```
int outPin = 13;
int inPin = 2;
int state = HIGH;
int reading;
int previous = LOW;
long time = 0;
long debounce = 200;
void setup() {
 pinMode(outPin,OUTPUT);
 pinMode(inPin,INPUT);
void loop() {
 reading = digitalRead(inPin);
 if(reading == HIGH && previous == LOW && millis()-time > debounce){
  if(state == HIGH)
   state = LOW;
  else
   state = HIGH;
  time = millis();
 digitalWrite(outPin,state);
 previous = reading;
```