No: Date: 10/2/2023 (hapter 5 Vectors 5.1 Vectors in 3 dimensions Notation: L, J, K i,i,k i, j, k (1,1,1) let & = 2 i + i - 3 k magnitude, | = 1 = 122+12+(-3)2 = 14 unit vector, $\hat{Q} = \frac{\hat{u}}{1/3!} = \frac{2\hat{c} + \hat{j} - 3h}{\sqrt{14}}$ $= \frac{1}{\sqrt{14}} \hat{c} + \frac{1}{\sqrt{14}} \hat{j} - \frac{3}{\sqrt{14}} \hat{k}$ direction (osines: (05 $\alpha = \frac{2}{\sqrt{14}}$) (05 $\beta = \frac{7}{\sqrt{14}}$) (05 $\gamma = \frac{7}{\sqrt{14}}$ direction angles: $\alpha = (os^{-1}(\frac{2}{\sqrt{14}}), B = (os^{-1}(\frac{2}{\sqrt{14}}), \beta = cos^{-1}(-\frac{2}{\sqrt{14}})$ perpendicular Paralle ! (0 = 90°) (0=0°@ 180°) () q.b=0 1) a = kb , keir (2,1,2)= k (6,3,6) 1 If w = y xy, then = h y 2=6H 1=3K 1=6K H=3 H=3 K=3 : Parallel exist (3,1,1) = k (b, 2,3) 3 = 6k 2k = 1 3k = 1 $k = \frac{1}{3}$ $k = \frac{1}{3}$ $k = \frac{1}{3}$ (3) 19 x b 1 = 12/16/ - Parallel does not exist (a · p = 19/16/ 9.6 = - 19/16/ (3) axb = 0

5.2 Dot product	No: Date: 11-2-2022
/0.1	p=20+4j+h q=0+j+h
0	P.9 = 2(1)+4(1)+1(1)
= a, b, + a, b, +a, b,	= 7
@ a.b = 1211b/1050	121= Nor2+1412+112
	$= \sqrt{21}$
3 P= 32+42-34	
= (3,4,-3)	19 = /11/2+11/2+11/2
2 = 50 + 31 -4k	= \sqrt{3}
= (5,3,-4)	$\theta = (0s^{-1})\left(\frac{\underline{a} - \underline{b}}{121121}\right)$
$\mathcal{L} = -5\dot{\lambda} + 2\dot{\lambda} - 3k$	0 = (05 -1 (\frac{7}{\siz1 \siz3})
= 1-5,21-3>	= 28,13 0
(b)	p=>6+8j-k q=i-j-3k
	p.9 = 2(11+8(11-1(-3)
$= \begin{pmatrix} 3 \\ 4 \\ -3 \end{pmatrix} \begin{pmatrix} 5 \\ 3 \\ -4 \end{pmatrix}$	= -3
[-3] [-4]	1 p 1 = \(\lambda_{(2)}^2 + (8)^2 + (-1)^2 \)
= 3(5)+4(3)+(-3)(-4)	= ,569
= 39	12 = /(112+1-1)2+1-3/2
	$=\sqrt{n}$
(b) 2.(p-x)	0=(05-1 (2-1)
= 9-p - 9.x	$\theta = 10s^{-1}\left(\frac{-3}{\sqrt{69}\sqrt{11}}\right)$
	$= -\frac{3}{\sqrt{759}}$
$= \begin{pmatrix} 5 \\ 3 \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix} \begin{pmatrix} 5 \\ 3 \end{pmatrix} \begin{pmatrix} -5 \\ 2 \end{pmatrix} \\ -4 \end{pmatrix} \begin{pmatrix} -3 \end{pmatrix}$	= 1759
	$\begin{array}{cccccccccccccccccccccccccccccccccccc$
= 39-[-25+6+12] 510	
= 46	2i-j+3h = h (-6i+3j+1k)
	2 = - 6h -1 = 3h
(1) (P+39)-3x	h=-1/3 h=-1/3
~ ~ ~ ~	3 = 1 h
$= \begin{pmatrix} \frac{3}{4} \\ -3 \end{pmatrix} + 3 \begin{pmatrix} \frac{5}{3} \\ -4 \end{pmatrix} \cdot 3 \begin{pmatrix} -\frac{3}{2} \\ -3 \end{pmatrix}$	$3 = \lambda \left(-\frac{1}{3}\right)$
	1 = -9
$= \left[\left(\begin{array}{c} \frac{3}{4} \\ -3 \end{array} \right) + \left(\begin{array}{c} \frac{15}{9} \\ -12 \end{array} \right) , \left(\begin{array}{c} -\frac{15}{6} \\ -9 \end{array} \right)$	/ - 1
18/ /-15	
$= \begin{pmatrix} 18 \\ 13 \\ -15 \end{pmatrix}, \begin{pmatrix} -15 \\ 6 \\ -9 \end{pmatrix}$	
= 18(-15) + 13(6) + (-15)(-9) = -57	

	5.3 vector Product	
	$\frac{a \times b}{a_1} = \begin{vmatrix} \frac{i}{2} & \frac{j}{2} & \frac{k}{2} \\ a_1 & a_2 & a_3 \end{vmatrix}$	
	a, a, a,	and Commission of Europe Control and Commission Commiss
	b, b2 b3	
	$= \begin{array}{ c c c c c c c c c c c c c c c c c c c$	a : k
	$\begin{vmatrix} b_1 & b_3 \end{vmatrix} - \begin{vmatrix} b_1 & b_3 \end{vmatrix} - \begin{vmatrix} b_1 & b_3 \end{vmatrix}$	b2
-	@ ax b	
	9 x b = 9 b sin 0 (4) 7 19 x b1	
		D
9.	9 = 2i - 3j + k b = i - 4j + 5k 10/91	1
(a)	$ \begin{array}{c c} \underline{a} \times \underline{b} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{h} \\ 2 & -3 & 1 \\ 1 & -4 & 5 \end{vmatrix} $	(A)
	1 - 4 5	
	= -3 -	OD
	=[-15-(-41]i-[10-1]i+[-8-1-3]]k	=
	= -11i+9i+5k	(001
	· ·	ŧ
(b)	$b \times q = \begin{vmatrix} i & j & k \end{vmatrix}$	area
	7 - 4 5	
	$= \frac{ -4 ^{5} \dot{y} - \frac{1}{2} \dot{y} + \frac{1}{2} ^{-4}/k}{ -3 ^{2}}$	
	$= [-4 - (-15)]\hat{i} - (1 - 10)\hat{j} + [-3 - (-8)]k$	dependent between the following communicative services and
	= 112+91+56	

$$\frac{V \cdot E}{z} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} - \begin{pmatrix} a_1 \\ a_2 \\ q_3 \end{pmatrix} + t \begin{pmatrix} d \\ e \\ f \end{pmatrix}$$

$$(E \frac{x-a_1}{d} = \frac{y-a_2}{e} = \frac{z-a_3}{f}$$

- from question, direction vector = v

| | parallo|
| ine | other | v = v,

line to plane z=n

