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MACHINE CruiseMachine
SEES CruiseCtx
VARIABLES
       cruise_system_state
       cruise_speed_up
       cruise\_speed\_down
       brake_pedal_perc
       acc\_pedal\_perc
       cruise\_start\_stop
       current_speed
       acc\_pedal\_command
       brake_pedal_command
       cruise\_speed
INVARIANTS
       inv1: cruise\_system\_state \in BUTTON\_STATE
       inv2: cruise\_speed\_up \in BUTTON\_STATE
       inv3: cruise\_speed\_down \in BUTTON\_STATE
       inv4: brake\_pedal\_perc \in \mathbb{N}
       inv5: brake\_pedal\_perc \ge 0
       inv6: brake\_pedal\_perc \le 100
       inv7: acc\_pedal\_perc \in \mathbb{N}
       inv8: acc\_pedal\_perc \ge 0
       inv9: acc\_pedal\_perc \le 100
       inv10: cruise\_start\_stop \in BUTTON\_STATE
       inv11: cruise\_speed \in \mathbb{N}
       inv13: cruise\_speed \ge 1000
       inv14: cruise\_speed \in \mathbb{N}
       inv15: current\_speed \ge 0
       inv16: current\_speed < CAR\_MAX\_SPEED
       inv17: acc\_pedal\_command \in PEDAL\_COMMAND
       inv18: brake\_pedal\_command \in PEDAL\_COMMAND
EVENTS
Initialisation
      begin
            act1: cruise\_system\_state := FALSE
            act2: cruise\_speed\_up := FALSE
            act3: cruise\_speed\_down := FALSE
            act4: cruise\_start\_stop := FALSE
            act5: cruise\_speed := 50000
            act6: acc\_pedal\_perc := 0
            act7: brake\_pedal\_perc := 0
            act8: acc\_pedal\_command := 0
            act9: brake\_pedal\_command := 0
            act10: current\_speed := 0
      end
Event cruise_increase_speed \langle \text{ordinary} \rangle =
      when
            grd1: cruise\_system\_state = FALSE
            grd2: cruise\_speed\_up = TRUE
            grd3: cruise\_speed\_down = FALSE
            \verb|grd4: cruise\_speed| \leq CRUISE\_MAX\_SPEED - 2500
      then
            act1: cruise\_speed := cruise\_speed + 2500
```

end

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Event cruise_decrease_speed \langle \text{ordinary} \rangle =
      when
            grd1: cruise\_system\_state = FALSE
             grd2: cruise\_speed\_down = TRUE
             grd3: cruise\_speed\_up = FALSE
             grd4: cruise\_speed \ge 3500
      then
             act1: cruise\_speed := cruise\_speed - 2500
      end
Event cruise_start_stop (ordinary) \hat{=}
      when
             \mathbf{grd1:} \quad cruise\_start\_stop = TRUE
      then
             act1: cruise\_system\_state := CHANGE\_STATE(cruise\_system\_state)
      end
Event accelerate_vehicle (ordinary) \hat{=}
      when
             grd1: current_speed < cruise_speed</pre>
             grd2: cruise\_system\_state = TRUE
             grd3: brake\_pedal\_perc = 0
             grd4: brake\_pedal\_command = 0
      then
             act1: acc\_pedal\_command := 1
      end
Event decelerate_vehicle (ordinary) \hat{=}
      when
             grd1: current_speed > cruise_speed
            grd2: cruise\_system\_state = TRUE
             grd3: brake\_pedal\_perc = 0
             grd4: acc\_pedal\_perc > 0
      then
             act1: acc\_pedal\_command := 2
      end
Event increase_acc_pedal \langle \text{ordinary} \rangle =
      when
             grd1: acc\_pedal\_command = 1
             grd2: acc\_pedal\_perc \le 98
            grd3: cruise\_system\_state = TRUE
      then
             act1: acc\_pedal\_command := 0
             act2: acc\_pedal\_perc := acc\_pedal\_perc + 2
      end
Event decrease_acc_pedal (ordinary) \hat{=}
      when
             grd1: acc\_pedal\_command = 2
             grd2: acc\_pedal\_perc \ge 2
             grd3: cruise\_system\_state = TRUE
      then
             act1: acc\_pedal\_command := 0
             act2: acc\_pedal\_perc := acc\_pedal\_perc - 2
      end
Event increase_brake_pedal \langle \text{ordinary} \rangle =
      when
             grd1: brake\_pedal\_command = 1
             grd2: brake\_pedal\_perc \le 98
             grd3: cruise\_system\_state = TRUE
      then
             act1: brake\_pedal\_command := 0
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