

**CALIFORNIA STATE POLYTECHNIC UNIVERSITY, POMONA
COLLEGE OF ENGINEERING**

ECE 3301L Spring 2019 Session 2 Microcontroller Lab

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**LAB3
Introduction to Assembly language**

PART A)

This lab will expose you to the concept of writing PIC18 assembly language. For this purpose, we are going to implement a simple code. Let us take the following exercise:

Pseudo C Code:

Initialize PORTA as an output port

```
while (1)
{
    turn on the LED;
    wait();
    turn off the LED;
    wait();
}
```

Or the actual c code:

```
void main()
{
    ADCON1 = 0x0F;           // Force Ports A & B to be all digital
    TRISA= 0x00;             // set PORTA as outputs

    while (1)
    {
        PORTA = 0x0A;        // set bits 1 and 3 of PORTA on
        for (i=0xFF; i>0; i--) // wait for (outer loop)
        {
            for (j=0xFF; j>0; j--); // inner wait loop
        }

        PORTA = 0x05;        // set bits 0 and 2 of PORTA on
        for (i=0xFF; i>0; i--) // wait for (outer loop)
        {
            for (j=0xFF; j>0; j--); // inner wait loop
        }
    }
}
```

In this lab, we are going to write in Assembly language instead of C language. As you are familiar by now with the use of MPLAB X, you will need to do the same to compile an assembly program as you have done in lab#2. The only differences are in two areas.

First, instead of selecting the XC8 compiler, you will need to select the 'mpasm' option.

Second, the next difference is in the creation of the new file. We are not going to use the C source code but instead the Assembly source code. When you are at the step to add the new file, do File>New File. A new window will appear. Select 'Assembler' and then 'AssemblyFile.asm' and hit Next. You will need to enter the new file name. In this case, I would call it 'Lab3p1'. Hit Finish.

The next phase is to create the assembly file. Copy the following text and paste into the file.

```
; THIS FIRST ASSEMBLY LANGUAGE PROGRAM WILL FLASH AN LED CONNECTED  
; TO THE PINS 0 THROUGH 3 OF PORT B
```

```
#include<P18F4321.inc>
```

```
config    OSC = INTIO2  
config    WDT = OFF  
config    LVP = OFF  
config    BOR = OFF
```

```
; Constant declarations
```

```
Delay1 equ    0xFF  
Delay2 equ    0xFF
```

```
ORG        0x0000
```

```
; CODE STARTS FROM THE NEXT LINE
```

```
START:
```

```
MOVLW      0x0F          ; Load W with 0x0F0  
MOVWF      ADCON1        ; Make ADCON1 to be all digital  
  
MOVLW      0x00          ; Load W with 0x00  
MOVWF      TRISA         ; Make PORT A as outputs
```

```
MAIN_LOOP:
```

```
MOVLW      0x0A          ; Load W with value 0x0A  
MOVWF      PORTA         ; Output to PORT A
```

; NESTED DELAY LOOP

```
    MOVLW    Delay1    ; Load constant Delay1 into W
    MOVWF    0x21      ; Load W to memory 0x21
```

LOOP_OUTER_1:

```
    NOP                ; Do nothing
    MOVLW    Delay2    ; Load constant Delay2 into W
    MOVWF    0x20      ; Load W to memory 0x20
```

LOOP_INNER_1:

```
    NOP                ; Do nothing
    DECF     0x20,F     ; Decrement memory location 0x20
    BNZ      LOOP_INNER_1 ; If value not zero, go back to LOOP_INNER_1
```

```
    DECF     0x21,F     ; Decrement memory location 0x21
    BNZ      LOOP_OUTER_1 ; If value not zero, go back to LOOP_OUTER_1
```

```
    MOVLW    0x05      ; Load W with value 0x05
    MOVWF    PORTA     ; Output to PORT A (flipping the LEDs)
```

; NESTED DELAY LOOP AGAIN

```
    MOVLW    Delay1    ; Load constant Delay1 into W
    MOVWF    0x21      ; Load W to memory 0x21
```

LOOP_OUTER_2:

```
    NOP                ; Do nothing
    MOVLW    Delay2    ; Load constant Delay2 into W
    MOVWF    0x20      ; Load W to memory 0x20
```

LOOP_INNER_2:

```
    NOP                ; Do nothing
    DECF     0x20,F     ; Decrement memory location 0x20
    BNZ      LOOP_INNER_2 ; If value not zero, go back to LOOP_INNER_2
```

```
    DECF     0x21,F     ; Decrement memory location 0x21
    BNZ      LOOP_OUTER_2 ; If value not zero, go back to LOOP_OUTER_2
```

; START ALL OVER AGAIN

```
    GOTO     MAIN_LOOP ;Go back to main loop
    END
```

When done, do ‘File’ and ‘Save’.

You can now build and download your program to the controller board just like you have done in the previous lab.

You will need to use the connections from the previous lab (Lab #2). The four LEDs connected to PORTA should be used. If your program was built properly, the LEDs should blink at a constant speed.

PART B)

The next example is to read the four switches connected to PORT B and display them to the LEDs connected to PORTA. This is the same exercise as PART 2) of Lab #2.

Pseudo C Code:

```
IN = PORTB & 0x0F;  
PORTA = IN;
```

Compile and run the following program (make sure that this is in a new folder called lab3p2):

```
; THIS SECOND ASSEMBLY LANGUAGE PROGRAM WILL READ THE VALUES OF  
; ALL THE BITS 0-3 OF PORT A AND OUTPUT THEM  
; TO THE PINS 0 THROUGH 3 OF PORT B
```

```
#include<P18F4321.inc>
```

```
config    OSC = INTIO2  
config    WDT = OFF  
config    LVP = OFF  
config    BOR = OFF
```

```
ORG       0x0000
```

START:

```
MOVLW     0x0F           ; Load W with 0x0F0  
MOVWF     ADCON1         ; Make ADCON1 to be all digital
```

```
MOVLW     0xFF           ; Load W with 0xFF  
MOVWF     TRISB          ; Set PORT B as all inputs
```

```
MOVLW     0x00           ; Load W with 0x00  
MOVWF     TRISA          ; Make PORT A as outputs
```

MAIN_LOOP:

```
MOVF      PORTB, W       ; Read from PORT A and move it into W  
ANDLW     0x0F           ; Mask with 0x0F  
MOVWF     PORTA          ; Move from W to PORT A
```

```
GOTO      MAIN_LOOP      ; Loop forever
```

```
END
```

PART C)

The third example is to test the switch at PORT B Bit 0 and to set/clear bits 0 and 1 of PORTA according to the logic state of that bit.

If PORT B Bit 0 = 0, then set bit 0 and clear bit 1 of PORTA

If PORTB Bit 0 = 1, then clear bit 0 and set bit 1 of PORTA.

Pseudo C Code:

```
if ((PORTB & 0x01) == 0) PORTA = 0x01;
else PORTA = 0x02;
```

Compile and run the following program:

```
#include<P18F4321.inc>
```

```
config    OSC = INTIO2
config    WDT = OFF
config    LVP = OFF
config    BOR = OFF
```

```
ORG       0x0000
```

```
; CODE STARTS FROM THE NEXT LINE
```

```
START:
```

```
MOVLW     0xFF      ; Load W with 0xFF
MOVWF     TRISB      ; Set PORT B as all inputs

MOVLW     0x00      ; Load W with 0x00
MOVWF     TRISA      ; Make PORTA bits 0-7 as outputs

MOVLW     0x0F      ; Load W with 0x0F
MOVWF     ADCON1     ; Set ADCON1
```

```
MAIN_LOOP:
```

```
BTFSC     PORTB, 0   ; If Bit 0 of PORTB = 0 skip the next instruction
GOTO      CASEB1     ; else go to CASEB1 (PORTB Bit 0 = 1)
```

```
CASEB0:
```

```
BSF        PORTA, 0   ; case PORTB bit 0 = 0, set bit 0 of PORTA
BCF        PORTA, 1   ; and clear bit 1 of PORTA
GOTO      LOOP       ; go back to Main Loop
```

```
CASEB1:
```

```
BCF        PORTA, 0   ; case PORTB bit 0 = 1, clear bit 0 of PORT A
BSF        PORTA, 1   ; set bit 1 of PORTA
GOTO      MAIN_LOOP  ; go back to Loop
```

PART D)

Take the Assembly program below and modify it to meet the following conditions:

- 1) The RGB LED at D1 should show the color RED.
- 2) The RGB LED at D2 should show the color WHITE.
- 3) Both LEDs D1 and D2 should blink ON and OFF with a period of 20 msec (10 msec being ON and 10 msec being OFF)
- 4) Place a scope probe at the pin of either D1 or D2 with the active color to measure the period of that signal. The precision should be at +/- 0.2 msec.

```
#include<P18F4321.inc>
```

```
config          OSC = INTIO2
config          WDT = OFF
config          LVP = OFF
config          BOR = OFF

Color_PORTC     equ    0x??    ;<- replace ?? with proper value
Color_PORTD     equ    0x??    ;<- replace ?? with proper value
Color_Off       equ    0x??    ;<- replace ?? with proper value

OUTER_VALUE     equ    0x??    ;<- replace ?? with proper value
INNER_VALUE     equ    0x??    ;<- replace ?? with proper value

ORG             0x0000

; CODE STARTS FROM THE NEXT LINE

START:

    MOVLW       0x00           ; Load W with 0x00
    MOVWF       TRISC         ; Make PORT C bits 0-7 as outputs
    MOVWF       TRISD         ; Make PORT D bits 0-7 as outputs

MAIN_LOOP:

    MOVLW       Color_PORTC    ; Load W with the desired color for PORTC
    MOVWF       0x22           ; save desired color into register 0x22
    MOVLW       Color_PORTD    ; Load W with the desired color for PORTD
    MOVWF       0x23           ; save desired color into register 0x23

    MOVLW       OUTER_VALUE    ; Load OUTER_VALUE into W
    MOVWF       0x24           ; save it o register 0x24

    MOVLW       INNER_VALUE    ; Load INNER_VALUE into W
    MOVWF       0x25           ; save it to register 0x25
```

COLOR_LOOP:

```
MOVFF    0x22,PORTC    ; Get saved color of PORTC and output to that Port
MOVFF    0x23,PORTD    ;Get saved color of PORTD and output to that Port
MOVFF    0x24,0x21     ; Copy saved outer loop cnt from 0x24 to 0x21
```

; NESTED DELAY LOOP TO HAVE THE FIRST HALF OF WAVEFORM

LOOP_OUTER_1:

```
NOP                      ; Do nothing
MOVFF    0x25,0x20      ; Load saved inner loop cnt from 0x25 to 0x20
```

LOOP_INNER_1:

```
NOP                      ; Do nothing
DECF     0x20,F          ; Decrement memory location 0x20
BNZ LOOP_INNER_1        ; If value not zero, go back to LOOP_INNER_1
```

```
DECF     0x21,F          ; Decrement memory location 0x21
BNZ LOOP_OUTER_1        ; If value not zero, go back to LOOP_OUTER_1
```

```
MOVLW    Color_Off      ; Load W with the second desired color
MOVWF    PORTC           ; Output to PORT C to turn off the RGB LED D1
MOVWF    PORTD           ; Output to PORT D to turn off the RGB LED D2
MOVFF    0x24,0x21      ; Copy saved outer loop cnt from 0x24 to 0x21
```

; NESTED DELAY LOOP TO HAVE THE FIRST HALF OF WAVEFORM BEING LOW

LOOP_OUTER_2:

```
NOP                      ; Do nothing
MOVFF    0x25,0x20      ; Load saved inner loop cnt from 0x25 to 0x20
```

LOOP_INNER_2:

```
NOP                      ; Do nothing
DECF     0x20,F          ; Decrement memory location 0x20
BNZ LOOP_INNER_2        ; If value not zero, go back to LOOP_INNER_2
```

```
DECF     0x21,F          ; Decrement memory location 0x21
BNZ LOOP_OUTER_2        ; If value not zero, go back to LOOP_OUTER_2
```

; START ALL OVER AGAIN

```
GOTO     MAIN_LOOP      ; Go back to main loop
END
```

PART E)

Take the Assembly program in part D and modify it to meet the following conditions:

- 1) Use the two switches connected to PORT B bits 1 and 0 as inputs.
- 2) Based on those two inputs, make the LED D1 blink ON and OFF with the color and frequency as indicated on the table below. **The LED D2 will always blink with the WHITE color**
- 3) Place a scope probe at any pin of D2 to measure the period of that signal. The precision should be at +/-0.2 msec. Since D2 is always WHITE, any pin of D2 should reflect the blinking period of the LED D1

PORT B		RGB LED D1 at PORT D bits 0-2
Bit_1	Bit_0	Action
0	0	RED color blinking every 20 msec
0	1	GREEN color blinking every 40 msec
1	0	BLUE color blinking every 80 msec
1	1	WHITE color blinking every 160 msec

Hint:

- 1) Make sure to start the program by setting the TRISB, TRISC and TRISD registers for proper direction of the input and output pins. Also, don't forget to program the ADCON1 register.
- 2) Use the 'BTFSC' instruction to test the logic state of the input bit you want to check.
- 3) Add codes between the labels 'MAIN_LOOP' and 'COLOR_LOOP' to determine what color to output and how long to generate the timing for that color. Use the instruction 'BTFSC' used in PART C) to test the bits of PORTB to determine the color to display