angle
- Assume *no energy dependence* in scattering or external sources.

$$\frac{1}{v} \frac{\partial \phi}{\partial t} - \boldsymbol{\nabla} \cdot D(x) \boldsymbol{\nabla} \phi + \Sigma_a \phi(x, t) = S$$

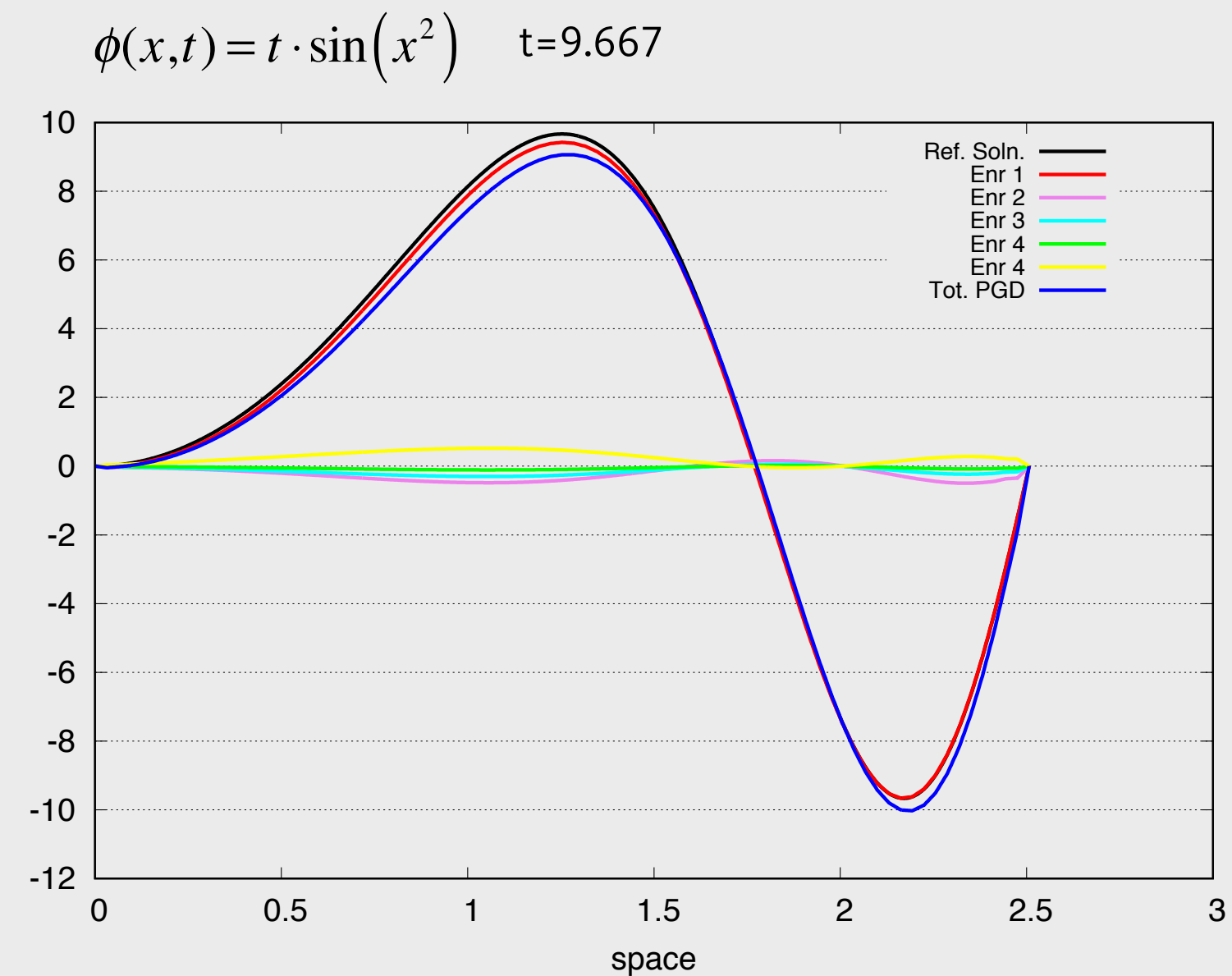


Table 1: L2 norm of difference between reference and approximated solutions.

Enr. Num.	$\phi(x, t) = t \cdot \sin(x)$	$\phi(x, t) = t \cdot \sin(x^2)$
1	3.5022	0.5422
2	2.9955	1.3486
3	2.9460	1.8117
4	2.9410	1.9600
5	2.9405	1.4243
6	2.9401	1.9105

DOE Nuclear Engineering Advanced Modeling and Simulation

- Understanding the operational characteristics and overall safety of the core of a nuclear reactor is arguably one of the most important aspects of any reactor design.
- Goal of program is to develop state-of-the-art computational methods to accelerate the development and deployment of novel nuclear power technologies.

Basic Algorithm

```
for m = 1 to m_max
  define X^(0), T^(0) (initialization)
  for k = 1 to k_max
    compute X^(k) = F_m(T^(k-1))
    compute T^(k) = G_m(X^(k))
    check convergence of X^(k)T^(k)
  end
  X^(k) = X^(k) / (||X^(k)|| ||T^(k)||)
  normalize T^(k) = T^(k) / (||X^(k)|| ||T^(k)||)

  set K^(k) = K_m and T^(k) = T_m
  set phi_m = phi_{m-1} + K_m T_m and check convergence
end
```

Future Work

- Solution enrichment analysis
 - Why doesn't test #2 improve monotonically?
 - Unrecoverable error in both test cases.
- Nonlinear sources.
- Analysis of higher order polynomials.
- Spatial discontinuities.