

Introduction to Computer Graphics

4. Clipping

I-Chen Lin

National Yang Ming Chiao Tung University

Textbook: E. Angel, D. Shreiner Interactive Computer Graphics, 6th Ed., Pearson
Ref: D.D. Hearn, M. P. Baker, W. Carithers, Computer Graphics with OpenGL, 4th Ed., Pearson

Intended Learning Outcomes

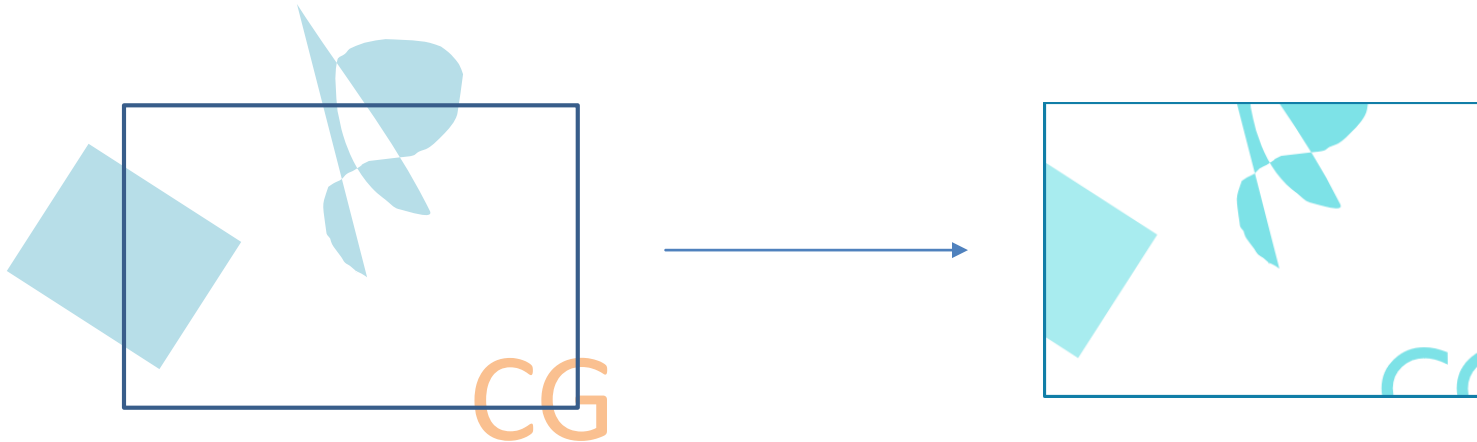
- ▶ On completion of this chapter, a student will be able to:
 - ▶ Identify the polygons that should be clipped and explain the reason behind.
 - ▶ Describe the typical clipping operations and algorithms.
 - ▶ Indicate the stage where clipping is applied within the graphics pipeline.

Objectives

- ▶ Introduce basic implementation strategies
- ▶ 2D Clipping
 - ▶ Lines
 - ▶ Polygons
- ▶ Clipping in 3D

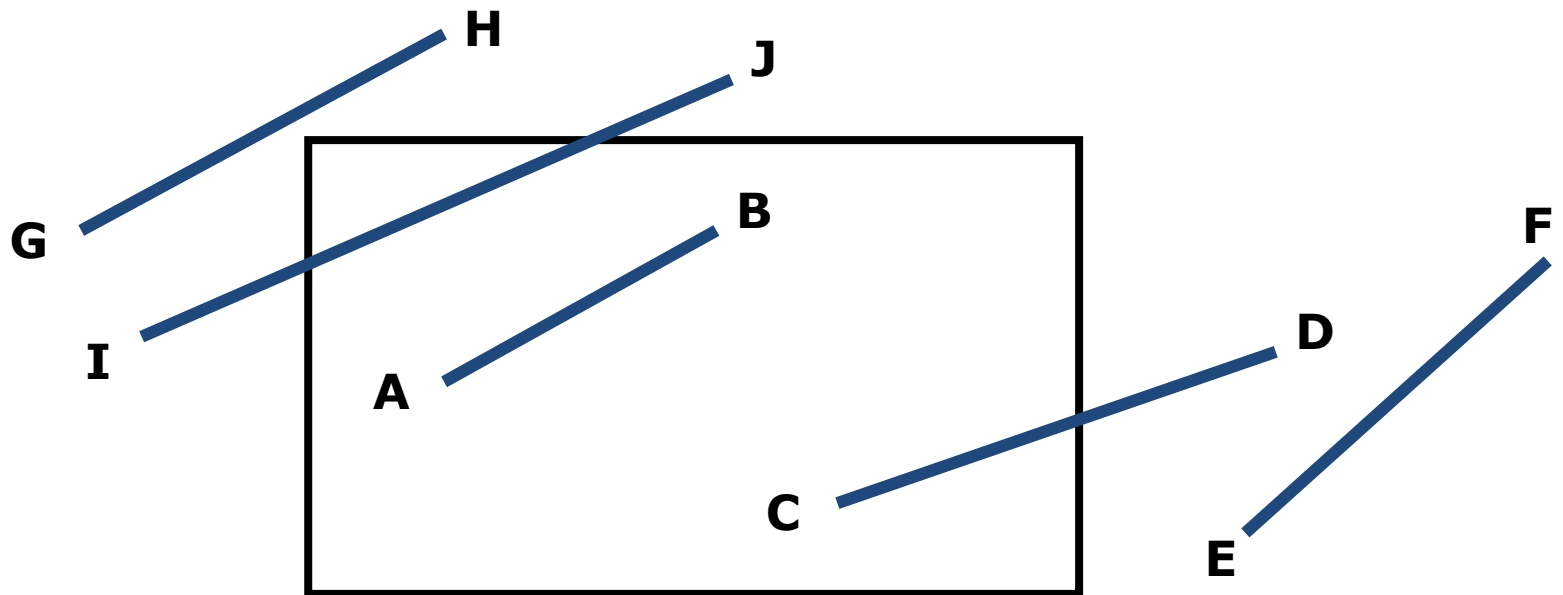
Clipping

- ▶ 2D against clipping window
- ▶ 3D against clipping volume
- ▶ Easy for line segments polygons
- ▶ Hard for curves and text
 - ▶ Convert to lines or polygons first



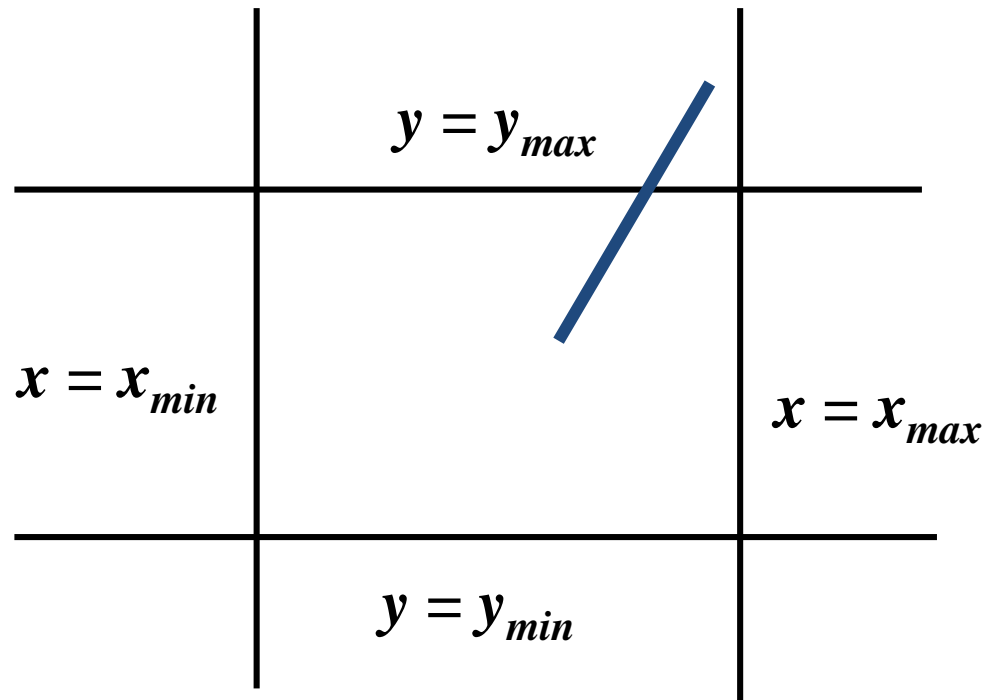
Clipping 2D Line Segments

- ▶ Brute force approach: compute intersections with all sides of clipping window
 - ▶ Inefficient: one division per intersection



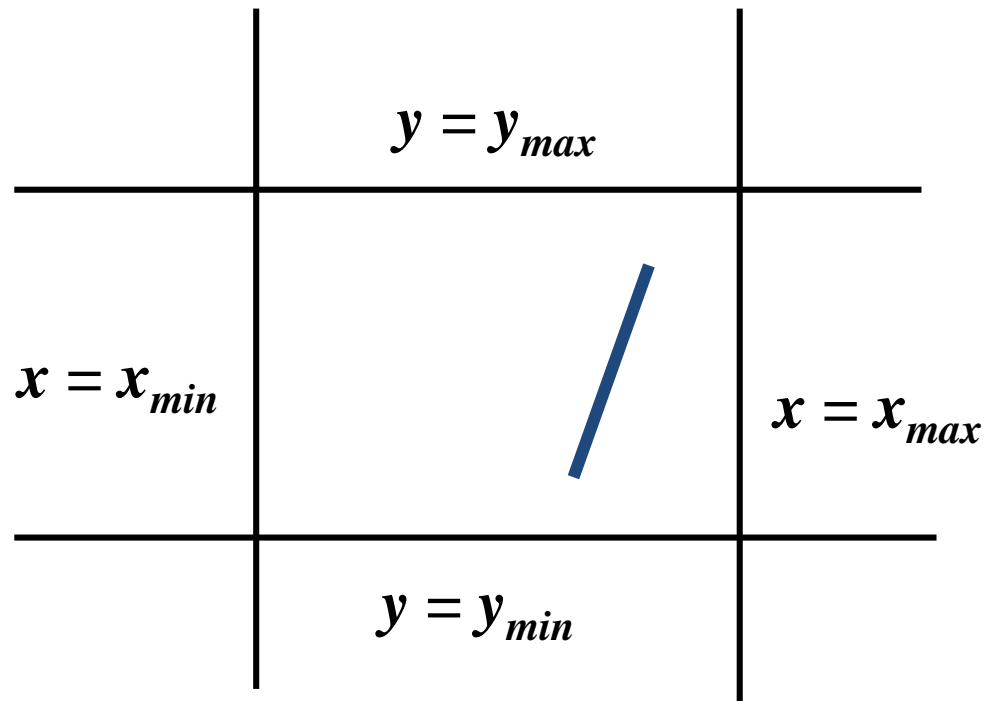
Cohen-Sutherland Algorithm

- ▶ Idea: eliminate as many cases as possible without computing intersections
- ▶ Start with four lines that determine the sides of the clipping window



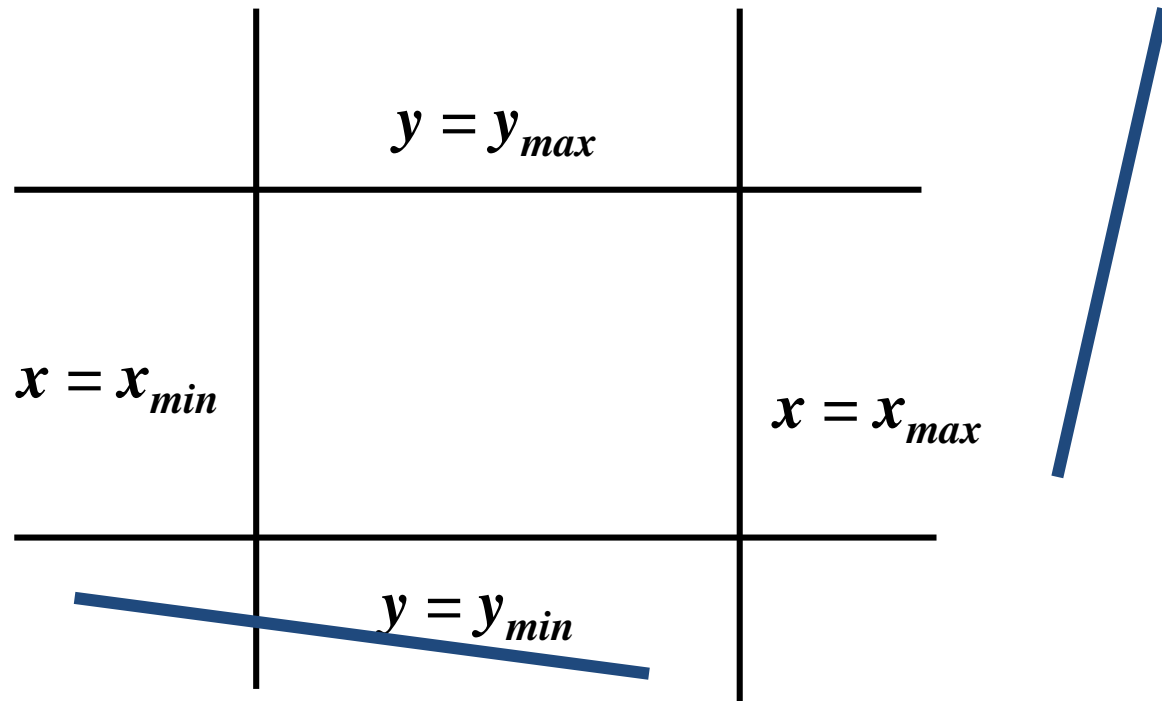
Case 1

- ▶ Case 1: both endpoints of a line segment inside all four lines
 - ▶ Draw (accept) the line segment as is



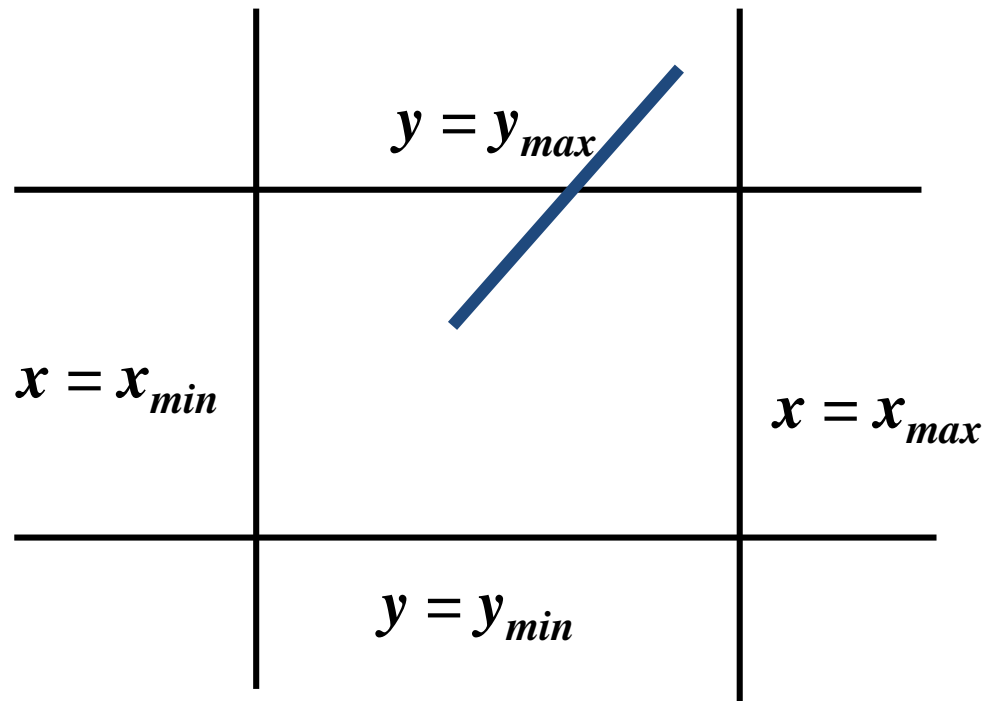
Case 2

- ▶ Case 2: both endpoints outside all lines and on same side of a line
 - ▶ Discard (reject) the line segment



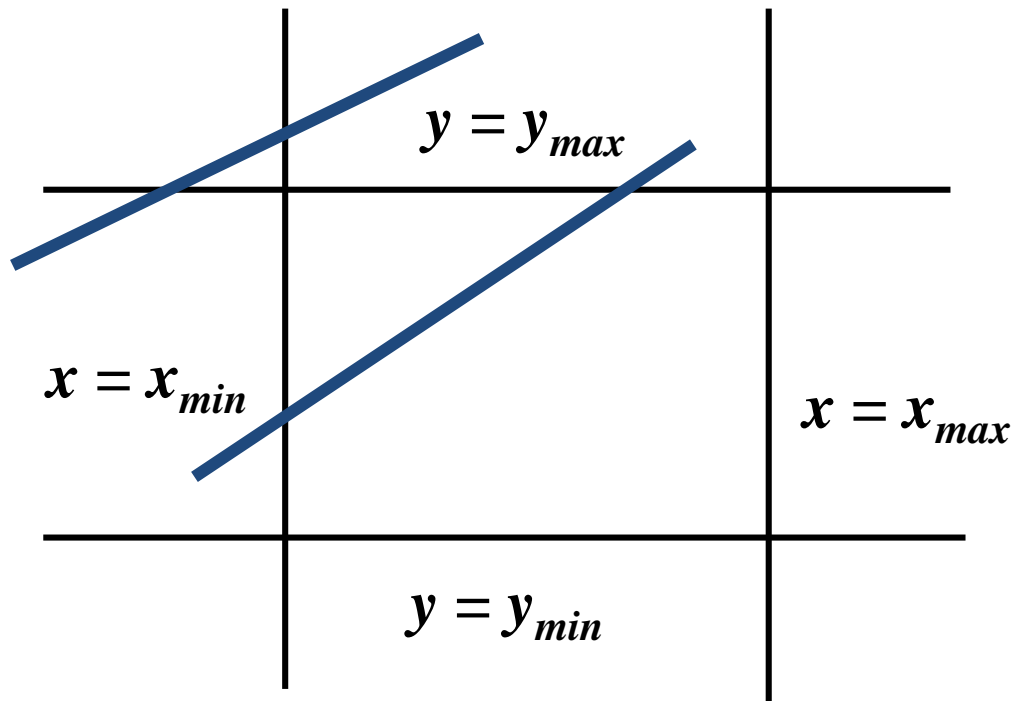
Case 3

- ▶ One endpoint inside, one outside
 - ▶ Must do at least one intersection



Case 4

- ▶ Both outside
 - ▶ May have part inside
 - ▶ Must do at least one intersection



Defining Outcodes

- ▶ For each endpoint, define an outcode
 - ▶ [b0 b1 b2 b3]
- ▶ Outcodes divide space into 9 regions
- ▶ Computation of outcode requires at most 4 subtractions

1001	1000	1010
0001	0000	0010
0101	0100	0110

b0 = 1 if $y > y_{\max}$, 0 otherwise

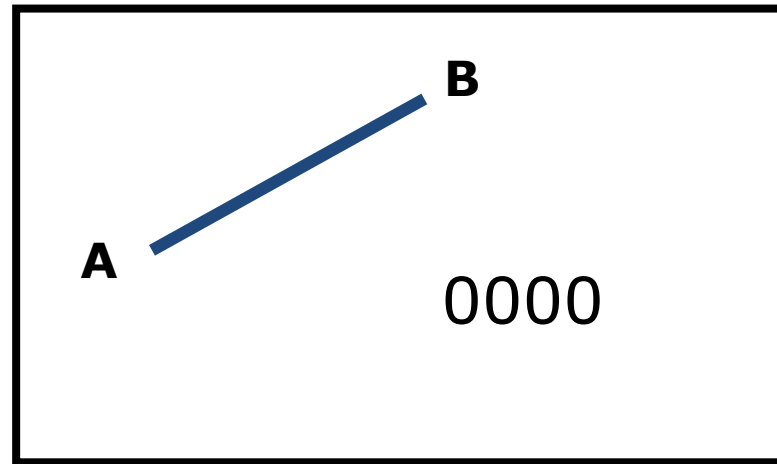
b1 = 1 if $y < y_{\min}$, 0 otherwise

b2 = 1 if $x > x_{\max}$, 0 otherwise

b3 = 1 if $x < x_{\min}$, 0 otherwise

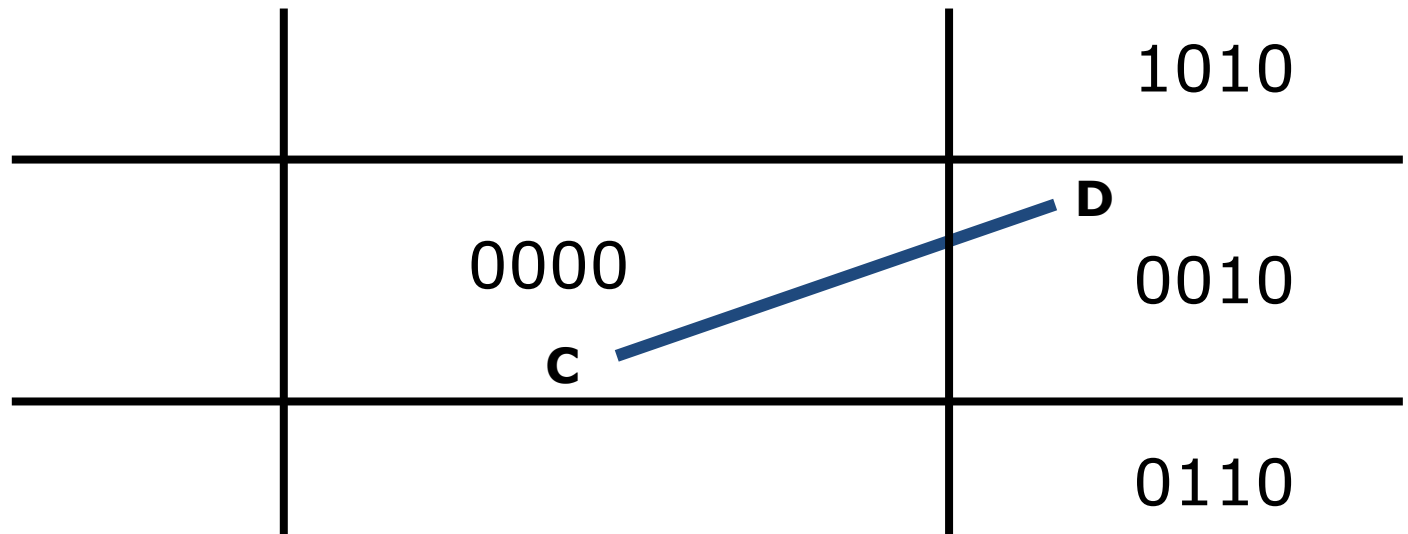
Using Outcodes

- ▶ AB: $\text{outcode}(A) = \text{outcode}(B) = 0$
- ▶ Accept the line segment



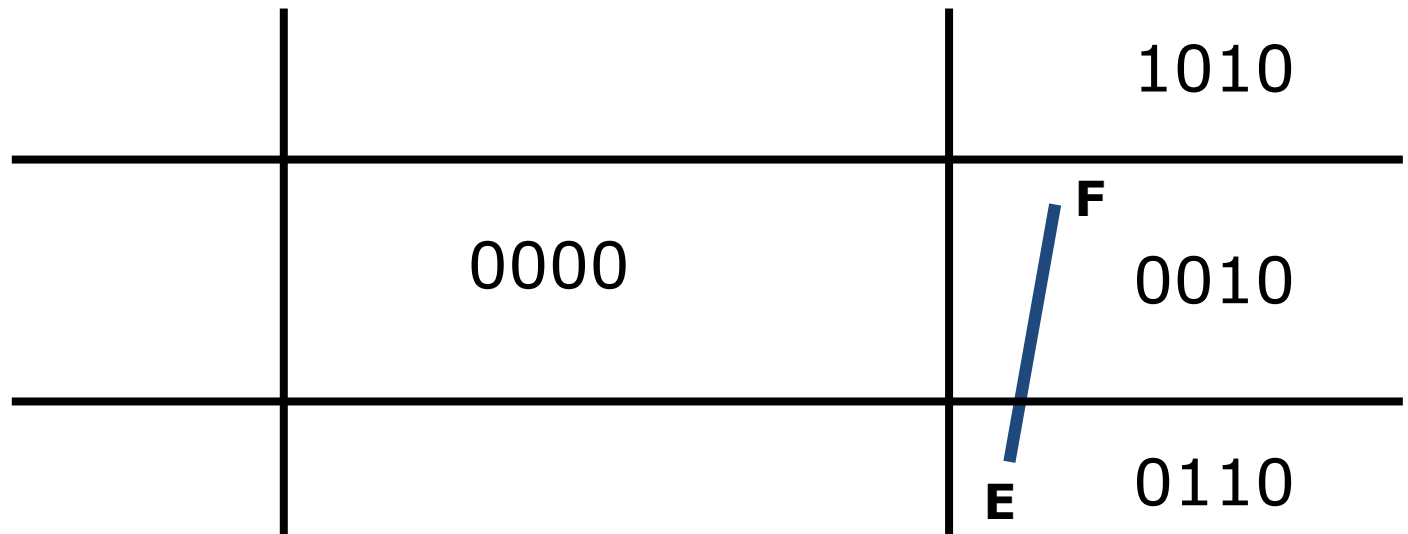
Using Outcodes

- ▶ CD: outcode (C) = 0, outcode(D) \neq 0
 - ▶ Compute intersection
 - ▶ Location of 1 in outcode(D) determines which edge to intersect with
 - ▶ Note if there were a segment from C to a point in a region with 2 ones in outcode, we might have to do two intersections



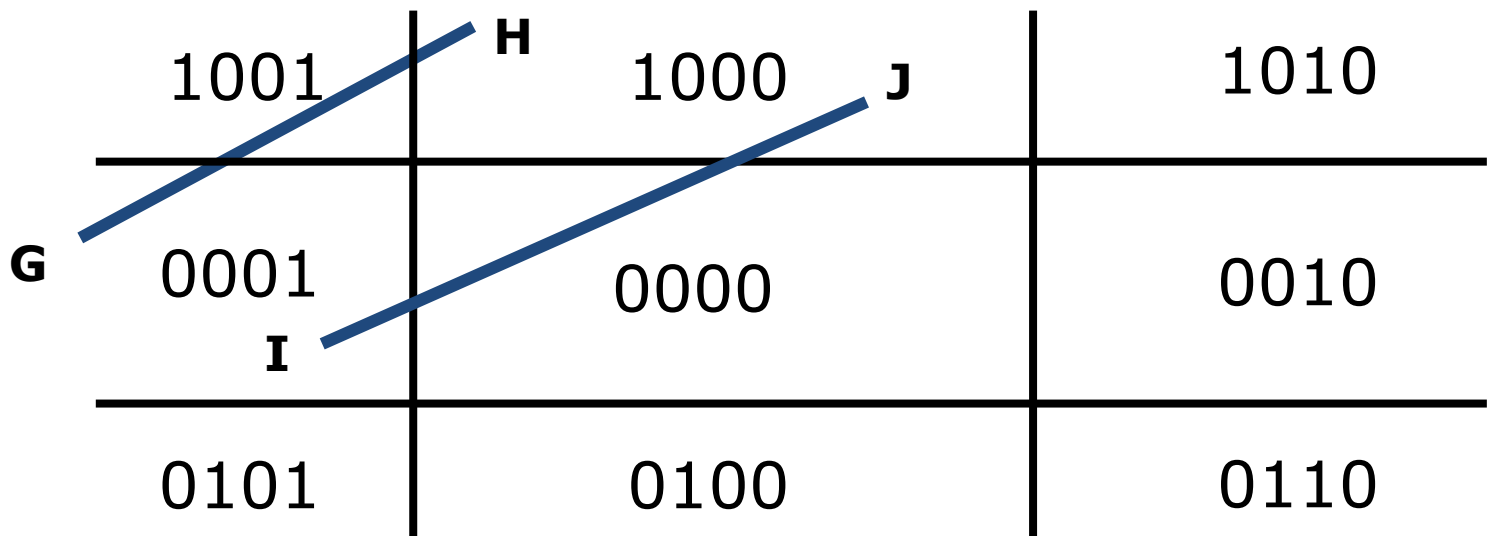
Using Outcodes

- ▶ EF: outcode(E) logically ANDed with outcode(F) (bitwise) $\neq 0$
 - ▶ Both outcodes have a 1 bit in the same place
 - ▶ The line segment is outside of corresponding side of clipping window
 - ▶ reject



Using Outcodes

- ▶ GH and IJ: same outcodes, neither zero but logical AND yields zero
 - ▶ Shorten line segment by intersecting with one of sides of window
 - ▶ Compute outcode of intersection (new endpoint of shortened line segment)
 - ▶ Re-execute algorithm

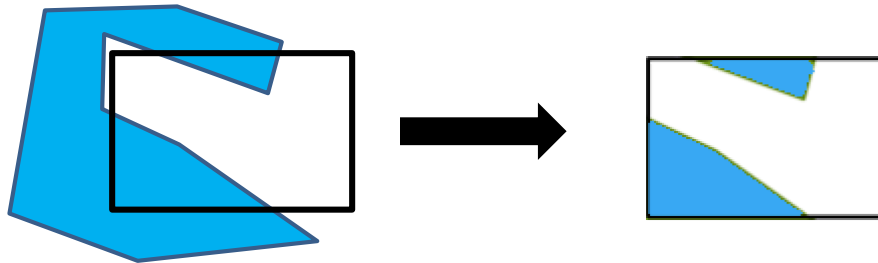


Efficiency

- ▶ In many applications, the clipping window is small relative to the size of the entire data base
 - ▶ Most line segments can be eliminated based on their outcodes.
- ▶ Inefficiency when code has to be re-executed for line segments that must be shortened in more than one step

Polygon Clipping

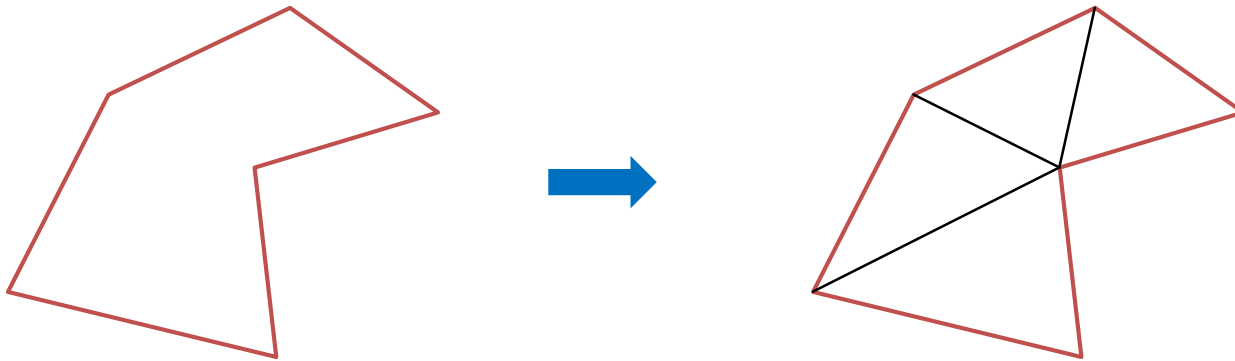
- ▶ Not as simple as line segment clipping
 - ▶ Clipping a line segment yields at most one line segment
 - ▶ Clipping a polygon can yield multiple polygons



- ▶ However, clipping a convex polygon can yield at most one other polygon

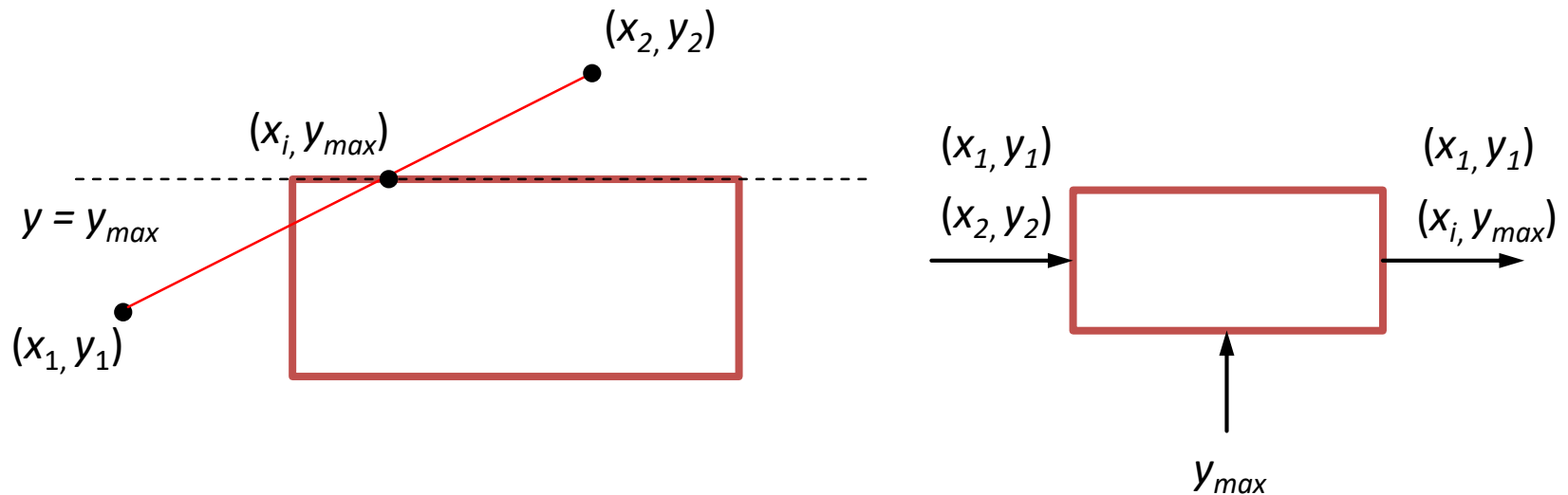
Tessellation and Convexity

- ▶ One strategy is to replace nonconvex (concave) polygons with a set of triangular polygons (a tessellation)
- ▶ Also makes fill easier



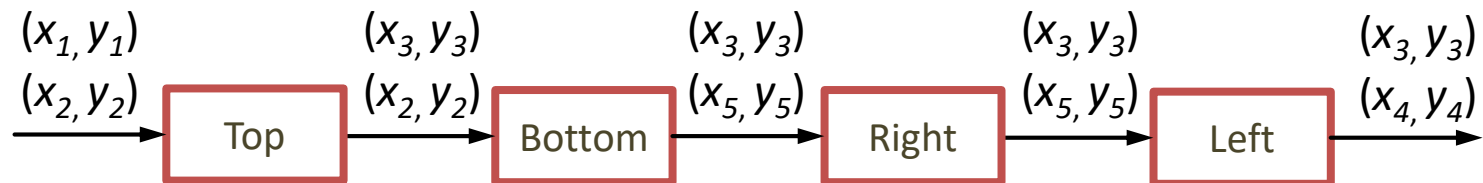
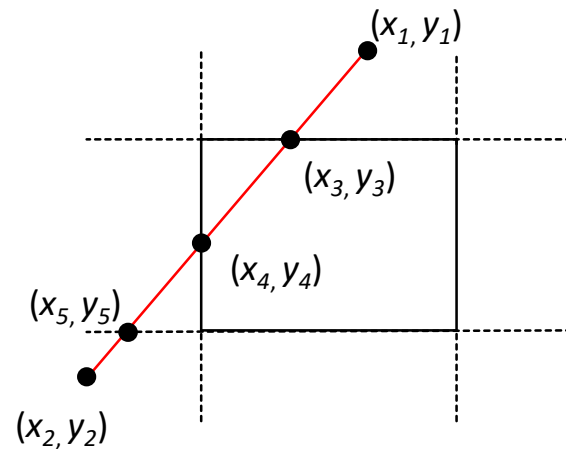
Clipping as a Black Box

- ▶ Consider line segment clipping as a process that takes in two vertices and produces either no vertices or the vertices of a clipped line segment.



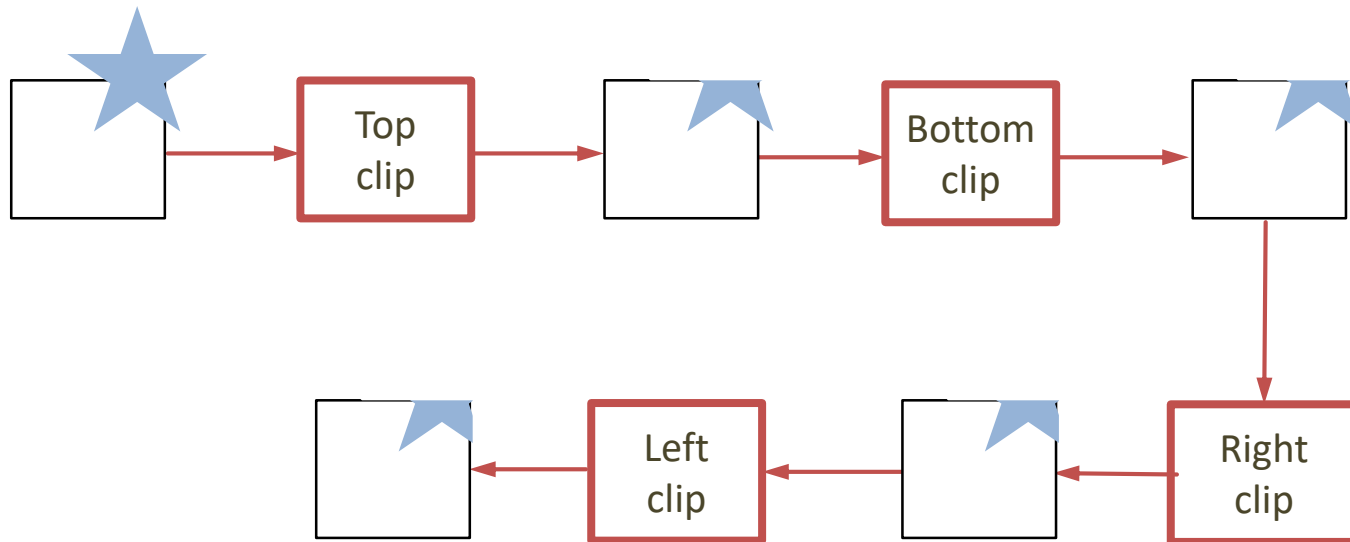
Pipeline Clipping of Line Segments

- ▶ Clipping against each side of window is independent of other sides
 - ▶ Can use four independent clippers in a pipeline



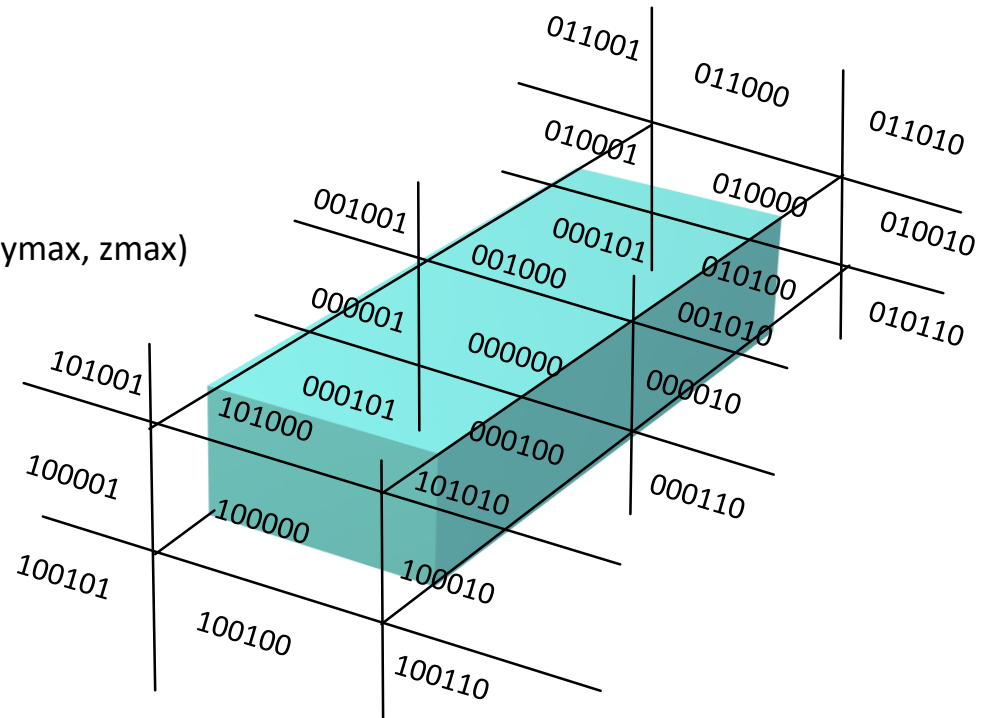
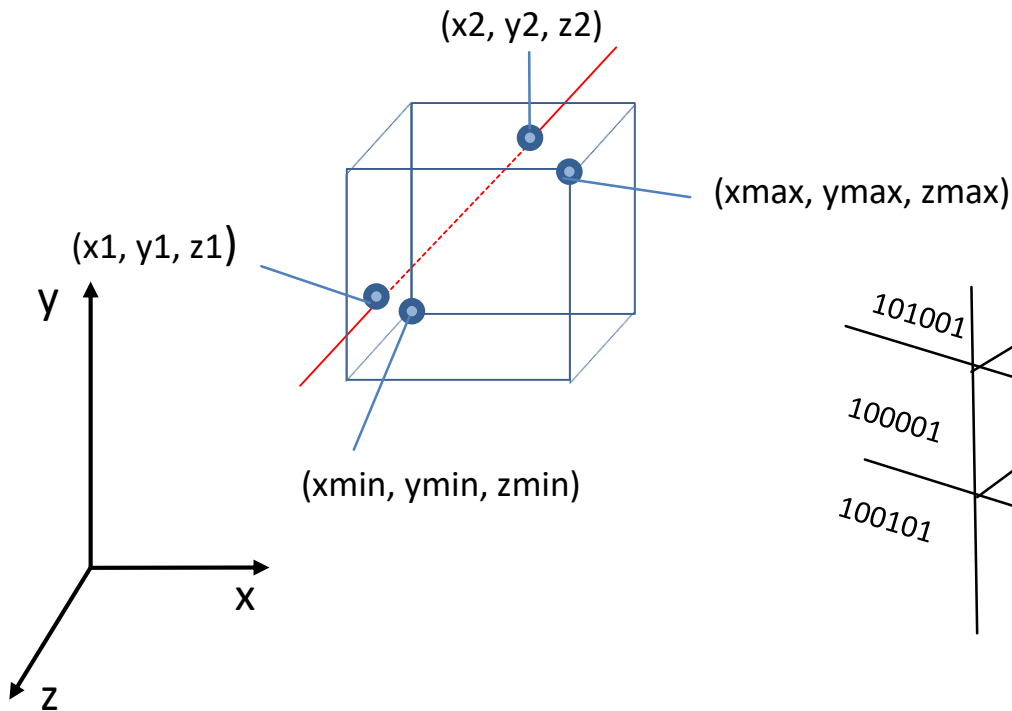
Pipeline Clipping of Polygons

- ▶ Sutherland-Hodgman algorithm
- ▶ Strategy used in SGI Geometry Engine
- ▶ Small increase in latency



Cohen-Sutherland Method in 3D

- ▶ Use 6-bit outcodes
 - ▶ When needed, clip line segments against planes



Cohen-Sutherland Method in 3D

Check for outcodes:

$$-1 \leq x_p \leq 1, -1 \leq y_p \leq 1, -1 \leq z_p \leq 1$$

Since

$$\begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} \xRightarrow{\text{SRT...}} \begin{bmatrix} x_h \\ y_h \\ z_h \\ h \end{bmatrix} \xRightarrow{\text{Divide h}} \begin{bmatrix} x_h/h \\ y_h/h \\ z_h/h \\ 1 \end{bmatrix} = \begin{bmatrix} x_p \\ y_p \\ z_p \\ 1 \end{bmatrix}$$

To avoid unnecessary float division, We can check

$$-h \leq x_h \leq h, -h \leq y_h \leq h, -h \leq z_h \leq h$$

Cohen-Sutherland Method in 3D

- ▶ If $\text{outcode}(A) == \text{outcode}(B) == 0$
 - ▶ Accept the whole line segment.
- ▶ If $(\text{outcode}(A) \text{ and } \text{outcode}(B)) \neq 0$
 - ▶ Reject the line segment.

- ▶ Other cases

- ▶ Calculate an intersection (according to outcode bits)
 - ▶ Then check outcode again

- ▶ Note: use parametric forms

$$x_h = x_{ha} + (x_{hb} - x_{ha})u$$

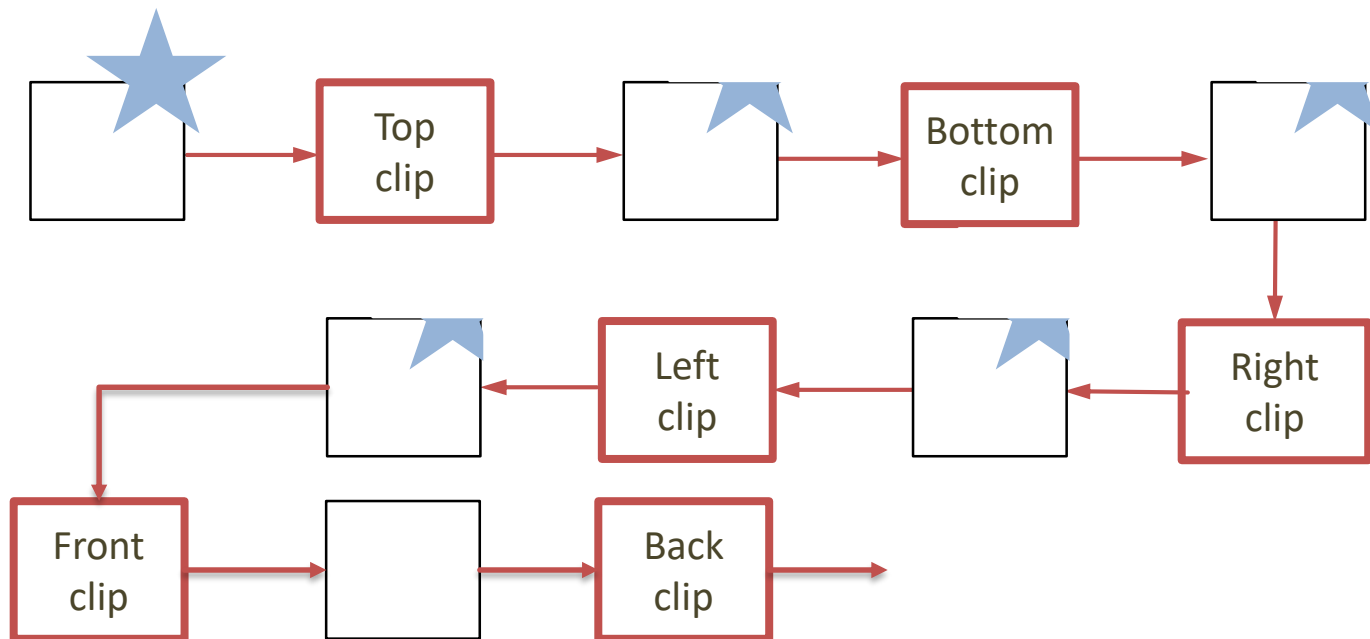
$$y_h = y_{ha} + (y_{hb} - y_{ha})u$$

$$z_h = z_{ha} + (z_{hb} - z_{ha})u$$

$$h = h_a + (h_b - h_a)u$$

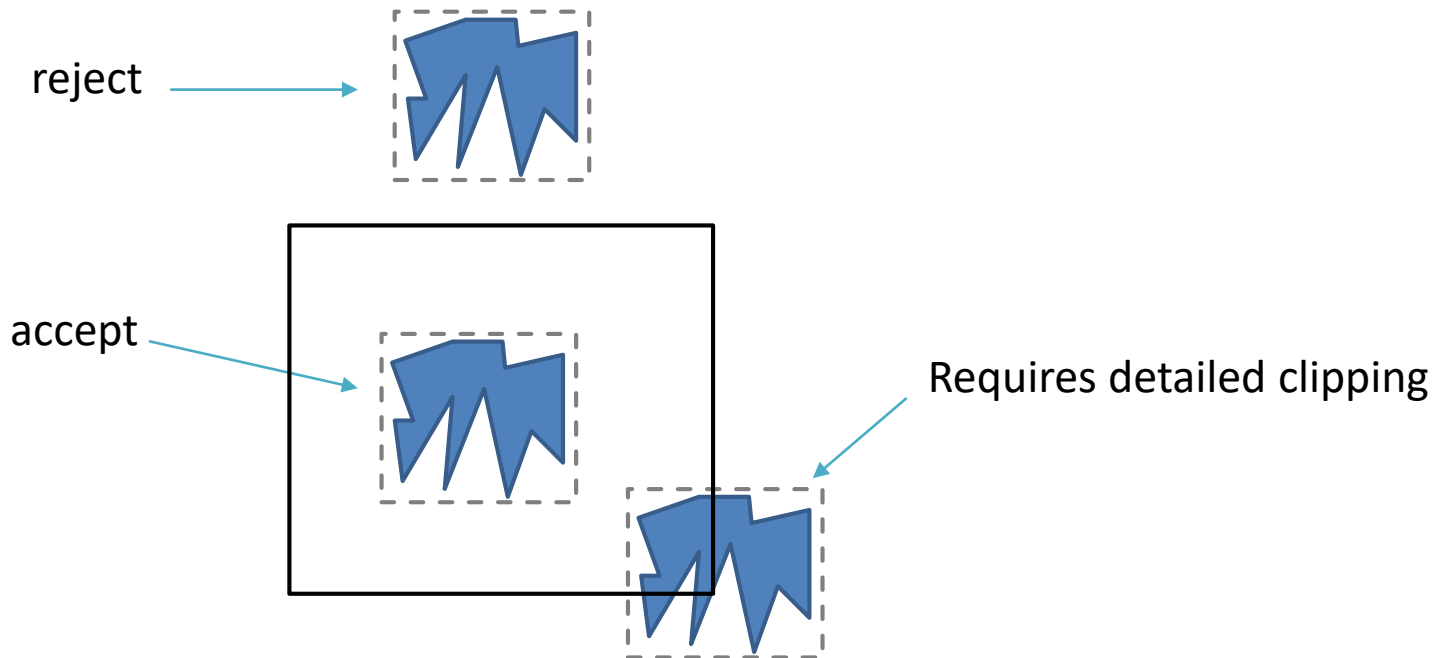
Polygon Clipping in 3D

- ▶ Similar to 2D clipping
 - ▶ Bounding box
 - ▶ Clipping with each clipping plane
 - ▶ Etc.....



Bounding Boxes

- ▶ Rather than doing clipping on a complex polygon, we can use an axis-aligned bounding box or extent
 - ▶ Smallest rectangle aligned with axes that encloses the polygon
 - ▶ Simple to compute: max and min of x and y



*Usually handled by your own data structure/program, **not within the pipeline !!***