Philosophers in antiquity used the concept of force in the study of stationary and moving objects and simple machines, but thinkers such as Aristotle and Archimedes retained fundamental errors in understanding force. In part this was due to an incomplete understanding of the sometimes non-obvious force of friction, and a consequently inadequate view of the nature of natural motion. A fundamental error was the belief that a force is required to maintain motion, even at a constant velocity. Most of the previous misunderstandings about motion and force were eventually corrected by Galileo Galilei and Sir Isaac Newton. With his mathematical insight, Sir Isaac Newton formulated laws of motion that were not improved-on for nearly three hundred years. By the early 20th century, Einstein developed a theory of relativity that correctly predicted the action of forces on objects with increasing momenta near the speed of light, and also provided insight into the forces produced by gravitation and inertia.

With modern insights into quantum mechanics and technology that can accelerate particles close to the speed of light, particle physics has devised a Standard Model to describe forces between particles smaller than atoms. The Standard Model predicts that exchanged particles called gauge bosons are the fundamental means by which forces are emitted and absorbed. Only four main interactions are known: in order of decreasing strength, they are: strong, electromagnetic, weak, and gravitational.:2–10:79 High-energy particle physics observations made during the 1970s and 1980s confirmed that the weak and electromagnetic forces are expressions of a more fundamental electroweak interaction.

Aristotle provided a philosophical discussion of the concept of a force as an integral part of Aristotleian cosmology. In Aristotle's view, the terrestrial sphere contained four elements that come to rest at different "natural places" therein. Aristotle believed that motionless objects on Earth, those composed mostly of the elements earth and water, to be in their natural place on the ground and that they will stay that way if left alone. He distinguished between the innate tendency of objects to find their "natural place" (e.g., for heavy bodies to fall), which led to "natural motion", and unnatural or forced motion, which required continued application of a force. This theory, based on the everyday experience of how objects move, such as the constant application of a force needed to keep a cart moving, had conceptual trouble accounting for the behavior of projectiles, such as the flight of arrows. The place where the archer moves the projectile was at the start of the flight, and while the projectile sailed through the air, no discernible efficient cause acts on it. Aristotle was aware of this problem and proposed that the air displaced through the projectile's path carries the projectile to its target. This explanation demands a continuum like air for change of place in general.

Newton's First Law of Motion states that objects continue to move in a state of constant velocity unless acted upon by an external net force or resultant force. This law is an extension of Galileo's insight that constant velocity was associated with a lack of net force (see a more detailed description of this below). Newton proposed that every object with mass has an innate inertia that functions as the fundamental equilibrium "natural state" in place of the Aristotelian idea of the "natural state of rest". That is, the first law contradicts the intuitive Aristotelian belief that a net force is required to keep an object moving with constant velocity. By making rest physically indistinguishable from non-zero constant velocity, Newton's First Law directly connects inertia with the concept of relative velocities. Specifically, in systems where objects are moving with different velocities, it is impossible to determine which object is "in motion" and which object is "at rest". In other words, to phrase matters more technically, the laws of physics are the same in every inertial frame of reference, that is, in all frames related by a Galilean transformation.