

1. Description

1.1. Project

Project Name	pinMapF3
Board Name	custom
Generated with:	STM32CubeMX 6.9.2
Date	12/06/2023

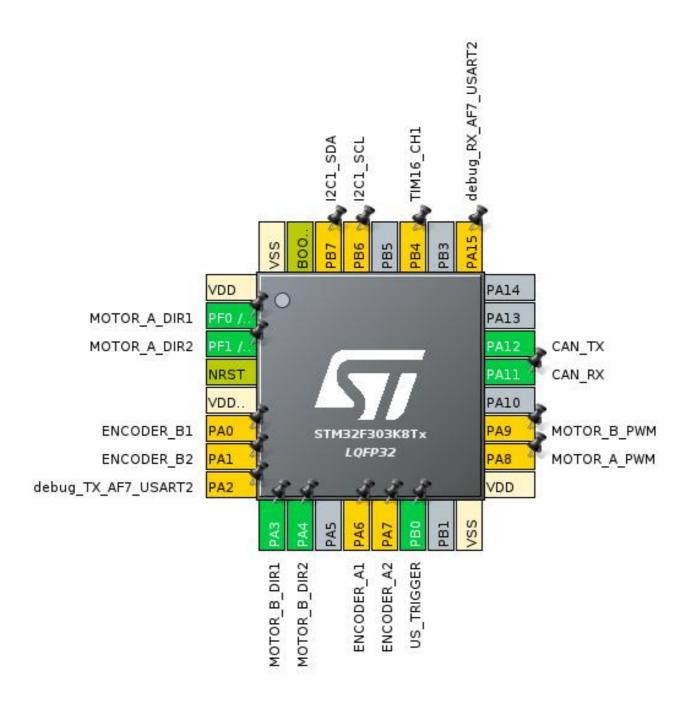
1.2. MCU

MCU Series	STM32F3
MCU Line	STM32F303
MCU name	STM32F303K8Tx
MCU Package	LQFP32
MCU Pin number	32

1.3. Core(s) information

Core(s)	Arm Cortex-M4

2. Pinout Configuration



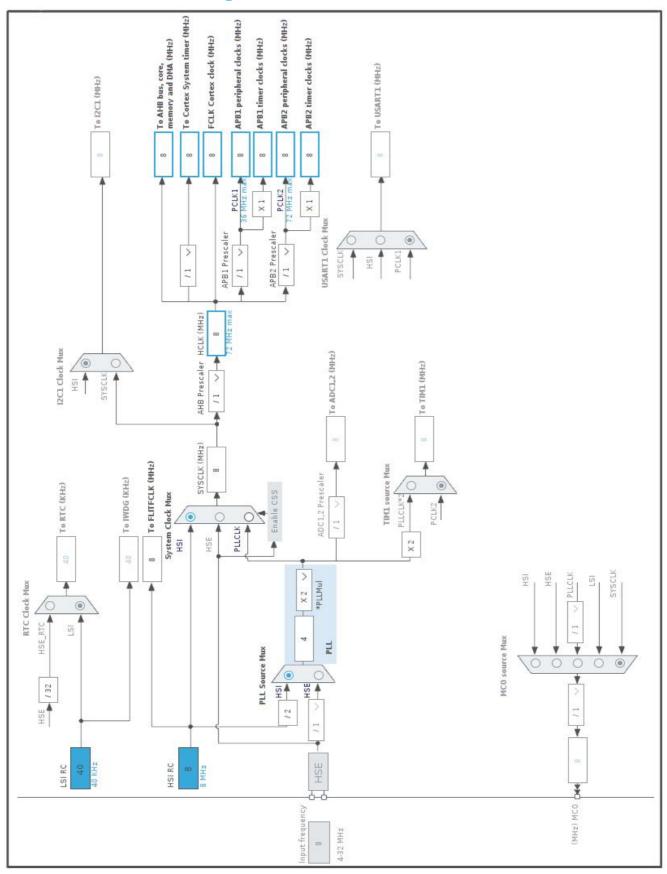
3. Pins Configuration

Pin Number LQFP32	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
1	VDD	Power		
2	PF0 / OSC_IN *	1/0	GPIO_Output	MOTOR_A_DIR1
3	PF1 / OSC_OUT *	I/O	GPIO_Output	MOTOR_A_DIR2
4	NRST	Reset		
5	VDDA/VREF+	Power		
6	PA0 **	I/O	TIM2_CH1	ENCODER_B1
7	PA1 **	I/O	TIM2_CH2	ENCODER_B2
8	PA2 **	I/O	USART2_TX	debug_TX_AF7_USART2
9	PA3 *	I/O	GPIO_Output	MOTOR_B_DIR1
10	PA4 *	I/O	GPIO_Output	MOTOR_B_DIR2
12	PA6 **	I/O	TIM3_CH1	ENCODER_A1
13	PA7 **	I/O	TIM3_CH2	ENCODER_A2
14	PB0 *	I/O	GPIO_Output	US_TRIGGER
16	VSS	Power		
17	VDD	Power		
18	PA8 **	I/O	TIM1_CH1	MOTOR_A_PWM
19	PA9 **	I/O	TIM1_CH2	MOTOR_B_PWM
21	PA11	I/O	CAN_RX	
22	PA12	I/O	CAN_TX	
25	PA15 **	I/O	USART2_RX	debug_RX_AF7_USART2
27	PB4 **	I/O	TIM16_CH1	
29	PB6 **	I/O	I2C1_SCL	
30	PB7 **	I/O	I2C1_SDA	
31	BOOT0	Boot		
32	VSS	Power		

^{*} The pin is affected with an I/O function

^{**} The pin is affected with a peripheral function but no peripheral mode is activated

4. Clock Tree Configuration



5. Software Project

5.1. Project Settings

Name	Value	
Project Name	pinMapF3	
Project Folder	/home/beatrice/circee/code_f3/pinMapF3	
Toolchain / IDE	EWARM V8.32	
Firmware Package Name and Version	STM32Cube FW_F3 V1.11.0	
Application Structure	Basic	
Generate Under Root	No	
Do not generate the main()	No	
Minimum Heap Size	0x200	
Minimum Stack Size	0x400	

5.2. Code Generation Settings

Name	Value
STM32Cube MCU packages and embedded software	Copy all used libraries into the project folder
Generate peripheral initialization as a pair of '.c/.h' files	No
Backup previously generated files when re-generating	No
Keep User Code when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power	No
consumption)	
Enable Full Assert	No

5.3. Advanced Settings - Generated Function Calls

Rank Function Name		Peripheral Instance Name
1	MX_GPIO_Init	GPIO
2	SystemClock_Config	RCC
3	MX CAN Init	CAN

1. Power Consumption Calculator report

1.1. Microcontroller Selection

Series	STM32F3
Line	STM32F303
MCU	STM32F303K8Tx
Datasheet	DS9866_Rev5

1.2. Parameter Selection

Temperature	25
Vdd	3.6

1.3. Battery Selection

Battery	Li-SOCL2(A3400)
Capacity	3400.0 mAh
Self Discharge	0.08 %/month
Nominal Voltage	3.6 V
Max Cont Current	100.0 mA
Max Pulse Current	200.0 mA
Cells in series	1
Cells in parallel	1

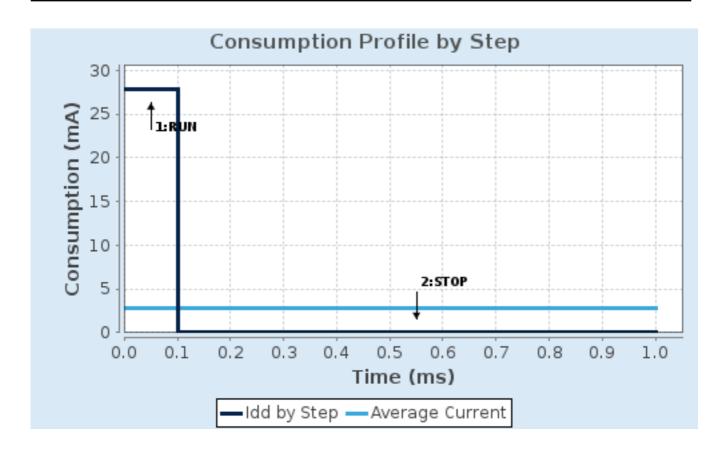
1.4. Sequence

Step	Step1	Step2
Mode	RUN	STOP
Vdd	3.6	3.6
Voltage Source	Battery	Battery
Range	No Scale	No Scale
Fetch Type	RAM	n/a
CPU Frequency	72 MHz	0 Hz
Clock Configuration	HSEBYP PLL	Regulator LP
Clock Source Frequency	8 MHz	0 Hz
Peripherals		
Additional Cons.	0 mA	0 mA
Average Current	27.84 mA	9.55 µA
Duration	0.1 ms	0.9 ms
DMIPS	90.0	0.0
Ta Max	98.99	105
Category	In DS Table	In DS Table

1.5. Results

Sequence Time	1 ms	Average Current	2.79 mA
Battery Life	1 month, 20 days,	Average DMIPS	90.0 DMIPS
	5 hours		

1.6. Chart



2. Peripherals and Middlewares Configuration

2.1. CAN

mode: Activated

2.1.1. Parameter Settings:

Bit Timings Parameters:

Prescaler (for Time Quantum) 16

Time Quantum

2000.0 *

Time Quanta in Bit Segment 1 1 Time

Time Quanta in Bit Segment 2 1 Time

Time for one Bit 6000 *

Baud Rate 166666 *

ReSynchronization Jump Width 1 Time

Basic Parameters:

Time Triggered Communication Mode

Automatic Bus-Off Management

Disable

Automatic Wake-Up Mode

Disable

Automatic Retransmission

Disable

Receive Fifo Locked Mode

Disable

Transmit Fifo Priority

Disable

Advanced Parameters:

Operating Mode Normal

2.2. RCC

2.2.1. Parameter Settings:

System Parameters:

VDD voltage (V) 3.3
Prefetch Buffer Enabled

Flash Latency(WS) 0 WS (1 CPU cycle)

RCC Parameters:

HSI Calibration Value 16
HSE Startup Timout Value (ms) 100
LSE Startup Timout Value (ms) 5000

2.3. SYS

Timebase Source: SysTick

* User modified value

3. System Configuration

3.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
CAN	PA11	CAN_RX	Alternate Function Push Pull	No pull-up and no pull-down	High *	
	PA12	CAN_TX	Alternate Function Push Pull	No pull-up and no pull-down	High *	
Single Mapped Signals	PA0	TIM2_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	ENCODER_B1
	PA1	TIM2_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	ENCODER_B2
	PA2	USART2_TX	Alternate Function Push Pull	No pull-up and no pull-down	High *	debug_TX_AF7_USART2
	PA6	TIM3_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	ENCODER_A1
	PA7	TIM3_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	ENCODER_A2
	PA8	TIM1_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR_A_PWM
	PA9	TIM1_CH2	Alternate Function Push Pull	No pull-up and no pull-down	Low	MOTOR_B_PWM
	PA15	USART2_RX	Alternate Function Push Pull	No pull-up and no pull-down	High *	debug_RX_AF7_USART2
	PB4	TIM16_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Low	
	PB6	I2C1_SCL	Alternate Function Open Drain	No pull-up and no pull-down	High *	
	PB7	I2C1_SDA	Alternate Function Open Drain	No pull-up and no pull-down	High *	
GPIO	PF0 / OSC_IN	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR_A_DIR1
	PF1 / OSC_OUT	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR_A_DIR2
	PA3	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR_B_DIR1
	PA4	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	MOTOR_B_DIR2
	PB0	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	US_TRIGGER

3.2. DMA configuration

nothing configured in DMA service

3.3. NVIC configuration

3.3.1. NVIC

Interrupt Table	Enable	Preenmption Priority	SubPriority	
Non maskable interrupt	true	0	0	
Hard fault interrupt	true	0	0	
Memory management fault	true	0	0	
Pre-fetch fault, memory access fault	true	0	0	
Undefined instruction or illegal state	true	0	0	
System service call via SWI instruction	true	0	0	
Debug monitor	true	0	0	
Pendable request for system service	true	0	0	
System tick timer	true	0	0	
PVD interrupt through EXTI line 16	unused			
Flash global interrupt	unused			
RCC global interrupt	unused			
CAN TX interrupt	unused			
CAN RX0 interrupt	unused			
CAN RX1 interrupt	unused			
CAN SCE interrupt	unused			
Floating point unit interrupt	unused			

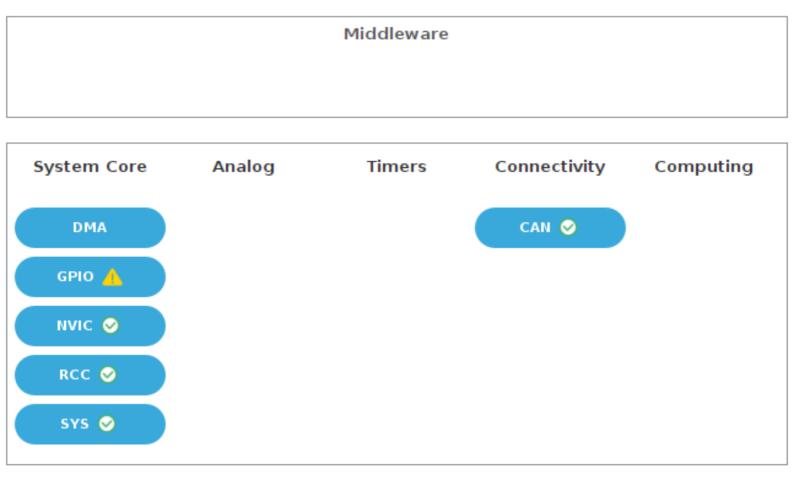
3.3.2. NVIC Code generation

Enabled interrupt Table	Select for init sequence ordering	Generate IRQ handler	Call HAL handler
Non maskable interrupt	false	true	false
Hard fault interrupt	false	true	false
Memory management fault	false	true	false
Pre-fetch fault, memory access fault	false	true	false
Undefined instruction or illegal state	false	true	false
System service call via SWI instruction	false	true	false
Debug monitor	false	true	false
Pendable request for system service	false	true	false
System tick timer	false	true	true

* User modified value

4. System Views

- 4.1. Category view
- 4.1.1. Current



5. Docs & Resources

Type Link

BSDL files https://www.st.com/resource/en/bsdl_model/stm32f3_bsdl.zip

System View https://www.st.com/resource/en/svd/stm32f3-svd.zip

Description

Presentations https://www.st.com/resource/en/product_presentation/stm32-

stm8_embedded_software_solutions.pdf

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