Intro to ML Homework4

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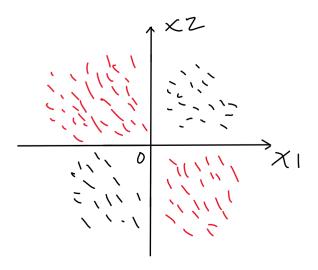
1 Question 1

(a)

A single perception is:

$$y = sign(\langle w, x_i \rangle + b)$$

Thus we can see that output y will also depend on w and b, and labels will be divided into two parts by a straight decision boundary. However the XOR function we want to classify is like:

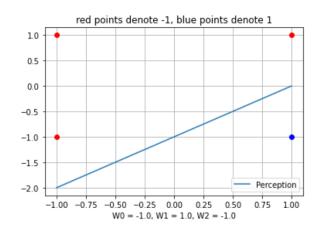


(black points denote "-1" label, red points denote "1" label)

So we can't classify XOR by a single perception's straight decision boundary. For instance, there could be situation that y=1 when $x_1=x_2$ in perception which is not in consistency with a standard two-variable XOR function.

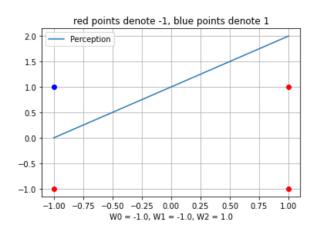
- (b) To solve this question, I consider -1 in perception equivalent to 0 in logical calculus, and in graph I plot, it will use 1 and -1 to show result of perception. Besides, I used perception in colab to help getting decision boundary. X axis is x_1 , y axis is x_2 . Weights I got are at the bottom of each graph.
- (i) For x1(AND)(NOT(x2)) there are four situations in **logical calculus**:
- (1) $x_1 = 1, x_2 = 1, label = 0$ (2) $x_1 = 1, x_2 = 0, label = 1$ (3) $x_1 = 0, x_2 = 1, label = 0$ (4) $x_1 = 0, x_2 = 0, label = 0$

Equation for decision boundary in **perception**: $-1 + x_1 - x_2 = 0$



- (ii) For (NOT(x1))(AND)x2 there are four situations in logical calculus:
- (1) $x_1 = 1, x_2 = 1, label = 0$ (2) $x_1 = 1, x_2 = 0, label = 0$
- (3) $x_1 = 0, x_2 = 1, label = 1$ (4) $x_1 = 0, x_2 = 0, label = 0$

Equation for decision boundary in **perception**: $1 + x_1 + x_2 = 0$

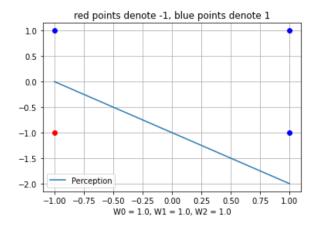


(iii) For x1(OR)x2 there are four situations in logical calculus:

(1)
$$x_1 = 1, x_2 = 1, label = 1$$
 (2) $x_1 = 1, x_2 = 0, label = 1$

(3)
$$x_1 = 0, x_2 = 1, label = 1$$
 (4) $x_1 = 0, x_2 = 0, label = 0$

Equation for decision boundary in **perception**: $-1 - x_1 + x_2 = 0$



(c) In XOR, it can be considered that points of 1, 3 quadrant are of same class and the same for points in 2, 4 quadrant. So we can combine x1(AND)(NOT(x2)) and (NOT(x1))(AND)x2, because they can respectively distinguish points at 4 quadrant, 2 quadrant.

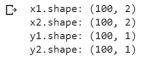
$$y = sign(w_0 + w_1 * sign(-1 + x_1 - w_2) + w_2 * sign(-1 - x_1 + x_2))$$

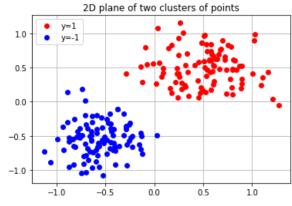
2 Question 2

(a) plot 2-D plane of points

(a)

```
[ ] import numpy as np
    import matplotlib.pyplot as plt
    meanx1 = (0.5, 0.5)
    covx1 = [[0.07, 0], [0, 0.07]]
    x1 = np.random.multivariate_normal(meanx1, covx1, 100)
    meanx2 = (-0.5, -0.5)
    covx2 = [[0.07, 0], [0, 0.07]]
    x2 = np.random.multivariate_normal(meanx2, covx2, 100)
    print("x1.shape:" ,x1.shape)
    print("x2.shape:" ,x2.shape)
    plt.figure(1)
    plt.title("2D plane of two clusters of points")
    plt.plot(x1[:,0],x1[:,1],'ro',label="y=1")
    plt.plot(x2[:,0],x2[:,1],'bo',label="y=-1")
    plt.legend()
    plt.grid()
    y1 = np.random.normal(loc=1.0, scale=0.0, size=100)
    y2 = np.random.normal(loc=-1.0, scale=0.0, size=100)
    y1 = y1.reshape(y1.shape[0],1)
    y2 = y2.reshape(y2.shape[0],1)
    print("y1.shape:" ,y1.shape)
    print("y2.shape:" ,y2.shape)
```





(b) do perception on separated points

(b)

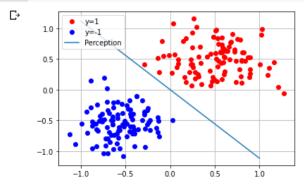
```
def perception(x,y,epoch,learning_rate):
      import numpy as np
      import matplotlib.pyplot as plt
      pairs = np.concatenate((x, y), axis=1)
      #print("pairs.shape: ",pairs.shape,"pairs:")
      np.random.shuffle(pairs)
      #print(pairs)
      X = pairs[:,0:pairs.shape[1]-1]
      y = pairs[:,pairs.shape[1]-1:pairs.shape[1]]
      #print(X)
      #print(y)
      n = X.shape[0]
      d = X.shape[1]
      x0 = np.ones((n,1))
      X = \text{np.hstack}((x0,X)) \# \text{ add a column of 1 to the left of } X \text{ matching for } w0
      w = np.zeros(d+1)
      print("X.shape: ",X.shape," y.shape: ",y.shape," w.shape: ",w.shape)
      cost = []
      converge = False;
      for T in range(1,epoch+1):
        Lw = 0
        for i in range(n):
          if np.matmul(w,X[i].T)*y[i] <= 0 :</pre>
            Lw = Lw - np.matmul(w,X[i].T)*y[i]
            w = w - learning_rate*(-1)*y[i]*X[i]
```

```
cost.append(Lw)
 if (Lw == 0 and converge == False) :
    converge = True
    print("no change in epoch {} ".format(T))
plt.figure()
plt.title("L(w) Variation with Epoch")
iterations = range(1,epoch+1)
plt.plot(iterations,cost,'r')
plt.xlabel("epoch")
plt.ylabel("L(w)")
plt.grid()
print("w: ",w)
print("Last Loss L(w): ",cost[-1])
y_pred = X@w.T
y_pred[y_pred<0]=-1</pre>
y_pred[y_pred>=0]=1
acc = 0
for i in range(n):
 if y_pred[i] == y[i]:
   acc += 1
print("final accuracy: ", acc/200)
```

```
[ ] x = np.concatenate((x1, x2), axis=0)
    y = np.concatenate((y1, y2), axis=0)
    perception(x,y,100,1)
no change in epoch 2
   w: [0.
                 1.0992005 1.29950527]
    Last Loss L(w): 0
    final accuracy: 1.0
                   , 1.0992005 , 1.29950527])
    array([0.
                   L(w) Variation with Epoch
      0.40
      0.35
      0.30
      0.25
     € 0.20
      0.15
      0.10
      0.05
      0.00
                                             100
```

```
plt.figure()

plt.plot(x1[:,0],x1[:,1],'ro',label="y=1")
plt.plot(x2[:,0],x2[:,1],'bo',label="y=-1")
linex1 = [-1 , 1]
#boundary w0 + w1*x1 + w2*x2 = 0
linex2 = [(0.0 - w[0] - w[1]*linex1[0]) / w[2],(0.0 - w[0] - w[1]*linex1[1]) / w[2]]
plt.plot(linex1,linex2,label = "Perception")
plt.legend()
plt.grid()
```



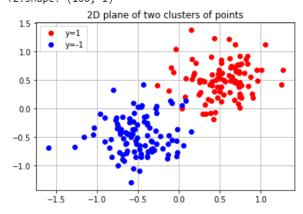
Result is shown above. Perception on this case converge at epoch 2 which is very fast.

(c) Perform perception on overlapping points

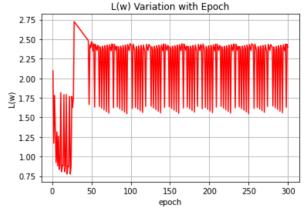
(c)

```
[3] import numpy as np
     import matplotlib.pyplot as plt
     mean1 = (0.5, 0.5)
     cov1 = [[0.09, 0], [0, 0.09]]
     X1 = np.random.multivariate_normal(mean1, cov1, 100)
     mean2 = (-0.5, -0.5)
     cov2 = [[0.09, 0], [0, 0.09]]
     X2 = np.random.multivariate_normal(mean2, cov2, 100)
     print("X1.shape:" ,X1.shape)
print("X2.shape:" ,X2.shape)
     plt.figure(1)
     plt.title("2D plane of two clusters of points")
     plt.plot(X1[:,0],X1[:,1],'ro',label="y=1")
     plt.plot(X2[:,0],X2[:,1],'bo',label="y=-1")
     plt.legend()
     plt.grid()
     Y1 = np.random.normal(loc=1.0, scale=0.0, size=100)
     Y2 = np.random.normal(loc=-1.0, scale=0.0, size=100)
     Y1 = Y1.reshape(Y1.shape[0],1)
     Y2 = Y2.reshape(Y2.shape[0],1)
     print("Y1.shape:" ,Y1.shape)
print("Y2.shape:" ,Y2.shape)
```

X1.shape: (100, 2)
X2.shape: (100, 2)
Y1.shape: (100, 1)
Y2.shape: (100, 1)

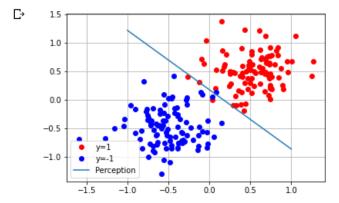


```
[4] x = np.concatenate((X1, X2), axis=0)
y = np.concatenate((Y1, Y2), axis=0)
w = perception(x,y,300,1)
```



```
[5] plt.figure()

plt.plot(X1[:,0],X1[:,1],'ro',label="y=1")
plt.plot(X2[:,0],X2[:,1],'bo',label="y=-1")
linex1 = [-1 , 1]
#boundary w0 + w1*x1 + w2*x2 = 0
linex2 = [(0.0 - w[0] - w[1]*linex1[0]) / w[2],(0.0 - w[0] - w[1]*linex1[1]) / w[2]]
plt.plot(linex1,linex2,label = "Perception")
plt.legend()
plt.grid()
```



According to results shown above, algorithm did not converge but it still generate a decision boundary with good accuracy of 98.5%.

3 Question 3

(a)

$$SE = \sum_{i=1}^{n} (\phi(x_i)w - y_i)^2$$

(b)Loss function with a L2 regularizer as shown below, and derive closed form expression for w.

$$L(w) = \frac{1}{2} \|\Phi w - y\| + \frac{\alpha}{2} \|w\|_2^2$$
$$\frac{\partial L}{\partial w} = \Phi^T (\Phi w - y) + \alpha w = 0$$
$$(\Phi^T \Phi + \alpha I)w = \Phi^T y$$
$$w = (\Phi^T \Phi + \alpha I)^{-1} \Phi^T y$$

(c)

$$f(z) = \langle w, \phi(x_i) \rangle = \phi(z) * w = \phi(z) * (\Phi^T \Phi + \alpha I)^{-1} \Phi^T y$$

(d) For w in (b), use Sherman-Morrison-Woodbury identity for matrix to transform:

$$(A^{-1} + B^T C^{-1} B)^{-1} B^T C^{-1} = A B^T (B A B^T + C)^{-1}$$

Consider w, $(\alpha I)^{-1}$ as A, Φ as B, I as C, so:

$$w = (((\alpha I)^{-1})^{-1} + \Phi^{T} I^{-1} \Phi)^{-1} \Phi^{T} I^{-1} * y$$

$$= (\alpha I)^{-1} \Phi^{T} (\Phi(\alpha I)^{-1} \Phi^{T} + I^{-1})^{-1} * y$$

$$= (\alpha I)^{-1} \Phi^{T} ((\alpha I)^{-1} \Phi \Phi^{T} + I^{-1})^{-1} * y$$

$$= (\alpha)^{-1} \Phi^{T} ((\alpha)^{-1} M + I)^{-1} * y$$
(1)

Matrix M above is : (use d^r represent dimension after lifting for input)

$$M = \Phi\Phi^{T} = \begin{bmatrix} x_{1}^{(1)} & x_{1}^{(2)} & \dots & x_{1}^{(d^{r})} \\ x_{2}^{(1)} & x_{2}^{(2)} & \dots & x_{2}^{(d^{r})} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n}^{(1)} & x_{n}^{(2)} & \dots & x_{n}^{(d^{r})} \end{bmatrix} * \begin{bmatrix} x_{1}^{(1)} & x_{2}^{(1)} & \dots & x_{n}^{(1)} \\ x_{1}^{(2)} & x_{2}^{(2)} & \dots & x_{n}^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ x_{1}^{(d^{r})} & x_{2}^{(d^{r})} & \dots & x_{n}^{(d^{r})} \end{bmatrix}$$

$$M = \begin{bmatrix} K(x_1, x_1) & K(x_1, x_2) & \dots & K(x_1, x_n) \\ K(x_2, x_1) & K(x_2, x_2) & \dots & K(x_2, x_n) \\ \vdots & \vdots & \ddots & \vdots \\ K(x_n, x_1) & K(x_n, x_2) & \dots & K(x_n, x_n) \end{bmatrix}$$

Then for f(z) in (c):

$$f(z) = \langle w, \phi(x_i) \rangle = \phi(z) * w = \phi(z) * (\alpha)^{-1} \Phi^T ((\alpha)^{-1} M + I)^{-1} * y$$

= $(\alpha)^{-1} \phi(z) \Phi^T ((\alpha)^{-1} M + I)^{-1} * y$
= $(\alpha)^{-1} N((\alpha)^{-1} M + I)^{-1} * y$
= $N(M + \alpha I)^{-1} * y$

Matrix N above is: (d^r) represent dimension after lifting for input)

$$N = \phi(z)\Phi^{T} = \begin{bmatrix} z_{1}^{(1)} & z_{1}^{(2)} & \dots & z_{1}^{(d^{r})} \end{bmatrix} * \begin{bmatrix} x_{1}^{(1)} & x_{2}^{(1)} & \dots & x_{n}^{(1)} \\ x_{1}^{(2)} & x_{2}^{(2)} & \dots & x_{n}^{(2)} \\ \vdots & \vdots & \ddots & \vdots \\ x_{1}^{(d^{r})} & x_{2}^{(d^{r})} & \dots & x_{n}^{(d^{r})} \end{bmatrix}$$
$$N = \begin{bmatrix} K(z_{1}, x_{1}) & K(z_{1}, x_{2}) & \dots & K(z_{1}, x_{n}) \end{bmatrix}$$

So
$$f(z) = N(M + \alpha I)^{-1}y$$
 has no $\phi(x)$.

Thus the calculations in (b) and (c) can be performed by invoking the kernel dot product alone without explicitly writing down $\phi(x)$ ever.

4 Question 4

- (a) Load data set and display 10 representatives from each class
- (a)

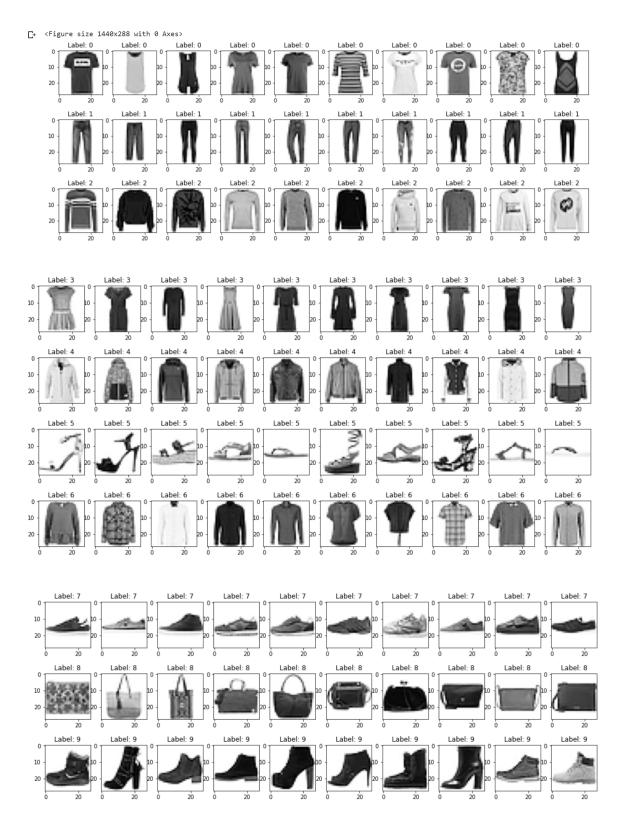
load dataset

find representatives' indices for 10 classes

plot representatives for 10 classes

```
[15] import matplotlib.pyplot as plt
%matplotlib inline
# Only use this if using iPython
plt.figure(figsize = (20,4)) # set area of plot 20 inch width 4 inch height

for i in range(10):
    no = 1
    f = plt.figure()
    f.set_figheight(18)
    f.set_figheight(18)
    for index in range(10):
    plt.subplot(10,10,no) #subplot(row,column,index)
    plt.imshow(np.reshape(train_images[labels[i*10 + index]],(28,28)), cmap='Greys')#cmap=plt.cm.gray
    plt.title('Label: {}'.format(train_labels[labels[i*10 + index]]))
    no += 1
```



(b)&(c) Implement the following classification methods: k-NN, logistic regression, and support vector machines (with linear and rbf kernels).Report best possible test-error performances by tuning hyperparameters in each of your methods.

(b)

Extract 5000 for train and 500 for test to make program running time not too long, then flatten images and normalize data.

```
train_flat = np.zeros(shape=(5000,784))
   test_flat = np.zeros(shape=(500,784))
    for i in range(5000):
     train_flat[i] = train_images[i].flatten()
   for i in range(500):
     test_flat[i] = test_images[i].flatten()
    #print(train_flat[1])
    from sklearn.preprocessing import StandardScaler
   scaler = StandardScaler()#normalize data
   train_flat = scaler.fit_transform(train_flat)
   test_flat = scaler.fit_transform(test_flat)
   train_labels = train_labels[0:5000]
   test_labels = test_labels[0:500]
    print("train_flat.shape: ",train_flat.shape," test_flat.shape: ",test_flat.shape)
    print("train_labels.shape: ",train_labels.shape," test_labels.shape: ",test_labels.shape)
train_labels.shape: (5000,) test_labels.shape: (500,)
```

K-NN

After trying several K, K = 9 is best for this KN-N. As we can see, accuracy is 83.00%, which is acceptable.

Logistic Regression

```
[21] from sklearn.linear_model import LogisticRegression
   logisticReg = LogisticRegression(penalty = '12', tol = 0.01,solver = 'saga',C=0.05)
   %time logisticReg.fit(train_flat,train_labels)

CPU times: user 8.35 s, sys: 17 μs, total: 8.35 s
   Wall time: 8.37 s
   LogisticRegression(C=0.05, class_weight=None, dual=False, fit_intercept=True, intercept_scaling=1, l1_ratio=None, max_iter=100, multi_class='auto', n_jobs=None, penalty='12', random_state=None, solver='saga', tol=0.01, verbose=0, warm_start=False)

[22] %time lrscore = logisticReg.score(test_flat,test_labels)
   print(lrscore)

CPU times: user 2.85 ms, sys: 997 μs, total: 3.84 ms
   Wall time: 2.62 ms
   0.85
```

After tuning the parameters, penalty = 'l2', tol = 0.01, solver = 'saga', C=0.05 is best for this method. As we can see, accuracy is 85.00%, which is even better than KN-N.

SVMs(linear kernel)

After tuning the parameter, C = 0.001 is best for this linear-kernel SVMs. As we can see, accuracy is 85.60%, which higher than logistic regression.

SVMs(RBF kernel)

Wall time: 1.41 s

0.874

After tuning the parameter, C=5 (less regularization strength compared to linear kernel) is good for this linear-kernel SVMs. As we can see, accuracy is 87.40%, which is higher than any others.

(d) Report train- and test-running time of each of your methods in the form of a table, and comment on the relative tradeoffs across the different methods.

Method	Train Time	Test Time	Accuracy
KN-N	0.346s	3.94s	83.00%
Logistic Regression	8.42s	0.0102s	85.00%
SVMs(Linear)	7.20s	1.28s	85.60%
SVMs(RBF)	9.68s	1.41s	87.40%
Method		Tradeoffs	
KN-N		As we can see that KN-N takes very quick	
		to train but longest time to test, in	
		practical use we often want test to be	
		quick.	
Logistic Regression		Logistic regression has an advantage that	
		it tests fastest among these methods	
		although it need long time to train.	
SVMs(Linear)		SVMs(Linear) is not as fast as logistic	
		regression on test time but more accurate	
		than logistic regression.	
SVMs(RBF)		SVMs(RBF) has longest time to train but	
		highest accuracy.	