

## Lesson 2: Elementary Signals

### About this presentation

Dr Chris Jobling ([c.p.jobling@swansea.ac.uk](mailto:c.p.jobling@swansea.ac.uk))

Digital Technium 123

Office Hours: Mondays 12:00 pm (noon).

You can view the notes for this presentation in [HTML](#) and [PDF](#).

The source code of this presentation is available in Markdown format from GitHub: [elementary\\_signals.md](#).

The GitHub repository [EG-247 Resources](#) also contains the source code for all the Matlab/Simulink examples.

### Review of Homework Problem from Lesson 1

Consider a signal

$$x = f(t) = \begin{cases} 0 & : t < -1 \\ t + 1 & : -1 \leq t \leq 1 \\ 0 & : t > 1 \end{cases}$$

Sketch this signal

---

Sketch the effect on this signal of applying the following basic signal operations

#### Amplitude scaling

- $2f(t)$
- $0.5f(t)$

#### Time scaling

- $f(2t)$
- $f(0.5t)$

### Mirroring

- $-f(t)$
- $f(-t)$
- $-f(-t)$

### Time shifting - delay and advance

- $f(t - 1)$
  - $f(t + 1)$
- 

### Try this

#### A combination of transformations

- $-2f(-t + 2)$

Note that this involves *amplitude scaling*, *amplitude mirroring*, *time mirroring*, and a *time shift*. Each operation can be performed in sequence in any order.

**Quiz: consider this circuit:**

## Elementary signals

### Unit Step Function

#### Definition

$$u_0(t) = \begin{cases} 0 & t < 0 \\ 1 & t > 0 \end{cases}$$

---

### Sketch

### Computing/Plotting in Matlab

In Matlab, we use the `heaviside` function (Named after [Oliver Heaviside](#)).

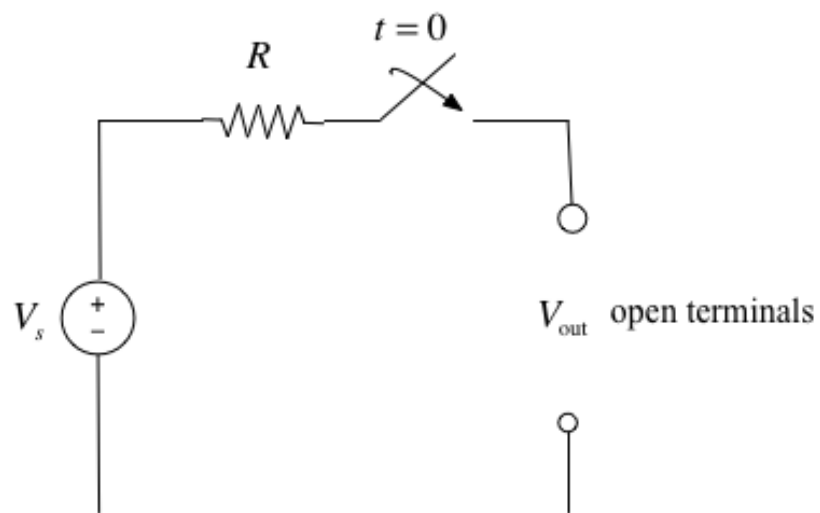


Figure 1: Circuit for quiz

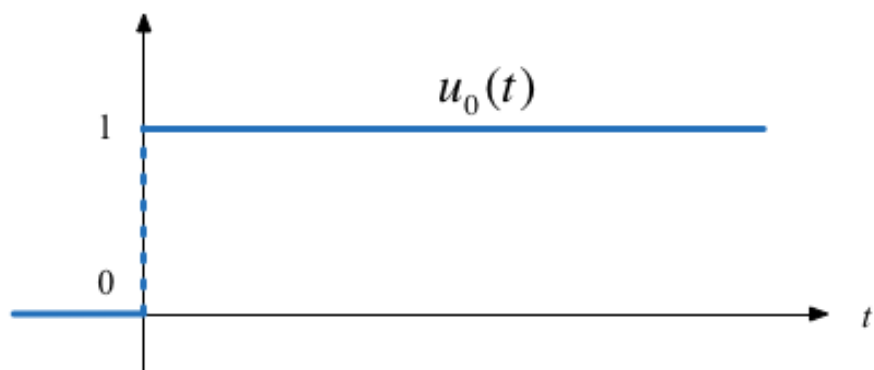


Figure 2: Unit step function

```
syms t
ezplot heaviside(t), [-1,1])
```

See: [heaviside\\_function.m](#)

---

## Result

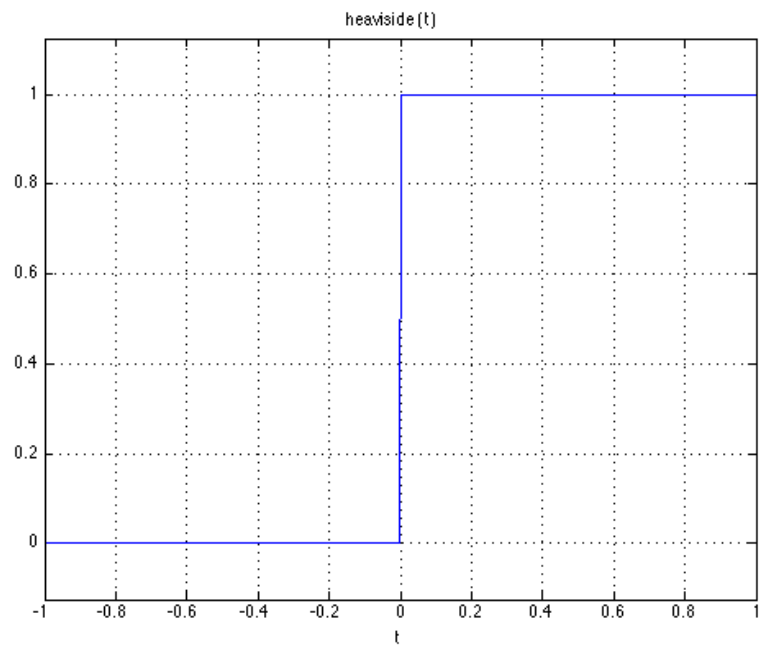


Figure 3: The Heaviside function (unit step)

Note that, so it can be plotted, Matlab defines the *heaviside function* slightly differently from the mathematically ideal unit step:

$$\text{heaviside}(t) = \begin{cases} 0 & t < 0 \\ 1/2 & t = 0 \\ 1 & t > 0 \end{cases}$$

## Circuit Revisited

Consider the network shown below, where the switch is closed at time  $t = T$ .

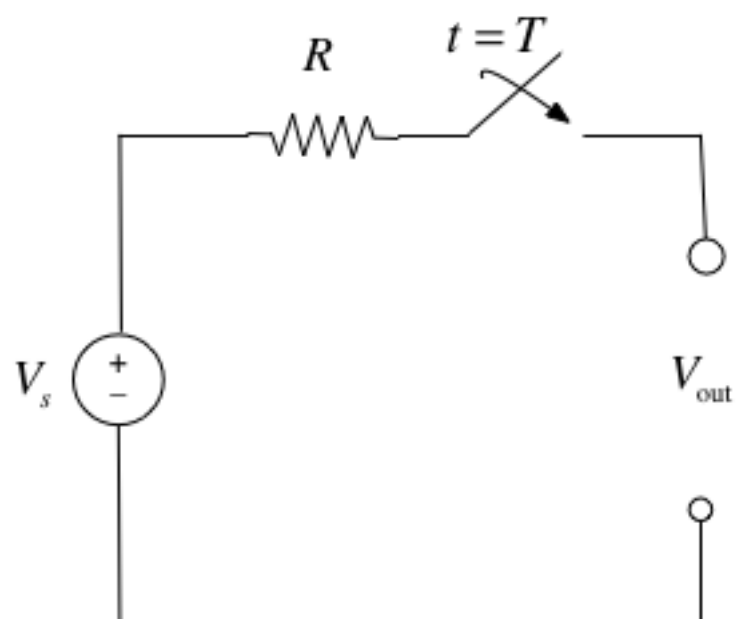


Figure 4: The circuit revisited

---

Express the output voltage  $v_{\text{out}}$  as a function of the unit step function, and sketch the appropriate waveform.

## Simple Signal Operations

### Amplitude Scaling

Sketch  $Au_0(t)$  and  $-Au_0(t)$

### Time Reversal

Sketch  $u_0(-t)$

### Time Delay and Advance

Sketch  $u_0(t - T)$  and  $u_0(t + T)$

### Example 1

Which of these signals represents  $-Au_0(t + T)$ ?

### Example 2

What is represented by

- 
1.  $-Au_0(t - T)$
  2.  $-Au_0(-t + T)$
  3.  $-Au_0(-t - T)$
  4.  $-Au_0(t - T)$

## Synthesis of Signals from Unit Step

Unit step functions can be used to represent other time-varying functions such as rectangular pulses, square waves and triangular pulses.

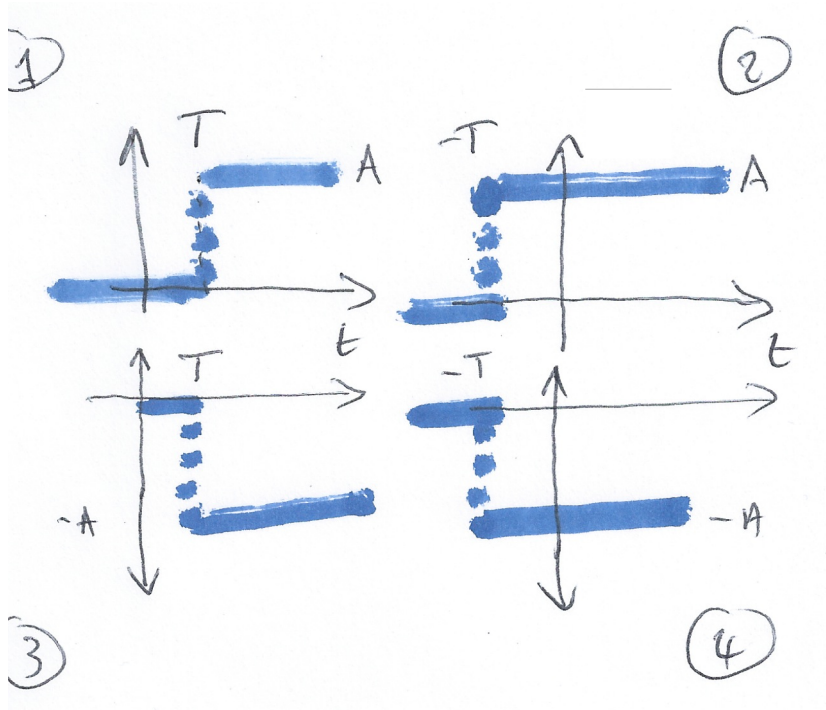


Figure 5: Example 1

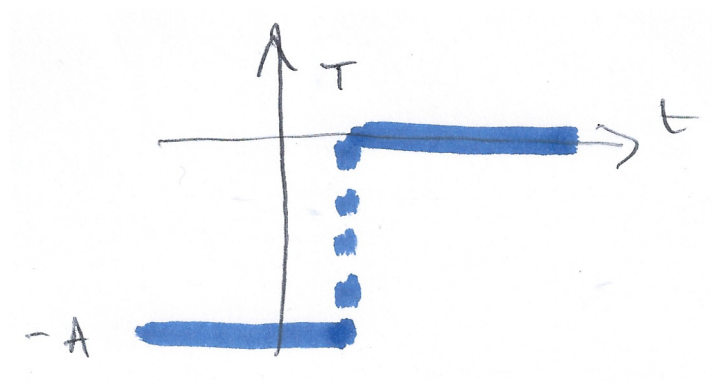


Figure 6: Example 2

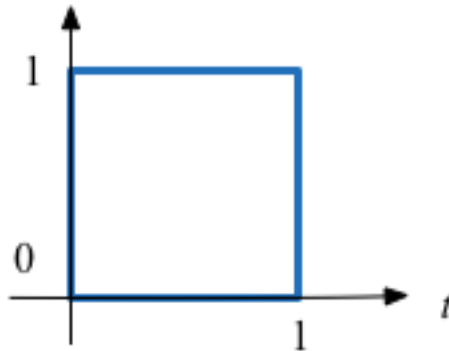


Figure 7: Rectangle function

### Synthesize Rectangular Pulse

### Synthesize Square Wave

### Synthesize Symmetric Rectangular Pulse

### Synthesize Symmetric Triangular Pulse

### Homework

Show that the waveform shown below



can be represented by the function

$$v(t) = (2t + 1)u_0(t) - 2(t - 1)u_0(t - 1) - tu_0(t - 2) + (t - 3)u_0(t - 3)$$

### The Ramp Function



In the circuit shown in the previous slide  $i_s$  is a constant current source and the switch is closed at time  $t = 0$ . Show that the voltage across the capacitor can be represented as



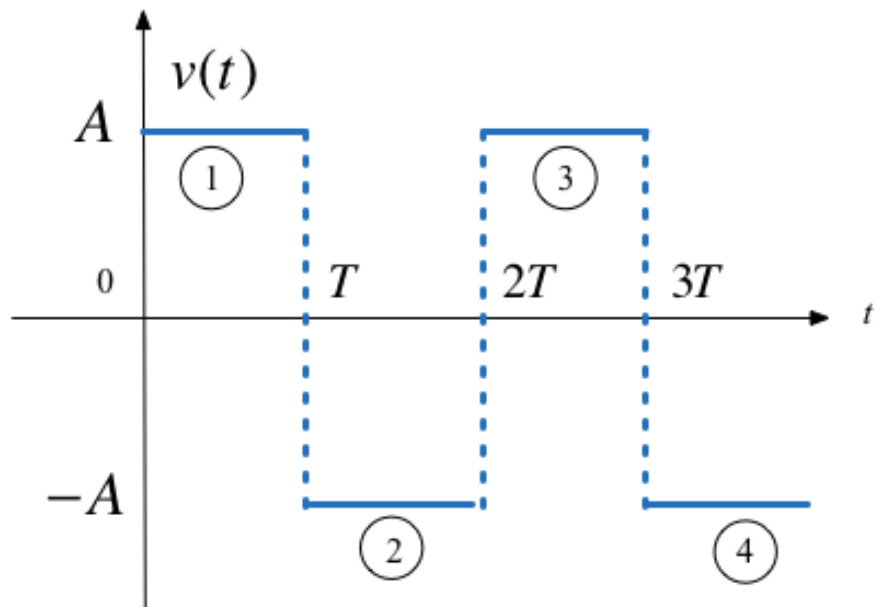


Figure 8: Square wave

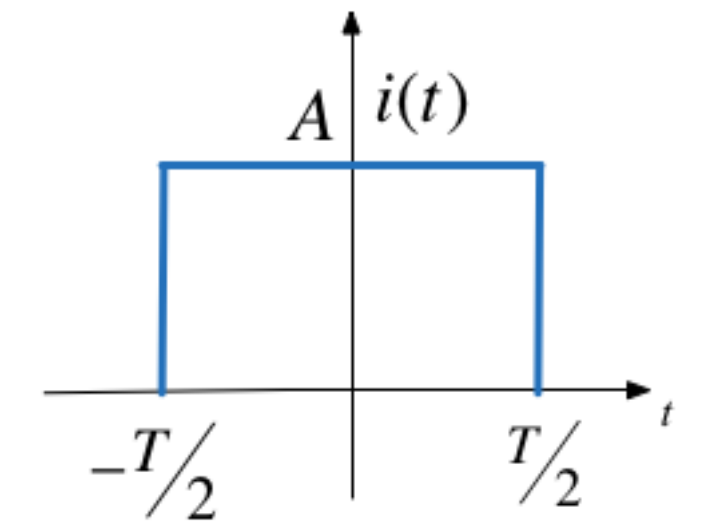


Figure 9: Symmetric rectangular pulse

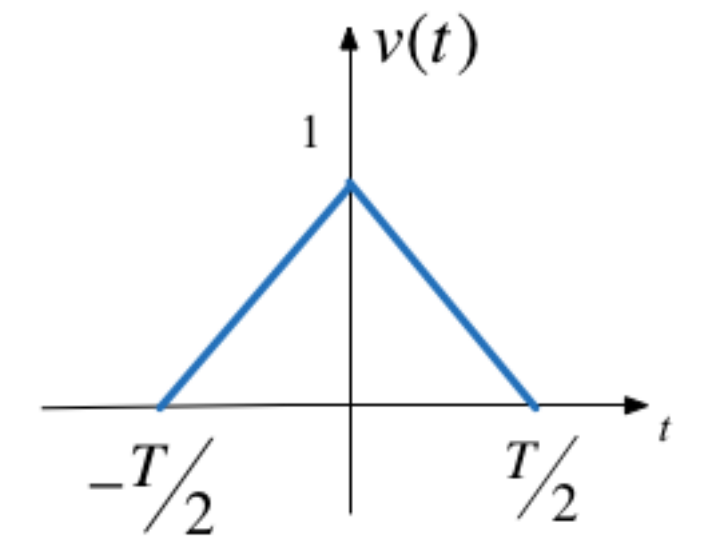


Figure 10: Symmetric triangular pulse

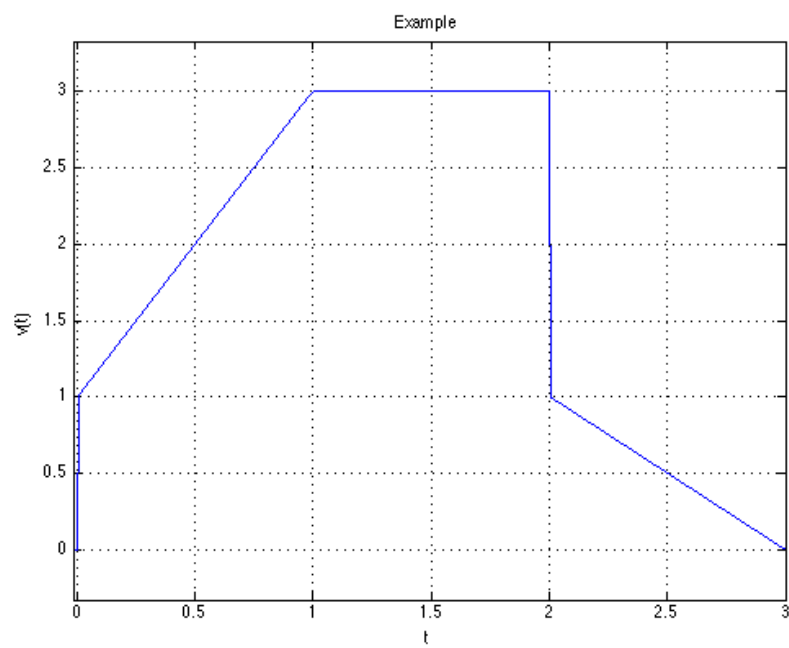


Figure 11: Homework

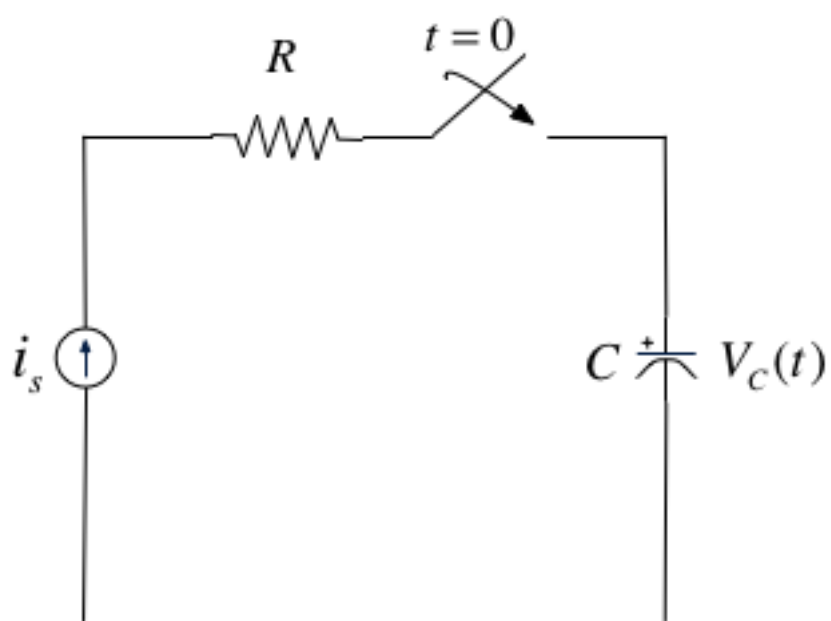


Figure 12: RC circuit

$$v_C(t) = \frac{i_s}{C} t u_0(t)$$

and sketch the wave form.

---

## The unit ramp function

The unit ramp function is defined as

$$u_1(t) = \int_{-\infty}^t u_0(\tau) d\tau$$

so

$$u_1(t) = \begin{cases} 0 & t < 0 \\ t & t \geq 0 \end{cases}$$

and

$$u_0(t) = \frac{d}{dt} u_1(t)$$

Note

Higher order functions of  $t$  can be generated by the repeated integration of the unit step function.

For future reference, you should determine  $u_2(t)$ ,  $u_3(t)$  and  $u_n(t)$  for yourself and make a note of the general rule:

$$u_{n-1} = \frac{1}{n} \frac{d}{dt} u_n(t)$$

Details are given in equations 1.26—1.29 in the textbook.

## The Dirac Delta Function

---

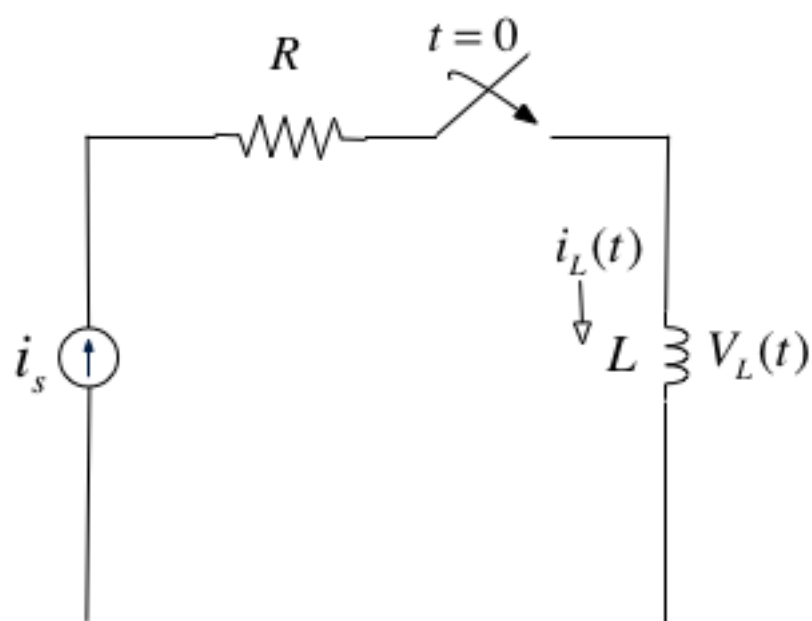


Figure 13: RL circuit

In the circuit shown on the previous slide, the switch is closed at time  $t = 0$  and  $i_L(t) = 0$  for  $t < 0$ . Express the inductor current  $i_L(t)$  in terms of the unit step function and hence derive an expression for  $v_L(t)$ .

Note

To solve this problem we need to invent a function that represents the derivative of the unit step function. This function is called  $\delta(t)$  or the *dirac delta* function (named after [Paul Dirac](#)).

## The delta function

The *unit impulse* or the *delta function*, denoted as  $\delta(t)$ , is the derivative of the unit step.

This function is tricky because  $u_0(t)$  is discontinuous at  $t = 0$  but it must have the properties

$$\int_{-\infty}^t \delta(\tau) d\tau = u_0(t)$$

and

$\delta(t) = 0$  for all  $t \neq 0$ .

## Sketch of the delta function



Figure 14: The delta function

## Important properties of the delta function

### Sampling Property

The *sampling property* of the delta function states that

$$f(t)\delta(t-a) = f(a)\delta(t-a)$$

or, when  $a = 0$ ,

$$f(t)\delta(t) = f(0)\delta(t)$$

Multiplication of any function  $f(t)$  by the delta function  $\delta(t)$  results in sampling the function at the time instants for which the delta function is not zero.

The study of discrete-time (sampled) systems is based on this property.

*You should work through the proof for yourself.*

### Sifting Property

The *sifting property* of the delta function states that

$$\int_{-\infty}^{\infty} f(t)\delta(t-\alpha)dt = f(\alpha)$$

That is, if multiply any function  $f(t)$  by  $\delta(t-\alpha)$ , and integrate from  $-\infty$  to  $+\infty$ , we will get the value of  $f(t)$  evaluated at  $t = \alpha$ .

*You should also work through the proof for yourself.*

### Higher Order Delta Functions

the  $n$ th-order *delta function* is defined as the  $n$ th derivative of  $u_0(t)$ , that is

$$\delta^n(t) = \frac{d^n}{dt^n}[u_0(t)]$$

The function  $\delta'(t)$  is called the *doublet*,  $\delta''(t)$  is called the *triplet* and so on.

By a procedure similar to the derivation of the sampling property we can show that

$$f(t)\delta'(t-a) = f(a)\delta'(t-a) - f'(t)\delta(t-a)$$


---

Also, derivation of the sifting property can be extended to show that

$$\int_{-\infty}^{\infty} f(t)\delta^n(t-\alpha)dt = (-1)^n \frac{d^n}{dt^n}[f(t)] \Big|_{t=\alpha}$$

## Examples

### Example 3

Evaluate the following expressions

1.

$$3t^4\delta(t-1)$$

2.

$$\int_{-\infty}^{\infty} t\delta(t-2)dt$$

3.

$$t^2\delta'(t-3)$$

### Example 4

---

1. Express the voltage waveform  $v(t)$  shown above as sum of unit step functions for the time interval  $-1 < t < 7$  s
2. Using the result of part (1), compute the derivative of  $v(t)$  and sketch it's waveform.

## Self-study

Do the end of the chapter exercises (Section 1.7) from the textbook. Don't look at the answers until you have attempted the problems.



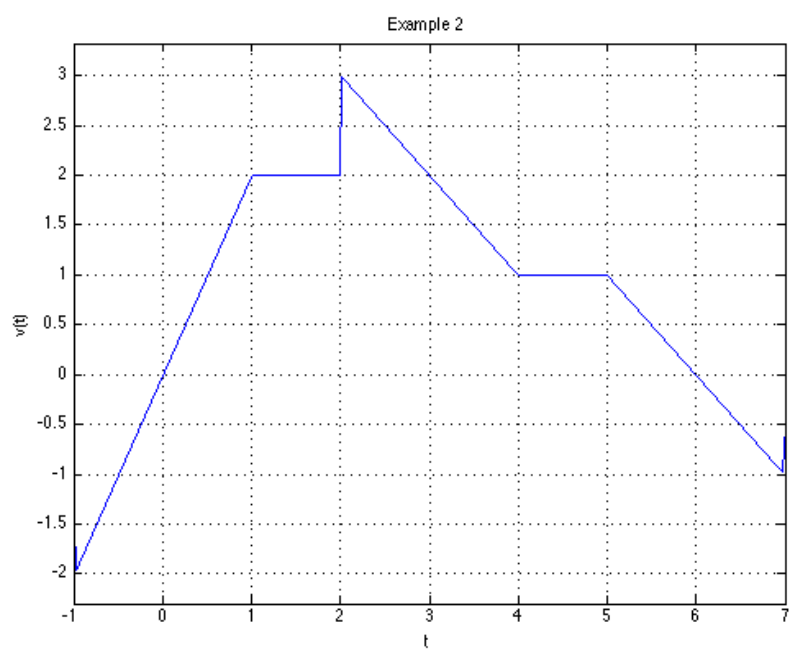


Figure 15: Example 4

## Lab Work

In the lab, a week on Friday, we will solve Example 2 using Matlab/Simulink following the procedure given between pages 1-17 and 1-22 of the textbook. We will also explore the **heaviside** and **dirac** functions.