

## Exercises

2. Hand-simulating backpropagation of error as in the previous example, repeat the calculation for the following two cases:

High output-layer weights:  $w_{11}^{(1)} = 3.0, w_{12}^{(1)} = -3.0, w_{21}^{(1)} = 3.0, w_{22}^{(1)} = 3.0$

Small output-layer weights:  $w_{11}^{(1)} = 0.3, w_{12}^{(1)} = -0.3, w_{21}^{(1)} = 0.3, w_{22}^{(1)} = 0.3$

Observe the relative changes in the weights in each case.

## Give it Some Thought

1. How will you generalize the technique of backpropagation of error so that it can be used in a *multilayer perceptron* with more than one hidden layer?
2. Section 5.1 suggested that all attributes should be normalized here to the interval  $[-1.0, 1.0]$ . How will the network's classification and training be affected if the attributes are not so normalized? (hint: this has something to do with the sigmoid function)

## Computer Assignments

1. Write a program that implements backpropagation of error for a predefined number of output and hidden neurons. Use a fixed learning rate,  $\eta$ .
2. Apply the program implemented in the previous task to some benchmark domains from the UCI repository.<sup>3</sup> Experiment with different values of  $\eta$ , and see how they affect the speed of convergence.