

## Acceptance Tests

<b>Test for</b> <b>US-D1</b> <a href="#">↗</a>	<b>Display thermal imaging in real-time</b> <a href="#">↗</a>
<b>Objective</b>	Verify that the system displays the FLIR camera's thermal imaging in real-time on the Raspberry Pi operating system and can stream to the web application for remote monitoring.
<b>Test Steps</b>	<ol style="list-style-type: none"><li>1. Set up the FLIR camera and connect it to the Raspberry Pi.</li><li>2. Start the system and open the thermal imaging application on the Raspberry Pi.</li><li>3. Verify that the thermal imaging is displayed in real-time with high clarity and a consistent refresh rate.</li><li>4. Access the FarmBot web application and confirm that the real-time thermal imaging is being streamed correctly.</li></ol>
<b>Expected Result</b>	<ul style="list-style-type: none"><li>• The thermal imaging is displayed in real-time on the Raspberry Pi with high clarity.</li><li>• The thermal imaging is successfully streamed to the web application for remote monitoring.</li></ul>

<b>Test for</b> <b>US-D2</b> <a href="#">↗</a>	<b>Understand FLIR camera's data interface</b> <a href="#">↗</a>
<b>Objective</b>	Verify that the system identifies and documents the data interface type of the FLIR camera and assesses compatibility with FarmBot's mainboard.
<b>Test Steps</b>	<ol style="list-style-type: none"><li>1. Connect the FLIR camera to the Raspberry Pi using both Ethernet and USB interfaces.</li><li>2. Identify and document the data interface type used by the FLIR camera.</li><li>3. Check the compatibility of the identified interface with FarmBot's mainboard.</li><li>4. Develop and document a communication strategy that ensures seamless data exchange between the FLIR camera and FarmBot's mainboard.</li></ol>
<b>Expected Result</b>	<ul style="list-style-type: none"><li>• The data interface type (Ethernet or USB) of the FLIR camera is identified and documented.</li><li>• Compatibility with FarmBot's mainboard is assessed and documented.</li><li>• A communication strategy is developed and documented.</li></ul>

<b>Test for</b> <b>US-D3</b> <a href="#">↗</a>	<b>Know sensor's dimensions and mounting details</b> <a href="#">↗</a>
<b>Objective</b>	Verify that the sensor's dimensions and mounting details are documented and that a stable, easily installable mounting solution is designed.
<b>Test Steps</b>	<ol style="list-style-type: none"><li>1. Measure and document the sensor's dimensions and mounting details.</li><li>2. Design a mounting solution for the sensor that fits within FarmBot's operational environment.</li><li>3. Create an installation guide with step-by-step instructions and safety precautions.</li><li>4. Test the installation process using the guide to ensure ease of use and stability.</li></ol>

<b>Expected Result</b>	<ul style="list-style-type: none"> <li>• The sensor's dimensions and mounting details are documented.</li> <li>• A stable and easily installable mounting solution is designed.</li> <li>• The installation guide is comprehensive and easy to follow.</li> <li>• The sensor is installed successfully and operates stably.</li> </ul>
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<b>Test for US-D4</b> <a href="#">↗</a>	<b>Adjust hardware integration for adaptability</b> <a href="#">↗</a>
<b>Objective</b>	Ensure that the FLIR camera and integration components support hardware adjustments for adaptability and are user-friendly.
<b>Test Steps</b>	<ol style="list-style-type: none"> <li>1. Test the FLIR camera and integration components for hardware adjustments.</li> <li>2. Verify that the camera supports plug-and-play functionality without the need for additional drivers or complex configuration steps.</li> <li>3. Evaluate the user experience during the integration process, focusing on ease of use and minimizing technical barriers.</li> </ol>
<b>Expected Result</b>	<ul style="list-style-type: none"> <li>• The FLIR camera and integration components support hardware adjustments for adaptability.</li> <li>• The camera is easily connectable to FarmBot without additional drivers or complex configurations.</li> <li>• The integration process is user-friendly, with minimal technical barriers</li> </ul>

<b>Test for US-D5</b> <a href="#">↗</a>	<b>Ensure camera's power cable compatibility</b> <a href="#">↗</a>
<b>Objective</b>	Verify that the camera's power cable is compatible with the movement range of FarmBot's robotic arm.
<b>Test Steps</b>	<ol style="list-style-type: none"> <li>1. Design a power cable for the camera that is flexible and long enough for FarmBot's full range of motion.</li> <li>2. Install the power cable and connect it to the camera and FarmBot.</li> <li>3. Move the robotic arm through its full range of motion while capturing thermal images.</li> <li>4. Assess the efficiency and reliability of the thermal imaging capture process.</li> <li>5. Verify that the power cable design adheres to safety standards and is durable under operational conditions.</li> </ol>
<b>Expected Result</b>	<ul style="list-style-type: none"> <li>• The power cable is designed and installed successfully, accommodating the full range of motion.</li> <li>• The thermal imaging capture process is efficient and reliable.</li> <li>• The power cable meets safety standards and is durable.</li> </ul>

<b>Test for US-D6</b> <a href="#">↗</a>	<b>Specify new sensor's power specifications</b> <a href="#">↗</a>
<b>Objective</b>	Verify that the new sensor's power specifications are documented and compatible with FarmBot's electrical system.
<b>Test Steps</b>	<ol style="list-style-type: none"> <li>1. Document the required voltage and current specifications for the new sensor.</li> <li>2. Verify the compatibility of the sensor's power specifications with FarmBot's electrical system.</li> </ol>

	3. Implement and document safety protocols to prevent equipment damage due to power incompatibility.
<b>Expected Result</b>	<ul style="list-style-type: none"> <li>• The power specifications for the new sensor are documented.</li> <li>• The sensor's power specifications are compatible with FarmBot's electrical system.</li> <li>• Safety protocols are in place to prevent equipment damage.</li> </ul>

<b>Test for US-D7</b> <a href="#">↗</a>	<b>Design efficient server architecture</b> <a href="#">↗</a>
<b>Objective</b>	Verify that an efficient server architecture is designed to handle data requests and responses for thermal imaging data.
<b>Test Steps</b>	<ol style="list-style-type: none"> <li>1. Design a server architecture that can efficiently handle thermal imaging data.</li> <li>2. Establish performance metrics, including response times and data handling capacity.</li> <li>3. Test the server architecture against these metrics.</li> <li>4. Assess the scalability of the server architecture to accommodate future data volume increases.</li> </ol>
<b>Expected Result</b>	<ul style="list-style-type: none"> <li>• An efficient server architecture is designed.</li> <li>• Performance metrics are established and met.</li> <li>• The server architecture is scalable to handle future data volume increases.</li> </ul>

<b>Test for US-D8</b> <a href="#">↗</a>	<b>Design a database for thermal imaging data</b> <a href="#">↗</a>
<b>Objective</b>	Verify that a database is designed to store and manage thermal imaging data efficiently and securely.
<b>Test Steps</b>	<ol style="list-style-type: none"> <li>1. Develop a database schema for storing thermal imaging data.</li> <li>2. Implement security measures to protect the data from unauthorized access.</li> <li>3. Establish routines for regular data integrity checks.</li> <li>4. Test the database for efficient data retrieval and storage.</li> </ol>
<b>Expected Result</b>	<ul style="list-style-type: none"> <li>• A database schema is developed.</li> <li>• Security measures are in place to protect the data.</li> <li>• Regular data integrity checks ensure accuracy and consistency.</li> <li>• The database efficiently retrieves and stores thermal imaging data.</li> </ul>

<b>Test for US-D9</b> <a href="#">↗</a>	<b>Integrate thermal imaging in the web application</b> <a href="#">↗</a>
<b>Objective</b>	Ensure the thermal imaging functionality is seamlessly integrated into the FarmBot web application, including real-time viewing.
<b>Test Steps</b>	<ol style="list-style-type: none"> <li>1. Access the FarmBot web application.</li> <li>2. Navigate to the new thermal imaging page.</li> <li>3. Verify that real-time thermal imaging is displayed on the page.</li> <li>4. Interact with the interface, such as zooming in on images or switching views, to confirm responsiveness and functionality.</li> <li>5. Collect user feedback on the thermal imaging functionality.</li> </ol>

<b>Expected Result</b>	<ul style="list-style-type: none"> <li>• The thermal imaging page displays real-time images correctly.</li> <li>• The interface is responsive and user-friendly, with all features functioning as intended.</li> </ul>
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<b>Test for US-D10</b> <a href="#">↗</a>	<b>Provide ability to download thermal imaging data as temperature matrices</b> <a href="#">↗</a>
<b>Objective</b>	Verify that users can download thermal imaging data as temperature matrices for further analysis.
<b>Test Steps</b>	<ol style="list-style-type: none"> <li>1. Access the FarmBot web application and navigate to the thermal imaging page.</li> <li>2. Capture a thermal image and download it as a temperature matrix.</li> <li>3. Verify that the downloaded matrix accurately represents the thermal imaging data.</li> <li>4. Follow the user guide to use the temperature matrix for data analysis.</li> </ol>
<b>Expected Result</b>	<ul style="list-style-type: none"> <li>• The thermal image is successfully downloaded as a temperature matrix.</li> <li>• The temperature matrix accurately represents the captured thermal imaging data.</li> <li>• The user guide provides clear instructions for analyzing the matrix data.</li> </ul>

  

<b>Test for US-D11</b> <a href="#">↗</a>	<b>Display camera's relative coordinates on FarmBot</b> <a href="#">↗</a>
<b>Objective</b>	Ensure the web app displays the camera's relative coordinates on the FarmBot, allowing users to identify, record, and analyze thermal images captured at different positions.
<b>Test Steps</b>	<ol style="list-style-type: none"> <li>1. Access the FarmBot web application and navigate to the thermal imaging page.</li> <li>2. Move the FarmBot's robotic arm to various positions.</li> <li>3. Verify that the web app displays the camera's relative coordinates in real-time.</li> <li>4. Capture thermal images at different positions and record the coordinates.</li> <li>5. Analyze the captured images to ensure the coordinates are accurate.</li> </ol>
<b>Expected Result</b>	<ul style="list-style-type: none"> <li>• The camera's relative coordinates are displayed accurately and updated in real-time.</li> <li>• Users can record and analyze thermal images with correct positional data.</li> </ul>

  

<b>Test for US-U1</b> <a href="#">↗</a>	<b>Simple and easy-to-use web application interface</b> <a href="#">↗</a>
<b>Objective</b>	Verify that the web application interface for viewing thermal imaging is simple and easy to use.
<b>Test Steps</b>	<ol style="list-style-type: none"> <li>1. Access the FarmBot web application.</li> <li>2. Navigate to the thermal imaging page.</li> <li>3. Interact with the interface, checking for ease of navigation and usability.</li> <li>4. Verify that instructional content or tooltips are available and helpful.</li> </ol>
<b>Expected Result</b>	<ul style="list-style-type: none"> <li>• The interface is straightforward and easy to navigate.</li> <li>• Real-time thermal imaging is accessible with minimal latency.</li> <li>• Instructional content is clear and assists users in understanding the features.</li> </ul>

  

<b>Test for US-U2</b> <a href="#">↗</a>	<b>View and download historical data</b> <a href="#">↗</a>
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<b>Objective</b>	Verify that users can access and download historical thermal imaging data from the web application.
<b>Test Steps</b>	<ol style="list-style-type: none"><li>1. Access the FarmBot web application and navigate to the historical data section.</li><li>2. View historical thermal imaging data within the web application.</li><li>3. Download historical data for offline analysis.</li><li>4. Verify the accuracy and completeness of the downloaded data.</li></ol>
<b>Expected Result</b>	<ul style="list-style-type: none"><li>• Users can access and view historical thermal imaging data.</li><li>• Historical data can be downloaded for offline analysis.</li><li>• The downloaded data is accurate and complete.</li></ul>