Intro to ML (Lecture - 6)

- 1 R- neavest neighbor classifier
- D levceptuon

Structure | Publica setting

1) Training samples $x = \{(x_1y_1), (x_21y_2), \dots \}$ 2; e R 1 1:5 e R 60113 {-1,13 (Bivery costination)

Test point \(\hat{\pi} ∈ \mathbb{R}^d \)

Find gruction 9: x -> y

find function 9: x -> y

Rd -> 1

Any guess any function is as goods as any other Umbedgiy Assumptions about: Inductive Bias

Applications:
OInge classification Tagging

Ospam Classification

→ Mb3 — Audio

→ Audio

→

€ Negrest néigbor

Bias Assumption: Similar data points generally lie close to each other.

$$Dog \begin{bmatrix} \overline{x} & \overline{x} \\ x & \overline{x} \end{bmatrix} \xrightarrow{x} Cots$$

$$\begin{bmatrix} x & x \\ x & x \end{bmatrix} \xrightarrow{x} Cots$$

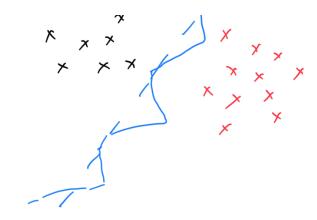
$$\begin{bmatrix} x & x \\ x & x \end{bmatrix} \xrightarrow{x} R^{d}$$

Algorithm & Psuedo coole:

To For tert point 2 compute d(2,2) + i E ?1...n distance blo &, xi 11 (12)1 Ж, it = argnin d(xîxi) **(** ĵ= j: (3) 1-nearest neighor classifier | Running time each test
point

R- nearest neighor | N: training points R- nearest neighbor Chajo Problems? outliers Θ label noise 3 0(md) large 3224×224×3 It onds up gonerating very compex decision are not the best ones { do not generalize }

- Overfit "Occain Pager"



for i in range (N):

$$d(\hat{x}_{i},x_{i}) = ||x-x_{i}||_{2}$$
if $d \leq \text{current-best}$

$$||x-x_{i}||_{2} = ||x-x_{i}||_{2}$$

$$||x-x_{i}||_{2} = ||x-x_{i}||_{2}$$

@ ferceptron

- 1 Early attempts to solve classification
- 2 1950's Krank Rosenblatt

3

Aim/Good:

Learn a linear separator blu two classes

Setting:

$$x = g(x_1y_1), (x_2,y_2), \dots (x_m,y_m)$$

Binary yi = &-1,13

Ain

Problem:

Loss: (Simplest possible)

$$L = Steb(-y; f(xi)) \qquad f(xi) = w'x$$

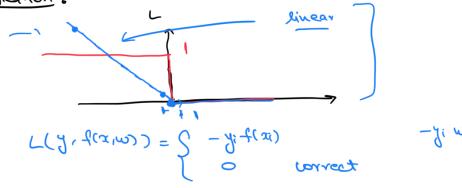
إ ځ	еþ	(-(٠.	5)	

	$\varphi_i = \frac{2}{3}(x_i) = \omega^{1} \times$			
	_ ŋ,		Loss	
	1	0.5	0	
Ð	-1	-6.5	0	
ر پرهن	l	- 0.5	١	
2,			l	

(gratient descent)

$$\frac{\partial L}{\partial \omega} = \begin{cases} 0 & \text{everywhere} \\ 0 & \text{when find} \end{cases}$$

Modification?



$$\overline{\partial \omega} = \begin{cases} 0 & \text{otherwise} \\ \omega^{t+1} = \omega^t + \eta(\eta) \end{cases}$$

- ω₀ = 0
- e for epoch in range (10000):

 for (xi,yi) in x:

 if f(xi) = yi:

 update
- all data are correctly classified: terminate

Puoblems:

- To breviously convectly classified example can be invocally sifted.
- @ No. of iteration

Theorem:

- as<u>surption</u>:

 () ||x|| ≤ 1 €

 (2) b=0

 - 6 Dosa is perfectly superable

If there exists a solution then perception algorithm is guaranteed to find it.

[converge to 0 onor in finite time]

Pf: -> w°=0 w*= optimum ااعدا/ كـ ١

margin - r = arginin) w1x7 7>0 1 0.2 /

(a)
$$|w^{*}|^{2} = |w^{*}|^{2} (|w^{*}|^{2} + |y|^{2} x)$$

$$= |w^{*}|^{2} |w^{*}| + |y|^{2} x$$

$$= |w^{*}|^{2} |w^{*}| + |y|^{2} x$$

$$= |w^{*}|^{2} |w^{*}|^{2} + |y|^{2} x$$

(3) $|w^{*}|^{2} = |w^{*}| + |y|^{2} x$

$$= |w^{*}|^{2} + |y|^{2} x$$

$$= |w^{*}|^{2} + |y|^{2} + |y|^{2} x$$

$$= |w^{*}|^{2} + |y|^{2} +$$

no of update

Perceptron Vs logistic:

1 Differences:

-> owher - probabilities

O if solution exist both of them will find it.

@ logistic regression -> motivated satisfics