

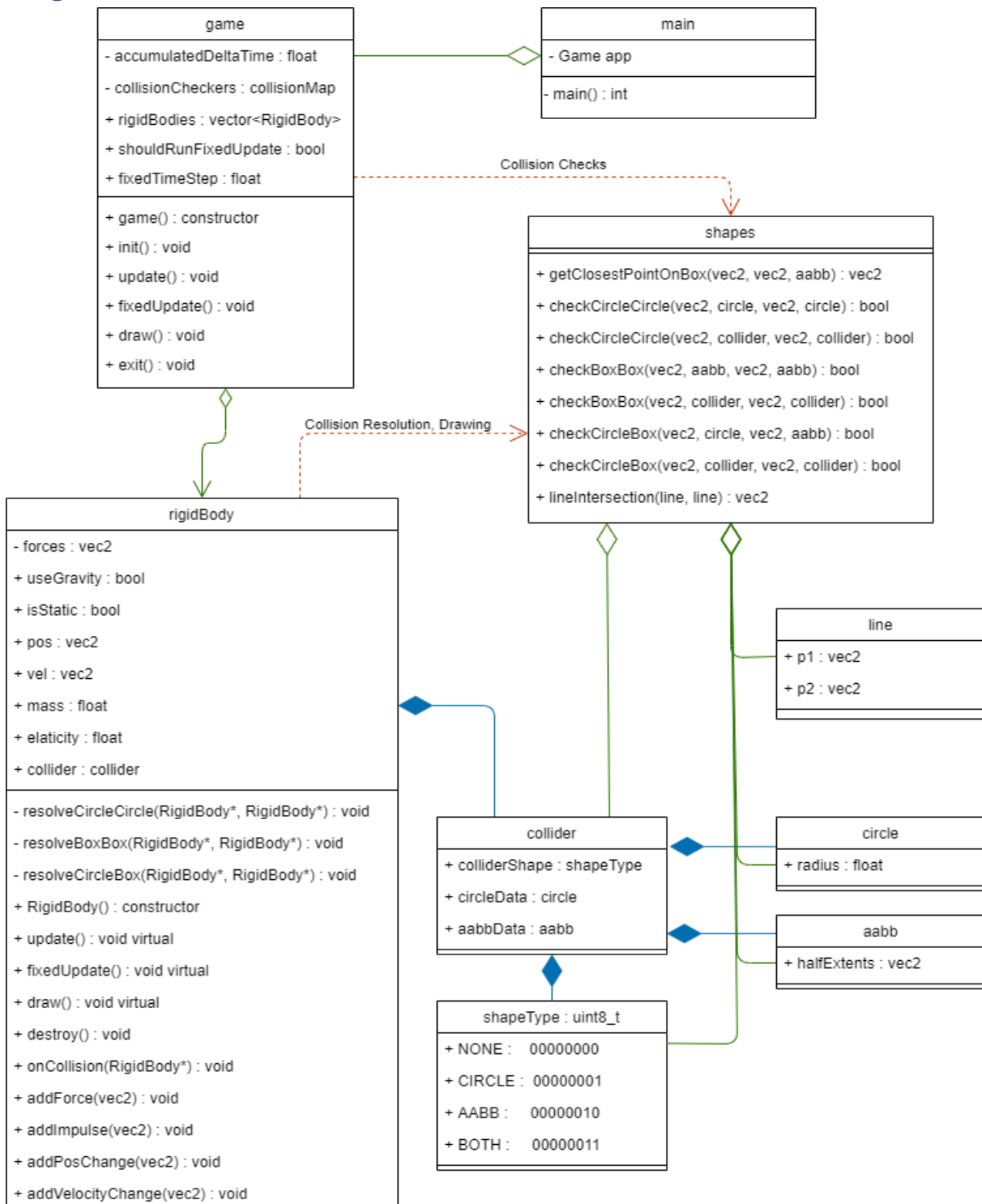
Custom Physics Simulation

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Demonstration Brief

Just a basic window that lets you spawn in circles by left clicking and squares by right clicking. Hold left control to disable gravity on newly spawned objects.

Class Diagram



Research Material

https://www.youtube.com/watch?v=3HjO_RGljCU&t=2s - Line Intersection

<https://en.cppreference.com/w/cpp/container/vector> - Vectors

Third Party Libraries

<https://github.com/g-truc/glm> - Math library used in project

<https://github.com/AIE-Seattle-Prog/raygame> - Window Rendering library used

Public API

class game

vector<[Rigidbody](#)> rigidBodies

Container of every [RigidBody](#) in the Game. After being spawned they should be added to this container. A [RigidBody](#) will erase itself from the vector if the [Destroy\(\)](#) function is called.

bool shouldRunFixedUpdate

Flag that gets set to true every [fixedTimeStep](#) seconds. This can be set true manually for an extra [fixedUpdate\(\)](#) call. This will not alter the timing of the next [fixedUpdate\(\)](#) call.

float fixedTimeStep

The target amount of time between every time [fixedUpdate\(\)](#) is called.

game() - constructor

Initialize all variables to suitable defaults.

void init()

Create our window and initialize our rendering context.

void update()

Called 60 times a second. Used for updating all the logic of our game.

void fixedUpdate()

Called every [fixedTimeStep](#) amount of seconds. Use for handling physics.

void draw()

Calls the [draw\(\)](#) function on every [RigidBody](#).

void exit()

Shuts down game and closes window.

class RigidBody

bool useGravity

If true this [RigidBody](#) will constantly be pulled downward.

bool isStatic

If true this [RigidBody](#) will not move around by physics at all and can only move by manually changing its [pos](#).

vec2 pos

The position in world space of this [RigidBody](#).

vec2 vel

Velocity of [RigidBody](#) in window pixels per second.

float mass

Mass of the [RigidBody](#).

float elasticity

The amount of energy kept after bouncing off another object 0.0 – 1.0.

[collider](#) collider

The collider and shape of the [RigidBody](#).

RigidBody() - constructor

Initializes all variables to default values.

void virtual update()

Updates logic of the [RigidBody](#).

void virtual fixedUpdate()

Updates physics, [pos](#), and forces of the [RigidBody](#).

void virtual draw()

Draws the [RigidBody](#)'s [collider](#).

void destroy()

Erases this [RigidBody](#) from [game::rigidbodies](#) deleting it from the game.

void onCollision([RigidBody](#)* other)

Called when this [RigidBody](#) contacts another [RigidBody](#), then calls the proper resolution function.

void addForce(vec2 force)

Creates a recurring force to alter the [RigidBody](#)'s [vel](#). Does not affect [static RigidBodies](#).

void addImpulse(vec2 impulse)

Instantly pushes the impulse against the [RigidBody](#). Does not affect [static RigidBodies](#).

void addPosChange(vec2 change)

Directly moves the [RigidBody](#)'s [pos](#) regardless of [mass](#) and other forces. Does not affect [static RigidBodies](#).

void addVelocityChange(vec2 velChange)

Directly changes the [RigidBody](#)'s [vel](#) regardless of [mass](#) and other forces. Does not affect [static RigidBodies](#).

shapes.h

vec2 getClosestPointOnBox(vec2 pos, vec2 posBox, [aabb](#) box)

Returns the point within the [aabb](#) that is closest to [pos](#) in local space relative to the [aabb](#).

bool checkCircleCircle(vec2 posA, [circle](#) circleA, vec2 posB, [circle](#) circleB)

Returns true if the [circles](#) are colliding.

bool checkCircleCircle(vec2 posA, [collider](#) circleA, vec2 posB, [collider](#) circleB)

Returns true if the [circles](#) are colliding. [Colliders](#) must contain [circleData](#).

bool checkBoxBox(vec2 posA, [aabb](#) boxA, vec2 posB, [aabb](#) boxB)

Returns true if the [boxes](#) are colliding.

bool checkBoxBox(vec2 posA, [collider](#) boxA, vec2 posB, [collider](#) boxB)

Returns true if the [boxes](#) are colliding. [Colliders](#) must contain [aabbData](#).

bool checkCircleBox(vec2 posA, [circle](#) circle, vec2 posB, [aabb](#) box)

Returns true if the [circle](#) and [box](#) are colliding.

bool checkCircleBox(vec2 posA, [collider](#) circle, vec2 posB, [collider](#) box)

Returns true if the [circle](#) and [box](#) are colliding. [Colliders](#) must contain [circleData](#) and [aabbData](#) respectively.

bool checkCirclePoint(vec2 pos, vec2 posCirc, [circle](#) circle)

Returns true if the point is within the bounds of the [circle](#).

bool checkBoxPoint(vec2 pos, vec2 posBox, [aabb](#) box)

Returns true if the point is within the bounds of the [box](#).

bool checkPoint(vec2 pos, vec2 posObj, [collider](#) col)

Returns true if the point is within the bounds of the [collider](#). Can use either [circle](#) or [aabb](#).

vec2 lineIntersection([line](#) a, [line](#) b)

Returns the point of intersection for the two [lines](#). Parallel lines will return a vec2 of { 0,0 }.

struct collider

[shapeType](#) colliderShape

Stores what data should be accessed, either [CIRCLE](#) or [AABB](#). Both [circleData](#) and [aabbData](#) read/write to the same memory location so only one can be used per collider.

[circle](#) circleData

Stores [circle](#) data.

[aabb](#) aabbData

Stores [aabb](#) data.

struct circle

float radius

Radius of the [circle](#).

struct aabb

vec2 halfExtents

Size of the [aabb](#) divided by 2.

struct shapeType : uint8_t

NONE

Shorthand for 00000000.

CIRCLE

Shorthand for 00000001.

AABB

Shorthand for 00000010.

BOTH

Shorthand for 00000011.

struct line

vec2 p1

One point on the [line](#).

vec2 p2

Second point on the [line](#).

Potential Future Improvements

- Add raycasting.
- Add support for more shapes.
- Add spatial partitioning.

Credits

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