

Linear Algebra In Machine Learning

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1 Symmetric Matrices

Theorem 1.1. Suppose $A \in \mathbb{R}^{n \times n}$ is symmetric, then

1. every eigenvalue λ of A is a real number, and there exists a real orthonormal eigenvector $\mu \in \mathbb{R}^n$ corresponding to λ such that $A\mu = \lambda\mu$. Note that, eigenvalues are the roots of characteristic polynomial

$$\det(A - \lambda I) = 0$$

2. eigenvectors corresponding to distinct eigenvalues are necessarily orthogonal, that is

$$\left. \begin{array}{l} A\mu^{(1)} = \lambda_1\mu^{(1)} \\ A\mu^{(2)} = \lambda_2\mu^{(2)} \\ \lambda_1 \neq \lambda_2 \end{array} \right\} \Rightarrow \mu^{(1)} \cdot \mu^{(2)} = 0$$

3. there exists a diagonal matrix $\Lambda \in \mathbb{R}^{n \times n}$ and an orthogonal matrix $U \in \mathbb{R}^{n \times n}$ such that

$$A = U\Lambda U^\top,$$

which is also called symmetric eigenvalue decomposition. The diagonal entries of Λ are the eigenvalues of A and the columns of U are the corresponding eigenvectors, where

$$A\mu^{(i)} = \lambda_i\mu^{(i)}, \quad i = 1, \dots, n$$

- 4.

$$A = U\Lambda U^\top = U\Lambda U^{-1} \quad (\text{Spectrum Theorem})$$

because U is orthogonal, which means the columns of U are orthonormal (i.e. any two of them are orthogonal and each has norm 1), for $i \neq j$, $\mu^{(i)} \cdot \mu^{(j)} = 0$ and $\|\mu^{(i)}\|_2 = 1$, then $U^\top = U^{-1}$ because $U^\top U = I = U^{-1}U$.

2 Positive Definite

A matrix $A \in S^n$ (symmetric) is called positive definite if for all vectors $x \neq 0$ and $x \in \mathbb{R}^n$,

$$x^\top Ax > 0$$

which implies all eigenvalues of A are positive, and we denote $A \succ 0$ and $A \in S_{++}^n$. If $-A$ is positive definite, we say A is negative definite, and write it as $A \prec 0$. If A satisfies $x^\top Ax \succeq 0$ for all $x \in \mathbb{R}^n$, then A is positive semidefinite, and denote $A \succeq 0$, $A \in S_+^n$.

Theorem 2.1. Suppose $A \in S_+^n$ (symmetric positive semidefinite), then

1. the eigenvalues of A are nonnegative, that is $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_n \geq 0$, where

$$\lambda_1 = \lambda_{\max}(A) = \sup_{x \neq 0} \frac{x^\top Ax}{x^\top x}$$

$$\lambda_n = \lambda_{\min}(A) = \inf_{x \neq 0} \frac{x^\top Ax}{x^\top x}$$

$$\lambda_{\min}(A)x^\top x \leq x^\top Ax \leq \lambda_{\max}(A)x^\top x \quad \text{for any } x$$

2. determinant of A is greater than and equal to 0, since $\det(A) = \prod_i^n \lambda_i$
3. trace of A is greater than and equal to 0, since $\text{trace}(A) = \sum_i^n \lambda_i$
4. $A = M^\top M$ for some matrix M , since $A = U\Lambda U^\top = U\Lambda^{1/2}\Lambda^{1/2}U^\top$ and $M = \Lambda^{1/2}U^\top$
5. $x^\top Ax = 0$ implies $Ax = 0$, because $x^\top Ax = x^\top M^\top Mx = \|Mx\|_2 = 0$ and $Ax = M^\top Mx = M^\top 0 = 0$
6. A is nonsingular (invertible) if and only if $A \succ 0$
7. any principal submatrix of A is positive semidefinite

3 Schur Complements and Additional Characteristic of SPD Matrices

The Schur complement comes up in solving linear equations, by eliminating one block of variables. Let M be an $n \times n$ matrix written as a 2×2 block matrix

$$M = \begin{bmatrix} A & B \\ C & D \end{bmatrix}$$

where A is $p \times p$ matrix and D is a $q \times q$ matrix, with $n = p + q$. We can try to solve the linear system

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} c \\ d \end{bmatrix}$$

that is

$$Ax + By = c \quad Cx + Dy = d$$

Now, we assume that D is invertible, we first solve for y getting

$$y = D^{-1}(d - Cx)$$

and substitute y back into first equation, we get

$$Ax + B(D^{-1}(d - Cx)) = c$$

that is

$$(A - BD^{-1}C)x = c - BD^{-1}d$$

Now, if the matrix $A - BD^{-1}C$ is invertible, then we obtain the solution to our system

$$x = (A - BD^{-1}C)^{-1}(c - BD^{-1}d)$$

$$y = D^{-1}(d - Cx) = D^{-1}(d - C(A - BD^{-1}C)^{-1}(c - BD^{-1}d))$$

The matrix $A - BD^{-1}C$ is called the Schur complement of D in M . If A is invertible, then by eliminating x first using the first equation, we find that the Schur complement of A in M is $D - CA^{-1}B$.

The above equations can be expanded and written as

$$x = (A - BD^{-1}C)^{-1}c - (A - BD^{-1}C)^{-1}BD^{-1}d$$

$$\begin{aligned} y &= D^{-1}d - D^{-1}C(A - BD^{-1}C)^{-1}c + D^{-1}C(A - BD^{-1}C)^{-1}BD^{-1}d \\ &= -D^{-1}C(A - BD^{-1}C)^{-1}c + (D^{-1} + D^{-1}C(A - BD^{-1}C)^{-1}BD^{-1})d \end{aligned}$$

According to

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} A & B \\ C & D \end{bmatrix}^{-1} \begin{bmatrix} c \\ d \end{bmatrix}$$

we can see that

$$\begin{aligned}
\begin{bmatrix} A & B \\ C & D \end{bmatrix}^{-1} &= \begin{bmatrix} (A - BD^{-1}C)^{-1} & -(A - BD^{-1}C)^{-1}BD^{-1} \\ -D^{-1}C(A - BD^{-1}C)^{-1} & (D^{-1} + D^{-1}C(A - BD^{-1}C)^{-1}BD^{-1}) \end{bmatrix} \\
&= \begin{bmatrix} (A - BD^{-1}C)^{-1} & 0 \\ -D^{-1}C(A - BD^{-1}C)^{-1} & D^{-1} \end{bmatrix} \begin{bmatrix} I & -BD^{-1} \\ 0 & I \end{bmatrix} \\
&= \begin{bmatrix} I & 0 \\ -D^{-1}C & I \end{bmatrix} \begin{bmatrix} (A - BD^{-1}C)^{-1} & 0 \\ 0 & D^{-1} \end{bmatrix} \begin{bmatrix} I & -BD^{-1} \\ 0 & I \end{bmatrix}
\end{aligned}$$

Since

$$(XYZ)^{-1} = Z^{-1}Y^{-1}X^{-1}$$

and

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

we can have

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} I & BD^{-1} \\ 0 & I \end{bmatrix} \begin{bmatrix} (A - BD^{-1}C) & 0 \\ 0 & D \end{bmatrix} \begin{bmatrix} I & 0 \\ D^{-1}C & I \end{bmatrix}$$

We can see that

$$\det M = \det(A - BD^{-1}C) \det D$$

If A is invertible, then we can use the Schur complement, $D - CA^{-1}B$ of A to obtain the following factorization of M :

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix} = \begin{bmatrix} I & 0 \\ CA^{-1} & I \end{bmatrix} \begin{bmatrix} A & 0 \\ 0 & D - CA^{-1}B \end{bmatrix} \begin{bmatrix} I & A^{-1}B \\ 0 & I \end{bmatrix}$$

If $D - CA^{-1}B$ is invertible, we can invert all three matrices above and we get another formula for the inverse of M in terms of $D - CA^{-1}B$, namely

$$\begin{aligned}
\begin{bmatrix} A & B \\ C & D \end{bmatrix}^{-1} &= \begin{bmatrix} I & -A^{-1}B \\ 0 & I \end{bmatrix} \begin{bmatrix} A^{-1} & 0 \\ 0 & (D - CA^{-1}B)^{-1} \end{bmatrix} \begin{bmatrix} I & 0 \\ -CA^{-1} & I \end{bmatrix} \\
&= \begin{bmatrix} A^{-1} + A^{-1}B(D - CA^{-1}B)^{-1}CA^{-1} & -A^{-1}B(D - CA^{-1}B)^{-1} \\ -(D - CA^{-1}B)^{-1}CA^{-1} & (D - CA^{-1}B)^{-1} \end{bmatrix}
\end{aligned}$$

3.1 Matrix Inversion Lemma

If A, D and both Schur complements $A - BD^{-1}C$ and $D - CA^{-1}B$ are all invertible, by comparing the two expression for M^{-1} , we get the formula

$$(A - BD^{-1}C)^{-1} = A^{-1} + A^{-1}B(D - CA^{-1}B)^{-1}CA^{-1}$$

and

$$\begin{bmatrix} A & B \\ C & D \end{bmatrix}^{-1} = \begin{bmatrix} (A - BD^{-1}C)^{-1} & -A^{-1}B(D - CA^{-1}B)^{-1} \\ -(D - CA^{-1}B)^{-1}CA^{-1} & (D - CA^{-1}B)^{-1} \end{bmatrix}$$

If we set $D = I$ and change B to $-B$ we get

$$(A + BC)^{-1} = A^{-1} - A^{-1}B(I + CA^{-1}B)^{-1}CA^{-1}$$

a formula known as the matrix inversion lemma, or the Sherman-Woodbury-Morrison formula.

The $(A + BC)^{-1}$ can be used to solve the problem

$$(A + BC)x = b$$

where $A \in \mathbb{R}^{n \times n}, B \in \mathbb{R}^{n \times p}$ and $C \in \mathbb{R}^{p \times n}$. If p is small, then it gives us a method for solving $(A + BC)x = b$, which is same as problem

$$Ax + By = b, \quad y = Cx$$

or, in matrix form

$$\begin{bmatrix} A & B \\ C & -I \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} b \\ 0 \end{bmatrix}$$

It is more efficient to solve a larger set of equations when A, B, C are much sparser than $A + BC$. From $Ax + By = b$, we get $x = A^{-1}(b - By)$, and substitute into the $y = Cx$, we have $y = C(A^{-1}(b - By))$ and

$$\begin{aligned} y &= (I + CA^{-1}B)^{-1}CA^{-1}b \\ x &= (A^{-1} - A^{-1}B(I + CA^{-1}B)^{-1}CA^{-1})b \end{aligned}$$

Since $x = (A + BC)^{-1}b$, we have

$$(A + BC)^{-1} = A^{-1} - A^{-1}B(I + CA^{-1}B)^{-1}CA^{-1}$$

3.2 Additional Characteristics of SPD Matrices

Consider a matrix $X \in S^n$ partitioned as

$$X = \begin{bmatrix} A & B \\ B^\top & D \end{bmatrix}$$

where $D \in S^k$. If $\det D \neq 0$ (D is invertible), the Schur complement of D is matrix

$$S = A - BD^{-1}B^\top.$$

If $\det A \neq 0$ (A is invertible), the Schur complement of A is matrix

$$S = D - B^\top A^{-1}B.$$

Proposition 3.0.1. *For any symmetric matrix, M , of the form*

$$M = \begin{bmatrix} A & B \\ B^\top & D \end{bmatrix},$$

if D is invertible then the following properties hold:

1. $M \succ 0$ if and only if $D \succ 0$ and $A - BD^{-1}B^\top \succ 0$.
2. If $D \succ 0$, then $M \succeq 0$ if and only if $A - BD^{-1}B^\top \succeq 0$.

Proposition 3.0.2. *For any symmetric matrix, M , of the form*

$$M = \begin{bmatrix} A & B \\ B^\top & D \end{bmatrix},$$

if A is invertible then the following properties hold:

1. $M \succ 0$ if and only if $A \succ 0$ and $D - B^\top A^{-1}B \succ 0$.
2. If $A \succ 0$, then $M \succeq 0$ if and only if $D - B^\top A^{-1}B \succeq 0$.

4 Pseudo-Inverses and SVD

5 PCA and Multivariate Gaussian

References

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- [2] Appendix A.5.5 and C.4.3. Boyd, Stephen, and Lieven Vandenberghe. Convex optimization. Cambridge university press, 2004.
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[4]