[**DOING PHYSICS WITH MATLAB**](http://www.physics.usyd.edu.au/teach_res/mp/mphome.htm)

**DATA ANALYSIS**

**LINEAR FIT**

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**MATLAB SCRIPTS**

[Goto the directory containing the m-scripts and data files.](http://www.physics.usyd.edu.au/teach_res/mp/mscripts)

The Matlab scripts that are used to fit an equation to a set of experimental data:

**linear\_fit.m** Function used to fit a straight line to set of experimental data

**xyData1.mat xyData2.mat xyData3.mat** Sample data files

**CURVE FITTING - LEAST SQUARES FIT TO A STRAIGHT LINE**

**(Linear, Power, Exponential)**

A large part of physics involves taking measurements and determining a functional relationship describing the measurements so that a comparison can be made with the theoretical predictions of some model. One way to do this is by plotting the measurements and finding an equation that best fits the data. There are a number of methods that can be used to fit a theoretical curve to a set of measurements, for example, the least squares fit to a straight line.

Matlab can be used to find an equation to fit the measurements when the data is plotted in a figure window and using Tools / Basic Fitting. However, we will consider an alternative way of curve fitting by using the extrinsic function **linear\_fit.m** which uses a **least squares** method or **linear regression** in which there are no uncertainties in the *X* or *Y* data.

The function **linear\_fit.m** can be used to test whether a linear, power or exponential curve fits a set of experiment data as each relationship can be expressed in the form of a straight line where *X* and *Y* are the variables and the constants are the slope *m* and intercept *b*.

(1) Linear relationship **

(2) Power relationship 

(3) Exponential relationship 

The (*x*,*y*) data is enter into the *n*×2 array, where *n* is the number of data points, for example, xyData. The type of fit is selected by a variable called flag (1, 2 or 3). The *X*-range for the graph is determined by the values of the variables xmin and xmax. The function returns values for the coefficients *a*1 and *a*2 and the uncertainties in these quantities and and the correlation coefficient *r*, as shown in Fig. 1.

The **uncertainties** of the slope and intercept give an indication of the precision of the regression. Measurements are never perfect. In repeated measurements, there is usually some variation. To interpret the meaning of the uncertainties, consider a large set of measurements were made and in each case estimates were found for the slope and intercept. You would then expect that 68% the estimates for the slope would be in the range (*m* ± *Em*) and 68% of the intercepts in the range (*b* ± *Eb*). Hence, the smaller the uncertainties the more consistent are the repeated measurements. The **correlation coefficient** *r* is a measure of the how good the line of best fit is to the data. The value of *r* can vary from -1 to +1. There is no linear correlation between the measurements *x* and *y* and if *r* = 0. If *r* = +1, all the data points lie perfectly on the straight line with positive slope, with *x* and *y* increasing together. When all the data points lie on the line with negative slope, *y* decreases with increasing *x*, then *r* = -1.

Entering or changing the labeling of the graph is done within the m-script for **linear\_fit.m** or changing the m-script so that the labeling is entered into the Command Window using the input command.

How to use the function **linear\_fit** is outlined in Fig. 1.



Fig. 1 Parameters describing the use of the function **linear\_fit.m**.

Three examples are given to illustrate how to use the **linear\_fit.m** function for measurements related to a mass-spring system.

**Example 1 – Linear relationship**

A spring was loaded by adding weights to it, causing an extension. The load *F* was measured in newtons and the extension *e* in mm. The hypothesis to be tested is that the load *F* is proportional to the extension *e*

*F* = *k e*

where the constant of proportionality *k* is known as the spring constant which is normally measured in N.m-1. This relationship is known as Hooke’s Law. If the hypothesis is accepted, the value of the spring constant *k* and its uncertainty can be estimated.

The measurements for the load *F* and extension *e* were

|  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| *e* (mm) | 0 | 20 | 55 | 78 | 98 | 130 | 154 | 173 | 205 |
| *F* (N) | 0 | 0.50 | 1.00 | 1.50 | 2.00 | 2.50 | 3.00 | 3.50 | 4.00 |

Step 1: Enter the data in to the array xyData1 in the Command Window

*X* data: *e* → xyData1(:,1) *Y* data: *F* → xyData1(:,2)

The data can be copied and pasted from MS EXCEL into Matlab. For example, create the array xyData1 = zeros(9,2) and view it using Workspace / Variable Edit. Then, copy the data from MS EXCEL and paste into the Variable Edit Window for the array xyData1.

Step 2: In the Command Window, type and execute the fitting function

[a1, a2, Ea1, Ea2, r] = linear\_fit(xyData1, 0, 250, 1);

You can just type and execute linear\_fit(xyData1, 0, 250, 1) in the Command Window but not all values will be passed to the Workspace.

The output of this function to the Command Window is

y = m x + b

n = 9

slope m = 0.01957 Em = 0.0003751

intercept b = 0.0147 Eb = 0.04537

correlation r = 0.9987

The plot of the data and the fitted function and the fit parameters are shown in Fig. 2.



Fig. 2. Plot for the loaded spring showing the measurements, the straight line of best fit and values for the slope, intercept and correlation coefficient.

A straight line () fits the data well with a correlation *r* > 0.998, therefore the hypothesis can be accepted and that the quantities *a*1 and *a2* are meaningful. The uncertainty in a measurement should be quoted to only 1 or 2 significant figures, hence the final coefficients describing the straight fit should be written as

Intercept *a*1 = (0.01 ± 0.04) N

Slope *a2* = (19.6 ± 0.4) N.m-1

We can conclude within the uncertainties of the intercept that *b* = 0 and that the load, *F* and extension, *e* are proportional to each other *F = k x* and the slope of the straight line correspondence to the spring constant *k* is

*k* = (19.6 ± 0.4) N.m-1

**Example 2 – Power relationship**

A spring had a load added to it causing it to extend. The spring was then displacement from its equilibrium so that it vibrated up and down about its equilibrium position. The period *T* of the oscillations was measured for different loads *m*. The period *T* was measured in seconds and the load *m* was measured in kilograms. The hypothesis is to be tested is that the period of oscillations *T* is related to the load *m* by the relationship



where *k* is the spring constant measured in N.m-1. The measurements were entered into the array xyData2

|  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| *m* (kg) | 0.020 | 0.050 | 0.100 | 0.150 | 0.200 | 0.250 | 0.300 | 0.350 | 0.400 |
| *T* (s) | 0.20 | 0.31 | 0.46 | 0.53 | 0.62 | 0.71 | 0.76 | 0.84 | 0.91 |

You can’t have any measurements entered as zero since the log10(0) = -infinity.

In the Command Window, type and execute the fitting function

[a1, a2, Ea1, Ea2, r] = linear\_fit(xyData2, 0.01, 0.4, 2)

The output of this function to the Command Window is

y = a1 x ^(a2)

n = 9

a1 = 1.413 Ea1 = 0.009916

a2 = 0.5016 Ea2 = 0.007565

correlation r = 0.9992

The graphical output for a power relationship is displayed in Fig. 3.



Fig. 3. Least squares straight line fit and the power fit to the data for a vibrating mass/spring system and the fitting parameters.

A straight line fits the data well with a correlation *r* > 0.999, therefore the hypothesis can be accepted that an appropriate model to describe the period of vibration of the spring is



The coefficient describing the fit should be expressed to the correct number of significant figures

*a*1 = (1.41 ± 0.01) s.kg-1/2

*a*2 = (0.502 ± 0.008)

which confirms the hypothesis that .

The value of the spring constant *k* is determined from the coefficient *a*1



*k* = (19.7 ± 0.3) N.m-1

which agrees with the value of *k* from the data in Example 1, *k* = (19.6 ± 0.4) N.m-1.

**Example 3 – Exponential relationship**

A spring had a load added to it causing it to extend. The spring was then displacement from its equilibrium so that it vibrated up and down about its equilibrium position. The amplitude *A* of the vibration slowly decreased. The amplitude *A* of the vibration was measured in millimeters and the time *t* in seconds. The hypothesis is to be tested is that the amplitude of vibration *A* decreases exponentially with time *t*



where βis the decay constant. The measurements were entered into the matrix xyData3.

|  |  |  |  |  |  |  |  |  |  |
| --- | --- | --- | --- | --- | --- | --- | --- | --- | --- |
| *t* (s) | 0 | 10 | 20 | 30 | 40 | 50 | 60 | 70 | 80 |
| *A* (mm) | 20.0 | 12.5 | 8.0 | 5.0 | 3.5 | 2.5 | 1.5 | 1.0 | 05 |

In the Command Window, the following was entered and the fitting function was executed

[a1, a2, Ea1, Ea2, r] = linear\_fit(xyData3, 0, 80, 3)

The output of this function to the Command Window is

y = a1 exp(a2 \* x) n = 9

a1 = 19.9 a2 = -0.04396

Ea1 = 1.127 Ea2 = 0.001189

correlation r = -0.9974

The graphical output for the exponential fit is shown in a power relationship is displayed in Fig. 4.



Fig. 4. Least squares straight line fit and the exponential fit to the data for a vibrating mass/spring system and the fitting parameters.

A straight line fits the data well with a correlation *r* > 0.997, therefore the hypothesis can be accepted that an appropriate model to describe the decay in the amplitude is of the form



The initial amplitude *Ao* is given by the coefficient *a*1 and the decay constant *β* by the coefficient *a*2

*A*o = (19.9 ± 1.1) m

*β* = (-0.0440 ± 0.0012) s-1

**Method of Least Squares or Regression Analysis**

To avoid individual judgments in approximating the curves to fit a set of data in which any uncertainties are ignored, it is necessary to agree on a definition of ‘**best fit’**. One way to do this is that all the curves approximating a given set of experimental data, have the property that

 is a minimum

where (*yi* – *fi*) is the deviation between the value of the measurements (*xi*, *yi*) and the fitted values *fi* = *f*(*xi*). This approach of finding the curve of best fit is known as the Method of Least Squares or Regression Analysis.

A **straight line** fit is the simplest and most common curve fitted to a set of measurements. The equation of a straight line is



where the constants *m* and *b* are the **slope** or **gradient** of the straight line and the **intercept** (value of *y* when *x* = 0) respectively. If a straight line fits the data, we say that there is a **linear relationship** between the measurements *x* and *y* and if the intercept *b* = 0 then *y* is said to be proportional to *x* (*y* ∝ *x* or *y* = *m x*) where the slope *m* corresponds to the constant of proportionality.

Using the method of least squares for a set of *n* measurements (*xi*, *yi*), estimates of the slope *m*, intercept *b* and the uncertainties in the slope *Em* and intercept *Eb* for the line of best fit are

slope 

intercept 

standard error in slope



standard error in intercept



where



correlation coefficient



Simply quoting the values of the slope *m* and intercept *b* is not very useful, it is always best to give measures of the ‘goodness of the fit’ - the correlation coefficient *r*, and the uncertainties of the slope *Em* and intercept *Eb*.

Often the relationship between the *x* and *y* data is non-linear but of a form that can be easily reduced to one which is linear. Two very common relationships of this form are the power and exponential relationships

Power relationship 

Exponential relationship 

**Power relationship**



The *X* and *Y* data is used to determine the slope *m* and intercept *b* and hence the coefficients *a*1 and *a*2. The uncertainty in the power is= *Em* and the uncertainty *Eb* in the intercept *b* is determines the uncertainty 



log10*a*1 = *b* ⇒ 



**Exponential relationship**



The *X* and *Y* data is used to determine the slope *m* and intercept *b* and hence the coefficients *a*1 and *a*2. The uncertainty in the power is= *Em* and the uncertainty *Eb* in the intercept *b* is determines the uncertainty 

