

R4

1.

$$(1) I = \frac{1}{3} ML^2$$

$$(2) I \ddot{\theta} = -Mg \sin \theta \cdot \frac{L}{2}$$

$$\therefore \frac{1}{3} ML^2 \cdot \ddot{\theta} = -\frac{1}{2} MgL \sin \theta$$

$$(3) \ddot{\theta} = \frac{3}{ML^2} \cdot \left(-\frac{1}{2} MgL \sin \theta \right) = -\frac{3g}{2L} \cdot \theta$$

$$\therefore T = 2\pi \sqrt{\frac{2L}{3g}}$$

$$(4) \frac{1}{2} I \dot{\theta}(0)^2 = Mg \cdot \frac{L}{2}$$

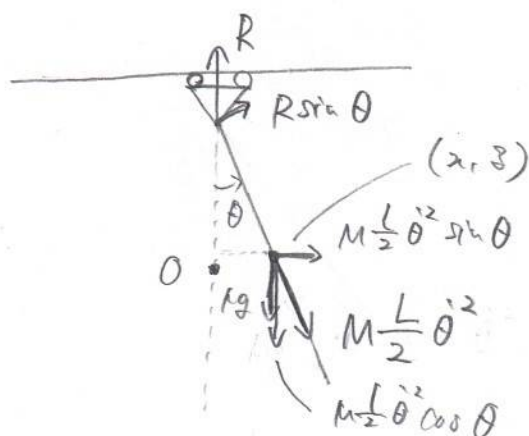
$$\therefore \frac{1}{2} \cdot \frac{1}{3} ML^2 \cdot \frac{v^2}{L^2} = \frac{MgL}{2}$$

$$v^2 = 3gL$$

$$\therefore v = \sqrt{3gL}$$

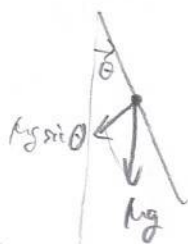
$$(5) I' = \frac{1}{12} ML^2$$

(6)



$$\begin{cases} M\ddot{x} = M \frac{L}{2} \ddot{\theta}^2 \sin \theta & - (1) \\ M\ddot{y} = R - M \frac{L}{2} \ddot{\theta}^2 \cos \theta - Mg & - (2) \\ I' \ddot{\theta} = -R \sin \theta \cdot \frac{L}{2} & - (3) \end{cases}$$

$$I = \int_0^L \frac{M}{L} x^2 dx = \frac{M}{L} \cdot \frac{1}{3} L^3 = \frac{1}{3} ML^2$$

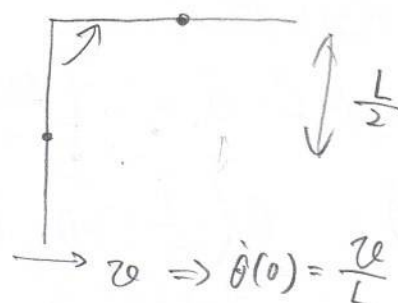


$$\omega = \sqrt{\frac{3g}{2L}}$$

$$v = r\omega$$

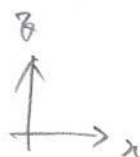
$$\omega = \frac{v}{r}$$

$$T = 2\pi \sqrt{\frac{2L}{3g}}$$



$$I' = \int_{-L/2}^{L/2} \frac{M}{L} x^2 dx$$

$$= 2 \cdot \frac{M}{L} \cdot \frac{1}{3} \cdot \frac{L^3}{8} = \frac{1}{12} ML^2$$



$$(7) \quad z = \frac{L}{2} - \frac{L}{2} \cos \theta = \frac{L}{2} (1 - \cos \theta)$$

$$\dot{z} = \frac{L}{2} \sin \theta \cdot \dot{\theta}$$

$$\ddot{z} = \frac{L}{2} \cos \theta \cdot \dot{\theta}^2 + \frac{L}{2} \sin \theta \cdot \ddot{\theta}$$

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$$\frac{ML}{2} \cos \theta \cdot \dot{\theta}^2 + \frac{ML}{2} \sin \theta \cdot \ddot{\theta} = R - \frac{ML}{2} \cos \theta \cdot \dot{\theta}^2 - Mg$$

$$\therefore R = \frac{ML}{2} \sin \theta \cdot \ddot{\theta} + ML \cos \theta \cdot \dot{\theta}^2 + Mg$$

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$$\frac{1}{2} ML^2 \cdot \ddot{\theta} = - \left(\frac{ML}{2} \sin \theta \cdot \ddot{\theta} + ML \cos \theta \cdot \dot{\theta}^2 + Mg \right) \sin \theta \cdot \frac{L}{2}$$

$$\ddot{\theta} = -6 \left(\frac{1}{2} \sin \theta \cdot \ddot{\theta} + \cos \theta \cdot \dot{\theta}^2 + \frac{g}{L} \right) \sin \theta$$

$$= -3 \sin^2 \theta \cdot \ddot{\theta} - 6 \sin \theta \cos \theta \cdot \dot{\theta}^2 - \frac{6g}{L} \sin \theta$$

$$\therefore \ddot{\theta} = - \frac{6 \sin \theta \cos \theta \cdot \dot{\theta}^2 + \frac{6g}{L} \sin \theta}{1 + 3 \sin^2 \theta}$$

$$(8) \quad \ddot{\theta} \approx - \frac{6g}{L} \theta$$

$$\therefore T = 2\pi \sqrt{\frac{L}{6g}}$$

$$\omega = \sqrt{\frac{6g}{L}}$$

$$T = 2\pi \sqrt{\frac{L}{6g}}$$

3.

I.

$$m v_x - (-u v_x) = 2u v_x$$

$$k_B = \frac{R}{N_A}$$

$$(P) \frac{v_x t}{2L}$$

$$(1) 2m v_x \cdot \frac{v_x t}{2L} = \frac{m v_x^2 t}{L}$$

(2) 体積

$$(3) \frac{1}{2} k_B T$$

$$(4) \frac{3}{2} k_B T$$

$$(5) 2$$

$$(6) \frac{5}{2} k_B T$$

$$(7) \frac{5}{2} R$$

$$F = N \cdot \frac{m \overline{v_x^2}}{L} = \frac{Nm \overline{v_x^2}}{L}$$

$$P = \frac{Nm \overline{v_x^2}}{L^3}$$

$$\overline{v_x^2} = \frac{1}{3} \overline{v^2}$$

$$PV = Nm \overline{v_x^2}$$

$$\frac{1}{2} m \frac{1}{3} \overline{v^2} = \frac{1}{2} k_B T \quad \frac{1}{2} RT = N_A \frac{1}{2} m \overline{v^2}$$

$$\frac{1}{2} m \overline{v^2} = \frac{3}{2} k_B T \quad \frac{1}{2} m \overline{v_x^2} = \frac{1}{2} \frac{R}{N_A} T$$

$$U = \frac{5}{2} k_B T \cdot N_A = \frac{5}{2} RT$$

II.

$$(1) T_H = \frac{PAV_1}{nR}$$

$$(2) \Delta U = 0$$

$$\begin{aligned} (3) Q_{AB} &= W_{AB} = \int_{A \rightarrow B} P dv \\ &= \int_{V_1}^{V_2} \frac{nRT_H}{V} dV \\ &= nRT_H \ln \frac{V_2}{V_1} \quad \text{— 吸熱} \\ &= PAV_1 \ln \frac{V_2}{V_1} \end{aligned}$$

$$\frac{nRT_H \ln \frac{V_2}{V_1} - nRT_L \ln \frac{V_2}{V_1}}{nRT_H \ln \frac{V_2}{V_1} + \frac{3}{2} nR(T_H - T_L)}$$

$$(4) Q_{BC} = \frac{3}{2} nR(T_L - T_H) \quad \text{— 放熱}$$

$$Q_{CD} = nRT_L \ln \frac{V_1}{V_2} \quad \text{— 放熱}$$

$$Q_{DA} = \frac{3}{2} nR(T_H - T_L) \quad \text{— 吸熱}$$

$$(5) \eta = \frac{Q_{AB} + Q_{BC} + Q_{CD} + Q_{DA}}{Q_{AB} + Q_{DA}} = \frac{(T_H - T_L) \ln \frac{V_2}{V_1}}{T_H \ln \frac{V_2}{V_1} + \frac{3}{2} (T_H - T_L)}$$

$$(5) \eta' = \frac{Q_{AB} + Q_{BC} + Q_{CD} + Q_{DA}}{Q_{AB}} = \frac{(T_H - T_L) \ln \frac{V_2}{V_1}}{T_H \ln \frac{V_2}{V_1}} = 1 - \frac{T_L}{T_H}$$