

Symmetries, Fields and Particles

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1 Introduction

Symmetries are hidden throughout undergraduate physics. Lagrangian mechanics relies on the principle of least action, where the action S is given by

$$S = \int_{t_1}^{t_2} dt L(q(t), \dot{q}(t); t). \tag{1}$$

Classical trajectories minimise S which gives us the Euler Lagrange equation,

$$\frac{\partial L}{\partial q} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = 0. \tag{2}$$

Theorem 1.1 (Noether’s Theorem): Invariance of L under some transformation implies an associated conserved quantity.

Example. Take a particle in a 3-dimensional potential which has Lagrangian

$$L = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2 + \dot{z}^2) - U(x, y, z). \tag{3}$$

There are a few notable symmetries here

- 1. L is independent of time t , i.e. under $t \mapsto t + \delta t$.

Claim. The Hamiltonian $H = T + U$ is conserved.

In general $H(x_i, p_i)$ is a function of $x_i = (x, y, z)$ and the conjugate momenta $p_i = \frac{\partial L}{\partial \dot{x}_i} = m\dot{x}_i$ and is written in terms of the Lagrangian through Legendre transform as

$$H(x_i, p_i; t) = \sum_i \dot{x}_i \frac{\partial L}{\partial \dot{x}_i} - L. \quad (4)$$

Therefore, if L does not depend on time one has

$$\frac{dH}{dt} = 0 - \frac{\partial L}{\partial t} = 0, \quad (5)$$

where we have used the Euler Lagrange equations to make the first term vanish.

2. If L is invariant under $x \mapsto x + \delta x$,

$$\frac{\partial L}{\partial x} = 0 \stackrel{\text{EL}}{\Rightarrow} \frac{\partial L}{\partial \dot{x}} = p_x \text{ is constant.} \quad (6)$$

3. If L is invariant under rotations about the z axis then the z -component of angular momentum $L_z = xp_y - yp_x$ is constant.

Similarly, in cylindrical coordinates $x = \rho \cos \theta$, $y = \rho \sin \theta$ and the Lagrangian becomes

$$L = \frac{1}{2} (m\dot{\rho}^2 + \rho^2 \dot{\theta}^2 + \dot{z}^2) - U(\rho, z). \quad (7)$$

Therefore, $\frac{\partial L}{\partial \theta} = 0 \Rightarrow \frac{\partial L}{\partial \dot{\theta}} = m\rho^2 \dot{\theta} = xp_y - yp_x = \text{constant}$.

1.1 Symmetry in Quantum Mechanics

Given a system whose states are elements of a Hilbert space \mathcal{H} . Here, symmetry implies there exists some invertible operator $U : \mathcal{H} \rightarrow \mathcal{H}$ which preserves inner products, up to an overall phase $e^{i\phi}$ (e.g. expectation values, transition amplitudes).

Definition 1.1: Let $|\Phi\rangle, |\Psi\rangle$ be any normalised vectors in \mathcal{H} . Denote $|U\Psi\rangle = U|\Psi\rangle$. U is a **symmetry transformation operator** if

$$|\langle U\Phi | U\Psi \rangle| = |\langle \Phi | \Psi \rangle|. \quad (8)$$

Proposition 1.1 (Wigner's theorem): Symmetry transformation operators are either

- a) linear and unitary, or
- b) anti-linear and anti-unitary, meaning for $\alpha, \beta \in \mathbb{C}$,

$$U(\alpha|\Psi\rangle + \beta|\Phi\rangle) = \alpha^* U|\Psi\rangle + \beta^* U|\Phi\rangle, \quad (9)$$

and

$$\langle U\Phi | U\Psi \rangle = \langle \Phi | \Psi \rangle^*, \quad (10)$$

respectively.

Most symmetries fall into the former category, but a notable exception is time-reversal symmetry, falling into the latter.

Suppose we have a system with time independent Hamiltonian H . We can write down the time evolution of operators in the Schrödinger picture (where the states depend on time and the operators are static) as

$$|\Psi(t)\rangle = e^{-iHt} |\Psi(0)\rangle. \quad (11)$$

Let's look at applying a symmetry operator U in each of the cases above.

a)

$$\langle U\Phi(t) | U\Psi(t) \rangle = \langle \Phi(t) | \Psi(t) \rangle \quad (12)$$

$$= \langle \Phi(t) | e^{-iHt} |\Psi(0)\rangle. \quad (13)$$

We should find the same result by transforming $|\Psi(0)\rangle$ before the evolution

$$|U\Psi(t)\rangle = e^{-iHt} |U\Psi(0)\rangle, \quad (14)$$

which implies

$$\langle U\Phi(t) | U\Psi(t) \rangle = \langle U\Phi(t) | e^{-iHt} |U\Psi(0)\rangle \quad (15)$$

$$= \langle \Phi(t) | U^\dagger e^{-iHt} U |\Psi(0)\rangle. \quad (16)$$

By comparing this to Eq. (13) we find that

$$U^\dagger e^{-iHt} U = e^{-iHt}. \quad (17)$$

Therefore U commutes with the Hamiltonian, $[U, H] = 0$.

Examples.

- 1) If H commutes with p , H cannot depend on x as $[x_i, p_j] = i\delta_{ij} \neq 0$. Therefore H is invariant under translations $x \rightarrow x + a$. One can construct a unitary operator that generates translations with $U = \exp(i\mathbf{p} \cdot \mathbf{a})$.
- 2) If H is rotationally symmetric the angular momentum operator commutes with H .

2 Lie Groups and algebras

2.1 Lie Groups

Definition 2.1: A **group** is a set G together with a binary operation \circ such that the following properties hold

- i) Closure: $g_2 \circ g_1 \in G, \forall g_1, g_2 \in G$,
- ii) Associativity: $g_3 \circ (g_2 \circ g_1) = (g_3 \circ g_2) \circ g_1, \forall g_1, g_2, g_3 \in G$,
- iii) Identity: $\exists e \in G$ such that $g \circ e = e \circ g = g, \forall g \in G$,
- iv) Inverse: $\forall g \in G, \exists g^{-1} \in G$ such that $g \circ g^{-1} = e = g^{-1} \circ g$.

The identity e and inverse of g are unique.

Proof. Assume there exists e_1, e_2 which are both identities. Then we have that $e_1 \circ e_2 = e_1$ but also $e_1 \circ e_2 = e_2$ thus $e_1 = e_2$ and we have uniqueness.

For inverses, suppose g has two inverses h and j . One has that

$$g \circ h = e \text{ and } g \circ j = e. \quad (18)$$

Left multiplying by j and h respectively we see that

$$j \circ g \circ h = j \circ e \text{ and } h \circ g \circ j = h \circ e, \quad (19)$$

where simplifying (as we can by associativity) the left operation, we see

$$e \circ h = j \text{ and } e \circ j = h, \quad (20)$$

both of which imply $h = j$ and thus we have uniqueness. \square

Definition 2.2: A group (G, \circ) is **commutative (abelian)** if

$$g_1 \circ g_2 = g_2 \circ g_1, \quad (21)$$

$\forall g_1, g_2 \in G$. Otherwise G is **non-commutative (non-abelian)**.