

$$\vec{A} = \begin{bmatrix} 4 & -1 & 0 & -1 & 0 & 0 \\ -1 & 4 & -1 & 0 & -1 & 0 \\ 0 & -1 & 4 & 0 & 1 & -1 \\ -1 & 0 & 0 & 4 & -1 & -1 \\ 0 & -1 & 0 & -1 & 4 & -1 \\ 0 & 0 & -1 & 0 & -1 & 4 \end{bmatrix} \quad \vec{b} = \begin{bmatrix} 0 \\ -1 \\ 9 \\ 4 \\ 8 \\ 6 \end{bmatrix}$$

(a) Jacobi method

$$U = \begin{bmatrix} 0 & -1 & 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 & -1 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 & -1 & -1 \\ 0 & 0 & 0 & 0 & 0 & -1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \quad L = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 & 0 & 0 \\ -1 & 0 & 0 & 0 & 0 & 0 \\ 0 & -1 & 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 & -1 & 0 \end{bmatrix} \quad D = \begin{bmatrix} 4 & 0 & 0 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 4 & 0 & 0 & 0 \\ 0 & 0 & 0 & 4 & 0 & 0 \\ 0 & 0 & 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 0 & 0 & 4 \end{bmatrix}$$

$$\vec{x} = -D^{-1}(L+U)\vec{x} + D^{-1}\vec{b} \equiv T\vec{x} + \vec{c} \quad \vec{x}^{(0)} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\Rightarrow \vec{x} = \begin{bmatrix} 1.1744519 \\ 1.6400099 \\ 2.44806863 \\ 3.05566192 \\ 3.949207 \\ 3.09939812 \end{bmatrix} \#$$

(b) Gauss-Seidel method

$$\vec{x} = -(D+L)^{-1}U\vec{x} + (D+L)^{-1}\vec{b} \equiv T_g\vec{x} + \vec{c} \quad \vec{x}^{(0)} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\vec{x} = \begin{bmatrix} 1.17473347 \\ 1.64315472 \\ 2.44825739 \\ 3.05595033 \\ 3.9496441 \\ 3.09947537 \end{bmatrix} \#$$

(c) SOR method $\omega = 0.5$

$$\bar{x} = (D + \omega L)^{-1} [(1 - \omega)D - \omega U] \bar{x} + \omega (D + \omega L)^{-1} \vec{b} \equiv T_{\omega} \bar{x} + \vec{c} \quad \bar{x}^{(0)} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\bar{x} = \begin{bmatrix} 1.27740673 \\ 1.77746127 \\ 2.52444282 \\ 3.33506718 \\ 4.31021642 \\ 3.75535492 \end{bmatrix} \#$$

(d) The conjugate gradient method

$$t_k = \frac{\vec{v}_k^T \vec{v}_k}{\vec{v}_k^T A \vec{v}_k} \quad \bar{x}^{(k)} = \bar{x}^{(k-1)} + t_k \vec{v}_k \quad \vec{v}_{k+1} = \vec{b} - A \bar{x}^{(k)} \quad \bar{x}^{(0)} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

$$\bar{x} = \begin{bmatrix} 1.17447536 \\ 1.64296141 \\ 2.44811446 \\ 3.05565523 \\ 3.94924477 \\ 3.09936634 \end{bmatrix}$$

輸出結果截圖

```
(a) Jacobi method:
X0:
[[1]
 [1]
 [1]
 [1]
 [1]
 [1]]
X1:
[[0.5 ]
 [0.5 ]
 [2.5 ]
 [1.75]
 [2.75]
 [2.  ]]
X2:
[[0.5625]
 [1.1875]
 [2.1875]
 [2.3125]
 [3.0625]
 [2.8125]]
X3:
[[0.875  ]
 [1.203125]
 [2.484375]
 [2.609375]
 [3.578125]
 [2.8125  ]]
X4:
[[0.953125 ]
 [1.484375 ]
 [2.359375 ]
 [2.81640625]
 [3.65625  ]
 [3.015625  ]]
X5:
[[1.07519531]
 [1.4921875 ]
 [2.4609375 ]
 [2.90625  ]
 [3.82910156]
 [3.00390625]]
X6:
[[1.09960938]
 [1.59130859]
 [2.41674805]
 [2.97705078]
 [3.85058594]
 [3.07250977]]
X7:
[[1.14208984]
 [1.59173584]
 [2.45330811]
 [3.00567627]
 [3.91021729]
 [3.0668335  ]]
X8:
[[1.14935303]
 [1.62640381]
 [2.43708801]
 [3.02978516]
 [3.9160614  ]
 [3.09088135]]
X9:
[[1.16404724]
 [1.62562561]
 [2.45030594]
 [3.03907394]
 [3.93676758]
 [3.08828735]]
X10:
[[1.16617489]
 [1.63778019]
 [2.44428635]
 [3.04727554]
 [3.93824673]
 [3.09676838]]
X11:
[[1.17126393]
 [1.63717699]
 [2.44907546]
 [3.0502975  ]
 [3.94545603]
 [3.09563327]]
X12:
[[1.17186862]
 [1.64144886]
 [2.44683856]
 [3.05308831]
 [3.94577694]
 [3.09863287]]
X13:
[[1.17363429]
 [1.64112103]
 [2.4485762  ]
 [3.05406961]
 [3.94829251]
 [3.09815387]]
X14:
[[1.17379766]
 [1.64262575]
 [2.4477456  ]
 [3.05502017]
 [3.94833613]
 [3.09921718]]
X15:
[[1.17441148]
 [1.64246985]
 [2.4483767  ]
 [3.05533774]
 [3.94921577]
 [3.09902043]]
X16:
[[1.1744519  ]
 [1.64300099]
 [2.44806863]
 [3.05566192]
 [3.949207  ]
 [3.09939812]]
```

(b)Gauss_seidel method:

X0:

[[1]
[1]
[1]
[1]
[1]
[1]]

X1:

[[0.5]
[0.375]
[2.34375]
[1.625]
[2.75]
[2.7734375]]

X2:

[[0.5]
[1.1484375]
[2.54296875]
[2.50585938]
[3.60693359]
[3.03747559]]

X3:

[[0.91357422]
[1.51586914]
[2.48660278]
[2.88949585]
[3.86071014]
[3.08682823]]

X4:

[[1.10134125]
[1.61216354]
[2.45957041]
[3.01221991]
[3.92780292]
[3.09684333]]

X5:

[[1.15609586]
[1.6358673]
[2.45122693]
[3.04518553]
[3.94447404]
[3.09892524]]

X6:

[[1.17026321]
[1.64149104]
[2.44898556]
[3.05341562]
[3.94845798]
[3.09936088]]

X7:

[[1.17372667]
[1.64279255]
[2.44842386]
[3.05538638]
[3.94938495]
[3.0994522]]

X8:

[[1.17454473]
[1.64308839]
[2.44828891]
[3.05584547]
[3.94959652]
[3.09947136]]

X9:

[[1.17473347]
[1.64315472]
[2.44825739]
[3.05595033]
[3.9496441]
[3.09947537]]

(c)SOC method:

X0:

[[1]
[1]
[1]
[1]
[1]
[1]]

X1:

[[0.75]
[0.71875]
[1.69921875]
[1.34375]
[1.9296875]
[1.97705078]]

X2:

[[0.6328125]
[0.76708984]
[2.06079102]
[1.73931885]
[2.57215118]
[2.59108067]]

X3:

[[0.62970734]
[0.91637611]
[2.25668371]
[2.09377682]
[3.03310479]
[2.9802014]]

X4:

[[0.69112279]
[1.08080197]
[2.36620417]
[2.38494203]
[3.36917057]
[3.23046004]]

X5:

[[0.77877939]
[1.22967025]
[2.42884705]
[2.61477227]
[3.61582311]
[3.39425129]]

X6:

[[0.86994501]
[1.35416202]
[2.4653723]
[2.79238856]
[3.79738679]
[3.50340803]]

X7:

[[0.95329133]
[1.45408731]
[2.48707472]
[2.92795505]
[3.93124969]
[3.57743207]]

X8:

[[1.02440096]
[1.53238433]
[2.5002332]
[3.03061286]
[4.0300535]
[3.62843937]]

X9:

[[1.08257513]
[1.59279989]
[2.50838982]
[3.10793993]
[4.10304915]
[3.66408706]]

X10:

[[1.12888004]
[1.63893982]
[2.51356713]
[3.165972]
[4.15702444]
[3.68930497]]

X11:

[[1.165054]
[1.67392561]
[2.51693433]
[3.20940892]
[4.19696716]
[3.70732767]]

X12:

[[1.19294382]
[1.70031847]
[2.51917704]
[3.24185929]
[4.22654676]
[3.72031681]]

X13:

[[1.21424413]
[1.72015522]
[2.52070418]
[3.26606811]
[4.2484659]
[3.72974216]]

X14:

[[1.23039998]
[1.73502387]
[2.52176461]
[3.28411006]
[4.26471746]
[3.73661884]]

X15:

[[1.24259173]
[1.74614616]
[2.52251325]
[3.29754603]
[4.27677261]
[3.74165765]]

X16:

[[1.25175739]
[1.75445349]
[2.52304894]
[3.30754647]
[4.28571851]
[3.74536226]]

X17:

[[1.25862869]
[1.76065126]
[2.52343635]
[3.31498692]
[4.29235931]
[3.74809308]]

X19:

[[1.26760861]
[1.76871283]
[2.52392598]
[3.32463671]
[4.30095263]
[3.75160242]]

X20:

[[1.270473]
[1.77127537]
[2.52407864]
[3.32769686]
[4.30367315]
[3.75270768]]

X21:

[[1.27260803]
[1.77318266]
[2.52419147]
[3.32997204]
[4.30569437]
[3.75352707]]

X22:

[[1.27419835]
[1.77460185]
[2.52427505]
[3.33166349]
[4.30719624]
[3.75413495]]

X23:

[[1.27538234]
[1.77565763]
[2.52433707]
[3.33292094]
[4.30831231]
[3.75458615]]

X24:

[[1.27626349]
[1.77644292]
[2.52438313]
[3.33385571]
[4.30914175]
[3.75492118]]

X25:

```
[[1.27691908]  
[1.77702696]  
[2.52441736]  
[3.33455061]  
[4.30975822]  
[3.75517004]]
```

X26:

```
[[1.27740673]  
[1.77746127]  
[2.52444282]  
[3.33506718]  
[4.31021642]  
[3.75535492]]
```

(d)The conjugate gradient method:

X0:

[[1]
[1]
[1]
[1]
[1]
[1]]

X1:

[[0.42718447]
[0.42718447]
[2.7184466]
[1.8592233]
[3.00485437]
[2.14563107]]

X2:

[[0.56211407]
[1.23109279]
[2.17986204]
[2.35925654]
[3.10123266]
[2.87923993]]

X3:

[[0.92007309]
[1.20944218]
[2.52388538]
[2.65417226]
[3.65199427]
[2.81632135]]

X4:

[[0.96232489]
[1.4994266]
[2.35753236]
[2.83203247]
[3.66857921]
[3.02619379]]

X5:

[[1.09076258]
[1.49695727]
[2.47125314]
[2.91966299]
[3.85060631]
[3.00523938]]

X6:

[[1.10307331]
[1.5945775]
[2.41761117]
[2.98124112]
[3.85507246]
[3.07438863]]

X7:

[[1.14663676]
[1.59389736]
[2.45582624]
[3.00989794]
[3.91632287]
[3.06776298]]

X8:

[[1.1505979]
[1.62678307]
[2.43792065]
[3.03082655]
[3.91776207]
[3.09098041]]

X9:

[[1.16530763]
[1.62655619]
[2.45079247]
[3.04042583]
[3.9384187]
[3.08878561]]

X10:

[[1.16662826]
[1.63764526]
[2.4447658]
[3.04749997]
[3.93889925]
[3.09660833]]

X11:

[[1.17159164]
[1.63756861]
[2.44910555]
[3.05073284]
[3.94586703]
[3.0958709]]

X12:

[[1.1720359]
[1.64130884]
[2.44707361]
[3.05312033]
[3.94602872]
[3.09850884]]

X13:

[[1.17371028]
[1.64128297]
[2.44853727]
[3.05421042]
[3.94837907]
[3.09826029]]

X14:

[[1.17386004]
[1.64254458]
[2.44785193]
[3.05501586]
[3.94843358]
[3.09915004]]

X15:

[[1.17442485]
[1.64253585]
[2.44834563]
[3.05538353]
[3.94922638]
[3.09906622]]

X16:

[[1.17447536]
[1.64296141]
[2.44811446]
[3.05565523]
[3.94924477]
[3.09936634]]