L SciCoNet: Scientific Computing Neural Networks

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Mar 29, 2019 @Crunch Seminar

Why SciCoNet?

Being able to go from idea to result with the least possible delay is key to doing good research. — Keras

➤ A deep learning library designed for scientific computing on top of TensorFlow.

SciCoNet

Use SciCoNet if you need a deep learning library that

- approximates functions from a dataset with constraints,
- approximates functions from multi-fidelity data,
- solves partial differential equations (PDEs),
- solves integro-differential equations (IDEs),
- solves fractional partial differential equations (fPDEs),
- **•** . . .

Why this logo, \mathcal{L} ?



The art of physics informed neural networks?

 \Rightarrow Design loss \mathcal{L}

Features

SciCoNet supports

- uncertainty quantification using dropout;
- domain geometries: interval, disk, hyercube and hypersphere;
- networks: fully connected, & ResNet;
- many different losses, metrics, optimizers, learning rate schedules, initializations, regularizations, etc.;
- callbacks to monitor the internal states and statistics of the model during training.

Main modules

Highly-configurable

- domain geometry,
- data, i.e., the type of problems and constraints,
- map, i.e., the function space,
- model, which trains the map to match the data and constraints,

Hands-on. Are you ready for the challenge?



Installation

- Dependencies: Matplotlib, NumPy, SALib, scikit-learn, SciPy, TensorFlow
- ▶ Download: https://github.com/lululxvi/sciconet

Challenge 1: Elementary school — dataset

examples/dataset.py import sciconet as scn fname_train = "examples/dataset.train" fname_test = "examples/dataset.test" data = scn.data.DataSet(fname_train=fname_train, fname_test=fname_test, col x=(0,), col y=(1,) $x \dim, y \dim = 1, 1$ layer size = [x dim] + [50] * 3 + [y dim]activation = "tanh" initializer = "Glorot normal" net = scn.maps.FNN(layer size, activation, initializer)

Challenge 1: Elementary school — dataset

```
model = scn.Model(data, net)
optimizer = "adam"
1r = 0.001
batch_size = 0
ntest = 0
model.compile(
    optimizer, lr, batch_size, ntest,
    metrics=["12 relative error"]
epochs = 50000
losshistory, train state = model.train(epochs)
scn.saveplot(
    losshistory, train state, issave=True, isplot=True
```

Challenge 2: Middle school — Poisson's equation

- $-\Delta y = \pi^2 \sin(\pi x)$
- ▶ $x \in [-1, 1]$
- $y(\pm 1) = 0$

$$y(x) = \sin(\pi x)$$

examples/pde.py

Challenge 3: High school — IDE

- $\int_{0}^{x} y(t)dt + \frac{dy}{dx} = 2\pi \cos(2\pi x) + \frac{\sin^{2}(\pi x)}{\pi}$
- ▶ $x \in [0, 1]$
- y(0) = 0

$$y(x) = \sin(2\pi x)$$

examples/ide.py

Challenge 4: College — turbulence

Variable fractional model [Song & Karniadakis, arXiv, 2018]

$$\nu(y)D_y^{\alpha(y)}U(y)=1, \ \forall y\in(0,1]$$

- ho $\alpha(0) = 1, 0 < \alpha < 1$
- \triangleright U(y): the mean velocity
- eddy viscosity: $\nu(y) = \Gamma(2 \alpha(y))Re_{\tau}^{-\alpha(y)}$
- ► (Caputo) fractional derivative:

$$D_y^{\alpha}U(y) = \frac{1}{\Gamma(1-\alpha)} \int_0^y (y-\tau)^{-\alpha} U'(\tau) d\tau$$

$$\approx \frac{1}{\Gamma(2-\alpha(y))} \sum_{j=0}^n ((j+1)^{1-\alpha} - j^{1-\alpha}) \frac{U^{n+1-j} - U^{n-j}}{(\Delta y)^{\alpha(y)}}$$

$$\nu(y)D_y^{\alpha(y)}U(y) \approx \sum_{i=1}^{n+1} j(jRe\Delta y)^{-\alpha(y)} (U^{n+2-j} - 2U^{n+1-j} + U^{n-j})$$

Challenge 4: College — turbulence





