The Buckingham Pi Theorem in Dimensional Analysis

Reading; F. M. White Fluid Mechanics Sections 5.1-5.4

Historical Note

The Buckingham Pi Theorem puts the 'method of dimensions' first proposed by Lord Rayleigh in his book "The Theory of Sound" (1877) on a solid theoretical basis, and is based on ideas of matrix algebra and concept of the 'rank' of non-square matrices which you may see in math classes. Although it is credited to E. Buckingham (1914), in fact, White points out that the theorem has also appeared earlier in independent publications by A. Vaschy (1892) and D. Riabouchinsky (1911).

The Theorem

Let $q_1, q_2, q_3...q_n$ be n dimensional variables that are physically relevant in a given problem and that are inter-related by an (unknown) dimensionally homogeneous set of equations. These can be expressed via a functional relationship of the form

$$F(q_1, q_2, ... q_n) = 0$$
 or equivalently $q_1 = f(q_2, ... q_n)$

If k is the number of fundamental dimensions required to describe the n variables, then there will be k primary variables and the remaining j = (n - k) variables can be expressed as (n - k) dimensionless and independent quantities or 'Pi groups', $\Pi_1, \Pi_2 ... \Pi_{n-k}$. The functional relationship can thus be reduced to the much more compact form:

$$\Phi(\Pi_1, \Pi_2 \dots \Pi_{n-k}) = 0$$
 or equivalently $\Pi_1 = \phi(\Pi_2, \dots \Pi_{n-k})$

⇒ Note that this set of non-dimensional parameters is <u>not unique</u>. They are however independent and form a complete set.

Application

- i) Clearly define the problem and think about which variables are important. Identify which is the main variable of interest i.e. $q_1 = f(q_2,...q_n)$. It is important to think physically about the problem. Are there any constraints; *i.e.* 'can I vary all of these variables independently'; e.g. weight of an object $F_w = \rho g \ell^3$ (only two of these are independent, unless g is also variable)
- ii) Express each of n variable in terms of its fundamental dimensions, $\{MLT\theta\}$ or $\{FLT\theta\}$ It is often useful to use one system to do problem, and then check that groups you obtain are dimensionless by converting to other system.
- iii) Determine the number of Pi groups, j = n k where k is the number of reference dimensions and select k primary or repeating variables.

 Typically pick variables which characterize the fluid properties, flow geometry, flow rate...
- iv) Form j dimensionless Π groups and check that they are all indeed dimensionless.
- v) Express result in form $\Pi_1 = \phi(\Pi_2, ..., \Pi_{n-k})$ where Π_1 contains the quantity of interest and interpret your result physically!
- vi) Make sure that your groups are indeed independent; i.e. can I vary one and keep others constant.
- vii) Compare with experimental data!

Tables 5.1 and 5.2 from White

Drag coefficient

Drag force

Dynamic force

Parameter	Definition	Qualitative ratio of effects	Importance	Quantity	Symbol	Dimensions	
						$MLT\Theta$	FLT(-)
Reynolds number	$Re = \frac{\rho UL}{\mu}$	Inertia	Always	Length	L	L	L
		Viscosity		Area	A	L^2	L^2
Mach number	$Ma = \frac{U}{a}$	Flow speed Sound speed	Compressible flow	Volume Velocity	1 ' \'	$\frac{L^3}{LT^{-3}}$	L^3
				Acceleration	dV/dt	LT^{-2}	$\frac{LT^{-1}}{LT^{-2}}$
Froude number	$F_{r} = \frac{U^2}{gL}$	Inertia	Free-surface flow	Speed of sound	aviai	LT^{-1}	LT^{-1}
		Gravity		Volume flow	Q	$L^{3}T^{-1}$	L^{1} $L^{3}T^{-1}$
	1. 图 图 图 图 图 图 图 图 图 图 图 图 图 图 图 图 图 图 图			Mass flow	in Q	$\frac{L}{MT}^{-1}$	FTL ⁻¹
Weber number	$We = \frac{\rho U^2 L}{Y}$	Inertia Surface tension	Free-surface flow	Pressure, stress	p, σ	$ML^{-1}T^{-2}$	FL ⁻²
				Strain rate	$\dot{\epsilon}$	T^{-1}	T^{+1}
Cavitation number (Euler number)	$Ca = \frac{p - p_v}{\rho U^2}$	<u>Pressure</u>	Cavitation	Angle	θ	None	None
		Inertia		Angular velocity	ω	T^{-1}	7
Prandtl number	$Pr = \frac{\mu c_p}{k}$	Dissipation Conduction	Heat convection	Viscosity	μ	$ML^{-1}T^{-1}$	FTL"
				Kinematic viscosity	1'	L^2T^{-1}	L^2T^{++}
Eckert number	$Ec = \frac{U^2}{c_p T_0}$		- Dissipation	Surface tension	Y	MT^{-2}	FL^{-1}
		Kinetic energy		Force	F	MLT^{-2}	F
		Enthalpy		Moment, torque	M	ML^2T^{-2}	FL
Specific-heat ratio	$k = \frac{c_p}{c_v}$	Enthalpy	Compressible flow	Power	P	ML^2T^{-3}	FLT ⁻¹
		Internal energy		Work, energy	W, E	$ML^2T^{-\frac{1}{2}}$	FL
Strouhal number	$St = \frac{\omega L}{U}$	Oscillation Mean speed	Oscillating flow	Density	ρ	ML^{-3}	FT^2L^{-4}
				Temperature	\mathcal{T}	(-)	(-)
				Specific heat	$C_{f^{**}}/C_{\mathfrak{t}^{*}}$	$L^{2}T^{-2}\Theta^{-1}$	$L^2T^{-2}\Theta^{-1}$
Roughness ratio	- 	Wall roughness	Turbulent, rough walls	Specific weight Thermal conductivity	Ÿ	$ML^{-2}T^{-2}$	FL ⁻¹
		Body length		Expansion coefficient	K C	MLT - 3(c) 1 (c) 1	$FT^{-1}\Theta^{-1}$
Grashof number	$Gr = \frac{\beta \Delta T g L^3 \rho^2}{\mu^2}$	Buoyancy Viscosity	Natural convection	1. Spansion Coefficient	β	(-)	(-) 1
Temperature ratio	$\frac{T_{\rm w}}{T_0}$	Wall temperature	Heat transfer				
	10	Stream temperature					
Pressure coefficient	$C_p = \frac{p - p_x}{\frac{1}{2}\rho U^2}$	Static pressure Dynamic pressure	Aerodynamics, hydrodynamics				
Lift coefficient	$C_L = \frac{L}{\frac{1}{2}\rho U^2 A}$	Lift force Dynamic force	Aerodynamics, hydrodynamics				

Aerodynamics, hydrodynamics