Algorithm

I implemented two major algorithms during the course of this project.

Value Iteration

- Iterate over the data set and pre-compute transition probabilities T and reward function R
- Loop over every state in possible states (10*10 cells)
 - Look at every action and find the one that maximizes bellman equation.
 - Save off the best action and its value into a map.
- End after k iterations over all states.

Normally in policy iteration, we would set an explicit stopping criteria using the Bellman residual, but I found this to be unnecessary. We only need ~20 iterations to get a pretty ideal answer for small. I found value iteration to be fairly intractable for medium and large.

By far, the T and R calculations are the most expensive step in my algorithm.

Q-Learning

- Loop over every item in our data set
 - Increment N count upon encountering a (state, action) pair.
 - Find the best action from the next state, save it for Q(s,a) update.
 - Use Q-Learning update step to calculate new Q(s,a) value.
 - Use 1/N(s,a) for learning rate
 - Update Q map with new Q(s,a)
- End after k iterations over all rows in data.

Some notes about my implementation:

I found out, empirically, that using a learning rate of 1 (no learning rate) was better for medium. Thus, I have a parameter for q-learning on whether I use the 1/N learning rate. This learning rate was inspired by a Piazza post by Prof. Kochenderfer.

We have 312020 total states and approximately only 500 given to us. I toyed around with approximation and didn't get anywhere. So, I instead toyed around with a default policy for states we haven't seen in our data. I found that a default policy of selecting 1 was best after trying random values and other defaults.

I use gamma = 1 for medium and gamma = 0.95 for large as per the prompt.

Analysis

A small comment about runtime is the difference between using iterrows with a pandas dataframe vs. using itertuples. Big runtime savings by using itertuples.

| Dataset | Algorithm | Runtime | Score |
|---------|-----------------|---------------------|--------|
| Small | Value Iteration | 6s (20 iters) | 27.4 |
| Medium | Q-Learning | 38s (100 iters) | 95.0 |
| Medium | Q-Learning | 3m10s (500 iters) | 102.1 |
| Medium | Q-Learning | 303m17s (50000 its) | 102.1 |
| Large | Q-Learning | 41s (100 iters) | 7460.7 |
| Large | Q-Learning | 3m15s (500 iters) | 7747.7 |
| Large | Q-Learning | 35m45s (5000 iters) | 7807.3 |
| Large | Q-Learning | 313m17s (50000 its) | 8003.2 |

I was able to get good scores with 100 iterations of Q-Learning. Runtime under 1 minute also seems fairly reasonable, but by running tons of iterations I was getting close to an upper bound for straight Q-Learning scores.