

# EVALUATING MODEL FIT

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#### **EVALUATING MODEL FIT**

## **LEARNING OBJECTIVES**

- ▶ Define regularization, bias, and error metrics for regression problems
- ▶ Evaluate model fit using loss functions
- Select regression methods based on fit and complexity

#### **COURSE**

# PRE-WORK

#### PRE-WORK REVIEW

- ▶ Understand goodness of fit (r-squared)
- ▶ Measure statistical significance of features
- ▶ Implement a sklearn estimator to predict a target variable

## R-SQUARES AND RESIDUALS

#### WHAT IS R-SQUARED? WHAT IS A RESIDUAL?

- ▶ R-squared, the central metric introduced for linear regression
- ▶ Which model performed better, one with an r-squared of 0.79 or 0.81?
- R-squared measures explain variance.
- ▶ But does it tell the magnitude or scale of error? (Hint: It is divided by sum of squared deviations from mean)
- ▶ We'll explore loss functions and find ways to refine our model.

## WHAT IS R-SQUARED? WHAT IS A RESIDUAL?

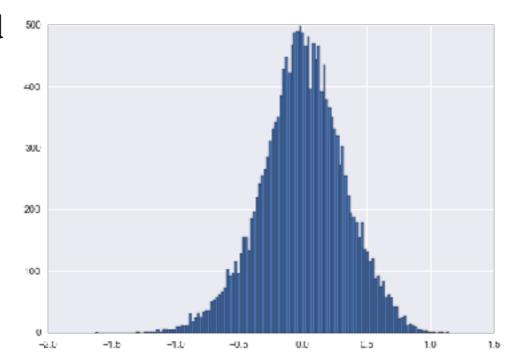
Percent of variance explained (R-squared)	Percent of standard deviation explained (1 minus square root of 1-minus-R-squared)
99.9%	97%
99.5%	93%
99%	90%
98%	86%
95%	78%
90%	68%
80%	55%
75%	50%
50%	29%
25%	13%
20%	11%
15%	7.8%
10%	5.1%
5%	2.5%
2%	1.0%

#### **INTRODUCTION**

## LINEAR MODELS AND ERROR

#### WHAT'S RESIDUAL ERROR?

- Residual error is the difference between predicted value and actual value.
- In linear models, residual error must be normal with a median close to zero.
- Individual residuals are useful to see the error of specific points, but it doesn't provide an overall picture for optimization.
- We need a metric to summarize the error in our model into one value.
- ▶ Mean square error: the mean residual error in our model



- To calculate MSE:
  - Calculate the difference between each target y and the model's predicted value y-hat (i.e. the residual)
  - Square each residual.
  - Take the mean of the squared residual errors.

MSE = 
$$\frac{1}{n} \sum_{i=1}^{n} (y_i - \tilde{y}_i)^2$$

▶ sklearn's metrics module includes a mean\_squared\_error function.

```
from sklearn import metrics
metrics.mean_squared_error(y, model.predict(X))
```

▶ For example, two arrays of the same values would have an MSE of 0.

```
from sklearn import metrics
metrics.mean_squared_error([1, 2, 3, 4, 5], [1, 2, 3, 4, 5])
0.0
```

▶ Two arrays with different values would have a positive MSE.

```
from sklearn import metrics
metrics.mean_squared_error([1, 2, 3, 4, 5], [5, 4, 3, 2, 1])
# (4^2 + 2^2 + 0^2 + 2^2 + 4^2) / 5
8.0
```

#### **HOW DO WE MINIMIZE ERROR?**

- ▶ The regression method we've used is called "Ordinary Least Squares".
- This means that given a matrix X, solve for the *least* amount of square error for y.

# RESIDUAL AND MEAN SQUARED ERROR

#### **ACTIVITY: KNOWLEDGE CHECK**

#### ANSWER THE FOLLOWING QUESTIONS (5 minutes)



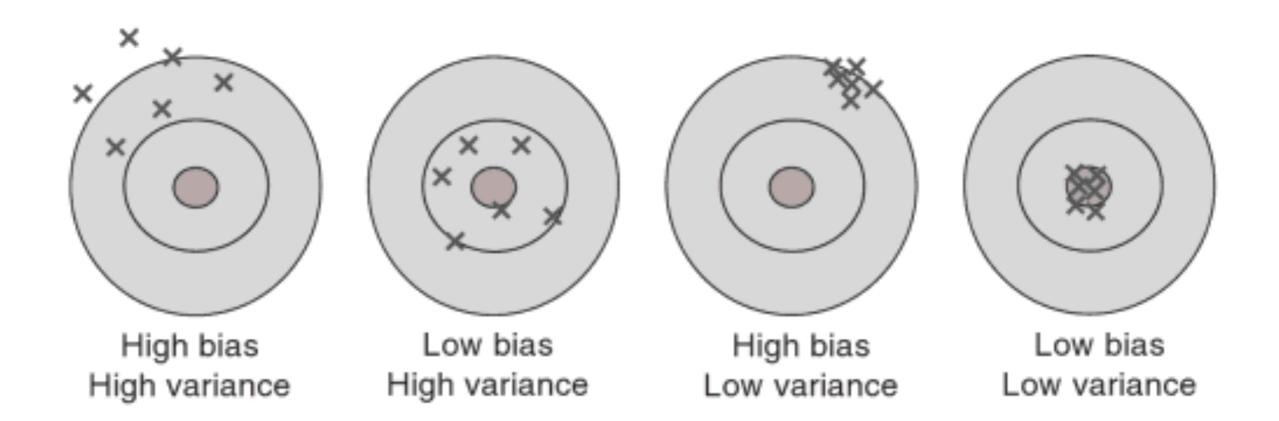
- 1. When is each of the following used?
  - a. R-squared
  - b. Residual error
  - c. Mean squared error

#### **DELIVERABLE**

Answers to the above questions

## BIAS-VARIANCE TRADEOFF

## **BIAS VS. VARIANCE**



#### **BIAS VARIANCE TRADEOFF**

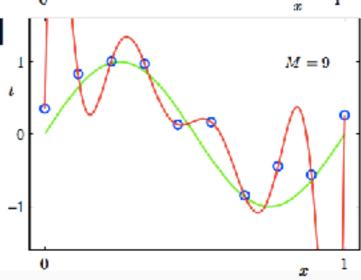
- When our error is **biased**, it means the model's prediction is consistently far away from the actual value.
- ▶ This could be a sign of poor sampling and poor data.
- One objective of a biased model is to trade bias error for generalized error. We prefer the error to be more evenly distributed across the model.
- This is called error due to variance.
- We want our model to *generalize* to data it hasn't seen even if doesn't perform as well on data it has already seen.

#### Bias-Variance tradeoff — Intuition

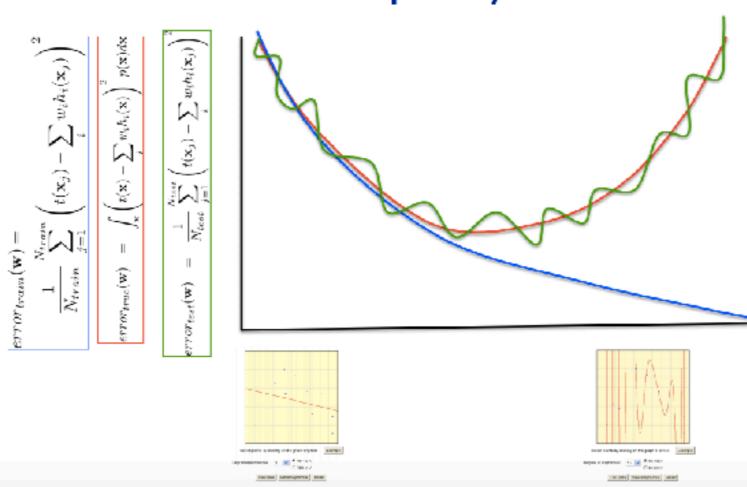
- Model too simple: does not fit the data well
  - A biased solution

- Model too complex: small changes to the data, solution changes a lot
  - A high-variance solution

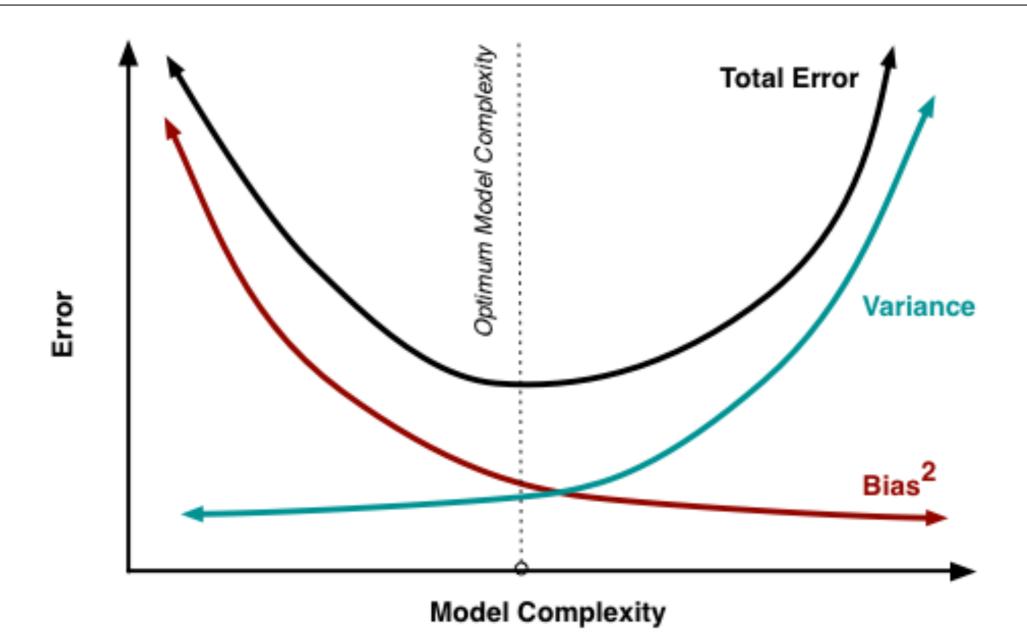




## Test set error as a function of model complexity



### **BIAS VARIANCE TRADEOFF**



#### **ACTIVITY: KNOWLEDGE CHECK**



#### ANSWER THE FOLLOWING QUESTIONS (5 minutes)

- 1. What data do you want to ideally use to determine the bias and variance errors? What data do you actually use?
- 2. Which of the following scenarios would be better for a weatherman?
  - a. Knowing that I can very accurately "predict" the temperature outside from previous days perfectly, but be 20-30 degrees off for future days
  - b. Knowing that I can accurately predict the general trend of the temperate outside from previous days, and therefore am at most only 10 degrees off on future days

#### **DELIVERABLE**

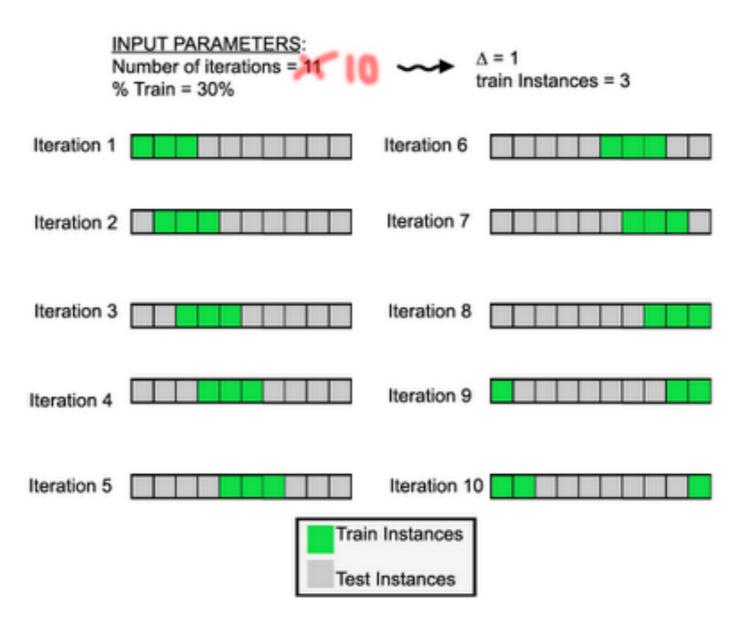
Answers to the above questions

# CROSS VALIDATION

#### **CROSS VALIDATION**

- ▶ Cross validation can help account for bias.
- ▶ The general idea is to
  - •Generate several models on different cross sections of the data
  - ▶ Measure the performance of each
  - ▶ Take the mean performance
- This technique swaps bias error for generalized error, describing previous trends accurately enough to extend to future trends.

#### **CROSS VALIDATION**



#### **K-FOLD CROSS VALIDATION**

- ▶ k-fold cross validation
  - ▶ Split the data into *k* group
  - Train the model on all segments except one
  - ▶Test model performance on the remaining set
- If k = 5, split the data into five segments and generate five models.

#### **USING K-FOLD CROSS VALIDATION WITH MSE**

Import the appropriate packages and load data.

```
from sklearn import cross_validation
wd = '../dataset/'
bikeshare = pd.read_csv(wd + 'bikeshare.csv')
weather = pd.get_dummies(bikeshare.weathersit, prefix='weather')
modeldata = bikeshare[['temp', 'hum']].join(weather[['weather_1', 'weather_2', 'weather_3']])
y = bikeshare.casual
```

#### **USING K-FOLD CROSS VALIDATION WITH MSE**

▶ Build models on subsets of the data and calculate the average score.

```
kf = cross_validation.KFold(len(modeldata), n_folds=5, shuffle=True)
scores = []
for train_index, test_index in kf:
    lm = linear_model.LinearRegression().fit(modeldata.iloc[train_index],
y.iloc[train_index])
    scores.append(metrics.mean_squared_error(y.iloc[test_index],
lm.predict(modeldata.iloc[test_index])))
print np.mean(scores)
```

#### **USING K-FOLD CROSS VALIDATION WITH MSE**

- ▶ This can be compared to the model built on all of the data.
- This score will be lower, but we're trading off bias error for generalized error:

  lm linear model LinearRegression() fit(modeldata v)

```
lm = linear_model.LinearRegression().fit(modeldata, y)
print metrics.mean_squared_error(y, lm.predict(modeldata))
```

▶ Which approach would predict new data more accurately?

# CROSS VALIDATION WITH LINEAR REGRESSION

#### **ACTIVITY: CROSS VALIDATION WITH LINEAR REGRESSION**



#### **DIRECTIONS (20 minutes)**

If we were to continue increasing the number of folds in cross validation, would error increase or decrease?

- 1. Using the previous code example, perform k-fold cross validation for all even numbers between 2 and 50.
- 2. Answer the following questions:
  - a. What does shuffle=True do?
  - b. At what point does cross validation no longer seem to help the model?
- 3. Hint: range(2, 51, 2) produces a list of even numbers from 2 to 50

#### **DELIVERABLE**

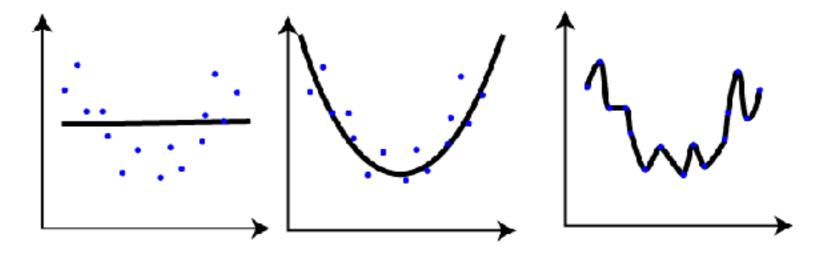
Answers to questions

# REGULARIZATION AND CROSS VALIDATION

#### WHAT IS REGULARIZATION? AND WHY DO WE USE IT?

- Regularization is an additive approach to protect models against overfitting (being potentially biased and overconfident, not generalizing well).
- ▶ Regularization becomes an additional weight to coefficients, shrinking them closer to zero.
- ▶ L1 (Lasso Regression) adds the extra weight to coefficients.
- ▶ L2 (Ridge Regression) adds the square of the extra weight to coefficients.
- Use Lasso when we have more features than observations (k > n) and Ridge otherwise.

### WHAT IS OVERFITTING?



- ▶ The first model poorly explains the data.
- ▶ The second model explains the general curve of the data.
- ▶ The third model drastically overfits the model, bending to every point.
- ▶ Regularization helps prevent the third model.

#### WHERE REGULARIZATION MAKES SENSE

▶ What happens to MSE if use Lasso or Ridge Regression directly?

```
lm = linear_model.LinearRegression().fit(modeldata, y)
print metrics.mean_squared_error(y, lm.predict(modeldata))
lm = linear_model.Lasso().fit(modeldata, y)
print metrics.mean_squared_error(y, lm.predict(modeldata))
lm = linear_model.Ridge().fit(modeldata, y)
print metrics.mean_squared_error(y, lm.predict(modeldata))
1672.58110765 # OLS
1725.41581608 # L1
1672.60490113 # L2
```

#### WHERE REGULARIZATION MAKES SENSE

- ▶ It doesn't seem to help. Why is that?
- ▶ We need to optimize the regularization weight parameter (called alpha) through cross validation.

#### **ACTIVITY: KNOWLEDGE CHECK**



#### ANSWER THE FOLLOWING QUESTIONS (10 minutes)

- 1. Why is regularization important?
- 2. What does it protect against and how?
- 3. Lasso zeros out coefficients while Ridge does not. So, Ridge is mainly used to tackle overfitting while Lasso is used to promote sparsity. True or False.
- 4. Discuss Ridge vs Lasso in the presence of highly correlated features.

#### **DELIVERABLE**

Answers to the above questions

## UNDERSTANDING REGULARIZATION EFFECTS

#### **QUICK CHECK**

- We are working with the bikeshare data to predict riders over hours/days with a few features.
- ▶ Does it make sense to use a ridge regression or a lasso regression?
- ▶ Why?

#### **UNDERSTANDING REGULARIZATION EFFECTS**

Let's test a variety of alpha weights for Ridge Regression on the bikeshare data.

```
alphas = np.logspace(-10, 10, 21)
for a in alphas:
    print 'Alpha:', a
    lm = linear_model.Ridge(alpha=a)
    lm.fit(modeldata, y)
    print lm.coef_
    print metrics.mean_squared_error(y, lm.predict(modeldata))
```

What happens to the weights of the coefficients as alpha increases? What happens to the error as alpha increases?

▶ Grid search exhaustively searches through all given options to find the best solution. Grid search will try all combos given in param\_grid.

```
param_ grid = {
    'intercept': [True, False],
    'alpha': [1, 2, 3],
}
```

- ▶ This param grid has six different options:
  - ▶intercept True, alpha 1
  - ▶intercept True, alpha 2
  - ▶intercept True, alpha 3
  - ▶intercept False, alpha 1
  - ▶intercept False, alpha 2
  - ▶intercept False, alpha 3

```
param_ grid = {
    'intercept': [True, False],
    'alpha': [1, 2, 3],
}
```

▶ This is an incredibly powerful, automated machine learning tool!

```
from sklearn import grid_search

alphas = np.logspace(-10, 10, 21)
gs = grid_search.GridSearchCV(
    estimator=linear_model.Ridge(),
    param_grid={'alpha': alphas},
    scoring='mean_squared_error')
```

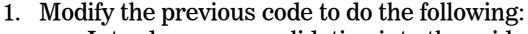
```
gs.fit(modeldata, y)

print -gs.best_score_ # mean squared error here comes in negative, so
let's make it positive.
print gs.best_estimator_ # explains which grid_search setup worked
best
print gs.grid_scores_ # shows all the grid pairings and their
performances.
```

## GRID SEARCH CV, SOLVING FOR ALPHA

#### **ACTIVITY: GRID SEARCH CV, SOLVING FOR ALPHA**

#### **DIRECTIONS (25 minutes)**



- a. Introduce cross validation into the grid search. This is accessible from the cv argument.
- b. Add fit\_intercept = True and False to the param\_grid dictionary.
- c. Re-investigate the best score, best estimator, and grid score attributes as a result of the grid search.

#### **DELIVERABLE**

New code and output that meets above requirements

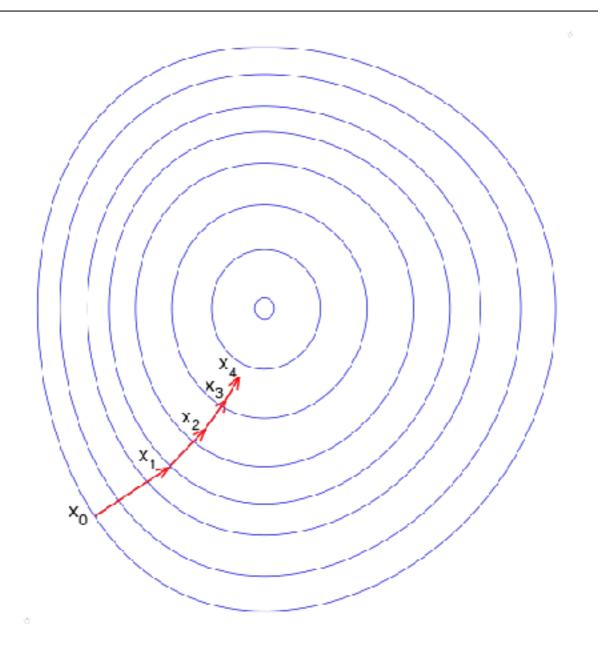


# MINIMIZING LOSS THROUGH GRADIENT DESCENT

#### **GRADIENT DESCENT**

- Gradient Descent can also help us minimize error.
- ▶ How Gradient Descent works:
  - A random linear solution is provided as a starting point
  - The solver attempts to find a next "step": take a step in any direction and measure the performance.
  - If the solver finds a better solution (i.e. lower MSE), this is the new starting point.
  - Repeat these steps until the performance is optimized and no "next steps" perform better. The size of steps will shrink over time.

#### **GRADIENT DESCENT**



#### A CODE EXAMPLE OF GRADIENT DESCENT

```
num_to_approach, start, steps, optimized = 6.2, 0., [-1, 1], False
while not optimized:
    current_distance = num_to_approach - start
    got_better = False
    next_steps = [start + i for i in steps]
    for n in next_steps:
        distance = np.abs(num_to_approach - n)
        if distance < current_distance:
            got_better = True
            print distance, 'is better than', current_distance
            current_distance = distance
            start = n</pre>
```

#### A CODE EXAMPLE OF GRADIENT DESCENT

```
if got_better:
    print 'found better solution! using', current_distance
    a += 1
else:
    optimized = True
    print start, 'is closest to', num_to_approach
```

▶ What is the code doing? What could go wrong?

#### **GLOBAL VS LOCAL MINIMUMS**

• Gradient Descent could solve for a *local* minimum instead of a *global* minimum.

A *local* minimum is confined to a very specific subset of solutions. The *global* minimum considers all solutions. These could be equal, but that's

not always true.



- Gradient Descent works best when:
  - We are working with a large dataset. Smaller datasets are more prone to error.
  - ▶ Data is cleaned up and normalized.
- Gradient Descent is significantly faster than OLS. This becomes important as data gets bigger.

- ▶ We can easily run a Gradient Descent regression.
- Note: The verbose argument can be set to 1 to see the optimization steps.

```
lm = linear_model.SGDRegressor()
lm.fit(modeldata, y)
print lm.score(modeldata, y)
print metrics.mean_squared_error(y, lm.predict(modeldata))
```

▶ Untuned, how well did gradient descent perform compared to OLS?

- Gradient Descent can be tuned with
  - ▶the learning rate: how aggressively we solve the problem
  - ▶epsilon: at what point do we say the error margin is acceptable
  - ▶iterations: when should be we stop no matter what

#### **INDEPENDENT PRACTICE**

### ON YOUR OWN

#### **ACTIVITY: ON YOUR OWN**



#### **DIRECTIONS (30 minutes)**

There are tons of ways to approach a regression problem.

- 1. Implement the Gradient Descent approach to our bikeshare modeling problem.
- 2. Show how Gradient Descent solves and optimizes the solution.
- 3. Demonstrate the grid\_search module.
- 4. Use a model you evaluated last class or the simpler one from today. Implement param\_grid in grid search to answer the following questions:
  - a. With a set of values between 10 ^ -10 and 10 ^ -1, how does MSE change?
  - b. Our data suggests we use L1 regularization. Using a grid search with l1\_ratios between 0 and 1, increasing every 0.05, does this statement hold true? If not, did gradient descent have enough iterations to work properly?
  - c. How do these results change when you alter the learning rate?

#### **DELIVERABLE**

Gradient Descent approach and answered questions

#### **ACTIVITY: ON YOUR OWN**



#### Starter Code

```
params = {} # put your gradient descent parameters here
gs = grid_search.GridSearchCV(
    estimator=linear_model.SGDRegressor(),
    cv=cross_validation.KFold(len(modeldata), n_folds=5, shuffle=True),
    param_grid=params,
    scoring='mean_squared_error',
gs.fit(modeldata, y)
print 'BEST ESTIMATOR'
print -gs.best_score_
print gs.best_estimator_
print 'ALL ESTIMATORS'
print gs.grid_scores_
```

#### **CONCLUSION**

## TOPIC REVIEW

#### **LESSON REVIEW**

- ▶ What's the (typical) range of r-squared?
- ▶ What's the range of mean squared error?
- ▶ How would changing the scale or interpretation of y (your target variable) effect mean squared error?
- ▶ What's cross validation, and why do we use it in machine learning?
- What is error due to bias? What is error due to variance? Which is better for a model to have, if it had to have one?
- ▶ How does gradient descent try a different approach to minimizing error?

#### **COURSE**

### BEFORE NEXT CLASS

### **DUE DATE**

- Project: Final Project, Deliverable 1
  - November 27
  - Upload via your student GitHub

#### **LESSON**

Q & A

#### **LESSON**

### EXIT TICKET

DON'T FORGET TO FILL OUT YOUR EXIT TICKET