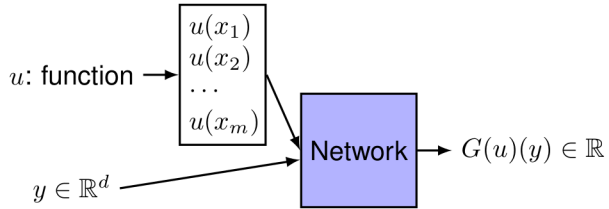


A

Inputs & Output

**B**

Training data

Input function u
at fixed sensors x_1, \dots, x_m

Output function $G(u)$
at random location y

