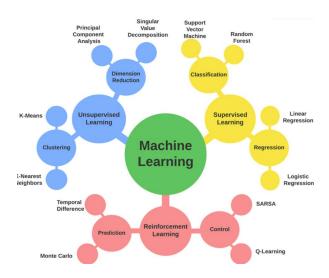
### Các phương pháp học máy Machine learning methods

4 TC: 2 LT - 2 TH

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### Các phương pháp học máy Machine learning methods

### Bổ sung kiến thức:

Đại số tuyến tính cơ bản

#### **Scalars**

Most everyday mathematics consists of manipulating numbers one at a time. Formally, we call these values scalars.

- For example, the temperature in Palo Alto is a balmy 72 degrees Fahrenheit.
  - What else?

Denote scalars by ordinary lower-cased letters (e.g., x, y, and z) and the space of all (continuous) real-valued scalars by  $\mathbf{R}$ .

• The expression  $x \in R$  is a formal way to say that x is a real-valued scalar.

#### **Scalars**

```
import torch
x = torch.tensor(3.0)
y = torch.tensor(2.0)
# x + y, x * y, x / y, x**y
```

```
(tensor(5.), tensor(6.), tensor(1.5000), tensor(9.))
```

#### **Vectors**

A vector can be thought as a fixed-length array of scalars.

Denote vectors by bold lowercase letters, (e.g., x, y, and z)

```
x = torch.arange(3)
# tensor([0, 1, 2])
```

#### **Vectors**

A vector can be thought as a fixed-length array of scalars.

- Refer to an element of a vector by using a subscript.
  - For example,  $x_2$  denotes the second element of **x**.

$$\mathbf{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix},$$

#### **Vectors**

```
x = torch.arange(3) # tensor([0, 1, 2])
x[2] # tensor(2)
len(x) # 3
x.shape # torch.Size([3])
```

#### **Vectors**

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```

#### **Matrices**

Scalars are 0 th-order tensors and vectors are 1 st-order tensors, matrices are 2 nd-order tensors.

- Denote matrices by bold capital letters (e.g., X, Y, and Z), and represent them in code by tensors with two axes.
- The expression  $\mathbf{A} \in \mathbb{R}$   $m \times n$  indicates that a matrix  $\mathbf{A}$  contains  $m \times n$  real-valued scalars, arranged as m rows and n columns.

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}.$$

#### **Matrices**

#### **Matrices**

Signify a matrix A's transpose by  $A^T$  and if  $B = A^T$ , then  $b_{ij} = a_{ij}$  for all i and j.

$$\mathbf{A} = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \cdot \mathbf{A}^{\top} = \begin{bmatrix} a_{11} & a_{21} & \cdots & a_{m1} \\ a_{12} & a_{22} & \cdots & a_{m2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1n} & a_{2n} & \cdots & a_{mn} \end{bmatrix}.$$

#### **Matrices**

```
A = torch.arange(6).reshape(3, 2)
# tensor([[0, 1], [2, 3], [4, 5]])

print(A.T)
# tensor([[0, 2, 4], [1, 3, 5]])
```

#### **Tensors**

A **tensor** is a **multi-dimensional data structure used for storing and processing data**. Tensors can be thought of as generalizations of scalars, vectors, and matrices to higher dimensions.

- 1. 0-D Tensor (Scalar): A single number, e.g., `3` or `-2.5`.
- 2. 1-D Tensor (Vector): A one-dimensional array of numbers, e.g., `[1, 2, 3]`.
- 3. 2-D Tensor (Matrix): A two-dimensional array, e.g., a matrix `[[1, 2], [3, 4]]`.
- 4. 3-D Tensor and Higher: Tensors with more dimensions. For instance, a color image can be represented as a 3-D tensor with dimensions for height, width, and the number of color channels (e.g., RGB). A 4-D tensor might represent a batch of images, with dimensions for batch size, height, width, and color channels.

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#### **Tensors**

```
torch.arange(24).reshape(2, 3, 4)
```

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```
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```

### **Elementwise operations**

 refer to mathematical operations that are performed on corresponding elements of two or more tensors or arrays.

```
A = torch.arange(6, dtype=torch.float32).reshape(2, 3)
B = A.clone() # Assign a copy of A to B by allocating new memory
A, A + B
```

### **Hadamard product**

The elementwise product of two matrices is called their Hadamard product (denoted ⊙).

$$\mathbf{A} \odot \mathbf{B} = \begin{bmatrix} a_{11}b_{11} & a_{12}b_{12} & \dots & a_{1n}b_{1n} \\ a_{21}b_{21} & a_{22}b_{22} & \dots & a_{2n}b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1}b_{m1} & a_{m2}b_{m2} & \dots & a_{mn}b_{mn} \end{bmatrix}.$$

#### Reduction

 refers to the process of performing operations that reduce the dimensionality of tensors.

```
x = torch.arange(3, dtype=torch.float32)
x, x.sum()
```

```
(tensor([0., 1., 2.]), tensor(3.))
```

#### Reduction

```
import torch
 2
    A = torch.arange(6, dtype=torch.float32).reshape(2, 3)
    print(A, A.shape)
 4
     # tensor([[0., 1., 2.],
               [3., 4., 5.]]) torch.Size([2, 3])
 6
 8
    B = A.sum()
    print(B, B.shape)
     #tensor(15.)
10
11
12
     B = A.sum(axis=0)
13
    print(B, B.shape)
14
     #tensor([3., 5., 7.]) torch.Size([3])
15
16
    B = A.sum(axis=1)
17
    print(B, B.shape)
    #tensor([ 3., 12.]) torch.Size([2])
```

### Dot product (Tích vô hướng)

- dot product of two vectors is a way of multiplying them together to produce a single number (a scalar).
  - Calculated by taking the sum of the products of their corresponding components.

#### For Two Vectors

Given two vectors:

• 
$$\mathbf{a} = [a_1, a_2, \dots, a_n]$$

• 
$$\mathbf{b} = [b_1, b_2, \dots, b_n]$$

Their dot product is calculated as:

$$\mathbf{a} \cdot \mathbf{b} = a_1 \cdot b_1 + a_2 \cdot b_2 + \cdots + a_n \cdot b_n$$

### Dot product (Tích vô hướng)

```
import torch
    y = torch.ones(3, dtype = torch.float32)
    print(y)
     # tensor([1., 1., 1.])
    x = torch.arange(3, dtype = torch.float32)
    print(x)
     # tensor([0., 1., 2.])
10
11
    z = torch.dot(x, y)
12
    print(z)
13
     # tensor(3.)
14
     z1 = torch.sum(x * y)
15
16
    print(z1)
17
    # tensor(3.)
18
```

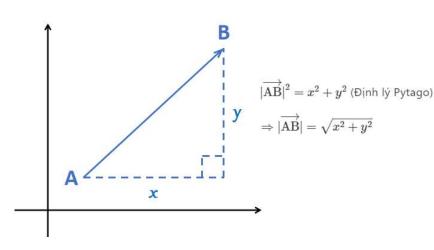
### Dot product (Tích vô hướng)

```
import torch
     y = torch.ones(3, dtype = torch.float32)
 3
     print(y)
 4
     # tensor([1., 1., 1.])
 6
     x = torch.arange(3, dtype = torch.float32)
 8
     print(x)
     # tensor([0., 1., 2.])
10
     z = torch.dot(x, y)
12
     print(z)
13
     # tensor(3.)
14
```

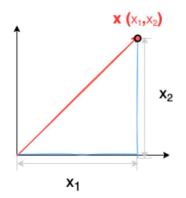
### **Euclidean Norm (L2 Norm)**

For a vector  $\mathbf{x} = [x_1, x_2, ..., x_n]$ , the Euclidean norm is:

$$\|\mathbf{x}\|_2 = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$



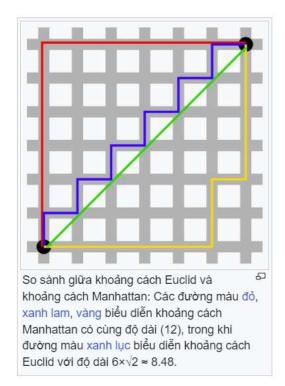
$$||x||_2 = \sqrt{x_1^2 + x_2^2}$$



### **Manhattan Norm (L1 Norm)**

For a vector  $\mathbf{x} = [x_1, x_2, ..., x_n]$ , the Manhattan norm is:

$$||\mathbf{x}||_1 = |x_1| + |x_2| + \cdots + |x_n|$$



#### **Norms**

```
import torch
     # Define a tensor
     tensor = torch.tensor([3.0, 4.0])
 4
 6
     # Compute the L1 norm (Manhattan norm)
     11 norm = torch.norm(tensor, p=1)
     print(f"L1 norm (Manhattan norm): {11_norm.item()}")
 8
 9
     # L1 norm (Manhattan norm): 7.0
10
11
     # Compute the L2 norm (Euclidean norm)
12
     12 norm = torch.norm(tensor, p=2)
     print(f"L2 norm (Euclidean norm): {12 norm.item()}")
13
     # L2 norm (Euclidean norm): 5.0
14
```