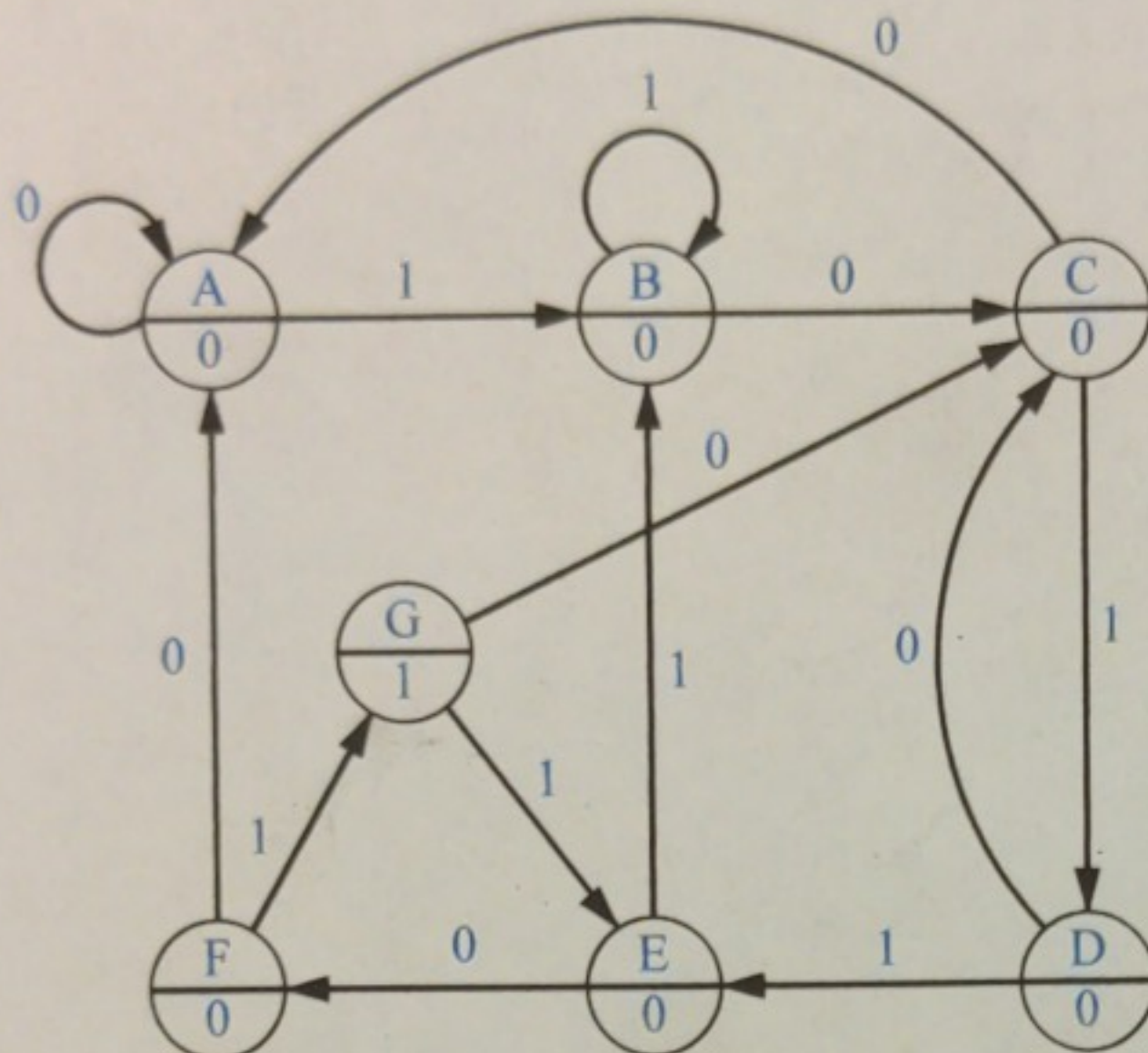


- 1.) You have been handed a state diagram that you have been asked to implement the design for. (Unused states: extra state encodings can be treated as "don't care" values and are used to simplify the combinational logic.)



Current State				Input	Next State				Outputs
State Name	Q2	Q1	Q0	X	State Name	Q2(t+1)	Q1(t+1)	Q0(t+1)	Z
A	0	0	0	0	A	0	0	0	0
A	0	0	0	1	B	0	0	1	0
B	0	0	1	0	C	0	1	0	0
B	0	0	1	1	B	0	0	1	0
C	0	1	0	0	A	0	0	0	0
C	0	1	0	1	D	0	1	1	0
D	0	1	1	0	C	0	1	0	0
D	0	1	1	1	E	1	0	0	0
E	1	0	0	0	F	1	0	1	0
E	1	0	0	1	B	0	0	1	0
F	1	0	1	0	A	0	0	0	0
F	1	0	1	1	G	1	1	0	0
G	1	1	0	0	C	0	1	0	1
G	1	1	0	1	E	1	0	0	1

- Implement the design using T flip-flops, JK flip-flops, and SR flip-flops
- Determine the Boolean expression for the inputs of the different types of flip-flops and the output.
- Draw the circuit using only the JK flip-flops using the Deeds software and verify that it works. You do not need to draw the circuits using the T or SR flip-flops. Include a screen shot of your schematic and include the Deeds file with your homework submission.



Current State				Input X	Next State				Outputs Z	Flip Flop Inputs		
State Name	Q2	Q1	Q0		State Name	Q2(t+1)	Q1(t+1)	Q0(t+1)		T2	T1	T0
A	0	0	0	0	A	0	0	0	0	0	0	0
A	0	0	0	1	B	0	0	1	0	0	0	1
B	0	0	1	0	C	0	1	0	0	0	1	1
B	0	0	1	1	B	0	0	1	0	0	0	0
C	0	1	0	0	A	0	0	0	0	0	1	0
C	0	1	0	1	D	0	1	1	0	0	0	1
D	0	1	1	0	C	0	1	0	0	0	0	1
D	0	1	1	1	E	1	0	0	0	1	1	1
E	1	0	0	0	F	1	0	1	0	0	0	1
E	1	0	0	1	B	0	0	1	0	1	0	1
F	1	0	1	0	A	0	0	0	0	1	0	1
F	1	0	1	1	G	1	1	0	0	0	1	1
G	1	1	0	0	C	0	1	0	1	1	0	0
G	1	1	0	1	E	1	0	0	1	0	1	0

Q(t)	Q(t+1)	T
0	0	0
0	1	1
1	0	1
1	1	0

Q<sub>2</sub>Q<sub>1</sub>

00	0	0	1	0
01	0	0	1	0
11	0	0	X	0
10	0	0	X	0

$$Z = Q_2 Q_1$$

Q<sub>2</sub>Q<sub>1</sub>

00	0	0	1	0
01	0	0	0	1
11	0	1	X	0
10	0	0	X	1

$$T_2 = Q_2 Q_1 \bar{X} + Q_1 Q_0 X + Q_2 Q_0 \bar{X} + Q_2 \bar{Q}_1 \bar{Q}_0 X$$

Q<sub>2</sub>Q<sub>1</sub>

00	0	1	0	0
01	0	0	1	0
11	0	1	X	1
10	1	0	X	0

$$T_1 = Q_2 Q_1 X + Q_1 Q_0 X + Q_2 Q_0 X + \bar{Q}_2 \bar{Q}_1 Q_0 \bar{X}$$

Q<sub>2</sub>Q<sub>1</sub>

00	0	0	0	1
01	1	1	0	1
11	0	1	X	1
10	1	1	X	1

$$T_0 = Q_2 \bar{Q}_1 + Q_1 Q_0 + Q_0 \bar{X} + \bar{Q}_2 \bar{Q}_0 X$$



Current State				Input	Next State				Outputs	Flip Flop Inputs					
State Name	Q2	Q1	Q0	X	State Name	Q2(t+1)	Q1(t+1)	Q0(t+1)	Z	J2	K2	J1	K1	J0	K0
A	0	0	0	0	A	0	0	0	0	0	X	0	X	0	X
A	0	0	0	1	B	0	0	1	0	0	X	0	X	1	X
B	0	0	1	0	C	0	1	0	0	0	X	1	X	X	1
B	0	0	1	1	B	0	0	1	0	0	X	0	X	X	0
C	0	1	0	0	A	0	0	0	0	0	X	X	1	0	X
C	0	1	0	1	D	0	1	1	0	0	X	X	0	1	X
D	0	1	1	0	C	0	1	0	0	0	X	X	0	X	1
D	0	1	1	1	E	1	0	0	0	1	X	X	1	X	1
E	1	0	0	0	F	1	0	1	0	X	0	0	X	1	X
E	1	0	0	1	B	0	0	1	0	X	1	0	X	1	X
F	1	0	1	0	A	0	0	0	0	X	1	0	X	X	1
F	1	0	1	1	G	1	1	0	0	X	0	1	X	X	1
G	1	1	0	0	C	0	1	0	1	X	1	X	0	0	X
G	1	1	0	1	E	1	0	0	1	X	0	X	1	0	X

Q(t)	Q(t+1)	J	K
0	0	0	X
0	1	1	X
1	0	X	1
1	1	X	0

$Z, Q_2Q_1$

	00	01	11	10
00	0	0	1	0
01	0	0	1	0
11	0	0	X	0
10	0	0	X	0

$$Z = Q_2Q_1$$

$J_1, Q_2Q_1$

	00	01	11	10
00	0	X	X	0
01	0	X	X	0
11	0	X	X	1
10	1	X	X	0

$$J_1 = Q_2Q_0X + \bar{Q}_2Q_0\bar{X}$$

$J_2, Q_2Q_1$

	00	01	11	10
00	0	0	X	X
01	0	0	X	X
11	0	1	X	X
10	0	0	X	X

~~$$J_2 = Q_2Q_0$$~~

$$J_2 = Q_1Q_0X$$

$K_1, Q_2Q_1$

	00	01	11	10
00	X	1	0	X
01	X	0	1	X
11	X	1	X	X
10	X	0	X	X

$$K_1 = Q_2X + Q_0X + \bar{Q}_2\bar{Q}_0\bar{X}$$

$K_2, Q_2Q_1$

	00	01	11	10
00	X	X	1	0
01	X	X	0	1
11	X	X	X	0
10	X	X	X	1

$$K_2 = Q_0\bar{X} + Q_2Q_1\bar{X} + \bar{Q}_1\bar{Q}_0X$$

$J_0, Q_2Q_1$

	00	01	11	10
00	0	0	0	1
01	1	1	0	1
11	X	X	X	X
10	X	X	X	X

$$J_0 = Q_2\bar{Q}_1 + \bar{Q}_2X$$

$K_0, Q_2Q_1$

	00	01	11	10
00	X	X	X	X
01	X	X	X	X
11	0	1	X	1
10	1	1	X	1

$$K_0 = Q_2 + Q_1 + X$$



Current State				Input X	Next State				Outputs Z	Flip Flop Inputs					
State Name	Q2	Q1	Q0		State Name	Q2(t+1)	Q1(t+1)	Q0(t+1)		S2	R2	S1	R1	S0	R0
A	0	0	0	0	A	0	0	0	0	0	X	0	X	0	X
A	0	0	0	1	B	0	0	1	0	0	X	0	X	1	0
B	0	0	1	0	C	0	1	0	0	0	X	1	0	0	1
B	0	0	1	1	B	0	0	1	0	0	X	0	X	X	0
C	0	1	0	0	A	0	0	0	0	0	X	0	1	0	X
C	0	1	0	1	D	0	1	1	0	0	X	X	0	1	0
D	0	1	1	0	C	0	1	0	0	0	X	X	0	0	1
D	0	1	1	1	E	1	0	0	0	1	0	0	1	0	1
E	1	0	0	0	F	1	0	1	0	X	0	0	X	1	0
E	1	0	0	1	B	0	0	1	0	0	1	0	X	1	0
F	1	0	1	0	A	0	0	0	0	0	1	0	X	0	1
F	1	0	1	1	G	1	1	0	0	X	0	0	0	0	1
G	1	1	0	0	C	0	1	0	1	0	1	X	0	0	X
G	1	1	0	1	E	1	0	0	1	X	0	0	1	0	X

Q(t)	Q(t+1)	S	R
0	0	0	X
0	1	1	0
1	0	0	1
1	1	X	0

$S_1$   $Q_2 Q_1$

$Q_0 X$

	00	01	11	10
0	0	0	X	0
0	0	X	0	0
0	0	0	X	1
1	X	X	X	0

$$S_1 = \overline{Q_2} Q_0 \overline{X} + Q_2 Q_0 X$$

$R_1$   $Q_2 Q_1$

$Q_0 X$

	00	01	11	10
0	X	1	0	X
0	X	0	1	X
0	X	1	X	0
1	0	0	X	X

$$R_1 = \overline{Q_2} \overline{Q_0} \overline{X} + Q_2 Q_0 X + Q_1 Q_0 X$$

$S_0$   $Q_2 Q_1$

$Q_0 X$

	00	01	11	10
0	0	0	0	1
0	1	1	0	1
0	X	0	X	0
1	0	0	X	0

$$S_0 = Q_2 \overline{Q_1} Q_0 + \overline{Q_2} \overline{Q_0} X$$

$R_0$   $Q_2 Q_1$

$Q_0 X$

	00	01	11	10
0	X	X	X	0
0	0	0	X	0
0	0	1	X	1
1	1	1	X	1

$$R_0 = Q_0 \overline{X} + Q_2 Q_0 + Q_1 Q_0$$

$Z$   $Q_2 Q_1$

$Q_0 X$

	00	01	11	10
0	0	1	0	0
0	0	1	0	0
0	0	X	0	0
0	0	X	1	0

$$Z = Q_2 Q_1$$

$S_2$   $Q_2 Q_1$

$Q_0 X$

	00	01	11	10
0	0	0	X	0
0	0	X	0	0
0	1	X	X	0
0	0	X	1	0

$$S_2 = Q_1 Q_0 X$$

$R_2$   $Q_2 Q_1$

$Q_0 X$

	00	01	11	10
0	X	X	1	0
0	X	X	0	1
0	X	0	X	0
0	X	X	X	1

$$R_2 = Q_0 X + Q_1 \overline{Q_0} \overline{X} + \overline{Q_1} \overline{Q_0} X$$