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# PSFUN

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Lo scopo della Matematica è di determinare il valore numerico delle incognite che si presentano nei problemi pratici. Newton, Euler, Lagrange, Cauchy, Gauss, e tutti i grandi matematici sviluppano le loro mirabili teorie fino al calcolo delle cifre decimali necessarie.

—Giuseppe Peano

Non esistono problemi dai quali si può prescindere. Non c'è niente di più penoso di coloro i quali suddividono il pensiero dell'uomo in un pensiero da cui non si può prescindere e in uno da cui si può prescindere. Fra costoro si celano i nostri futuri carnefici.

—Una partita a scacchi con Albert Einstein, Friedrich Dürrenmatt



## CHAPTER

# 1

## MATRIX FUNCTIONS

This library is focused on the computation of matrix-function [4] vector products

$$\mathbf{y} = f(A)\mathbf{x}, A \in \mathbb{R}^{n \times n}, \text{nnz}(A) = O(n), f : \mathbb{R} \rightarrow \mathbb{R}, \quad (1.1)$$

for large and sparse matrices in a distributed setting. Matrix functions are ubiquitous in models for applied sciences. They are involved in the solution of ordinary, partial, and fractional differential equations, systems of coupled differential equations, hybrid differential-algebraic problems, equilibrium problems, measures of complex networks, and many others.

To perform the computation in (1.1), we consider here two main approaches, the first one makes use of a definition based on the *Cauchy integral* for a matrix function: given a closed contour  $\Gamma$  lying in the region of analyticity of the function  $f(x)$  and containing the spectrum of  $A$ ,  $f(A)$  can be defined as

$$f(A) = \frac{1}{2\pi i} \int_{\Gamma} f(z)(zI - A)^{-1} dz. \quad (1.2)$$

By applying a quadrature formula on  $N$  points to (1.2), with weights  $\{c_j\}_{j=1}^N$  and nodes  $\{\xi_j\}_{j=1}^N$ , it is possible to approximate (1.1) as

$$\mathbf{y} = f(A)\mathbf{x} \approx \sum_{j=1}^N c_j (A + \xi_j I)^{-1} \mathbf{x},$$

that is then computationally equivalent to the solution of  $N$  linear systems with the same right-hand side.

The second approach to problem (1.1) resides instead on the use of projection algorithm. Specifically, we suppose having two  $k$ -th dimensional subspaces  $\mathcal{V}$  and  $\mathcal{W}$  spanned by the column of the matrices  $V, W \in \mathbb{R}^{n \times k}$ . Then, problem (1.1) can be projected and approximated on the two subspaces by doing

$$\mathbf{y} = f(A)\mathbf{x} \approx W f(V^T A W) V^T \mathbf{x},$$

where now  $A_k = V^T A W$  is a small matrix of size  $k \times k$ , to which we can apply many specific algorithms for the particular choice of  $f(x)$ , [4], or again a quadrature formula.

## 1.1 The PSFUN Library

The recent developments on softwares for sparse linear algebra have been made essential for a wide variety of scientific applications. Specifically, they have been dedicated to the construction of massively parallel sparse solvers for a particular matrix function  $f(x) = x^{-1}$ , i.e., for the solution of large and sparse linear system. A computational framework that lies at the core of pretty much all multi-physics and multi-scale simulations.

With this library, we try to face the analogous challenge of computing matrix-function vector products for more general functions than the inverse.

The library described here is substantially based on the parallel BLAS feature for sparse matrices made available by the [PSBLAS library](#), and is geared towards the possibility of running on machines with thousands of high-performance cores, and is divided in three main modules,

**Serial module:** this module implements (or interfaces) the computation of  $f(A)$ ,  $f(A)\mathbf{x}$  for matrices of small-size that can be handled in a sequential way,

**Krylov module:** this module implements distributed Krylov based methods for the reduction of problem (1.1) to the solution of problems of small dimensions,

**Quadrature module:** this module implements the approach in (1.2) by implementing different quadrature formulas.

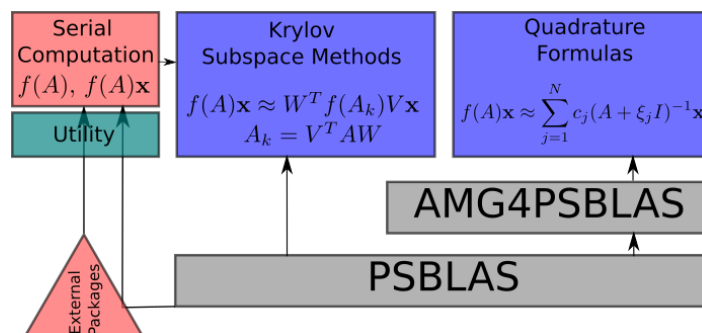


Fig. 1.1: Structure of the PSFUN library.

## 1.2 How To Install

The first step to install the PSFUN is to obtain and install the PSBLAS library from [psctoolkit](#). All the relevant information can be found there.

The actual version of the library works with the development version of PSBLAS, this can be done obtained via GitHub by doing

```
git clone https://github.com/sfilippone/psblas3.git
cd psblas3
./configure -with-<stuff>=... -prefix=/path/to/psblas
make -j
make install
```

in which the various `-with-<stuff>=...` options can be read from the output of the `./configure -h`, again please refer to the original documentation of PSBLAS for all the relevant information.

Auxiliary packages that can be used to with the library are:

- the package for the computation of  $\varphi$ -functions from [6], that can be obtained from the [ACM website](#).



To build the documentation [Sphinx](#) and [Sphinx-Fortran](#) (with the relevant dependencies) are needed. Building the documentation is optional, and can be skipped during the configuration phase. In every case a copy of the docs is included with the code.

After having installed all the dependencies, and the auxiliary packages the PSFUN library can be installed via `ccmake` (Version  $\geq 3.15$ ), by setting the position of PSBLAS, and all the auxiliary packages.

```
git clone https://github.com/Cirdans-Home/psfun.git
mkdir build
cd build
ccmake ../psfun/
make
make install
```



## CHAPTER

# 2

## SERIAL MODULE

This module contains the routines needed for the computation of  $f(A)x$  for  $A$  a matrix of small size. It interfaces external codes and algorithms that usually work with matrix memorized in dense storage. The intended use of the functions contained here is to use them at the lower level of a Krylov subspace method. The library directly contains the EXPOKIT code [11] for the computation of the matrix exponential, together with the scaling and squaring and Taylor algorithms [7][8] by J. Burkardt. For using the  $\varphi$ -functions, the code from [6] is needed. It can be [downloaded](#), compiled and linked to the main library in the install phase.

The module is centered on the `psfun_d_serial` type, this module contains all the options needed to set a specific matrix function to be computed. Not all the options are needed for every type of matrix-function, e.g., the field `integer(psb_ipk_) :: padedegree` is used only if a Padè type algorithm is employed. All the keywords needed to load the implemented functions and algorithmic variants are given in [Table 2.1](#).

Table 2.1: Implemented Methods

Function	Variant	Matrix	fname	variant	Source
$f(\alpha A)$	Diagonalization	Symmetric	"USERF"	"SYM"	
$\exp(\alpha A)$	Taylor	General	"EXP"	"TAYLOR"	[7][8]
	Scaling and Squaring	General	"EXP"	"SASQ"	[7][8]
	Generalized Padè	General	"EXP"	"GENPADE"	[11]
	Chebyshev	Hessenberg	"EXP"	"CHBHES"	[11]
	Chebyshev	General	"EXP"	"CHBGEN"	[11]
	Chebyshev	Symmetric	"EXP"	"CHBSYM"	[11]
$\varphi_k(\alpha A)$	Scaling and Squaring	Symmetric	"PHI"	"NONE"	[6]

## 2.1 Module

### Description

This module contains the generic interfaces for the computation of the different matrix functions included in the library. The idea is that this modules computes, in a serial way,  $y = f(\alpha A)x$ .

### Quick access

**Routines** *psfun\_d\_serial\_apply\_array()*, *psfun\_d\_serial\_apply\_sparse()*,  
*psfun\_d\_setinteger()*, *psfun\_d\_setpointer()*, *psfun\_d\_setreal()*,  
*psfun\_d\_setstring()*

### Needed modules

- `psb_base_mod`
- `scalesquare`

### Types

- type `psfun_d_serial_mod/unknown_type`

#### Type fields

- % `fname` [*character,optional/default='exp'*]
- % `padedegree` [*integer,optional/default=6*]
- % `phiorder` [*integer,optional/default=1*]
- % `scaling` [*real,optional/default=1.0\_psb\_dpk\_*]
- % `variant` [*character,optional/default='expokit'*]

### Variables

#### Subroutines and functions

subroutine `psfun_d_serial_mod/psfun_d_setstring(fun, what, val, info)`

Set function for setting options defined by a string

#### Parameters

- **fun** :: Function object
- **what** [*character,in*] :: String of option to set
- **val** [*character,in*] :: Value of the string
- **info** [*integer,out*] :: Output flag

Use `psb_base_mod`

subroutine `psfun_d_serial_mod/psfun_d_setreal(fun, what, val, info)`

Set function for setting options defined by a real

#### Parameters

- **fun** :: Function object
- **what** [*character,in*] :: String of option to set

- **val** [*real,in*] :: Real Value of the option
- **info** [*integer,out*] :: Output flag

Use `psb_base_mod`

subroutine `psfun_d_serial_mod/psfun_d_setinteger(fun, what, val, info)`

Set function for setting options defined by an integer

#### Parameters

- **fun** :: Function object
- **what** [*character,in*] :: String of option to set
- **val** [*integer,in*] :: Integer Value of the option
- **info** [*integer,out*] :: Output flag

Use `psb_base_mod`

subroutine `psfun_d_serial_mod/psfun_d_setpointer(fun, what, val, info)`

To set the function pointer inside the type

#### Parameters

- **fun** :: Function object
- **what** [*character,in*] :: String of option to set
- **val** :: Function to set
- **info** [*integer,out*] :: Output flag

Use `psb_base_mod`

subroutine `psfun_d_serial_mod/psfun_d_serial_apply_array(fun, a, y, x, info)`

This is the core of the function apply on a serial matrix to compute  $y = f(\alpha * A)x$ . It calls on the specific routines implementing the different functions. It is the function to modify if ones want to interface a new function that was not previously available or a new algorithm (variant) for an already existing function.

#### Parameters

- **fun** :: Function information
- **a** (,) [*real,in*] :: We need to work on a copy of a since the Lapack routine
- **y** (\*) [*real,out*] :: Output vector
- **x** (\*) [*real,in*] :: Input vector
- **info** [*integer,out*] :: Information on the output

Use `psb_base_mod, scalesquare`

subroutine `psfun_d_serial_mod/psfun_d_serial_apply_sparse(fun, a, y, x, info)`

This is the core of the function apply on a serial matrix to compute  $y = f(\alpha * A)x$  when A is memorized in a sparse storage. In this case the routine converts it to a dense storage and then calls the array version of itself. That is the one implementing the different functions. It is the function to modify if ones want to interface a new function that was not previously available or a new algorithm (variant) for an already existing function.

#### Parameters

- **fun** :: Function information
- **a** [*psb\_dspmat\_type,inout*] :: Matrix
- **y** (\*) [*real,out*] :: Output vector
- **x** (\*) [*real,in*] :: Input vector
- **info** [*integer,out*] :: Information on the output

Use `psb_base_mod`

## CHAPTER

# 3

## KRYLOV MODULE

Let  $V_k$  be an orthogonal matrix whose columns  $\mathbf{x}_1, \dots, \mathbf{x}_k$  span an arbitrary Krylov subspace  $\mathcal{W}_k(A, \mathbf{x})$  of dimension  $k$ . We obtain an approximation of  $f(A)\mathbf{x}$  by

$$f(A)\mathbf{x} = V_k f(V_k^T A V_k) V_k^T \mathbf{x}. \quad (3.1)$$

Different methods for the approximation of matrix functions are obtained for different choices of the projection spaces  $\mathcal{W}_k(A, \mathbf{x})$ .

Given a set of scalars  $\{\sigma_1, \dots, \sigma_{k-1}\} \subset \overline{\mathbb{C}}$  in the the extended complex plane  $\overline{\mathbb{C}}$ , that are not eigenvalues of  $A$ , let

$$q_{k-1}(z) = \prod_{j=1}^{k-1} (\sigma_j - z).$$

The **rational Krylov** subspace of order  $k$  associated with  $A, \mathbf{x}$  and  $q_{k-1}$  is defined by

$$\mathcal{Q}_k(A, \mathbf{x}) = [q_{k-1}(A)]^{-1} \mathcal{K}_k(A, \mathbf{x}),$$

where

$$\mathcal{K}_k(A, \mathbf{x}) = \text{Span}\{\mathbf{x}, A\mathbf{x}, \dots, A^{k-1}\mathbf{x}\}$$

is the standard polynomial Krylov space.

By defining the matrices

$$C_j = (\mu_j \sigma_j A - I) (\sigma_j I - A)^{-1},$$

where  $\{\mu_1, \dots, \mu_{k-1}\} \subset \overline{\mathbb{C}}$  are such that  $\sigma_j \neq \mu_j^{-2}$ , it is known that the rational Krylov space can also be written as follows [2]

$$\mathcal{Q}_k(A, \mathbf{x}) = \text{Span}\{\mathbf{x}, C_1\mathbf{x}, \dots, C_{k-1} \cdots C_2 C_1 \mathbf{x}\}.$$

This general formulation allows to recast most of the classical Krylov methods in terms of a rational Krylov method with a specific choice of  $\sigma_j$  and  $\mu_j$ . In particular,

- the **polynomial Krylov** method in which  $\mathcal{W}_k(A, \mathbf{x}) = \mathcal{K}_k(A, \mathbf{x})$  can be recovered by defining  $\mu_j = 1$  and  $\sigma_j = \infty$  for each  $j$ .

- The **extended Krylov** method [1][5], in which

$$\mathcal{W}_{2k-1}(A, \mathbf{x}) = \text{Span}\{\mathbf{x}, A^{-1}\mathbf{x}, A\mathbf{x}, \dots, A^{-(k-1)}\mathbf{x}, A^{k-1}\mathbf{x}\},$$

is obtained by setting

$$(\mu_j, \sigma_j) = \begin{cases} (1, \infty), & \text{for } j \text{ even,} \\ (0, 0), & \text{for } j \text{ odd.} \end{cases}$$

- The **shift-and-invert** rational Krylov [9][12], where

$$\mathcal{W}_k(A, \mathbf{x}) = \text{Span}\{\mathbf{x}, (\sigma I - A)^{-1}\mathbf{x}, \dots, (\sigma I - A)^{-(k-1)}\mathbf{x}\},$$

is defined by taking  $\mu_j = 0$  and  $\sigma_j = \sigma$  for each  $j$ .

The PSFUN library contains the implementation of several flavour of these methods that can be used for the computation of (3.1), the field in the `psfun_d_krylov` type represent the options needed to for setting up and applying the different implemented method for a given matrix function `fun` (represented by an object of type `psfun_d_serial`).

Table 3.1 has the info on the method available.

Table 3.1: Implemented Krylov Methods

Method	Class	Matrix Type	kname	Source
Arnoldi	Polynomial	General	"ARNOLDI"	[10]
Lanczos	Polynomial	Symmetric	"LANCZOS"	[10]

## 3.1 Stopping Criterion

## 3.2 Module

### Description

The `psfun_d_krylov_mod` contains the generic call to a Krylov subspace method for the computation of  $y = f(A)x$ , for  $A$  large and sparse.

### Quick access

**Routines** `psfun_d_parallel_apply()`, `psfun_d_plot_info()`

### Needed modules

- `psb_base_mod`
- `psfun_d_serial_mod`: This module contains the generic interfaces for the computation of the different matrix functions included in the library. The idea is that this modules computes, in a serial way,  $y = f(\alpha A)x \dots$
- `ogpf`



## Types

- type psfun\_d\_krylov\_mod/unknown\_type

### Type fields

– % kname [*character, optional/default='arnoldi'*]

## Variables

## Subroutines and functions

subroutine psfun\_d\_krylov\_mod/psfun\_d\_setstring(*meth, what, val, info*)

Set function for setting options defined by a string

### Parameters

- **meth**
- **what** [*character, in*]
- **val** [*character, in*]
- **info** [*integer, out*]

Use psb\_base\_mod

subroutine psfun\_d\_krylov\_mod/psfun\_d\_parallel\_apply(*meth, fun, a, desc\_a, y, x, eps,*  
*info*[, *itmax*[, *itrace*[, *istop*[, *iter*[,  
*err*[, *res*]]]]])

This is the generic function for applying every implemented Krylov method. The general iteration parameters (like the number of iteration, the stop criterion to be used, and the verbosity of the trace) can be passed directly to this routine. All the constitutive parameters of the actual method, and the information relative to the function are instead contained in the meth and fun objects. The Descriptor object :p psb\_desc\_type desc\_a [in]: Descriptor for the sparse matrix

### Parameters

- **meth** :: Krylov method object
- **fun** [*psfun\_d\_serial, inout*] :: Function object
- **a** [*psb\_dspmat\_type, in*] :: Distribute sparse matrix
- **y** [*psb\_d\_vect\_type, inout*] :: Output vector
- **x** [*psb\_d\_vect\_type, inout*] :: Input vector
- **eps** [*real, in*] :: Requested tolerance
- **info** [*integer, out*] :: Output flag
- **itmax** [*integer, in,*] :: Maximum number of iteration
- **itrace** [*integer, in,*] :: Trace for logoutput
- **istop** [*integer, in,*] :: Stop criterion
- **iter** [*integer, out,*] :: Number of iteration
- **err** [*real, out,*] :: Last estimate error
- **res** (\*) [*real, out, allocatable*] :: Vector of the residuals

Use psb\_base\_mod, psfun\_d\_serial\_mod

subroutine psfun\_d\_krylov\_mod/psfun\_d\_plot\_info(*meth, fun, iter, res, info*)

This function plots the convergence history of the Krylov method

### Parameters

- **meth** :: Krylov method
- **fun** [*psfun\_d\_serial,inout*] :: Function object
- **iter** [*integer,in*] :: Number of iteration
- **res** (\*) [*real,in*] :: Residual vector
- **info** [*integer,out*] :: Result of the Gnuplot call

Use `psb_base_mod`, `ogpf`

Call to `linspace()`

## CHAPTER

# 4

## QUADRATURE MODULE

This module makes use of the matrix function definition based on the *Cauchy integral*: given a closed contour  $\Gamma$  lying in the region of analyticity of the function  $f(x)$  and containing the spectrum of  $A$ ,  $f(A)$  can be defined as

$$f(A) = \frac{1}{2\pi i} \int_{\Gamma} f(z)(zI - A)^{-1} dz. \quad (4.1)$$

By applying a quadrature formula on  $N$  points to (4.1), with weights  $\{c_j\}_{j=1}^N$  and nodes  $\{\xi_j\}_{j=1}^N$ , it is possible to approximate (1.1) as

$$\mathbf{y} = f(A)\mathbf{x} \approx \sum_{j=1}^N c_j (A + \xi_j I)^{-1} \mathbf{x}, \quad (4.2)$$

that is then computationally equivalent to the solution of  $N$  linear systems with the same right-hand side.

### 4.1 Module

The construction of the quadrature module is made of several interconnected modules. The base module is the `psfun_base_quadrature_mod`, it contains the base module of which the different quadratures are extensions.

#### Needed modules

- `psb_base_mod`
- `psb_prec_mod`
- `psb_krylov_mod`
- *`psfun_utils_mod`*

## Types

- type `psfun_base_quadrature_mod/unknown_type`

### Type fields

– % `desc_a` [*psb\_desc\_type*]

Then the functions for working with the quadrature formula having either real (`psb_dpk_`) or complex quadrature nodes and weights for (4.2) are contained in the relative modules.

## Description

This module computes the matrix-function vector product by means of the approximation of  $f(A)\mathbf{x}$  based on quadrature formula, i.e., having computed the poles and the scalings of the formula solves  $N$  linear systems to approximate the product.

## Quick access

**Routines** `psfun_d_quadratureplot()`

## Needed modules

- `psfun_base_quadrature_mod`
- `psb_base_mod`
- `psfun_utils_mod`
- `ogpf`

## Types

- type `psfun_d_quadrature_mod/unknown_type`

### Type fields

– % `a` [*psb\_dspmat\_type,pointer*]  
– % `c` (\*) [*real,allocatable*]  
– % `eta` [*real*]  
– % `prec` [*psb\_dprec\_type*]  
– % `sign` [*real*]  
– % `xi` (\*) [*real,allocatable*]

## Subroutines and functions

subroutine `psfun_d_quadrature_mod/psfun_d_quadratureplot`(*quad*, *dfun* [, *filename*, *info* ])

Plots on the complex plane the quadrature poles, and plots the weights of the formula

### Parameters

- **quad** :: Quadrature rule
- **dfun** :: Function to integrate
- **filename** [*character,in,*]
- **info** [*integer,out*]

Use `psb_base_mod`, `ogpf`

## Description

This module computes the matrix-function vector product by means of the approximation of  $f(A)\mathbf{x}$  based on quadrature formula, i.e., having computed the poles and the scalings of the formula solves  $N$  linear systems to approximate the product.

## Quick access

**Routines** `psfun_z_computepoles()`, `psfun_z_quadratureplot()`,  
`psfun_z_setmatrix()`, `psfun_z_setpreconditioner()`

## Needed modules

- `psfun_base_quadrature_mod`
- `psb_base_mod`
- `psfun_utils_mod`
- `ogpf`

## Types

- type `psfun_z_quadrature_mod/unknown_type`

### Type fields

- % `a` [`psb_dspmat_type`, `pointer`]
- % `c` (\*) [`complex`, `allocatable`]
- % `eta` [`real`]
- % `prec` [`psb_dprec_type`, `pointer`]
- % `sign` [`real`]
- % `xi` (\*) [`complex`, `allocatable`]

## Subroutines and functions

subroutine `psfun_z_quadrature_mod/psfun_z_computepoles`(`quad`, `quadformula`, `zfun`, `n`,  
`info`[, `cparams`[, `rparams`]])

### Parameters

- **quad** :: Quadrature type
- **quadformula** [`external`] :: Quadrature formula
- **zfun** :: Function to integrate
- **n** [`integer`, `in`] :: Number of poles
- **info** [`integer`, `out`] :: Flag on the results
- **cparams** (\*) [`complex`, `in`,] :: Optional complex parameters
- **rparams** (\*) [`real`, `in`,] :: Optional real parameters

Use `psb_base_mod`, `psfun_z_computepoles__user__routines`

subroutine `psfun_z_quadrature_mod/psfun_z_setmatrix`(`quad`, `a`)

**Parameters**

- **quad** :: Quadrature type
- **a** [*psb\_dspmat\_type,target*] :: Matrix on which we work

Use `psb_base_mod`

subroutine `psfun_z_quadrature_mod/psfun_z_setpreconditioner(quad, prec)`

**Parameters**

- **quad** :: Quadrature type
- **prec** [*psb\_dprec\_type,target*] :: Preconditioner for the solution of the associate linear systems

Use `psb_base_mod`

subroutine `psfun_z_quadrature_mod/psfun_z_quadratureplot(quad, zfun, info[, filename])`

Plots on the complex plane the quadrature poles, and plots the weights of the formula

**Parameters**

- **quad** :: Quadrature rule
- **zfun** :: Function to integrate
- **info** [*integer,out*]
- **filename** [*character,in,*]

Use `psb_base_mod`, `ogpf`

These two modules make use of `abstract interface` for both the subroutine `dquadrule`/subroutine `zquadrule` and the generic function for which we compute the  $f(A)$ . This is implemented this way to permit the user to implement its own quadrature rule and functions. An example of how this can be achieved is contained in the functions included in the submodule `psfun_z_quadrules_mod` that implements the three routines from [3].

subroutine `hhtmethod1(zfun, xi, c, eta, sign, n, info[, cparams[, rparams]])`

Method 1 of Hale, Nicholas; Higham, Nicholas J.; Trefethen, Lloyd N. Computing  $\|A\|^\alpha, \log(\|A\|)$ , and related matrix functions by contour integrals. SIAM J. Numer. Anal. 46 (2008), no. 5, 2505–2523.

**Parameters**

- **zfun** :: Function to integrate
- **xi** (\*) [*complex,out,allocatable*] :: Poles of the formula
- **c** (\*) [*complex,out,allocatable*] :: Scaling of the formula
- **eta** [*real,out*] :: Global Scaling
- **sign** [*real,out*] :: Sign for A
- **n** [*integer,in*] :: Number of Poles
- **info** [*integer,out*] :: Flag on the results
- **cparams** (\*) [*complex,in,*] :: Optional complex parameters
- **rparams** (\*) [*real,in,*] :: Optional real parameters

Use `psb_base_mod`, `psfun_utils_mod` (`ellipkjp()`, `ellipj()`)

## CHAPTER

# 5

## UTILS MODULE

The `utils` module contains some functions and subroutines which are used in various places in the library and which do not specifically belong to any of the other modules. Routines for the computation of some special functions, e.g., elliptic integrals, Jacobi polynomials, etc., together with some internal service routines.

### 5.1 Module

#### Quick access

**Variables** *dpi*

#### Needed modules

- `psb_base_mod`

#### Variables

- `psfun_utils_mod/dpi` [*real,parameter=4.0\_psb\_dpk\_\*atan(1.0\_psb\_dpk\_)*]/

### 5.2 External libraries

To make some plots with the [Gnuplot](#) software directly from the Fortran code, we distribute a modified version of the `ogpf` library.





## CHAPTER

# 6

## LIBRARY USAGE EXAMPLES

### 6.1 Utils examples

program utiltest

Use psb\_base\_mod, *psfun\_utils\_mod*

### 6.2 Serial examples

program serialtest

Test program for the serial part of the library. This test program loads a matrix from file together with some options to test the serial computation of the matrix functions. Substantially, it test the interfacing with the library doing the serial part.

Use psb\_base\_mod, *psfun\_d\_serial\_mod*, psb\_util\_mod (mm\_mat\_read(),  
mm\_array\_write())

### 6.3 Parallel examples

Polynomial Krylov method examples

program arnolditest

Test for the parallel computation of matrix function by means of the *psfun\_d\_arnoldi* function. It applies the classical Arnoldi orthogonalization algorithm on a distributed matrix.

Use psb\_base\_mod, psb\_util\_mod, *psfun\_d\_serial\_mod*, *psfun\_d\_krylov\_mod*

program lanczostest

Test for the parallel computation of matrix function by means of the *psfun\_d\_lanczos* function. It applies the classical Lanczos orthogonalization algorithm on a distributed matrix.

Use psb\_base\_mod, *psfun\_d\_serial\_mod*, *psfun\_d\_krylov\_mod*, psb\_util\_mod



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