

# Kurs Bio144:

# Datenanalyse in der Biologie

Stefanie Muff & Owen L. Petchey

Lecture 6: ANCOVA, Introduction to Linear Algebra  
30./31. March 2017

# Overview (todo: check)

- ANCOVA
- ANCOVA as special cases of a linear model
- Introduction to linear Algebra

Note:

ANCOVA = ANalysi of COVAriance (Kovarianzanalyse)

## Course material covered today

The lecture material of today is based on the following literature:

- “Getting Started with R” chapter 6.3
- “Lineare regression” chapters 3.A (p. 43-45) and 3.4, 3.5 (p. 39-42)

# Recap of ANOVA

- ANOVA is a method to test if the means of **two or more groups are different**.
- Post-hoc tests and contrasts, including correction for  $p$ -values, to understand the differences between the groups.
- Two-way ANOVA for factorial designs, interactions.
- Interpretation of the results.
- Model checking.
- ANOVA as a special case of linear regression with categorical covariates.

# Analysis of Covariance (ANCOVA)

An ANCOVA is an analysis of variance (ANOVA), **including** also at least one **continuous covariate**.

There, ANCOVA is a **combination of ANOVA and regression**, so in principle, there is nothing new to it...

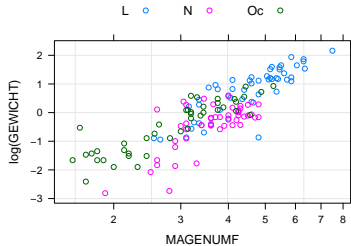
Given a categorical covariate  $x_i$  and a continuous covariate  $z_i$ . Then the ANCOVA equation (without interactions) is given as

$$y_i = \beta_0 + \beta_1 x_i^{(1)} + \dots + \beta_k x_i^{(k)} + \beta_z z_i + e_i ,$$

where  $x_i^{(k)}$  is the  $k$ th dummy variable ( $x_i^{(k)}=1$  if  $i$ th observation belongs to category  $k$ , 0 otherwise).

**Note:** It is straightforward to add interactions  $x_i^{(j)} z_i$  for all levels of  $x_i$ .

**Example:** Remember the earthworm study from week 3: “Magenumfang” was used to predict “Gewicht” of the worm, including as covariate also the worm species.



**Categorical** and **continuous** covariates were used to predict a continuous outcome (the weight of the worm).

```
> r.lm <- lm(log(GEWICHT) ~ MAGENUMF + Gattung,d.wurm)
> summary(r.lm)$coef
```

```

              Estimate Std. Error    t value    Pr(>|t|)
(Intercept) -2.5355459  0.22147279 -11.4485663 8.617670e-22
MAGENUMF      0.7118725  0.04528843  15.7186392 1.232126e-32
GattungN      -0.5151344  0.11009219  -4.6791186 6.760621e-06
GattungOc     -0.0907298  0.12791000  -0.7093254 4.793107e-01
```

**Remember:** What do the  $p$ -values ( $p = 0.48$  and  $p < 0.0001$ ) of the categorical covariate “Gattung” mean?

To understand if “Gattung” has an effect, **we need to carry out an  $F$ -test** (see slides 45/46, week 3). To this end, plot the ANOVA table:

```
> anova(r.lm)
```

Analysis of Variance Table

Response: log(GEWICHT)

```

      Df Sum Sq Mean Sq F value    Pr(>F)
MAGENUMF  1 104.866 104.866  409.69 < 2.2e-16 ***
Gattung   2   7.177   3.589   14.02 2.842e-06 ***
Residuals 139  35.579   0.256
---
```

Signif. codes: 0 ‘\*\*\*’ 0.001 ‘\*\*’ 0.01 ‘\*’ 0.05 ‘.’ 0.1 ‘ ’ 1

The **F-test** is also needed to check whether the **interaction term** between MAGENUMF and Gattung is needed:

```
> r.lm2<- lm(log(GEWICHT) ~ MAGENUMF * Gattung,d.wurm)
> summary(r.lm2)$coef
```

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	-2.1274390	0.30859958	-6.893849	1.816840e-10
MAGENUMF	0.6237919	0.06484623	9.619555	4.705940e-17
GattungN	-1.1510597	0.49399105	-2.330123	2.126052e-02
GattungOc	-0.7810625	0.39669094	-1.968945	5.097754e-02
MAGENUMF:GattungN	0.1500462	0.12178262	1.232082	2.200288e-01
MAGENUMF:GattungOc	0.1817710	0.10199782	1.782106	7.694701e-02

```
> anova(r.lm2)
```

Analysis of Variance Table

Response: log(GEWICHT)

	Df	Sum Sq	Mean Sq	F value	Pr(>F)
MAGENUMF	1	104.866	104.866	414.4743	< 2.2e-16 ***
Gattung	2	7.177	3.589	14.1835	2.521e-06 ***
MAGENUMF:Gattung	2	0.917	0.458	1.8112	0.1673
Residuals	137	34.662	0.253		

---

Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

→  $p = 0.167$  seems not to be significant.

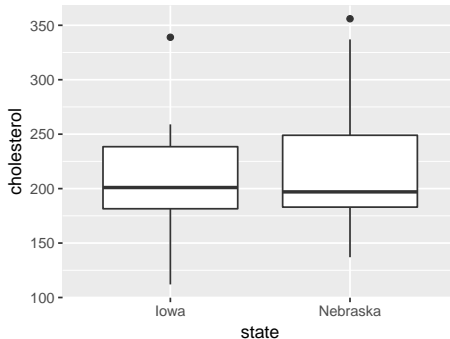


## A new example: cholesterol levels

**Example:** Cholesterol levels [mg/ml] for 30 women from two US states, Iowa and Nebraska, were measured.

**Question:** Do these levels differ between the states?

Age (years) may be a relevant covariable.



The model includes state, age and the interaction of the two. The model equation is thus given as

$$y_i = \beta_0 + \beta_1(\text{state})_i + \beta_2(\text{age})_i + \beta_3(\text{state})_i(\text{age})_i + e_i, \quad e_i \sim N(0, \sigma_e^2).$$

```
> r.lm <- lm(cholesterol ~ age*state,data=d.chol)
> anova(r.lm)
```

Analysis of Variance Table

Response: cholesterol

	Df	Sum Sq	Mean Sq	F value	Pr(>F)
age	1	48976	48976	26.3124	2.388e-05 ***
state	1	5456	5456	2.9315	0.09877 .
age:state	1	709	709	0.3809	0.54247
Residuals	26	48395	1861		

---

Signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

Interpretation?

Compare the results from the previous slide to the estimated coefficients:

```
> r.lm <- lm(cholesterol ~ age*state,data=d.chol)
> summary(r.lm)$coef
```

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	35.8112138	55.116605	0.6497355	0.521562661
age	3.2381449	1.008827	3.2098104	0.003516155
stateNebraska	65.4865523	61.983368	1.0565181	0.300450053
age:stateNebraska	-0.7177069	1.162845	-0.6171990	0.542471382

**Note:** The  $p$ -values for the age and state coefficients are not the same as in the anova table...

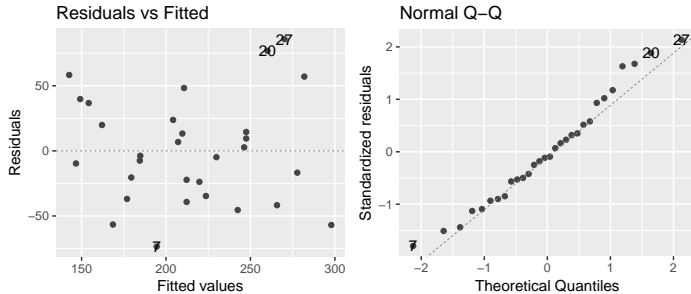
Compare the results for “state” also to the model without interaction:

```
> r.lm2 <- lm(cholesterol ~ age + state,data=d.chol)
> summary(r.lm2)$coef
```

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	64.489772	29.3024531	2.200832	3.648161e-02
age	2.697967	0.4959532	5.439963	9.361235e-06
stateNebraska	28.651025	16.5409806	1.732124	9.466292e-02

**Note:** the  $p$ -value for ‘state’ is now the same as on the previous slide (anova table). Reason: anova tests the models against one another in the **order** specified.

As always, some model checking is necessary:



→ This seems ok.

## A final word on ANCOVA

ANCOVA unifies several concepts that we approached in this course so far:

- Linear regression
- Categorical covariates
- Interactions (of continuous and categorical covariates)
- Analysis of Variance (ANOVA)

As such, it is a **special case of the linear model**.

# An introduction to linear Algebra

Who has some knowledge of linear Algebra?

## Overview

- The basics about
  - vectors
  - matrices
  - matrix algebra
  - matrix multiplication
- Why is linear Algebra useful?
- What does it have to do with data analysis and statistics?
- Regression equations in matrix notation.

## Motivation

Why are vectors, matrices and their algebraic rules useful?

**Example 1:** The observations for a covariate  $\mathbf{x}$  or the response  $\mathbf{y}$  for all individuals  $1 \leq i \leq n$  can be stored in a vector (vectors and matrices are always given in **bold** letters):

$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{pmatrix}, \quad \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \dots \\ y_n \end{pmatrix}.$$

**Example 2:** Covariance matrices for multiple variables. Say we have  $\mathbf{x}^{(1)}$  and  $\mathbf{x}^{(2)}$ . The **covariance matrix** is then given as

$$\begin{pmatrix} \text{Var}(\mathbf{x}^{(1)}) & \text{Cov}(\mathbf{x}^{(1)}, \mathbf{x}^{(2)}) \\ \text{Cov}(\mathbf{x}^{(1)}, \mathbf{x}^{(2)}) & \text{Var}(\mathbf{x}^{(2)}) \end{pmatrix}.$$

**Example 3:** The **data** (e.g. of some regression model) can be stored in a **matrix**:

$$\tilde{\mathbf{X}} = \begin{pmatrix} 1 & x_1^{(1)} & x_2^{(1)} \\ 1 & x_2^{(1)} & x_2^{(2)} \\ \dots & \dots & \dots \\ 1 & x_n^{(1)} & x_n^{(2)} \end{pmatrix} .$$

This is the so-called **design matrix** with a vector of 1's in the first column.

**Example 4:** A linear regression model can be written compactly using **matrix multiplication**:

$$\mathbf{y} = \tilde{\mathbf{X}} \cdot \tilde{\boldsymbol{\beta}} + \mathbf{e} ,$$

with  $\tilde{\boldsymbol{\beta}}$  the vector of regression coefficients and  $\mathbf{e}$  the vector of residuals.



Why do we discuss this topic in our course?

- Useful for **compact notation**.
- Enables you to **understand many statistical texts** (books, research articles) that remain inaccessible otherwise.
- More advanced concepts often rely on linear algebra, e.g. **principal component analysis** (PCA) or **random effects** models.
- Often useful for **efficient coding**, e.g. in R, which helps to increase speed and to reduce error rates.
- Is part of a **general education** (Allgemeinbildung) ;-)

# Matrices

An  $n \times m$  **Matrix** is given as

$$\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & a_{22} & \dots & a_{2m} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nm} \end{pmatrix},$$

with rows  $i = 1, \dots, n$  and columns  $j = 1, \dots, m$ .

**Quadratic matrix:**  $n = m$ . Example:

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 3 & 2 \\ 6 & 1 & 9 \end{pmatrix}$$

**Symmetric matrix:**  $a_{ij} = a_{ji}$ . Example:

$$\begin{pmatrix} 1 & 2 & 3 \\ 2 & 3 & 4 \\ 3 & 4 & 5 \end{pmatrix} .$$

**The diagonal of a quadratic matrix** is given by  $(a_{11}, a_{22}, \dots, a_{nn})$ .

Example: the diagonal of the above matrix is given as

$$(a_{11}, a_{22}, a_{33}) = (1, 3, 5) .$$

**Diagonal matrix:** A matrix that has entries  $\neq 0$  **only on the diagonal**.

Example:

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{pmatrix} .$$

**Transposing a matrix:** Given a matrix **A**. Exchange the rows by the columns and vice versa. This leads to the **transposed matrix**  $\mathbf{A}^\top$ :

$$\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1m} \\ a_{21} & a_{22} & \dots & a_{2m} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nm} \end{pmatrix} \Rightarrow \mathbf{A}^\top = \begin{pmatrix} a_{11} & a_{21} & \dots & a_{m1} \\ a_{12} & a_{22} & \dots & a_{m2} \\ \vdots & \vdots & & \vdots \\ a_{1n} & a_{2n} & \dots & a_{mn} \end{pmatrix}.$$

Examples (note also the change of dimensions):

$$\mathbf{A} = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \\ 9 & 10 & 11 & 12 \\ 13 & 14 & 15 & 16 \end{pmatrix} \Rightarrow \mathbf{A}^\top = \begin{pmatrix} 1 & 5 & 9 & 13 \\ 2 & 6 & 10 & 14 \\ 3 & 7 & 11 & 15 \\ 4 & 8 & 12 & 16 \end{pmatrix}$$

$$\mathbf{A} = \begin{pmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \end{pmatrix} \Rightarrow \mathbf{A}^\top = \begin{pmatrix} 1 & 5 \\ 2 & 6 \\ 3 & 7 \\ 4 & 8 \end{pmatrix}$$

- Transposing a matrix **twice** leads to the original matrix:

$$(\mathbf{A}^\top)^\top = \mathbf{A} .$$

- When a matrix is **symmetric**, then

$$\mathbf{A}^\top = \mathbf{A} .$$

This is true in particular for diagonal matrices.

# Vectors

A vector is nothing else than  $n$  numbers written in a column:

$$\mathbf{b} = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

**Transposing** a vector leads to a *row vector*:

$$\begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}^{\top} = \begin{pmatrix} b_1 & b_2 & \dots & b_n \end{pmatrix}$$

**Note:** By definition (by default), a vector is always a column vector.

## Addition and subtraction

- Adding and subtracting matrices and vectors is only possible when the objects have the **same dimension**.
- Examples: Elementwise addition (or subtraction)

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} + \begin{pmatrix} 3 & 2 & 1 \\ 6 & 5 & 4 \end{pmatrix} = \begin{pmatrix} 4 & 4 & 4 \\ 10 & 10 & 10 \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ 4 \end{pmatrix} - \begin{pmatrix} 3 \\ 9 \end{pmatrix} = \begin{pmatrix} -2 \\ -5 \end{pmatrix}$$

- But this addition is **not defined**:

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} + \begin{pmatrix} 3 & 6 \\ 2 & 5 \\ 1 & 4 \end{pmatrix} =$$

## Multiplication by a scalar

Multiplication with a “number” (scalar) is simple: Multiply each element in a vector or a matrix.

Examples:

$$3 \cdot \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix} = \begin{pmatrix} 3 & 6 & 9 \\ 12 & 15 & 18 \end{pmatrix}$$

$$-2 \cdot \begin{pmatrix} 1 \\ 4 \\ -2 \end{pmatrix} = \begin{pmatrix} -2 \\ -8 \\ 4 \end{pmatrix}$$



# Matrix multiplication

The multiplication of two matrices **A** and **B** is **defined if**

Number of columns in **A** = Number of rows in **B**.

It is easiest to explain matrix multiplication with an example:

$$\begin{pmatrix} 2 & 1 \\ -1 & 0 \\ 3 & 1 \end{pmatrix} \cdot \begin{pmatrix} 3 & 1 \\ 4 & -2 \end{pmatrix} = \begin{pmatrix} 2 \cdot 3 + 1 \cdot 4 & 2 \cdot 1 + 1 \cdot (-2) \\ (-1) \cdot 3 + 0 \cdot 4 & (-1) \cdot 1 + 0 \cdot (-2) \\ 3 \cdot 3 + 1 \cdot 4 & 3 \cdot 1 + 1 \cdot (-2) \end{pmatrix}$$
$$= \begin{pmatrix} 10 & 0 \\ -3 & -1 \\ 13 & 1 \end{pmatrix}$$

► Matrix multiplication app

# Matrix multiplication rules I

Attention: Matrix multiplication does **not** follow the same rules as scalar multiplication!!!

- It can happen that  $\mathbf{A} \cdot \mathbf{B}$  can be calculated, but  $\mathbf{B} \cdot \mathbf{A}$  is not defined (see example on previous slide).
- In general:  $\mathbf{A} \cdot \mathbf{B} \neq \mathbf{B} \cdot \mathbf{A}$ , even if both are defined.
- It can happen that  $\mathbf{A} \cdot \mathbf{B} = \mathbf{0}$  (0 matrix), although both  $\mathbf{A} \neq \mathbf{0}$  and  $\mathbf{B} \neq \mathbf{0}$ .
- The **Assoziativgesetz** holds:  $\mathbf{A} \cdot (\mathbf{B} \cdot \mathbf{C}) = (\mathbf{A} \cdot \mathbf{B}) \cdot \mathbf{C}$ .
- The **Distributivgesetz** holds:

$$\mathbf{A} \cdot (\mathbf{B} + \mathbf{C}) = \mathbf{A} \cdot \mathbf{B} + \mathbf{A} \cdot \mathbf{C}$$

$$(\mathbf{A} + \mathbf{B}) \cdot \mathbf{C} = \mathbf{A} \cdot \mathbf{C} + \mathbf{B} \cdot \mathbf{C}$$

## Matrix multiplication rules II

- Transposing inverts the order:  $(\mathbf{A} \cdot \mathbf{B})^\top = \mathbf{B}^\top \cdot \mathbf{A}^\top$ .
- The product  $\mathbf{A} \cdot \mathbf{A}^\top$  is **always symmetric**.
- All these rules also hold for **vectors**, which can be interpreted as  $n \times 1$  matrices:

$$\mathbf{a} \cdot \mathbf{b}^\top = \begin{pmatrix} a_1 b_1 & a_1 b_2 & \dots & a_1 b_m \\ a_2 b_1 & a_2 b_2 & \dots & a_2 b_m \\ \vdots & \vdots & & \vdots \\ a_n b_1 & a_n b_2 & \dots & a_n b_m \end{pmatrix}$$

If  $\mathbf{a}$  and  $\mathbf{b}$  have the **same length**:

$$\mathbf{a}^\top \cdot \mathbf{b} = \sum_i a_i b_i$$

## Short exercises

Given vectors **a** and **b** and matrix **C**:

$$\mathbf{a} = \begin{pmatrix} 1 \\ -2 \\ 3 \\ 0 \end{pmatrix}, \quad \mathbf{b} = \begin{pmatrix} -2 \\ 4 \end{pmatrix}, \quad \mathbf{C} = \begin{pmatrix} 1 & 0 \\ -1 & 2 \end{pmatrix}$$

Calculate, if defined

- $\mathbf{a}^T \cdot \mathbf{b}$
- $\mathbf{a} \cdot \mathbf{b}^T$
- $\mathbf{C} \cdot \mathbf{a}$
- $\mathbf{C} \cdot \mathbf{b}$

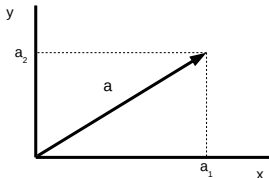
## The length of a vector

The **length of a vector**  $\mathbf{a}^T = (a_1, a_2, \dots, a_n)$  is defined as  $\|\mathbf{a}\|$  with

$$\|\mathbf{a}\|^2 = \mathbf{a}^T \cdot \mathbf{a} = \sum_i a_i^2.$$

This is basically the **Pythagoras** idea in 2, 3, ...  $n$  dimensions.

In 2 dimensions:  $\|\mathbf{a}\|^2 = a_1^2 + a_2^2$ :



## Identity matrix (Einheitsmatrix)

The identity matrix (of dimension  $m$ ) is probably the simplest matrix that exists. It has 1's on the diagonal and 0's everywhere else:

$$\mathbf{I} = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \dots & 1 \end{pmatrix}$$

Multiplication with the identity matrix leaves a  $m \times n$  matrix  $\mathbf{A}$  unchanged:

$$\mathbf{I} \cdot \mathbf{A} = \mathbf{A} \cdot \mathbf{I} = \mathbf{A} .$$

# Inverse matrix

Given a quadratic matrix  $\mathbf{A}$  that fulfills

$$\mathbf{B} \cdot \mathbf{A} = \mathbf{I} ,$$

then  $\mathbf{B}$  is called the **inverse** of  $\mathbf{A}$  (and vice versa). One then writes

$$\mathbf{B} = \mathbf{A}^{-1} .$$

Note:

- In that case it also holds that  $\mathbf{A} \cdot \mathbf{B} = \mathbf{I}$ .
- Therefore:  $\mathbf{A} = \mathbf{B}^{-1} \Leftrightarrow \mathbf{B} = \mathbf{A}^{-1}$

- The inverse of  $\mathbf{A}$  may **not exist**. If it exists,  $\mathbf{A}$  is **regular**, otherwise **singular**.
- $(\mathbf{A}^{-1})^{-1} = \mathbf{A}$ .
- The inverse of a matrix product is given as

$$(\mathbf{A} \cdot \mathbf{B})^{-1} = \mathbf{B}^{-1} \cdot \mathbf{A}^{-1} .$$

- It is

$$(\mathbf{A}^{\top})^{-1} = (\mathbf{A}^{-1})^{\top} .$$

Therefore one may also write  $\mathbf{A}^{-\top}$ .



## Linear regression in matrix notation

Linear regression with  $n$  data points can be understood as an **equation system with  $n$  equations**.

Remember example 4 from slide 16: We said that a linear regression model can be written compactly using **matrix multiplication**:

$$\mathbf{y} = \tilde{\mathbf{X}} \cdot \tilde{\boldsymbol{\beta}} + \mathbf{e} .$$

Task: Verify this now, using a model with two variables  $\mathbf{x}^{(1)}$  and  $\mathbf{x}^{(2)}$  and

$$\mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}, \quad \tilde{\mathbf{X}} = \begin{pmatrix} 1 & x_1^{(1)} & x_2^{(1)} \\ 1 & x_2^{(1)} & x_2^{(2)} \\ \dots & \dots & \dots \\ 1 & x_n^{(1)} & x_n^{(2)} \end{pmatrix}, \quad \tilde{\boldsymbol{\beta}} = \begin{pmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{pmatrix}, \quad \mathbf{e} = \begin{pmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \end{pmatrix} .$$

It can be shown (see Stahel 3.4f,g) that the least-squares estimates  $\hat{\beta}$  can be calculated as

$$\hat{\beta} = (\tilde{\mathbf{X}}^\top \tilde{\mathbf{X}})^{-1} \cdot \tilde{\mathbf{X}}^\top \cdot \mathbf{y}$$

Does this look complicated?

Let's test this in R ....

## Doing linear algebra in R

Let us look at model  $\mathbf{y} = \tilde{\mathbf{X}} \cdot \tilde{\boldsymbol{\beta}} + \mathbf{e}$  with coefficients  $\beta_0 = 10, \beta_1 = 5, \beta_2 = -2$  and variables

$i$	$x_i^{(1)}$	$x_i^{(2)}$
1	0	4
2	1	1
3	2	0
4	3	1
5	4	4

Thus the model is given as

$$y_i = 10 + 5x_i^{(1)} - 2x_i^{(2)} + e_i, \text{ for } 1 \leq i \leq n.$$

Let us start by generating the “true” response, calculated as  $\tilde{\mathbf{X}}\tilde{\boldsymbol{\beta}}$ :

```

>
> x1 <- c(0,1,2,3,4)
> x2 <- c(4,1,0,1,4)
> Xtilde <- matrix(c(rep(1,5),x1,x2),ncol=3)
> Xtilde

```

```

      [,1] [,2] [,3]
[1,]    1    0    4
[2,]    1    1    1
[3,]    1    2    0
[4,]    1    3    1
[5,]    1    4    4

```

```

> t.beta <- c(10,5,-2)
> t.y <- Xtilde%*%t.beta
> t.y

```

```

      [,1]
[1,]     2
[2,]    13
[3,]    20
[4,]    23
[5,]    22

```

Matrix multiplication in R is done by the `%*%` symbol.

Next, we generate the vector containing the  $e_i \sim N(0, \sigma_e^2)$  with  $\sigma_e^2 = 1$ :

```
> t.e <- rnorm(5,0,1)
> t.e
[1] 0.7514087 0.2224814 -0.2270811 -0.2698643 1.4572649
```

which we add to the “true”  $\mathbf{y} = \tilde{\mathbf{X}}\tilde{\boldsymbol{\beta}}$  values, to obtain the “observed” values:

```
> t.Y <- t.y + t.e
> t.Y
      [,1]
[1,] 2.751409
[2,] 13.222481
[3,] 19.772919
[4,] 22.730136
[5,] 23.457265
```

It is now possible to fit the model with `lm`:

```
> r.lm <- lm(t.Y ~ x1 + x2)
> summary(r.lm)$coef
```

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	9.500270	0.3651753	26.01564	0.001474245
x1	5.091937	0.1227028	41.49812	0.000580183
x2	-1.648651	0.1037028	-15.89784	0.003933286

Alternatively, we can use formula

$$\hat{\beta} = (\tilde{\mathbf{X}}^T \tilde{\mathbf{X}})^{-1} \tilde{\mathbf{X}}^T \mathbf{y}$$

to find the parameter estimates:

```
> solve(t(Xtilde) %*% Xtilde) %*% t(Xtilde) %*% t.Y  
  
      [,1]  
[1,]  9.500270  
[2,]  5.091937  
[3,] -1.648651
```

- `solve()` calculates the **inverse** (here the inverse of  $\tilde{\mathbf{X}}^T \tilde{\mathbf{X}}$ ).
- `t()` gives the **transposed** (here of  $\tilde{\mathbf{X}}^T$ ).

**Task:** Do this calculation by yourself and verify for each step that the dimensions of the matrices and the vector are indeed fitting, so that this expression is defined.

## Distribution of the $\beta$ coefficients

See chapter 3.5 in Stahel: Linear algebra is useful to find the actual distribution of the regression coefficients  $\beta$ .

No need to know this by heart – but please remember:

Finding the joint distribution for  $\beta$  is **much harder** without linear algebra.

## Appendix



# Some R commands for matrix algebra

Reading vectors and a matrices into R:

```
> a <- c(1,2,3)
```

```
> a
```

```
[1] 1 2 3
```

```
> A <- matrix(c(1,2,3,4,5,6),byrow=T,nrow=2)
```

```
> B <- matrix(c(6,5,4,3,2,1),byrow=T,nrow=2)
```

```
> A
```

```
      [,1] [,2] [,3]  
[1,]    1    2    3  
[2,]    4    5    6
```

```
> B
```

```
      [,1] [,2] [,3]  
[1,]    6    5    4  
[2,]    3    2    1
```

Adding and subtracting:

```
> A + B
```

```
      [,1] [,2] [,3]  
[1,]    7    7    7  
[2,]    7    7    7
```

```
> A - B
```

```
      [,1] [,2] [,3]  
[1,]   -5   -3   -1  
[2,]    1    3    5
```

However, be careful, R sometimes does unreasonable things:

```
> A + a
```

```
      [,1] [,2] [,3]  
[1,]     2     5     5  
[2,]     6     6     9
```

What happened here??

## Matrix multiplication:

```
> C <- A %*% t(B)
> C
```

```
      [,1] [,2]
[1,]   28  10
[2,]   73  28
```

```
> A%*%a
```

```
      [,1]
[1,]   14
[2,]   32
```

## Matrix inversion (possible for quadratic matrices only):

```
> solve(C)
```

```
      [,1]      [,2]
[1,]  0.5185185 -0.1851852
[2,] -1.3518519  0.5185185
```

```
> C %*% solve(C)
```

```
      [,1] [,2]
[1,]    1    0
[2,]    0    1
```

Why does `solve(A)` or `solve(B)` not work?