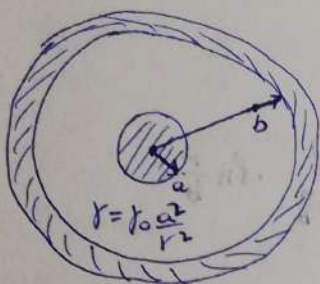


Ασκηση 11ος Τρόπος

$$\vec{J} = \frac{I}{2\pi r^2} \hat{r}$$

$$\vec{E} = \frac{\vec{J}}{\delta} = \frac{I}{2\pi \delta r^2} \hat{r} = \frac{I}{4\pi \delta_0 a^2} \hat{r}$$

$$\text{Άρα, } V = \int_a^b E dr = \frac{I}{4\pi \delta_0 a^2} (b-a) \quad \text{οπότε } R = \frac{V}{I} = \frac{b-a}{4\pi \delta_0 a^2}$$

2ος Τρόπος

$$\nabla \vec{J} = 0 \Rightarrow \nabla(\delta \nabla \Phi) = 0 \Rightarrow \frac{1}{r^2} \frac{\partial}{\partial r} \left(\delta_0 a^2 \frac{\partial \Phi}{\partial r} \right) = 0 \Rightarrow \frac{\partial^2 \Phi}{\partial r^2} = 0 \Rightarrow \Phi = A r + B$$

$$\cdot \text{για } r=b: \Phi(b)=0 \Rightarrow B = -Ab$$

$$\cdot \text{για } r=a: \Phi(a)=V \Rightarrow Aa + B = V$$

$$\text{οπότε } \Phi = \frac{V}{b-a} (b-r)$$

$$\vec{E} = -\nabla \Phi = \frac{V}{(b-a)} \hat{r} \quad \text{Άρα } \vec{J} = \delta \frac{V}{b-a} \hat{r}$$

$$I = \int J ds = \int \frac{\delta_0 a^2 V r^2}{(b-a) r^2} \sin \theta d\theta d\phi = \frac{4\pi \delta_0 a^2 V}{b-a} \quad \text{οπότε } R = \frac{V}{I} = \frac{b-a}{4\pi \delta_0 a^2}$$

3ος Τρόπος

$$dR = \frac{1}{\delta} \cdot \frac{1}{s} = \frac{1}{\delta} \cdot \frac{dr}{4\pi r^2} = \frac{dr}{4\pi \delta_0 a^2}$$

$$R = \int_a^b \frac{dr}{4\pi \delta_0 a^2} = \frac{b-a}{4\pi \delta_0 a^2}$$

4ος Τρόπος

$$\text{Έστω } \epsilon(r) = \frac{\epsilon_0 a^2}{r^2}, \text{ οπότε } \frac{\epsilon(r)}{\delta(r)} = \frac{\epsilon_0}{\delta_0} = \text{const.}$$

$$\text{Άρα, } RC = \frac{\epsilon_0}{\delta_0} \quad \text{Οπότε } C = \frac{1}{\int_a^b \frac{\delta_0 a^2}{r^2} 4\pi r^2 dr} = \frac{4\pi \delta_0 a^2}{b-a} \quad \text{Άρα } R = \frac{\epsilon_0}{\delta_0 C} = \frac{\epsilon_0 (b-a)}{\delta_0 4\pi \delta_0 a^2} = \frac{b-a}{4\pi \delta_0 a^2}$$

Ασκηση 2 (10.20)

a). $\nabla^2 \phi = 0$ σε όλο τον χώρο

$$\frac{\partial}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right) = 0 \Rightarrow r \frac{\partial \phi}{\partial r} = c_1 \Rightarrow \phi(r) = c_1 \ln r + c_2$$

$$\phi(a) = V \Rightarrow c_1 \ln a + c_2 = V \Rightarrow c_1 = -\frac{V}{\ln \frac{b}{a}}$$

$$\phi(b) = 0 \Rightarrow c_1 \ln b + c_2 = 0 \Rightarrow c_2 = \frac{\ln b \cdot V}{\ln \frac{b}{a}}$$

$$\Rightarrow \phi(r) = -\frac{V}{\ln \frac{b}{a}} \cdot \ln \frac{r}{b}$$

$$\vec{E} = -\nabla \phi = \frac{V}{\ln \frac{b}{a}} \cdot \frac{1}{r} \cdot \hat{r}$$

$$\vec{J} = \begin{cases} \frac{\partial_1 V}{\ln \frac{b}{a}} \cdot \frac{1}{r} \hat{r} \\ \frac{\partial_2 V}{\ln \frac{b}{a}} \cdot \frac{1}{r} \hat{r} \end{cases}$$

Για $i \in 1$, $\nabla \cdot (\epsilon_1 \nabla \phi_1) = \rho_1$ και $\nabla \cdot (\epsilon_2 \nabla \phi_2) = \rho_2$

$$\downarrow$$

$$\nabla^2 \phi_1 = \frac{\rho_1}{\epsilon_1}$$

$$0 = \frac{\rho_1}{\epsilon_1}$$

$$\downarrow$$

$$\nabla^2 \phi_2 = \frac{\rho_2}{\epsilon_2}$$

$$0 = \frac{\rho_2}{\epsilon_2}$$

Αρα $\rho_1 = \rho_2 = 0$

$$\sigma_1 = (\vec{0} - \vec{D}_1(b)) \cdot \hat{r} = -\frac{\epsilon_1 V}{\ln \frac{b}{a}} \cdot \frac{1}{b}$$

β). $R^H = \frac{V}{I^H}$

$$I^H = \int_0^n J_1 \cdot r \cdot d\varphi + \int_n^{2\pi} J_2 \cdot r \cdot d\varphi = \frac{(J_1 + J_2) V n}{\ln \frac{b}{a}}$$

$$\text{Οπότε } R^H = \frac{\ln \frac{b}{a}}{(J_1 + J_2) n}$$

Άσκηση 3 (10.21)

α) Για σταθερό λογίτι $\nabla^2 \phi = 0$ παντού

$$\begin{aligned} \text{Άρα } \cdot \frac{\partial^2 \phi}{\partial z^2} = 0 &\Rightarrow \phi(z) = (1z + c_2) \\ \cdot \phi(0) = 0, \phi(h) = V &\end{aligned} \left. \vphantom{\frac{\partial^2 \phi}{\partial z^2}} \right\} \Rightarrow \phi(z) = \frac{V}{h} z$$

$$\cdot \bar{E} = -\nabla \phi = -\frac{V}{h} \hat{z}$$

$$\cdot \bar{J} = \epsilon_0 \bar{E} = -\frac{\epsilon_0 V}{h} \hat{z}$$

$$\cdot \text{Άρα, } I = \oint \bar{J} \cdot d\bar{s} = \iint J_z dx dy = \frac{d \cdot (-V)}{h} (a f_1 + (b-a) f_2 + (c-b) f_3)$$

$$\text{Οπότε } R = \frac{(-V)}{I} = \frac{h}{d(a f_1 + (b-a) f_2 + (c-b) f_3)}$$

β) Για $f_2 = \frac{f_0 x}{a}$, λόγω συμμετρίας λογίτι $\phi(z) = \frac{V}{h} z$

$$\cdot \text{Άρα } \bar{E} = -\nabla \phi = -\frac{V}{h} \hat{z}$$

$$I = \oint \bar{J} \cdot d\bar{s} = \frac{d(-V)}{h} \left(\int_0^a f_1 dx + \int_a^b \frac{f_0 x}{a} dx + \int_b^c f_3 dx \right) \Rightarrow$$

$$\Rightarrow I = \frac{d(-V)}{h} \left(a f_1 + \frac{b^2 - a^2}{2a} f_0 + (c-b) f_3 \right)$$

$$\text{Οπότε } R = \frac{h}{d(a f_1 + \frac{b^2 - a^2}{2a} f_0 + (c-b) f_3)}$$