moho-inversion-example

March 23, 2016

1 Implementation of the Moho inversion algorithm

This notebook presents a Python class that implements the proposed method. We'll use the inverse problems framework of the library Fatiando a Terra. The class MohoGravityInvSpherical is defined in the mohoinv.py file.

1.1 Package imports

```
In [1]: # Insert plots into the notebook
        %matplotlib inline
In [2]: from __future__ import division, unicode_literals
        import numpy as np
        import multiprocessing
        from IPython.display import Image
        import matplotlib.pyplot as plt
        import seaborn # Makes the default style of the plots nicer
/home/leo/bin/anaconda/envs/moho/lib/python2.7/site-packages/matplotlib/__init__.py:872: UserWarning: axe
  warnings.warn(self.msg_depr % (key, alt_key))
  Load the required modules from Fatiando a Terra and show the specific version of the library used.
In [3]: from fatiando.vis import myv, mpl
        from fatiando.gravmag import tesseroid
        from fatiando import utils, gridder
        import fatiando
In [4]: print("Using Fatiando a Terra version: {}".format(fatiando.__version__))
Using Fatiando a Terra version: 3c4953c170e1e9d964325ccd133a5ef28e319e89
In [5]: from mohoinv import TesseroidRelief, MohoGravityInvSpherical, make_mesh
  Get the number of cores in the computer to run the forward modeling in parallel.
In [6]: ncpu = multiprocessing.cpu_count()
        ncpu
Out[6]: 4
```

1.2 Test the class on simple synthetic data

We can test and show how the class works on some simple synthetic data. We'll use the example model from the tesseroid-relief-example.ipynb notebook.

First, make the model of the Moho.

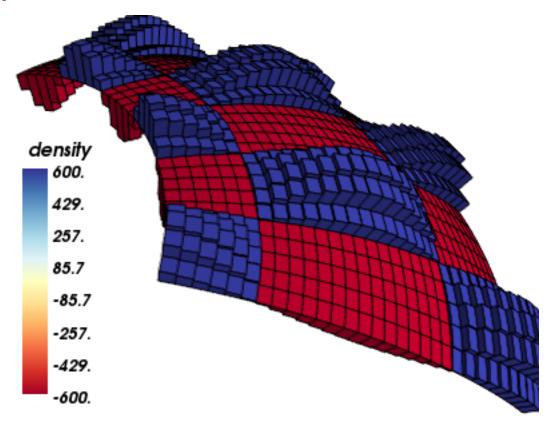
```
In [7]: # shape is nlat, nlon = the number of points in the grid
        shape = (30, 30)
        # Make a regular grid inside an area = (s, n, w, e)
        area = (20, 60, -40, 40)
        lat, lon, h = gridder.regular(area, shape, z=250e3)
        # Make a checkerboard relief undulating along the -35km height reference
        f = 0.15
        reference = -35e3
        relief = 10e3*np.sin(1.5*f*lon)*np.cos(f*lat) + reference
        # The density contrast is negative if the relief is below the reference
        density = 600*np.ones_like(relief)
        density[relief < reference] *= -1</pre>
In [8]: model = make_mesh(area, shape, relief, reference)
        model.addprop('density', density)
In [9]: def plot_result_3d(moho, fname):
            "Plot the tesseroid model in 3D."
            scale = (1, 1, 40) # Exaggerate the radial dimension
            datarange = np.abs([moho.props['density'].max(),
                                moho.props['density'].min()]).max()
            scene = myv.figure(zdown=False)
            plot = myv.tesseroids(moho, 'density', scale=scale)
            plot.module_manager.scalar_lut_manager.show_legend = True
            plot.module_manager.scalar_lut_manager.lut_mode = 'RdY1Bu'
            plot.module_manager.scalar_lut_manager.data_range = [-datarange, datarange]
            plot.module_manager.scalar_lut_manager.scalar_bar_representation.minimum_size = \]
                np.array([1, 1])
            plot.module_manager.scalar_lut_manager.scalar_bar_representation.position2 = \

                np.array([ 0.13741855,  0.64385382])
            plot.module_manager.scalar_lut_manager.scalar_bar_representation.position = \
                np.array([ 0.03303258, 0.07342193])
            plot.module_manager.scalar_lut_manager.scalar_bar_representation.maximum_size = \

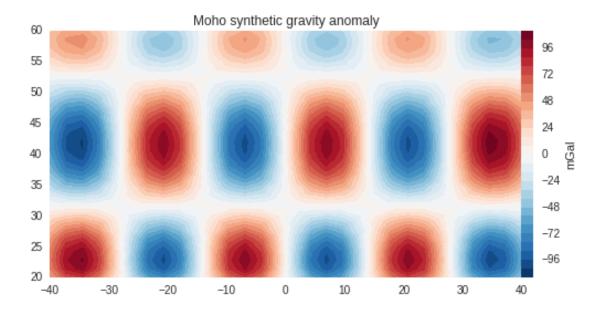
                np.array([100000, 100000])
            plot.module_manager.scalar_lut_manager.label_text_property.color = (0, 0, 0)
            plot.module_manager.scalar_lut_manager.title_text_property.color = (0, 0, 0)
            scene.scene.camera.position = [2252864.9143914036, -5202911.2574882135,
                                           8495162.9722945951]
            scene.scene.camera.focal_point = [3135763.9476126051, 1056258.4985192744,
                                              829277.18542720564]
            scene.scene.camera.view_angle = 30.0
            scene.scene.camera.view_up = [0.6164057832087273, 0.57367112225287575,
                                          0.53939350563383837]
            scene.scene.camera.clipping_range = [783483.44437851617, 16078402.004277557]
            scene.scene.camera.compute_view_plane_normal()
            scene.scene.render()
            myv.savefig(fname)
            #myv.show()
            myv.mlab.close()
            return Image(filename=fname)
```

In [10]: plot_result_3d(model, 'simple-synthetic-model.png')

WARNING:traits.has_traits:DEPRECATED: traits.has_traits.wrapped_class, 'the 'implements' class advisor h
Out[10]:



Now, generate some synthetic data by forward modeling.



1.3 Run the inversion

For this test, we'll use a mesh with the same dimensions and the original model.

```
In [13]: mesh = model.copy(deep=True)
    mesh.props['density'] = 600*np.ones(mesh.size)
```

Create the solver object.

```
In [14]: solver = MohoGravityInvSpherical(lat, lon, h, gz, mesh, njobs=ncpu)
```

Configure the optimization method to Gauss-Newton and set the initial estimate.

Out[15]: <mohoinv.MohoGravityInvSpherical at 0x7f7346642490>

Run the inversion and time the computation.

```
In [16]: %time solver.fit()
```

```
CPU times: user 56 ms, sys: 28 ms, total: 84 ms
```

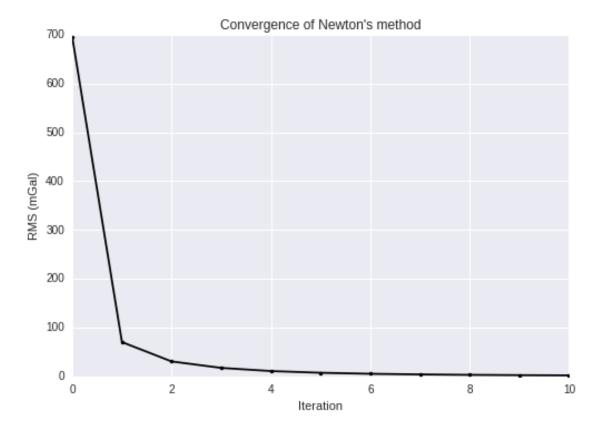
Wall time: 9.25 s

/home/leo/bin/anaconda/envs/moho/lib/python2.7/site-packages/fatiando/inversion/optimization.py:185: RuntimeWarning)

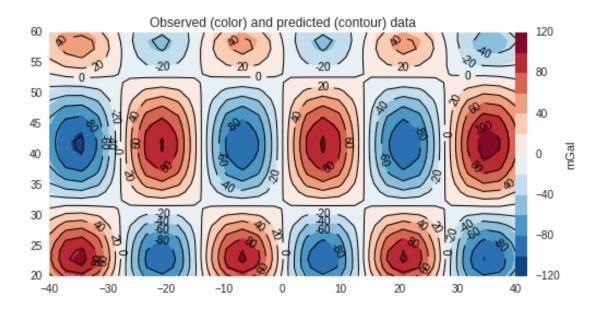
Plot the RMS error (Root Mean Square) per iteration to get an idea of the convergence of the method.

```
In [17]: rms = np.sqrt(solver.stats_['objective'])/np.sqrt(solver.ndata)
```

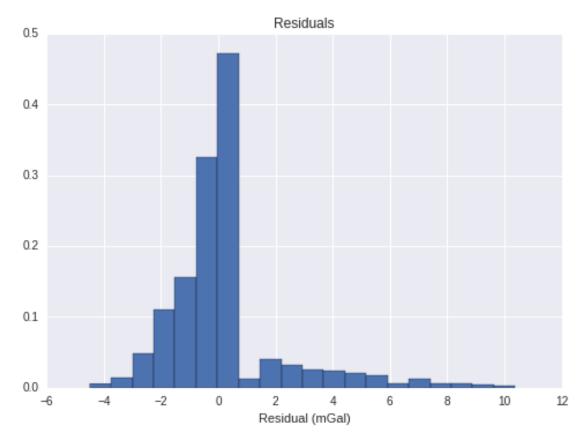
Out[18]: <matplotlib.text.Text at 0x7f7347757e50>



Plot the data misfit and residuals

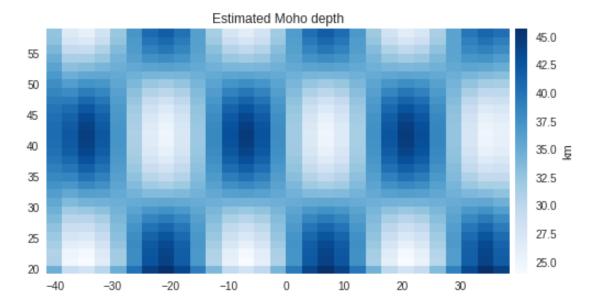


Mean: 0.214036548333 std: 2.02563704196



Map the estimated Moho depth.

Out [23]: (19.310344827586206, 59.310344827586206)



In [24]: plot_result_3d(moho, 'mohoinv-example.png')
Out[24]:

