



ICLR



NEURAL INFORMATION
PROCESSING SYSTEMS

Carnegie
Mellon
University

Penn
UNIVERSITY OF PENNSYLVANIA

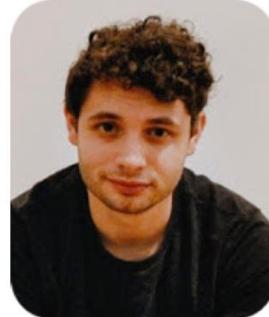
Microsoft

Thinking Fast with Transformers

Algorithmic Reasoning with Shortcuts



Bingbin Liu
CMU



Jordan T. Ash
MSR NYC



Surbhi Goel
UPenn

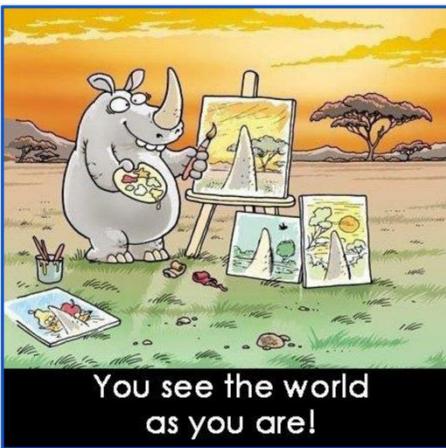
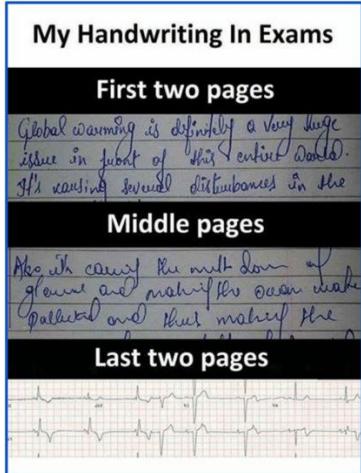


Akshay Krishnamurthy
MSR NYC



Cyril Zhang
MSR NYC

Reasoning in language models



```
9 // Get average runtime of successful runs in seconds
10 func averageRuntimeInSeconds(runs []Run) float64 {
11     var totalTime int
12     var failedRuns int
13     for _, run := range runs {
14         if run.Failed {
15             failedRuns++
16         } else {
17             totalTime += run.Time
18         }
19     }
20
21     averageRuntime := float64(totalTime) / float64(len(runs) - failedRuns) / 1000
22     return averageRuntime
}
```



GitHub Co-Pilot



Powerful and practically useful.



Unreliable with incorrect answers.

Capabilities and limitations?



Yes, I can help you with binary addition! Binary numbers use base 2, which means there are only two digits: 0 and 1. To add

⋮



So, the final result is:

111013011 3?

Agenda

*Q: How can **parallel** models such as Transformers model **sequential reasoning**?*

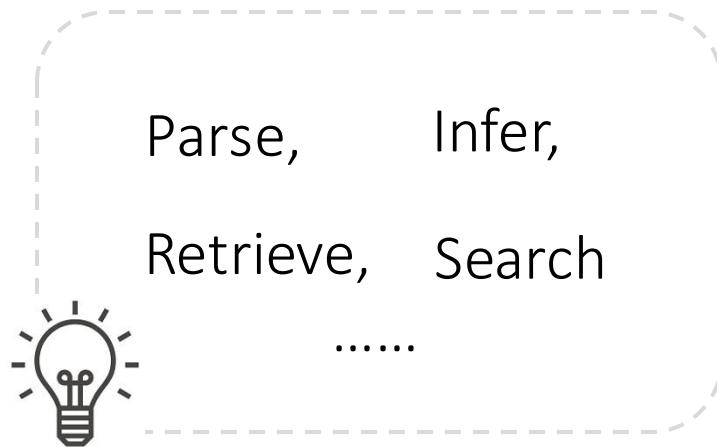
Formalizing with **automata**:



- Capabilities in theory (representational)
- Solutions found in practice (optimization, generalization)

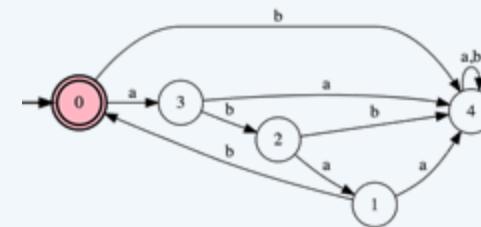
TL;DR: Transformers reason with **shallow solutions**, with computational advantages but statistical issues.

Formalizing reasoning



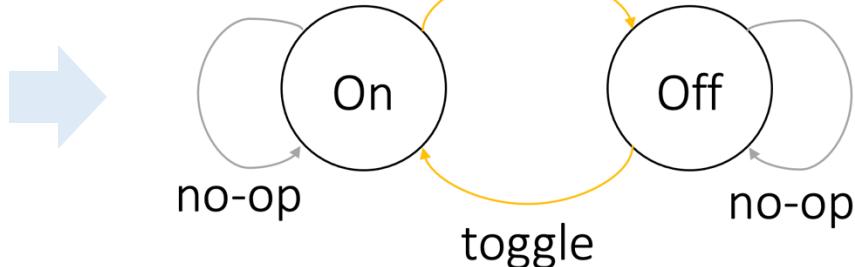
execute symbolic computations*

Transitions of discrete state machines



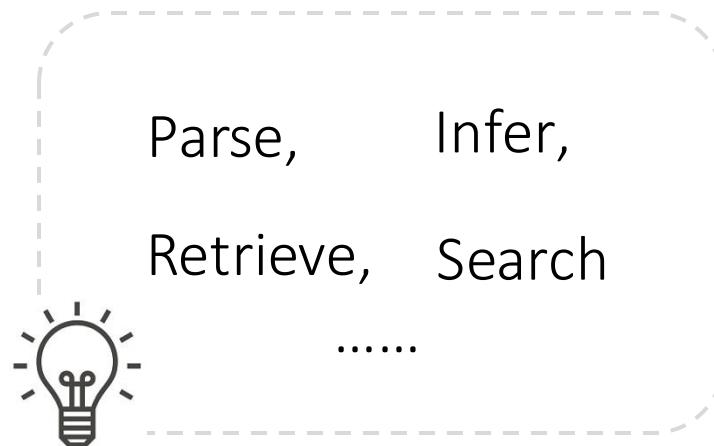
parity

An **on-off** switch is off.
(actions: **toggle** or **not**)
Now the switch is **?**.



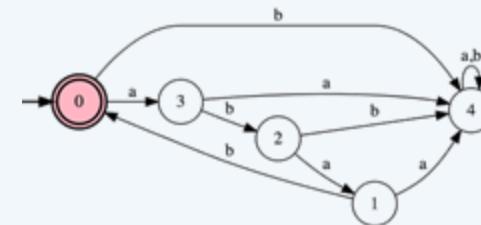
[Han 20, Anil et al. 22]

Formalizing reasoning



execute symbolic computations*

Transitions of
finite state machines



An on-off switch is off.
(actions: toggle or not)
Now the switch is ?.

Parity

[Han 20, Anil et al. 22]

$$\begin{array}{r} 00010011 \\ + 10100110 \\ \hline 10111001 \end{array}$$

Addition

[Nogueira et al. 21]

example@cmu.edu
@([a-zA-Z0-9_.+-]+)\.([a-zA-Z0-9_.+-])

Regular expressions

[Bhattamishra et al. 20]

```
12 <div>
13   <div>
14     <div>
15       <ul>
16         <li></li>
17         <li></li>
18         <li></li>
19         <li></li>
20       </ul>
21     </div>
22   </div>
23 </div>
```

Bounded nested brackets

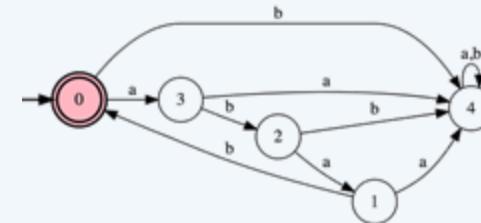
[Yao et al. 21]

Formalizing reasoning

Wide ranges of reasoning tasks

finite-state automata \leftrightarrow regular languages

Transitions of
finite state machines



An on-off switch is off.
(actions: toggle or not)
Now the switch is ?.

Parity

[Han 20, Anil et al. 22]

$$\begin{array}{r} 00010011 \\ + 10100110 \\ \hline 10111001 \end{array}$$

Addition

[Nogueira et al. 21]

example@cmu.edu

Regular expressions
[Bhattamishra et al. 20]

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20       </ul>
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22   </div>
23 </div>
```

Bounded nested brackets
[Yao et al. 21]

Formalizing reasoning with automata



(will reappear later)

Task: modeling the dynamics of \mathcal{A} .

Task: Simulating automata

$$\mathcal{A} = (Q, \Sigma, \delta)$$

states, inputs, transitions

Simulating \mathcal{A} : learn a *seq2seq function* for sequence length T .

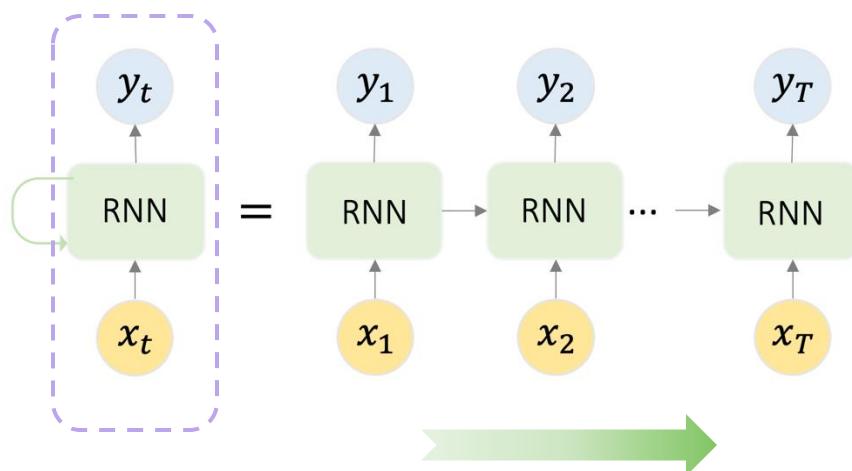
- Input = $\sigma_1, \sigma_2, \dots, \sigma_T \in \Sigma$ (alphabet), output = $q_1, q_2, \dots, q_T \in Q$ (states).

Architecture choices

RNN

sequential across positions

Natural for $q_t = \delta(q_{t-1}, \sigma_t)$

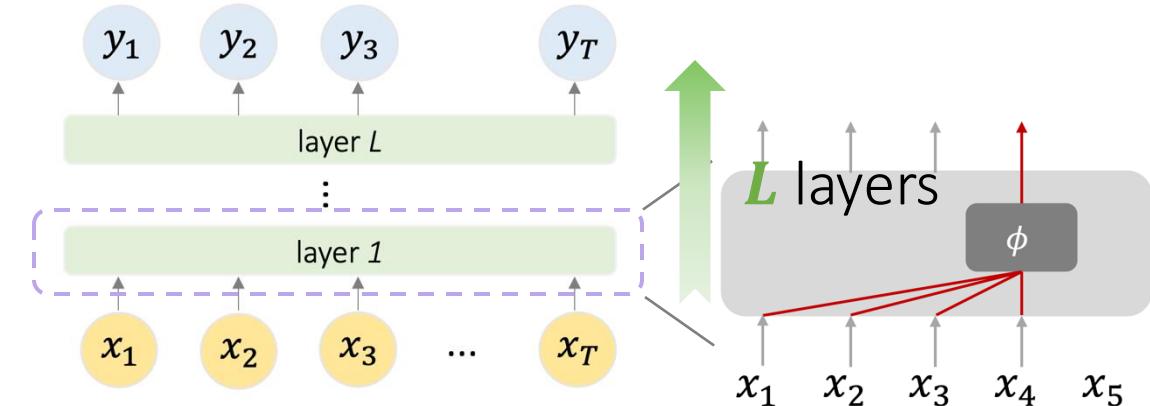


$\textcolor{teal}{T}$ positions

Transformer

parallel across positions

sequential across layers



Typically $L \ll T$.

Task: Simulating automata

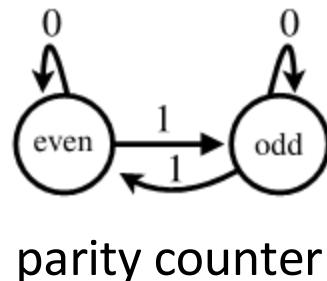
$$\mathcal{A} = (Q, \Sigma, \delta)$$

states, inputs, transitions

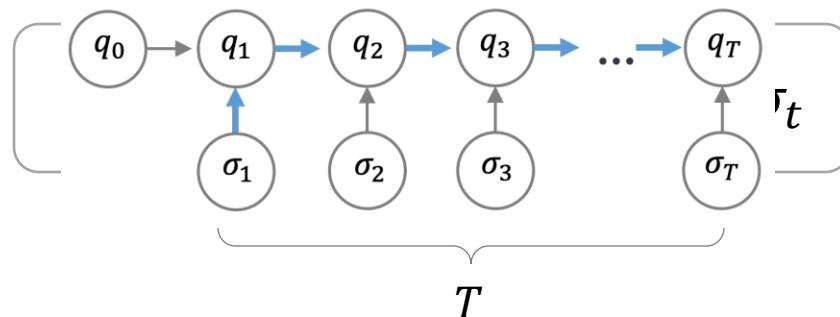
Simulating \mathcal{A} : learn a *seq2seq function* for sequence length T .

- Input = $\sigma_1, \sigma_2, \dots, \sigma_T \in \Sigma$ (alphabet), output = $q_1, q_2, \dots, q_T \in Q$ (states).

Note: more than 1 way to simulate \mathcal{A} .



Iterative solution



"RNN solutions"

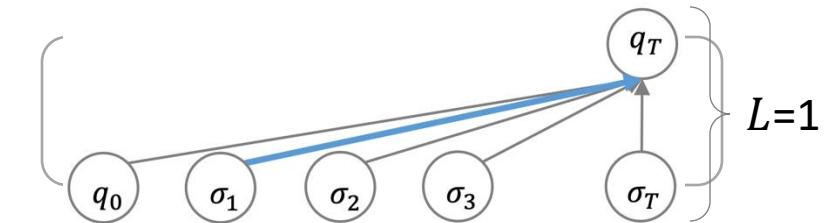
✗ Not shortcut

Shortcut

$O(T) \# \text{sequential steps}$



Parallel solution



"Transformer solutions"

✓ Shortcut

Transformers learn shortcut to automata

*Q: How **parallel** models such as Transformers perform **sequential** reasoning?*

Theoretically: **shortcut** solutions

- How short can the shortcuts be?
 - Measured by network depth.
- What structure/properties are needed?
 - Tools: group theory, Krohn-Rhodes.

Empirically:

- Can shortcuts be found?
 - Is theory predictive?
- What are the empirical solutions?
 - Same as the constructions?
 - Properties?

Solutions of Reasoning

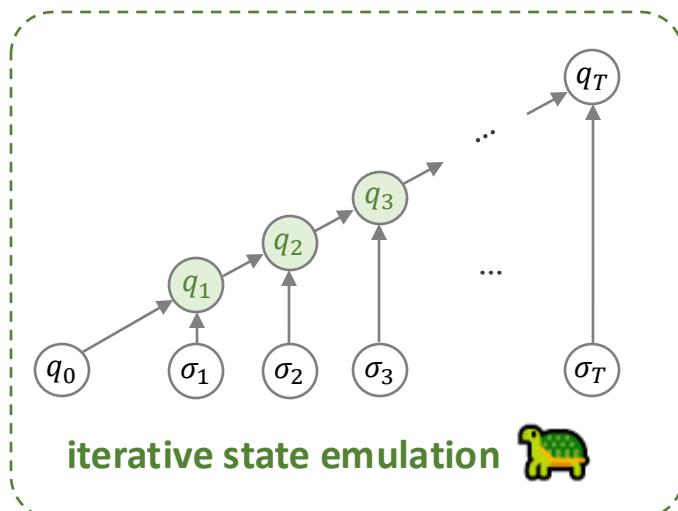
$$\mathcal{A} = (Q, \Sigma, \delta), \\ q_t = \delta(q_{t-1}, \sigma_t).$$



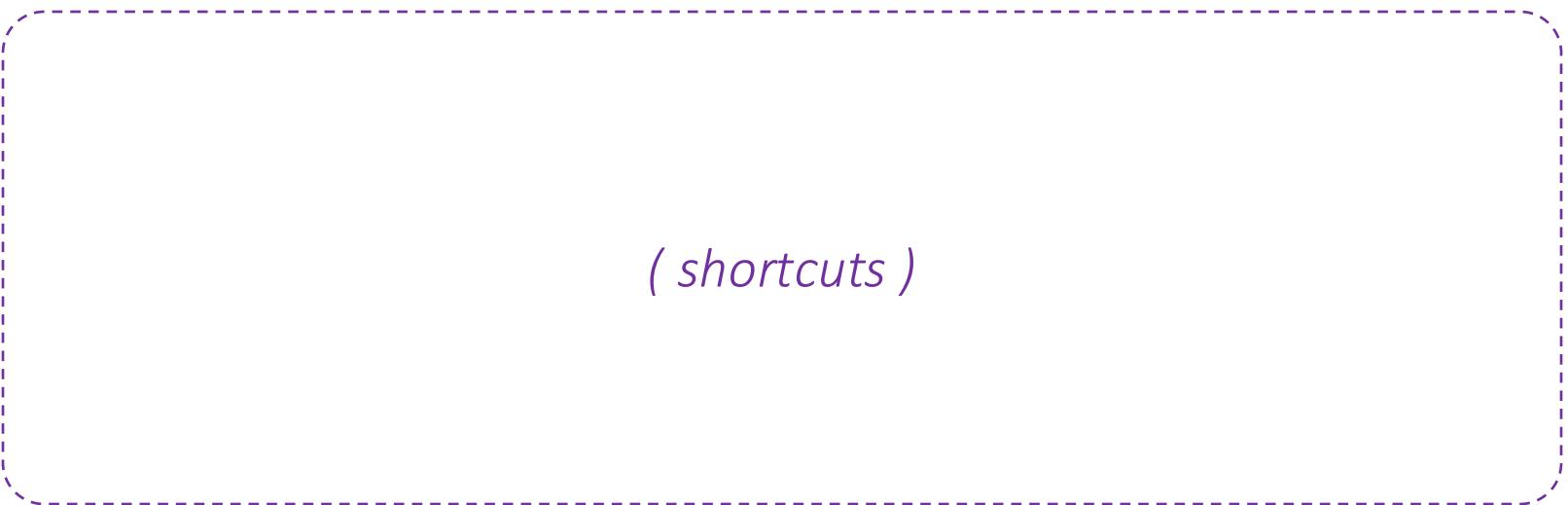
steps = T
definition of δ

steps = $O(\log T)$

steps = $O_{|Q|}(1)$



represented by RNNs



represented by Transformers

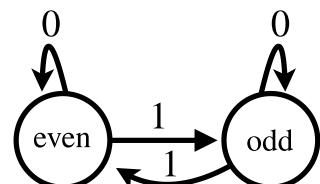
$O(\log T)$ steps

$$\mathcal{A} = (Q, \Sigma, \delta), \\ q_t = \delta(q_{t-1}, \sigma_t).$$

Goal: compute $q_t = (\delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1))(q_0)$, $t \in [T]$.
 $\delta(\cdot, \sigma): Q \rightarrow Q$

function \leftrightarrow matrix

composition \leftrightarrow multiplication



$$Q = \{\text{even, odd}\} \\ \Sigma = \{0, 1\}$$

parity counter

$$\delta(\cdot, 0) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix},$$

$$\delta(\cdot, 1) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$q_t = (\delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1)) q_0$$

$$e_{q_t} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \dots \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} e_{q_0}$$

$O(\log T)$ steps

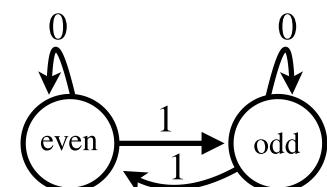
$\mathcal{A} = (Q, \Sigma, \delta),$
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Goal: compute $q_t = (\delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1))(q_0), t \in [T].$

$$\delta(\cdot, \sigma): Q \rightarrow Q$$

function \leftrightarrow matrix

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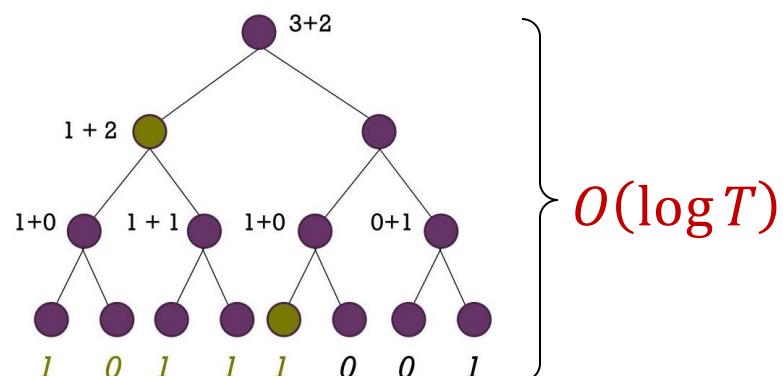


$$Q = \{\text{even, odd}\}$$
$$\Sigma = \{0, 1\}$$

parity counter

$$\delta(\cdot, 0) = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix},$$
$$\delta(\cdot, 1) = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

associativity



Can we use $o(\log T)$ layers?

We already have positive results.

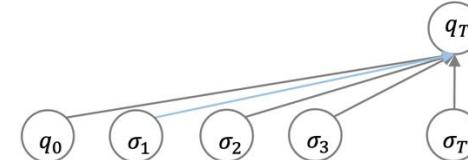
- Parity: only need to **count** #1s.

$$f \circ g = g \circ f$$

Counting works for **commutative** function composition: **$O(1)$ layers**.

$$q_t = (\delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1)) (q_0)$$

$$q_t = (\sum_{\tau \leq t} \sigma_\tau) \text{ mod } 2$$



$$f \circ g \neq g \circ f$$

How about ***non-commutative*** compositions?

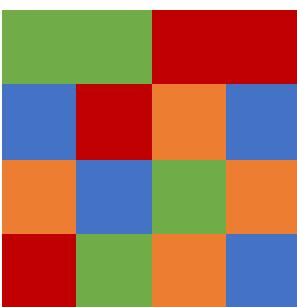
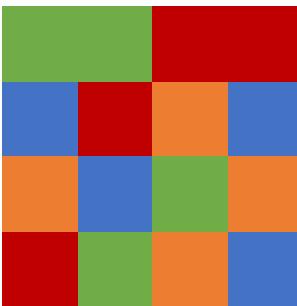
Decomposition



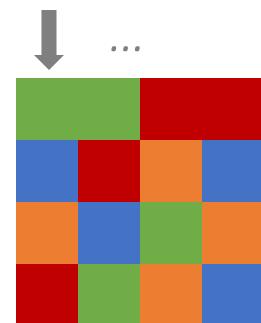
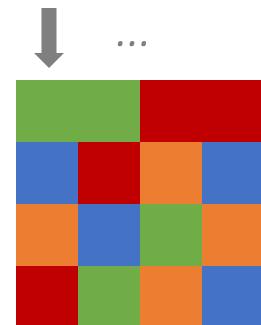
$\tilde{O}(|Q|^2)$ steps: decomposition

Aside: “Shortcut” in recognizing visual patterns [Huang and Pashler 07]

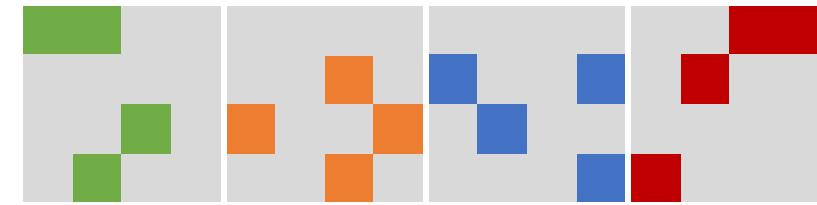
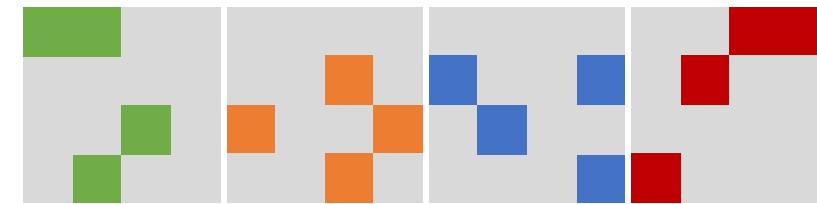
Matching?



1. tracing the cells
one by one



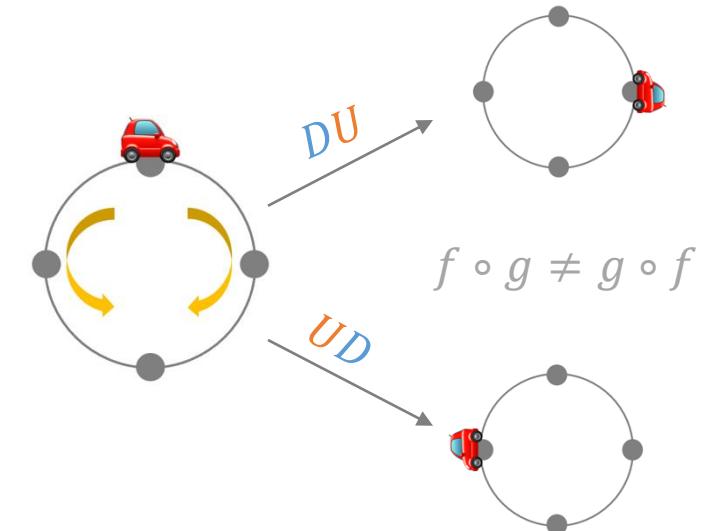
2. *shortcut* via *decomposition* (color)
(fewer sequential steps



Decomposition: car on a circle

$$Q = \{\text{🚗, 🚗}\} \times \{0, 1, 2, 3\}, \Sigma = \{D(\text{drive}), U(\text{U-turn})\}$$

$q_0 = (\text{🚗, } 0), \sigma_{1:T} = \textcolor{blue}{DDDUDDDUUD} \rightarrow q_T?$



- Direction = **parity (sum)** of U . (parity: $\{1, -1\} \leftrightarrow \{0, 1\}$)
 - Position = **signed sum mod 4** : sign = parity of U .
- $O(1)$ layer each

$D \ D \ D \ U \ D \ D \ U \ U \ D$

Parity: 1 1 1 -1 -1 -1 1 -1 -1 → 🚗

Signed sum: 1 1 1 0 -1 -1 0 0 -1 → 0

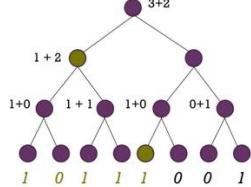
Decomposition: general



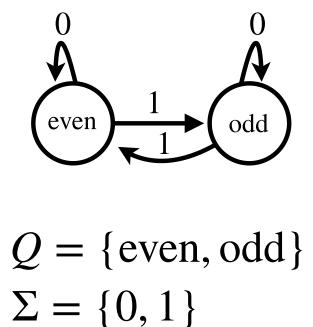
What are we decomposing?

Transformation **group**: $\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$ under composition.

Recall: group axioms

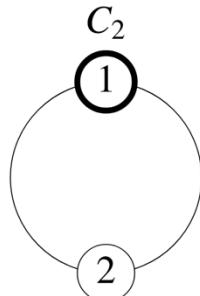


- **Associativity**: $(a \cdot b) \cdot c = a \cdot (b \cdot c)$
- **Inverse**: $a \cdot b = b \cdot a = e$ (**identity**)

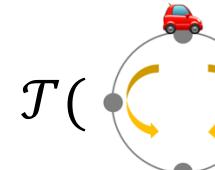


parity counter (mod 2)

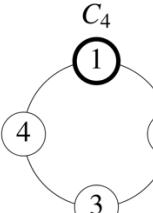
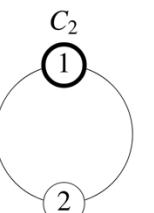
$$\xrightarrow{\mathcal{T}(\mathcal{A})}$$



cyclic group C_2



$$\mathcal{T}(\text{car on track}) = \text{Product}(\text{cyclic group } C_2, \text{cyclic group } C_4)$$



Decomposition: general

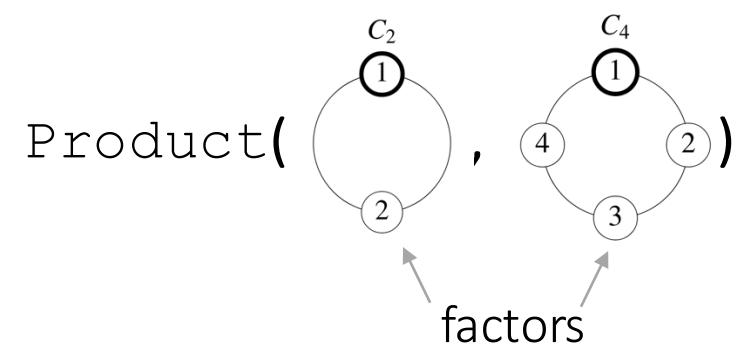
Group: associative + invertible

Transformation **group**: $\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$ under composition.

“Prime factorization” for groups:

$$G = H_n \triangleright H_{n-1} \cdots \triangleright H_1 \quad (\text{Jordan \& Hölder}) \quad [N = p_n \cdot p_{n-1} \cdots \cdot p_1 \quad (\text{Euclid})]$$

- H_{i-1} is a “factor” (normal subgroup) of H_i .
 $\rightarrow n = O(\log |G|)$
- H_{i+1}/H_i are “prime numbers” (simple groups).
If commutative (abelian): 1 layer



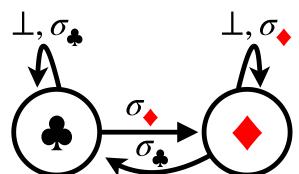
“Solvable G” ... with $O(\log|G|)$ layers ... **What is $|G|$?**

Decomposition: general

Group: associative + **invertible**

Transformation **group**: $\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$ under composition.

Invertible: $a \cdot b = b \cdot a = e$ (identity)



$$\delta(\cdot, \sigma_{\clubsuit}) = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$$

$$Q = \{\clubsuit, \diamondsuit\}$$
$$\Sigma = \{\sigma_{\clubsuit}, \sigma_{\diamondsuit}, \perp\}$$

1-bit memory unit

(aka. flipflop)

singular \rightarrow no inverse

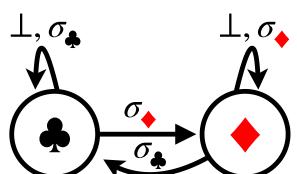
Decomposition: general

Semigroup: associative (+ identity)



Transformation **semigroup**: $\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$ under composition.

Invertible: $a \cdot b = b \cdot a = e$ (identity)



$$Q = \{\clubsuit, \diamondsuit\}$$

$$\Sigma = \{\sigma_{\clubsuit}, \sigma_{\diamondsuit}, \perp\}$$

1-bit memory unit

(aka. flipflop)

$$\delta(\cdot, \sigma_{\clubsuit}) = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$$

singular \rightarrow no inverse

$$|\mathcal{T}(\mathcal{A})| \leq O(|Q|^{|Q|})$$

i.e. with $O(|Q| \log |Q|)$ layers
 $\tilde{O}(|Q|)$

Semigroup: associativity only

Jordan & Hölder $(\mathcal{T}(\mathcal{A}))$: group



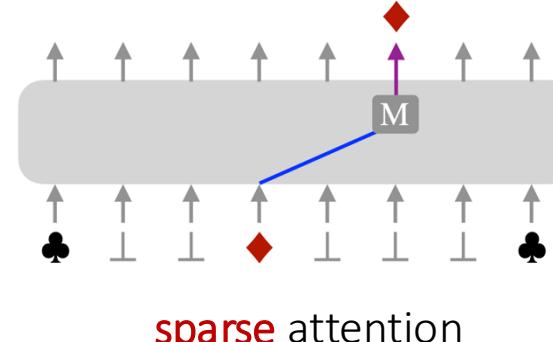
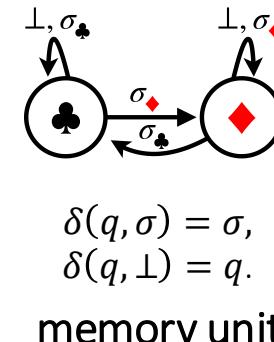
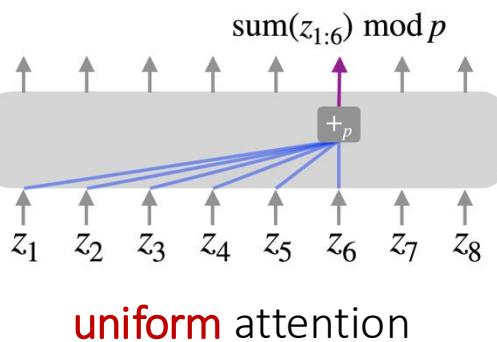
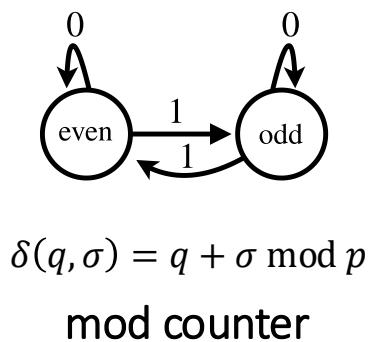
Krohn-Rhodes $(\mathcal{T}(\mathcal{A}))$: semigroup

$\tilde{O}(|Q|^2)$ steps: decomposition

constrain the type of “factors”

#factors $\leq \text{poly}(|Q|)$

Krohn-Rhodes: solvable \mathcal{A} decomposes into **2 types of factors**.



Each representable by 1 Transformer layer
+ “gluing” with $O(1)$ layers (using MLP).

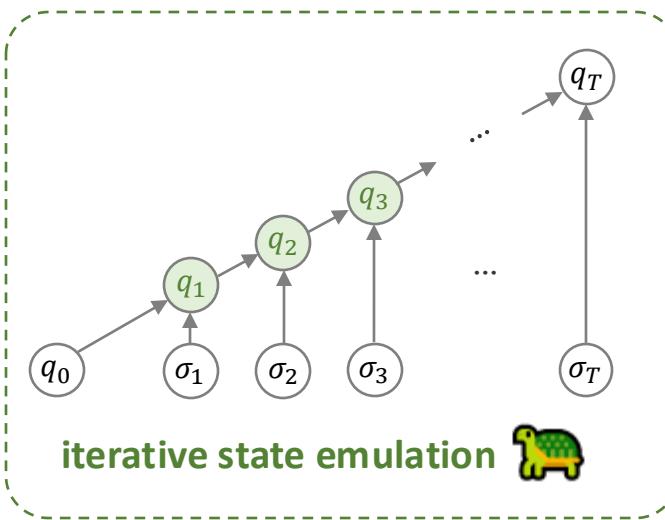
Solutions of Reasoning

$$q_t = (\delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1))(q_0)$$

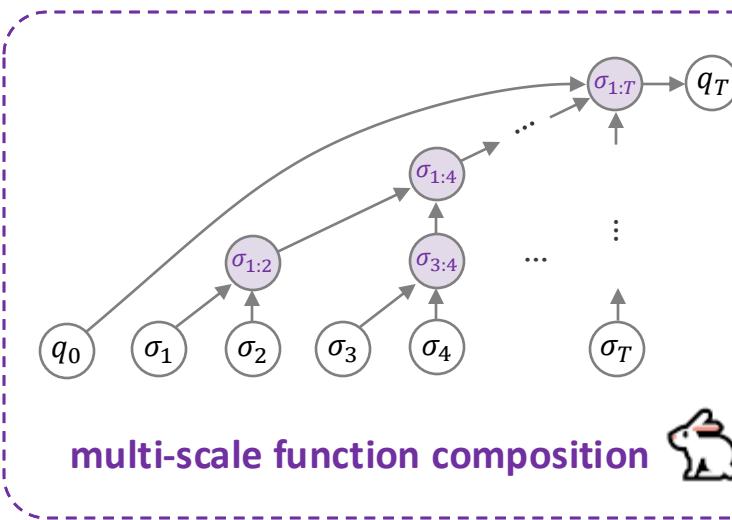
steps = T
definition of δ

steps = $O(\log T)$
associativity

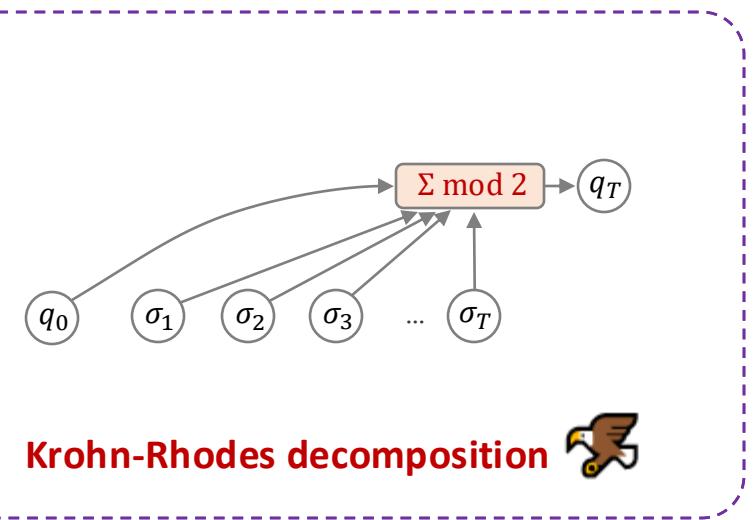
steps = $\tilde{O}(|Q|^2)$
algebraic structure



represented by RNNs



represented by Transformers



for *all* \mathcal{A}

for *solvable* \mathcal{A}

Simulating \mathcal{A} in practice



Can shortcuts be found?

Can shortcuts be learned?

Yes, across 19 automata & 16 depths.

- Shortcuts are found.
- Deeper factorization → more layers.
- Open challenges:
 - Stabilize training?
 - Interpret the solutions?

→ example: Gridworld

Non-solvable groups

Cyclic groups
(mod- n)

Gridworld

lighter > darker

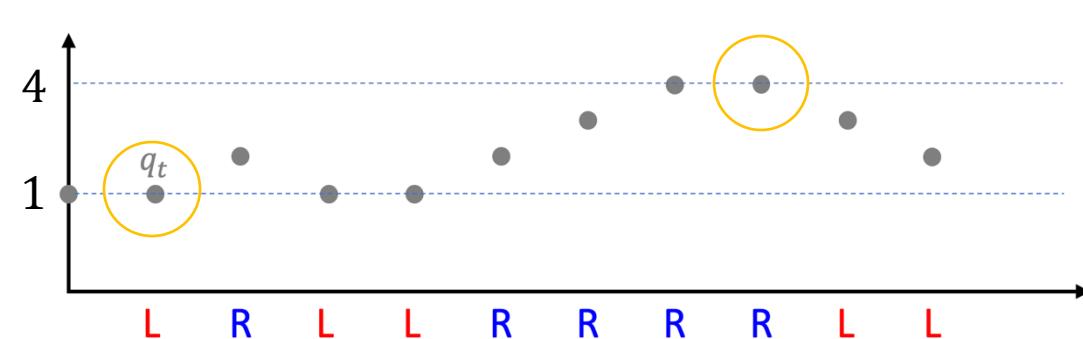
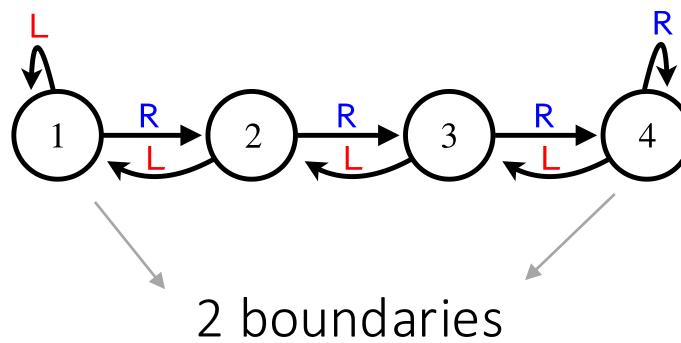
Transformer depth L ($T=100$)

	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
Dyck	99.3	100	1	100	100	100	100	100	100	100	100	100	100	100	100	100
Grid ₄	99.9	100	100	100	100	100	100	100	100	100	100	100	100	100	100	100
Grid ₉	92.2	100	100	100	100	100	100	100	100	100	100	100	100	100	100	100
C_2	77.6	99.8	99.9	100	100	99.5	100	99.7	100	100	100	100	100	100	100	100
C_3	54.6	94.6	96.7	99.4	100	100	99.8	100	99.9	100	100	100	100	100	99.8	100
C_4	95.1	92.3	84.2	99.9	99.7	99.9	100	100	100	100	100	100	100	100	100	100
C_5	89.0	99.1	99.9	100	100	100	100	100	100	100	100	100	100	100	100	100
C_6	59.8	98.7	75.5	99.9	99.8	99.9	99.9	100	100	100	99.8	99.9	100	99.8	99.9	99.9
C_7	90.9	95.0	99.9	99.9	100	99.9	100	100	100	100	100	99.8	100	100	100	100
C_8	79.6	96.2	99.8	99.8	99.9	100	99.9	99.9	100	99.4	99.9	99.9	99.9	100	99.9	99.9
C_2^2	90.5	98.8	99.9	100	100	99.9	100	100	99.9	99.9	100	100	100	100	100	100
C_3^2	65.0	77.9	99.9	97.9	100	99.8	98.2	99.9	100	100	91.9	95.9	91.7	90.6	87.5	80.6
D_6	25.4	27.2	47.4	75.2	100	100	100	100	100	100	100	100	100	100	100	100
D_8	45.6	98.0	100	100	100	100	100	100	100	100	100	100	100	100	100	100
Q_8	31.6	49.2	59.6	60.4	73.5	99.3	100	100	100	100	100	100	100	100	100	100
A_4	25.0	35.4	49.1	59.3	62.6	82.3	90.9	98.0	98.0	99.1	99.8	100	99.7	100	100	100
A_5	12.5	23.1	32.5	46.7	71.2	98.8	100	100	100	100	100	100	100	100	100	100
S_4	11.3	17.6	22.0	27.1	37.7	44.8	50.8	72.5	91.3	97.1	97.9	98.7	99.9	100	99.8	99.9
S_5	7.9	11.8	14.6	19.7	26.0	28.4	32.8	51.8	86.3	94.8	90.2	97.2	99.3	99.1	99.9	99.9

automation

Interpreting gridworld

1d gridworld: $Q = \{1, 2, 3, 4\}$, $\Sigma = \{\text{L}, \text{R}\}$.



- State matters: $\text{LR} \neq \text{RL}$ at state 1, but $\text{LR} = \text{RL}$ at state 3.

~~"You can only figure out where you are if you know q_{t-1} ."~~

$O(1)$ layer for

Puzzle: design a parallel algorithm to compute $\sigma_{1:T} \mapsto q_{1:T}$.

- Hint: *boundary detection*: no boundary = prefix sum.

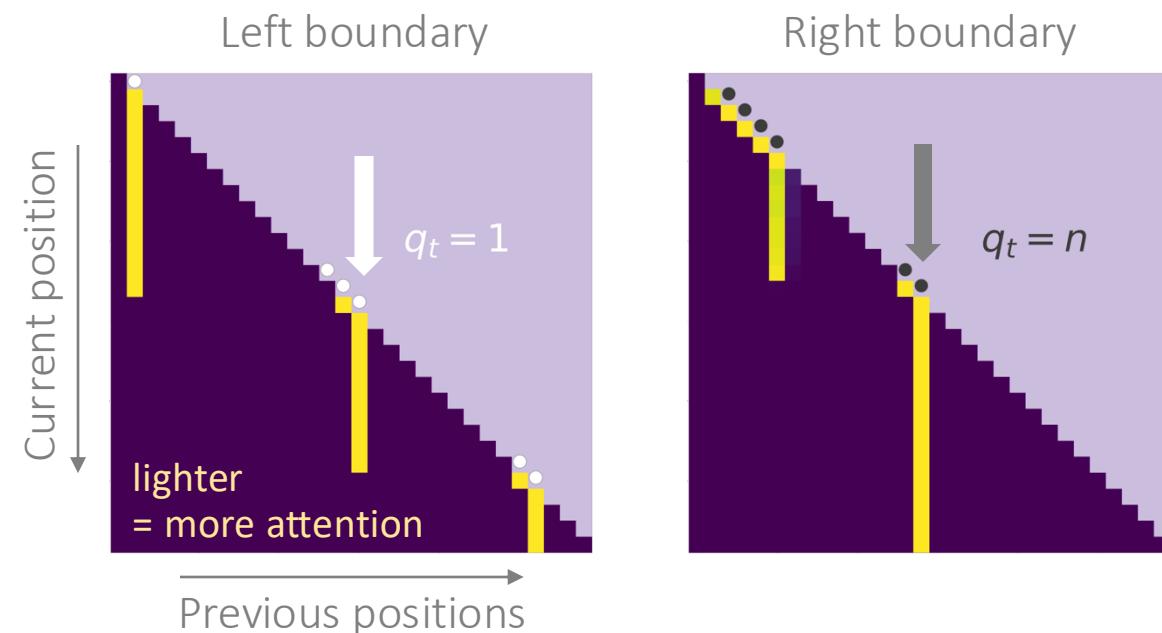
Transformers find boundaries:

$O(1)$ -layer (Krohn-Rhodes: $\tilde{O}(|Q|^2)$)

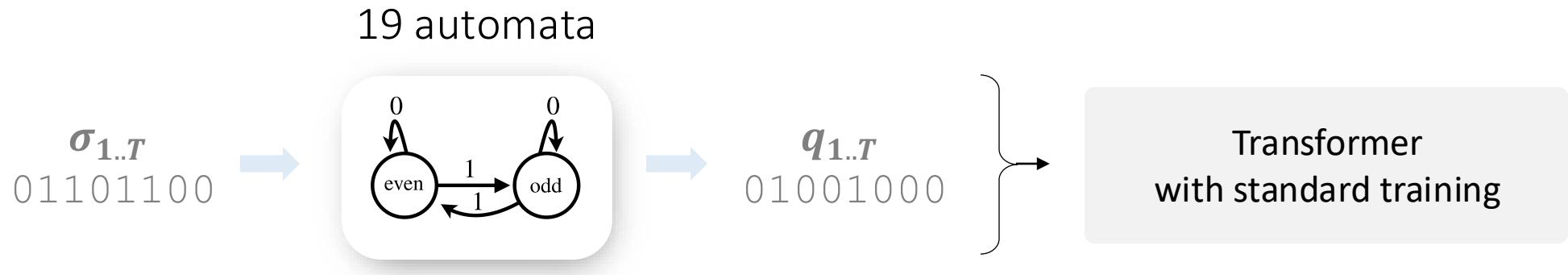
attention heatmaps
(GPT solved this before us 🤖)

→ algorithm extracted
“mechanistic interpretability”

*Caution: challenges of interpreting
attention maps [WLLR NeurIPS23]



Simulating \mathcal{A} in practice



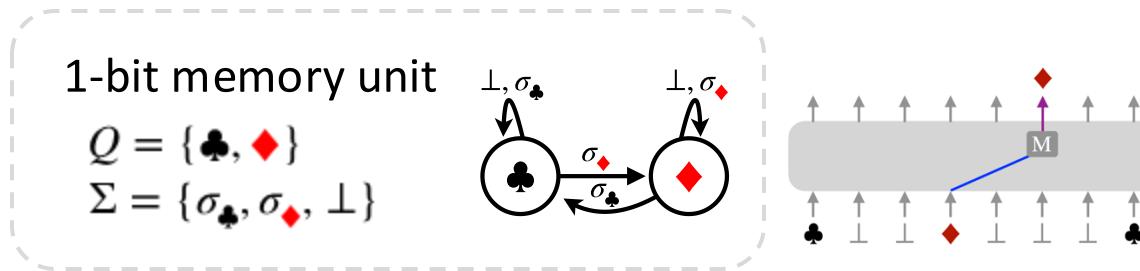
Can shortcuts
be found?

Yes; e.g. gridworld.

Robust Out-Of-Distribution?

Problems with shortcuts?

Flip-flop: A simple task where Transformers struggle out-of-distribution (OOD).

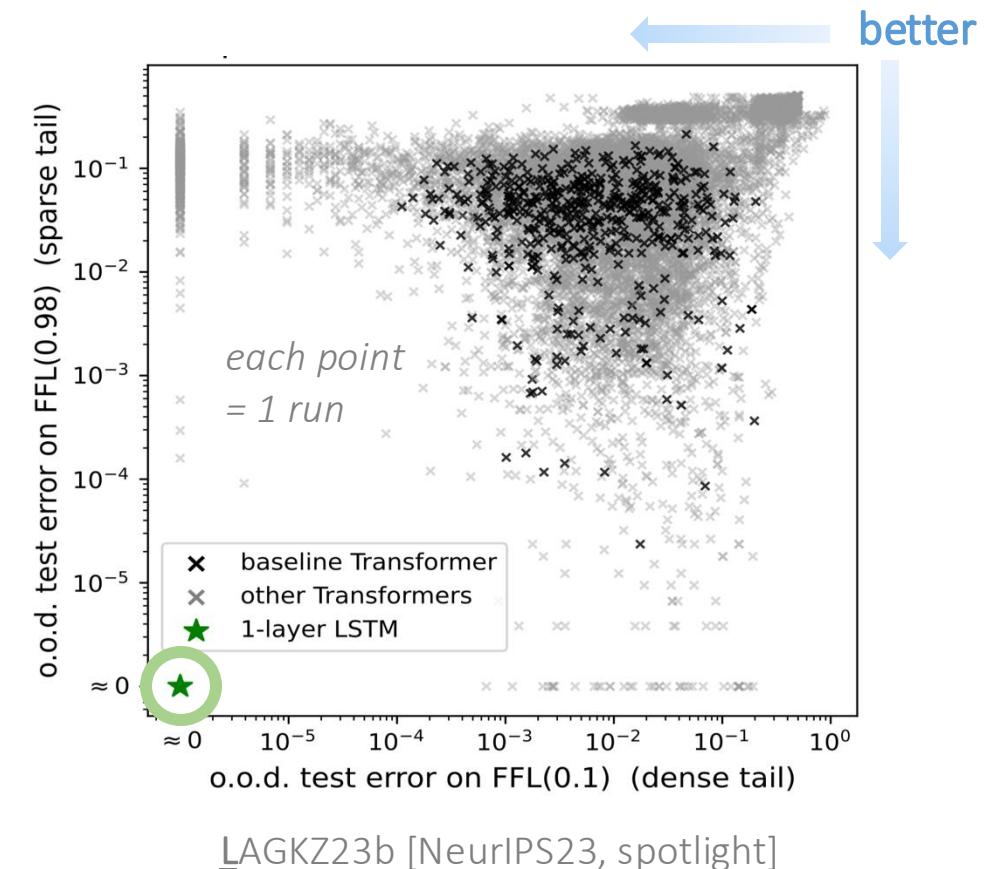


Attention glitches: imperfect retrieval.

- Inherent limitations of attention.
- Potential contributor to hallucination.

Mitigation: No perfect mitigations.

- unless introducing *long-tailed data*
also in prior work, e.g. priming [Jelassi et al. 23].



Flip-Flop Language Modeling (FFLM)

Flip-Flop Language (FFL): sequences of instruction-value pairs.

- 3 instructions: **w** (write) , **i** (ignore) , **r** (read).
- 2 values: {0, 1}; the value for **r** must be the same as the last **w**.

w 1 i 0 i 1 r 1 w 0 i 1 r 1
 ✓ ✗

Task: predict values following **r** (i.e. locate the most recent **w**)



Distributions: **FFL(p_i)**: $p_w = p_r = \frac{1-p_i}{2}$.

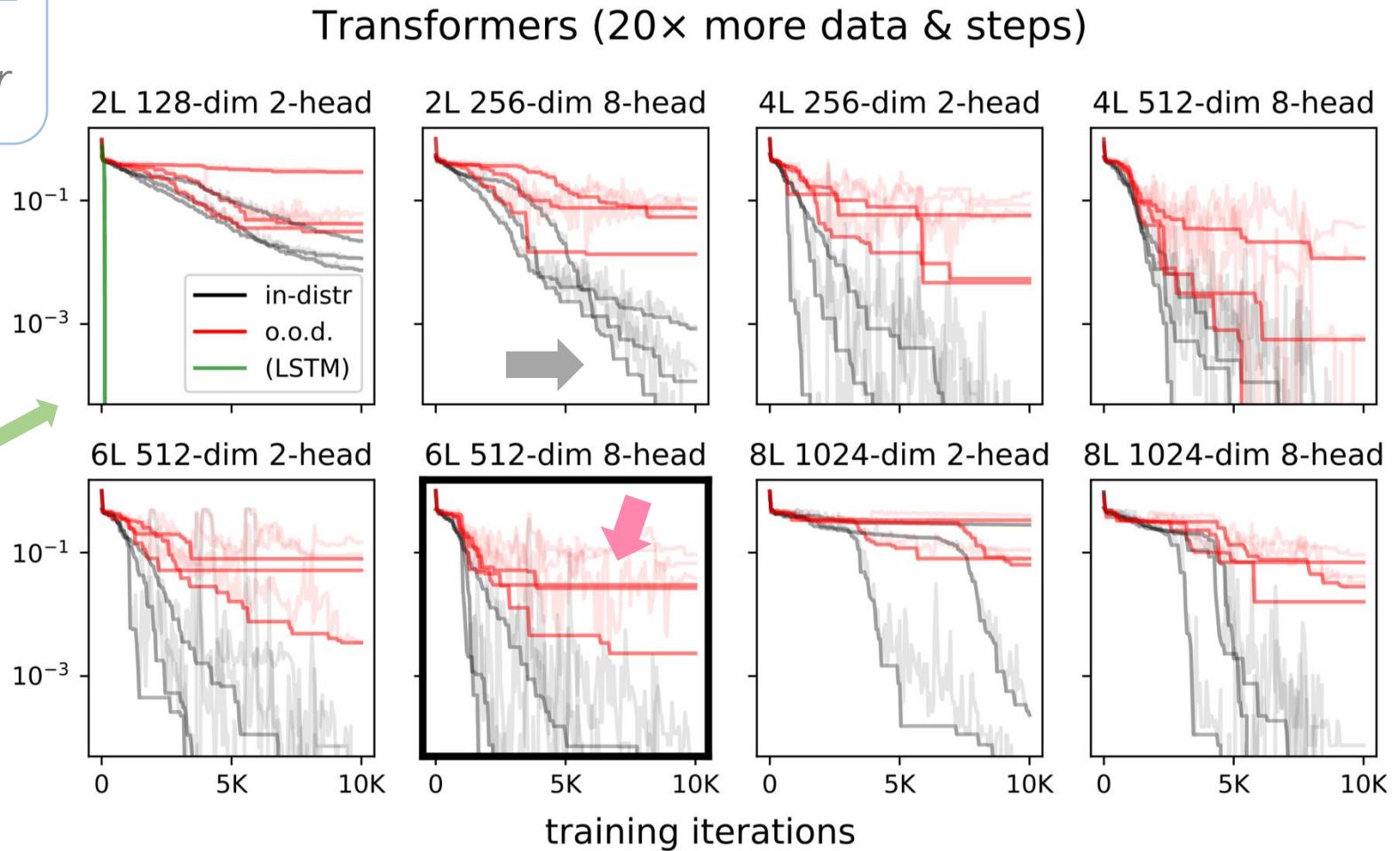
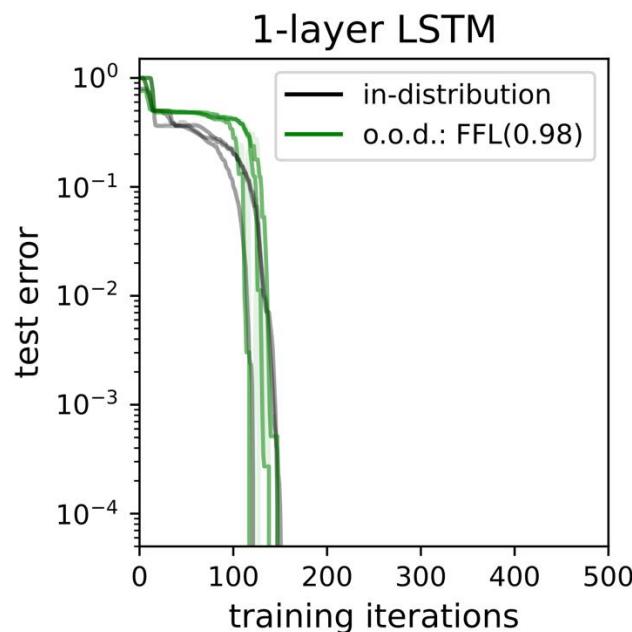
Why FFLM?

- An atomic unit underlying reasoning tasks [LAGKZ23a].
- Simple yet interesting.

FFLM Results

Train: FFL(0.8) $T = 512$
Test: FFL(0.9) ... sparser

Attention glitches



Attention Glitches

$\text{FFL}(p_i)$: various T , $p_w = p_r = 0.2$.

Def: *imperfect hard retrieval*.

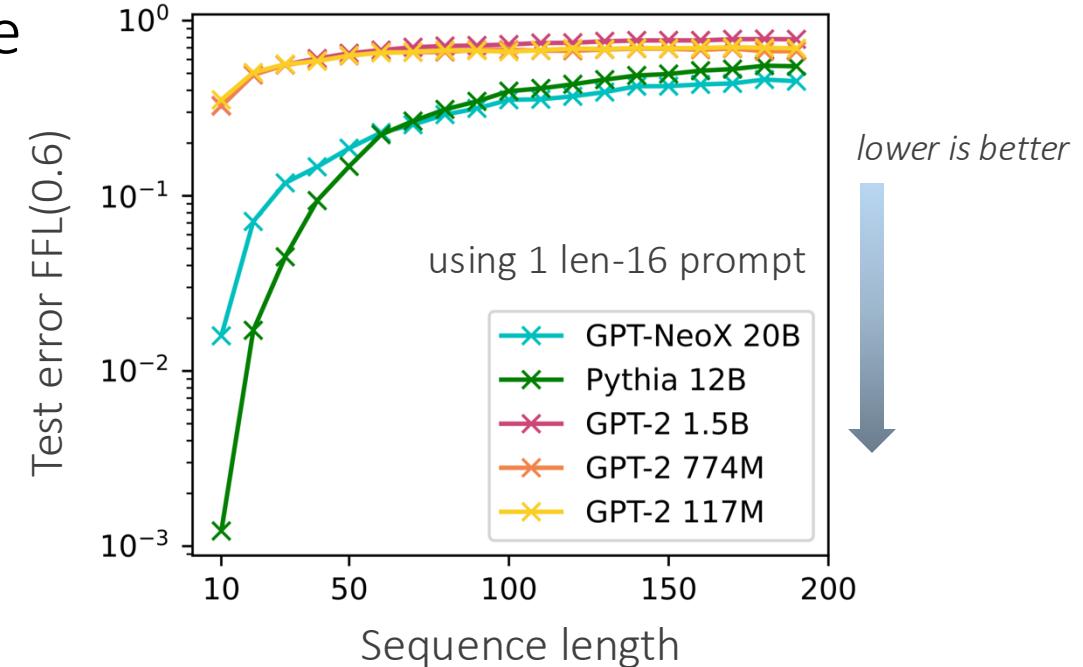
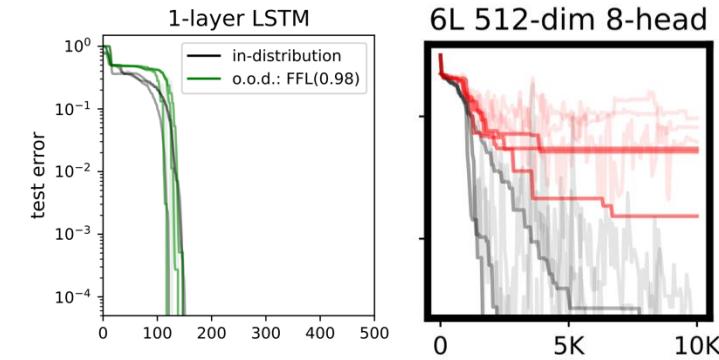
(R1) Transformers exhibit a long tail of errors.

(R2) 1-layer LSTMs extrapolate *perfectly*.

(R3) 10B-scale *natural-language* models are not robust either.

w 0 i 0 i 1 w 1 i 1 i 0 r ?

Alice turns the light off.
Then, Bob eats an apple.
Then, Bob eats a banana.
Then, Alice turns the light on.
Then, Bob eats a banana.
Then, Bob eats an apple.
Now, the light is



What causes glitching attentions?

$$\text{FFL}(p_i): p_w = p_r = \frac{1-p_i}{2}.$$

Not because of limitation on representation power (solvable with 2-layer 1-head).

Diluted soft attention: caused by more items in the softmax.

$$a_{\max} = \frac{\exp(z_{\max})}{\underbrace{\exp(z_1) + \dots + \exp(z_t)}_{e.g. \text{ ignores, earlier writes}} + \exp(z_{\max})}$$

- Pointed out in prior work [Hahn 20, Chiang & Cholak 22].
- Possible mitigation: scaling the logits (e.g. by $\log T$), hard attention.

What causes glitching attentions?

$$\text{FFL}(p_i): p_w = p_r = \frac{1-p_i}{2}.$$

Not because of limitation on representation power (solvable with 2-layer 1-head).

Diluted soft attention: more items in the softmax: scaling, hard attention.

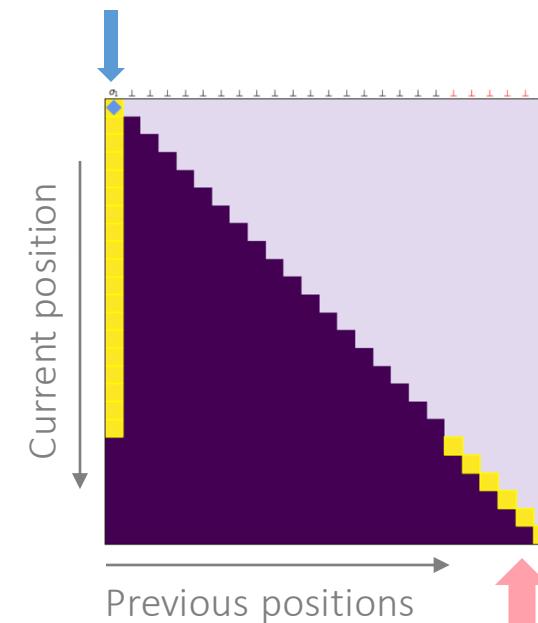
→ failure on denser sequences (more w)

Wrong argmax: hard attention won't work.

Setting: simple flip-flop: 1-layer 1-head.

Unlikely to precisely meet a necessary condition
for linear positional encoding.

→ failure on sparser sequences (fewer w)



Mitigations to attention glitches

- Incorporating OOD data.

direct

Ideal solution – No OOD issue if everything is in distribution! :)

- Resource scaling: larger, train for longer.

Fresh samples → better coverage

- Standard regularization

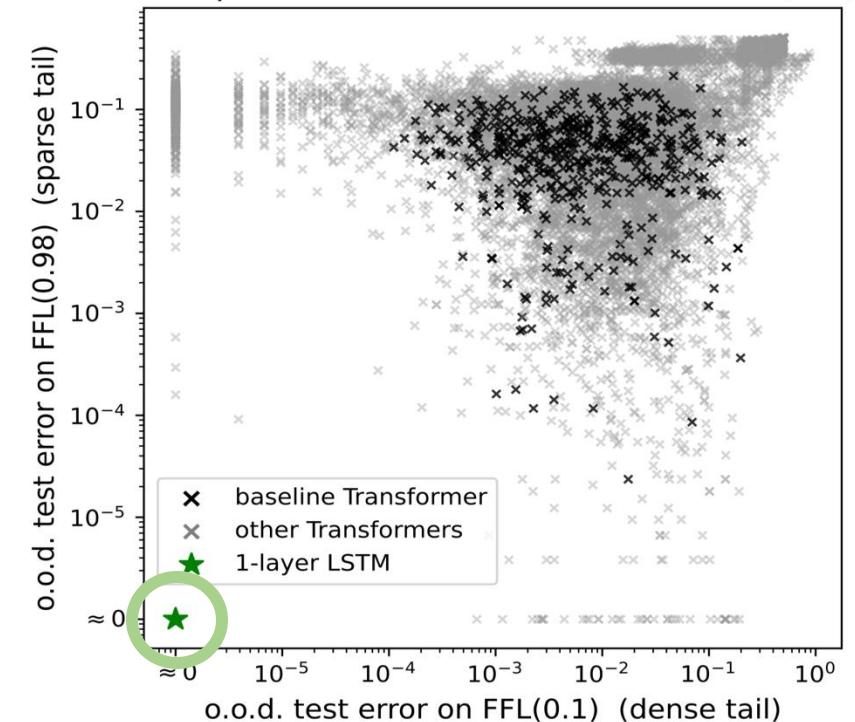
e.g. weight decay, dropout, position encoding.

- Attention-sharpening losses (entropy, $-\ell_2, -\ell_\infty$)

indirect

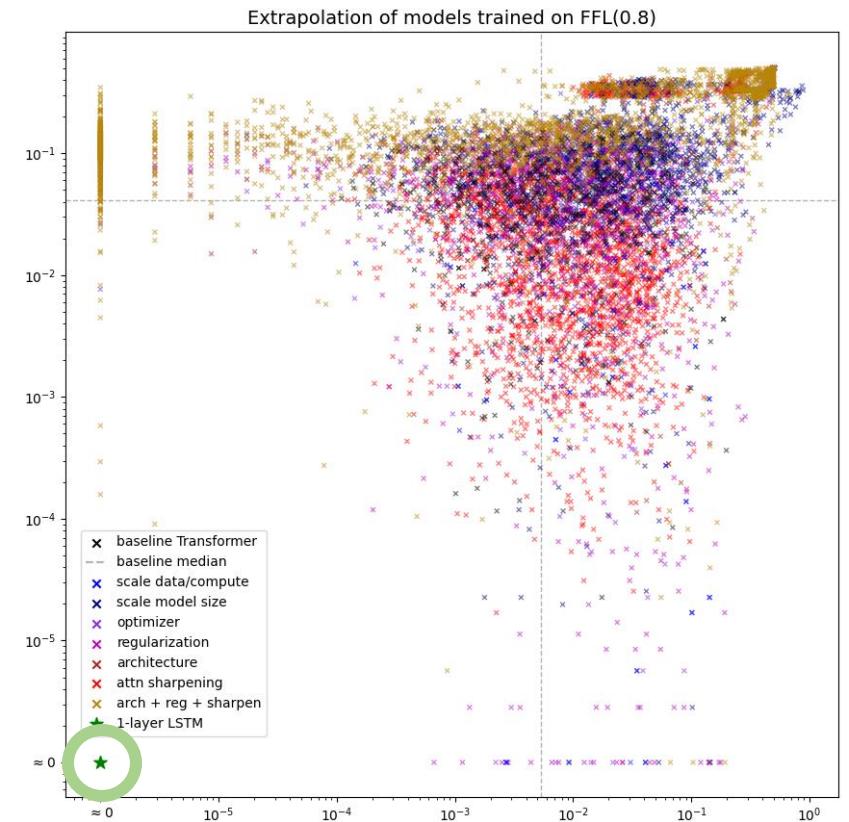
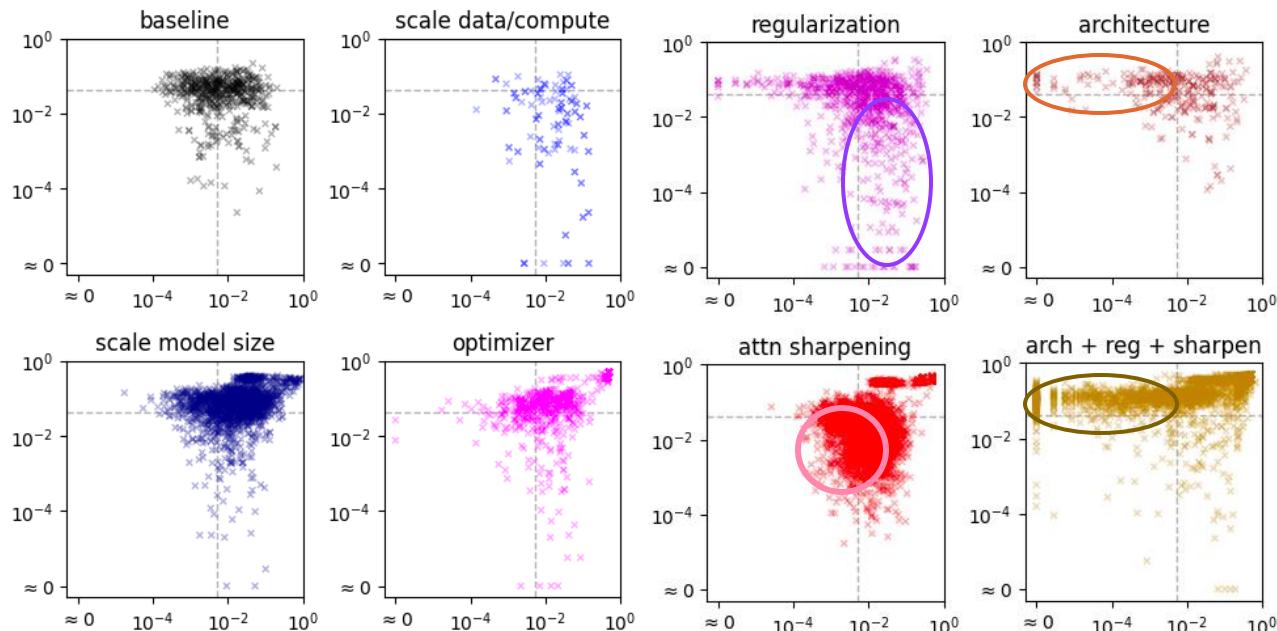
*No perfect mitigations,
except for OOD data.*

Extrapolation of models trained on FFL(0.8)



Attention glitches: no perfect mitigations

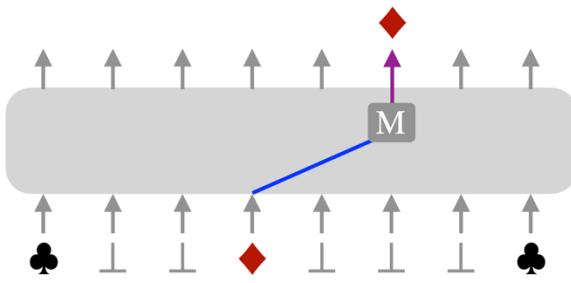
Dense-sparse trade-off: seldom improve both.
denser = x-axis, sparser = y-axis.



LSTM

OOD failures – the 2 atomic units

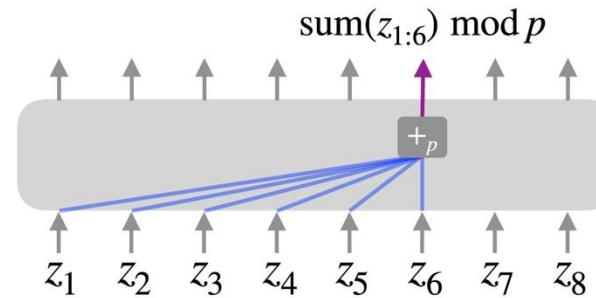
- Flip-flop → **sparse** attention



Attention: Flip-Flop Language Modeling

*... the simplest setup where
(closed-domain) hallucination occurs.*

- Parity → **uniform** attention

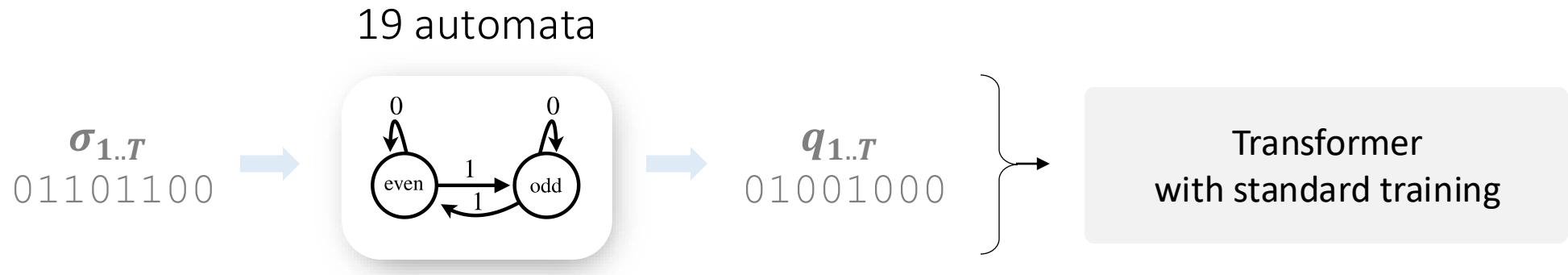


MLP: $q_t = (\sum_{i \in [t]} \sigma_i) \bmod 2$

↓
memorized → fail at unseen $(\sum_{i \in [t]} \sigma_i)$.
(failure of ReLU [Xu 20])

Solution: periodic activation, e.g. $\sin(x)$.

Empirical results



Can shortcuts
be found?

Yes; e.g. gridworld.

Robust Out-Of-Distribution?

Failure of: 1. Attention (flipflop)
2. MLP (parity)

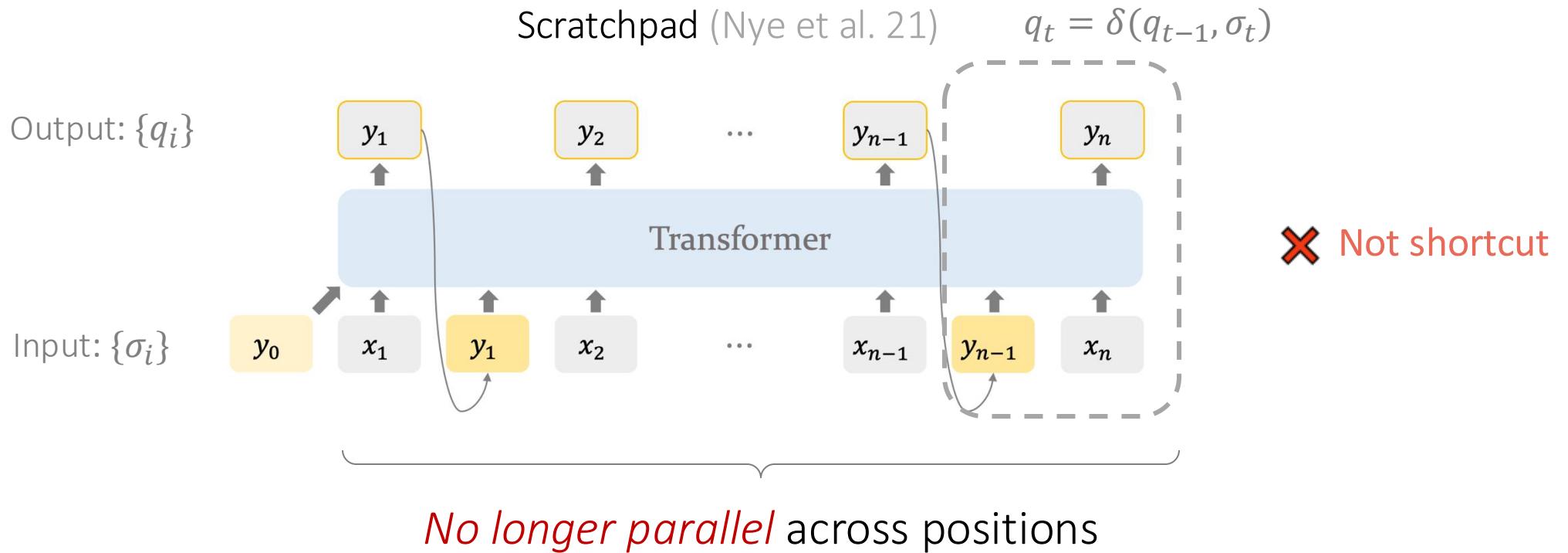
Any fixes?

Computational shortcuts exist, but practical **statistical shortcuts** are brittle.

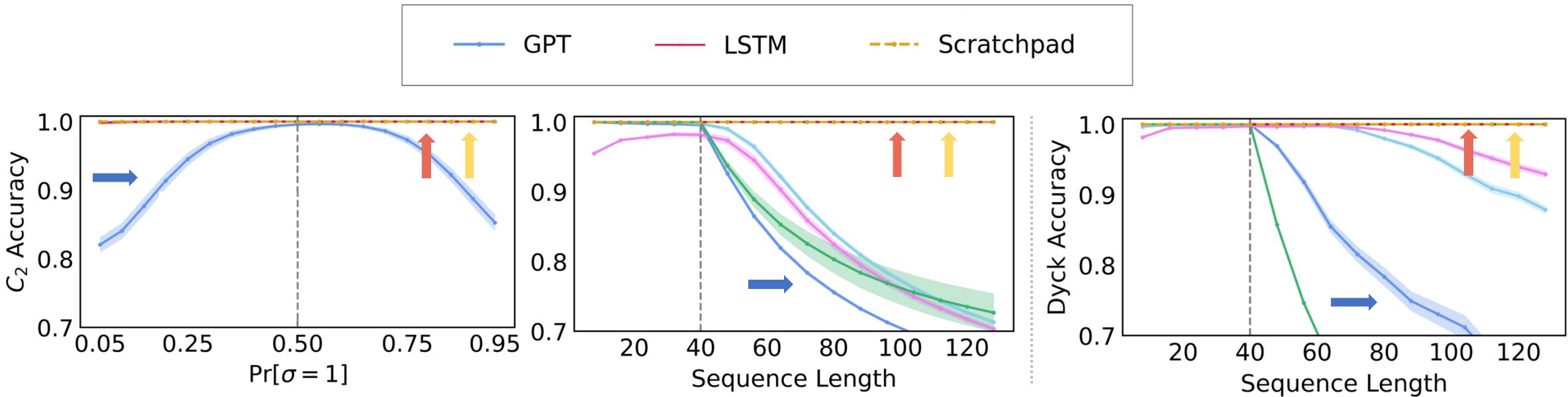


Autoregressive mode of Transformers

Fix to OOD: **iterative/autoregressive** solutions: use q_{t-1} as inputs.



Autoregressive mode of Transformers



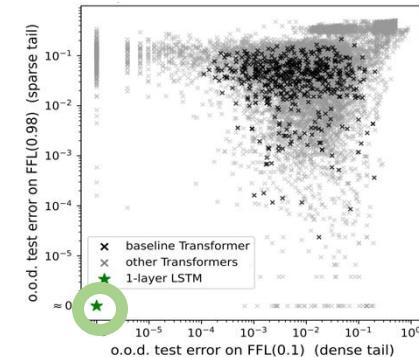
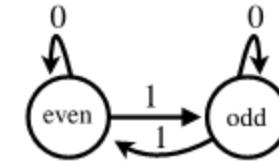
Transformers generalize, when made autoregressive with **scratchpad** [Nye et al. 22].

→ Can we learn *shortcuts that generalize*? ... attention glitches (*flipflop*)

Transformers Learn Shortcuts to Automata

Parallel solutions to sequential reasoning problems.

- **Theory:** Transformers learns $o(T)$ layers **shortcuts**.
 - All \mathcal{A} : $O(\log T)$ layers: divide-and-conquer.
 - This is also the lower bound for the general case.
 - All solvable \mathcal{A} : $O_{|\mathcal{Q}|}(1)$ layers: **Krohn-Rhodes Theory**.
 - Special case: $O(1)$ -layer simulation. 
- **Empirical study:** shortcuts can be found in practice.
 - *Benefit:* sequential computation steps \ll reasoning steps.
 - *Weakness:* the shortcuts are **brittle OOD, hallucination**.
 - **No perfect parallel solutions yet.**



Discussions

What can we learn from small-scale experiments?

- FFLM extensions: more values, selection criteria (multi-step reasoning).
- What insights transfer across scale? e.g. sharpen attention for code/math?

Perfect accuracy? More comprehensive metrics; understand the errors.

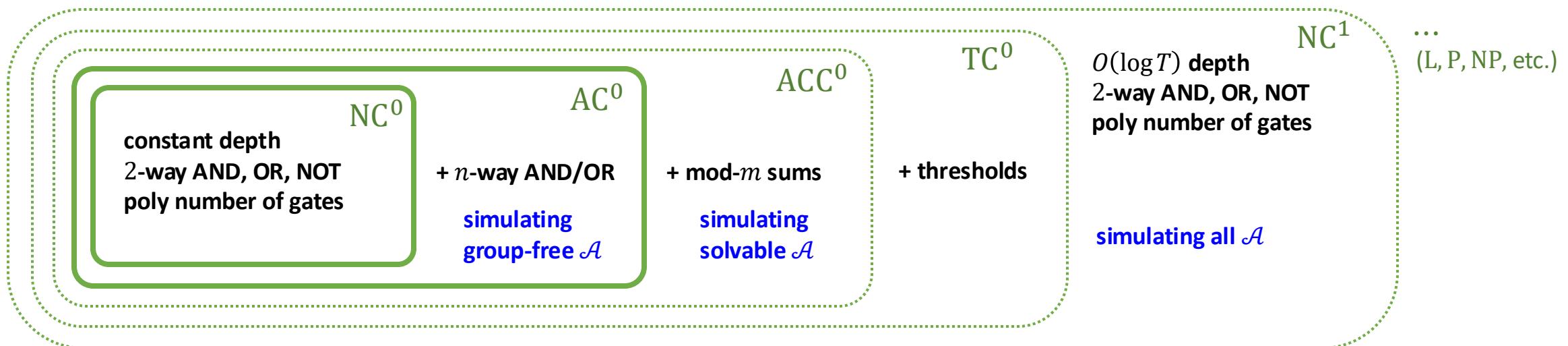
Architectural changes? e.g. recurrence, Mamba (S6), built-in operators.

Theory? Representational, optimization (stability), generalization.

Appendix

Quantifying efficient parallel circuits

- Goal: formalize “*Krohn-Rhodes implies efficient simulation*”
- Low-depth parallel algorithms are best captured by **circuit complexity**



Embarrassingly open: are any of the \square proper? $\text{ACC}^0 \stackrel{?}{=} \text{NP}$?



Factorization: from integers to groups

$$8 = 2 \times 2 \times 2$$

- Why groups get complicated: **combinatorial explosion**



C_8 : mod-8 addition



$E_8 \cong C_2 \times C_2 \times C_2$: 3-bit vectors under XOR



$C_4 \times C_2$: non-interacting mod-4 & parity



$D_8 \cong C_4 \rtimes C_2$: rotations/reflections of a square



Q_8 : multiplication of unit quaternions

} **non-abelian:** $gh \neq hg$

- **Finite group theory:** classical toolbox for understanding symmetries

$$C_8, E_8, C_4 \times C_2, D_8, Q_8 \leq (C_2 \wr C_2) \wr C_2$$

Jordan-Hölder factors (simple groups)

Krasner-Kaloujnine embedding (wreath product)

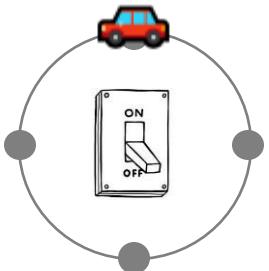
Decomposition: the glue

$$\mathcal{T}(\text{○}) = \text{Product}(\text{○}, \text{○})$$

Direct product \times , e.g. 🦓 $C_4 \times C_2$

Two *independent* groups

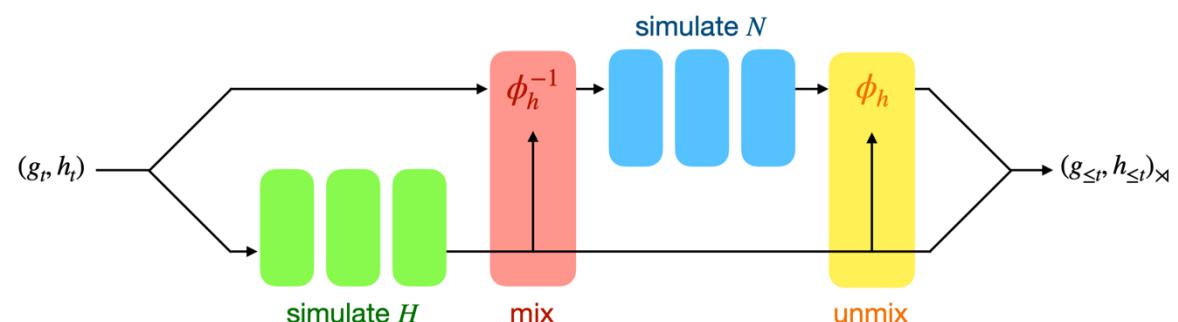
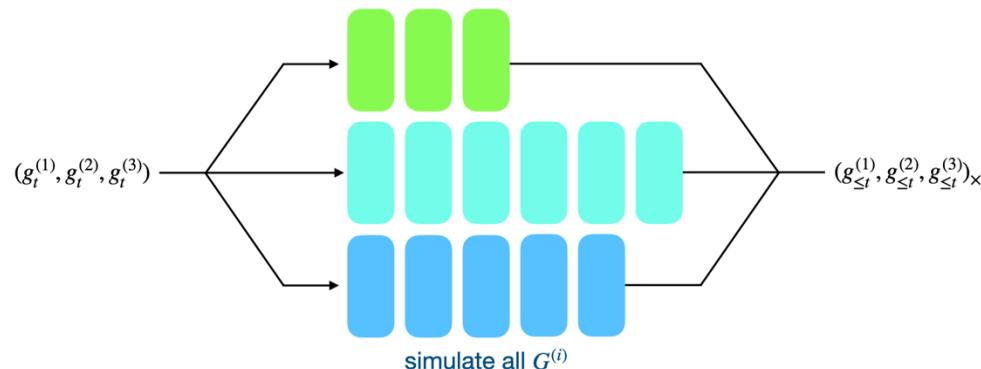
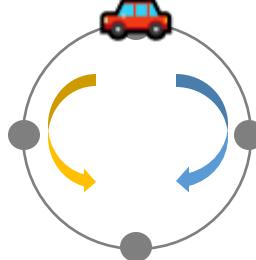
- $(g_1, h_1) \cdot (g_2, h_2) = (g_1 g_2, h_1 h_2)$
- e.g. car + a light switch



Semidirect product \rtimes , e.g. 🦀 $D_8 \cong C_4 \rtimes C_2$

Two *interacting* groups

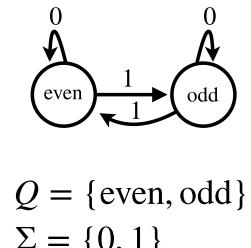
- $(g_1, h_1) \cdot (g_2, h_2) = (g_1 h_2 g_2 h_2^{-1}, h_1 h_2)$
- e.g. car + direction toggle



Transformation semigroups

$$q_t = (\delta(\cdot, \sigma_t) \circ \dots \circ \delta(\cdot, \sigma_1))(q_0)$$

$\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$ under composition (associativity).

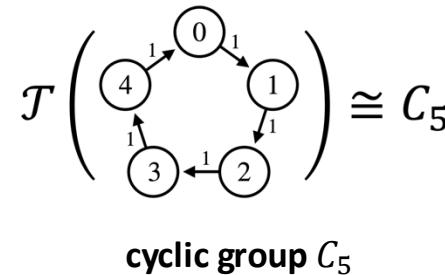


parity counter

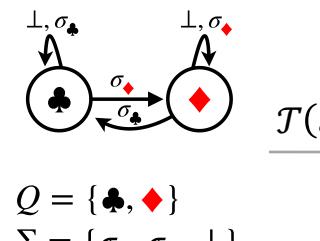
	0	1
0	0	1
1	1	0

$$\mathcal{T}(\mathcal{A})$$

cyclic group C_2



cyclic group C_5



1-bit memory unit

	σ_{\diamondsuit}	σ_{\clubsuit}	\perp
σ_{\diamondsuit}	σ_{\diamondsuit}	σ_{\diamondsuit}	σ_{\diamondsuit}
σ_{\clubsuit}	σ_{\clubsuit}	σ_{\clubsuit}	σ_{\clubsuit}
\perp	σ_{\diamondsuit}	σ_{\clubsuit}	\perp

$$\mathcal{T}(\mathcal{A})$$

flip-flop monoid

} non-invertible

Group G : a set G with operation $G \times G \rightarrow G$.

- Associativity: $(a \cdot b) \cdot c = a \cdot (b \cdot c)$
- Identity: $a \cdot e = e \cdot a = a$
- Inverse: $\forall a \in G, \exists b \in G$ s.t. $a \cdot b = b \cdot a = e$

Semigroup G : a generalization of group.

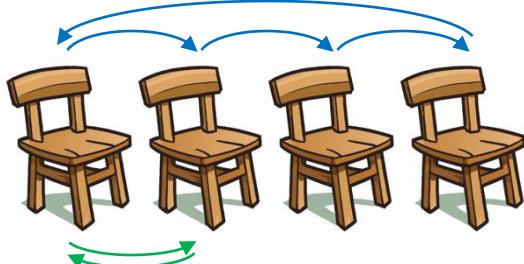
- Associativity.
- (+ Identity: a *monoid*.)

What about semigroups?

$\mathcal{T}(\mathcal{A}) := \{\delta(\cdot, \sigma) : \sigma \in \Sigma\}$ under composition

More complicated: **rank collapses**.

n -player musical chairs



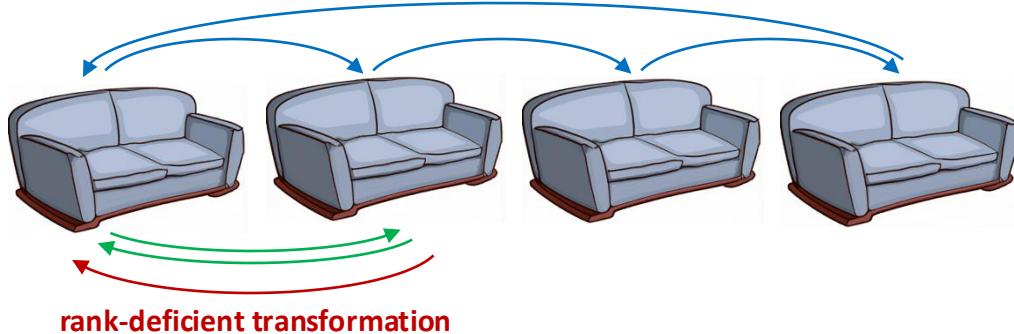
$$Q = \{\text{positions of } n \text{ players}\}$$

$$\Sigma = \{ \text{ cycle, swap } \}$$

$$\begin{bmatrix} & & 1 \\ 1 & 1 & \end{bmatrix} \quad \begin{bmatrix} 1 & 1 \\ & 1 \end{bmatrix}$$

$\mathcal{T}(\mathcal{A}) = S_n$: all $n!$ permutations on $[n]$

n -player musical sofas



$$Q = \{\text{positions of } n \text{ players}\}$$

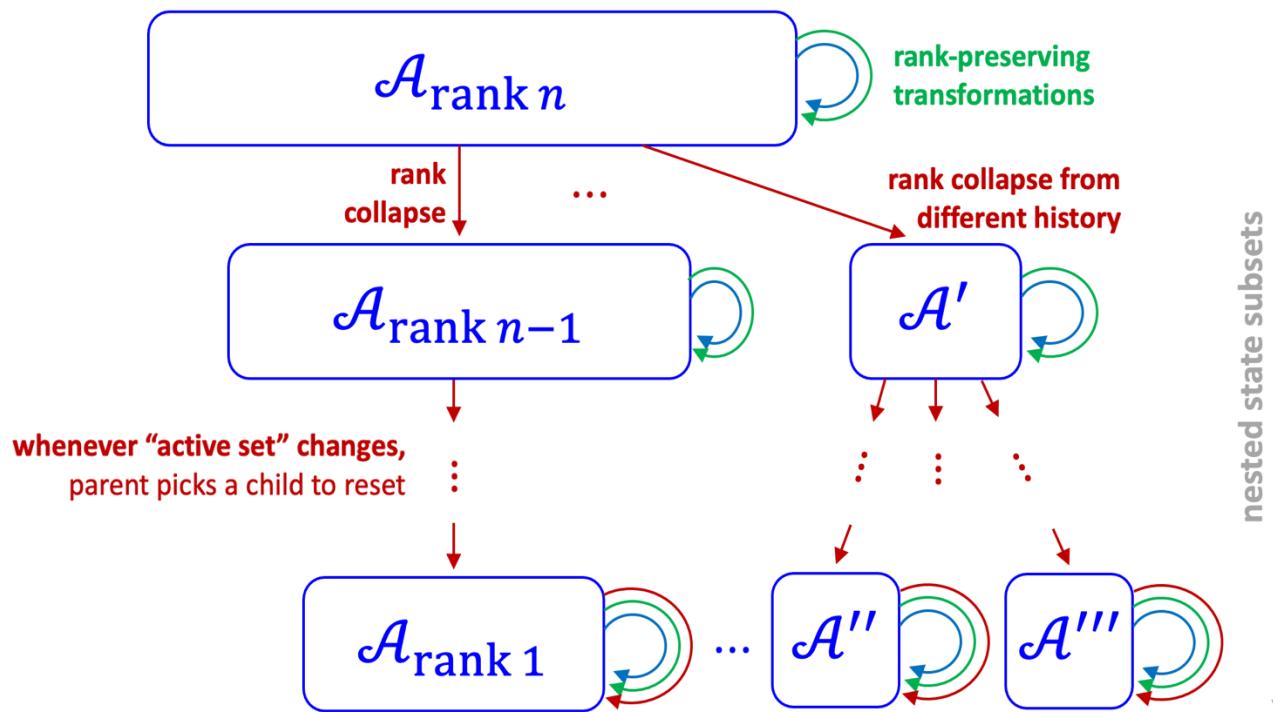
$$\Sigma = \{ \text{ cycle, swap, merge } \}$$

$$\begin{bmatrix} & & 1 \\ 1 & 1 & \end{bmatrix} \quad \begin{bmatrix} 1 & 1 \\ & 1 \end{bmatrix} \quad \begin{bmatrix} 1 & 1 \\ & 1 \end{bmatrix}$$

$\mathcal{T}(\mathcal{A}) = T_n$: all n^n functions $[n] \rightarrow [n]$

Krohn-Rhodes Intuitions

Tracking rank collapses (*holonomy decomposition*)



Number of layers: (recall: $|G| \leq n^n$)

- Solvable groups: $O(\log |G|)$
 - mod counter
- Permutation-reset semiautomaton: $O(\log |G|) + 2 \leq O(|Q| \log |Q|)$.
 - mod counter + memory unit
- Semiautomaton: $\leq |Q|$ levels.

Training with limited supervision

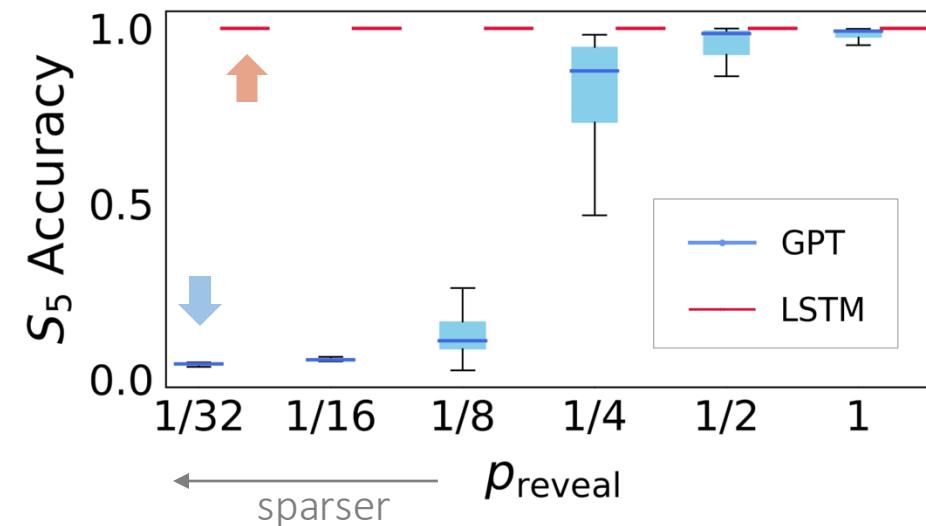
Less ideal setups?

Indirect supervision

train & test on a function of q_t .

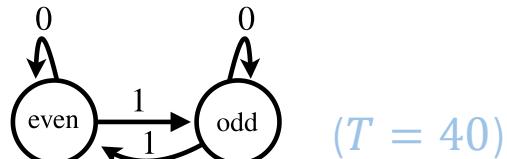
Dyck _{4,8}	Grid ₉	S_5	C_4	D_8
stack top	$\mathbb{1}_{\text{boundary}}$	$\pi_{1:t}(1)$	$\mathbb{1}_{0 \bmod 4}$	location
100.0	99.8	99.8	99.7	99.8

Incomplete supervision
 q_t is revealed w.p. $p_{\text{reveal}} \in [0,1]$.



LSTM is always 100% → Open: How to *improve Transformer training?*

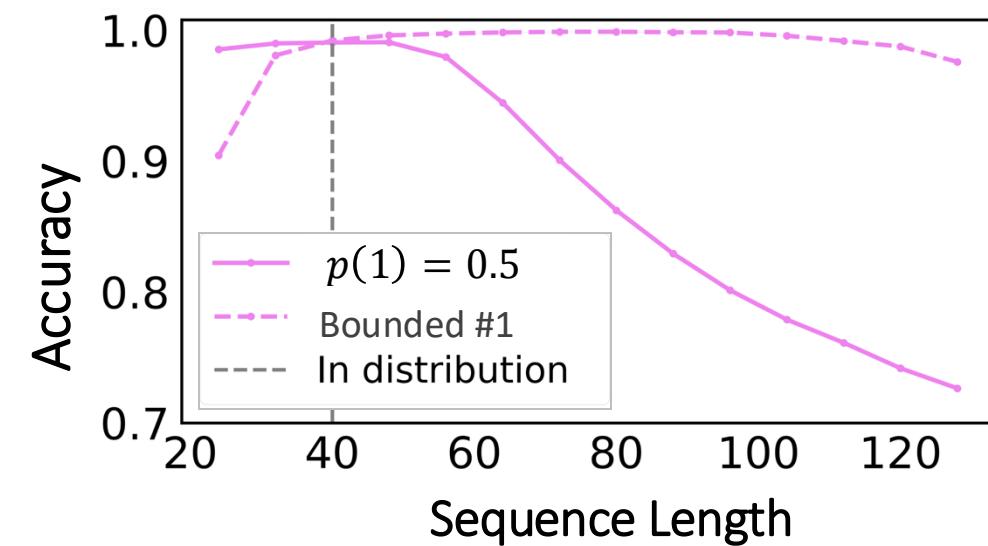
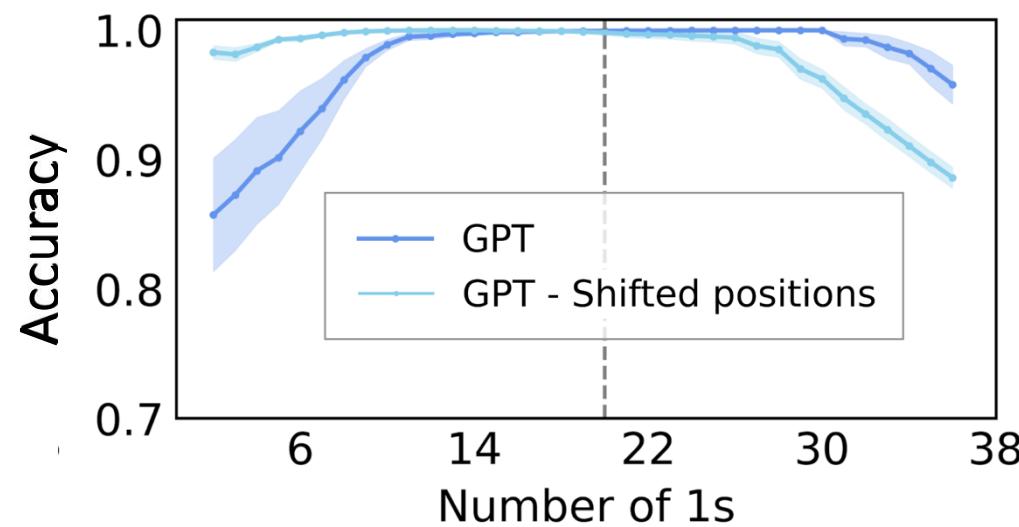
OOD Generalization - Parity



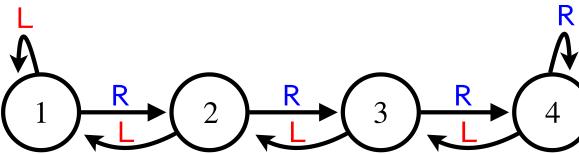
- train: $p(1) = 0.5$
- test: other $p(1)$.

$$q_t = \left(\sum_{i \in [t]} \sigma_i \right) \bmod 2$$

concentrates $\approx p(1) \cdot t$ \rightarrow fail at unseen $\left(\sum_{i \in [t]} \sigma_i \right)$.

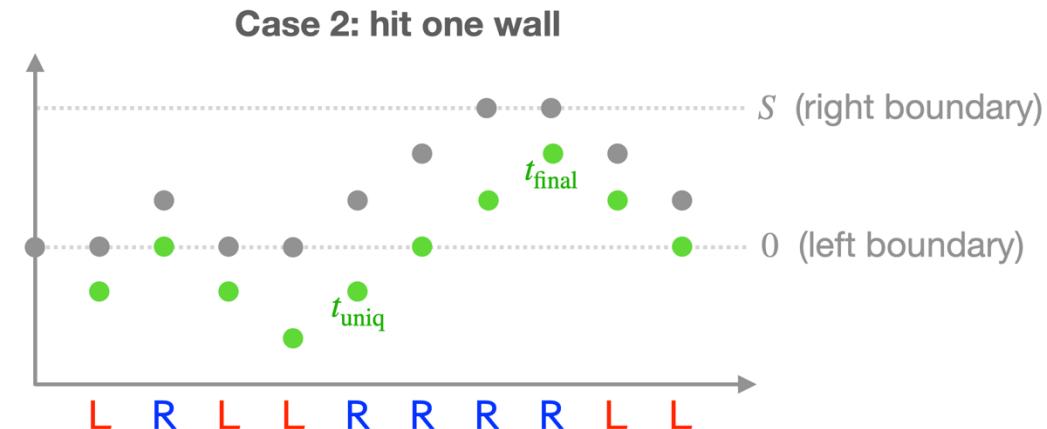
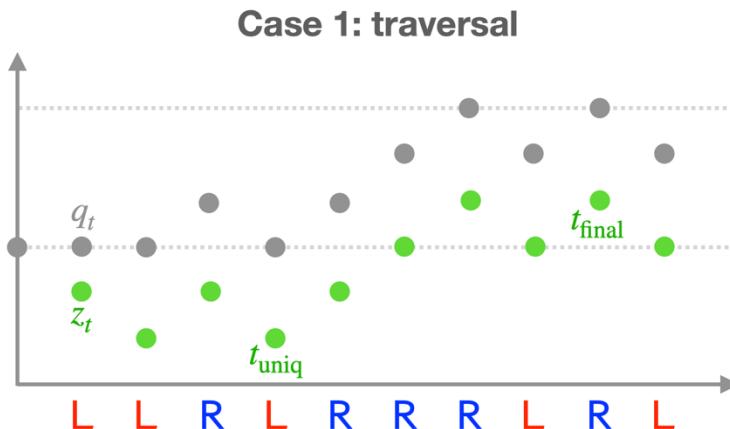


$O(1)$ layer for



- Parallel boundary detector:

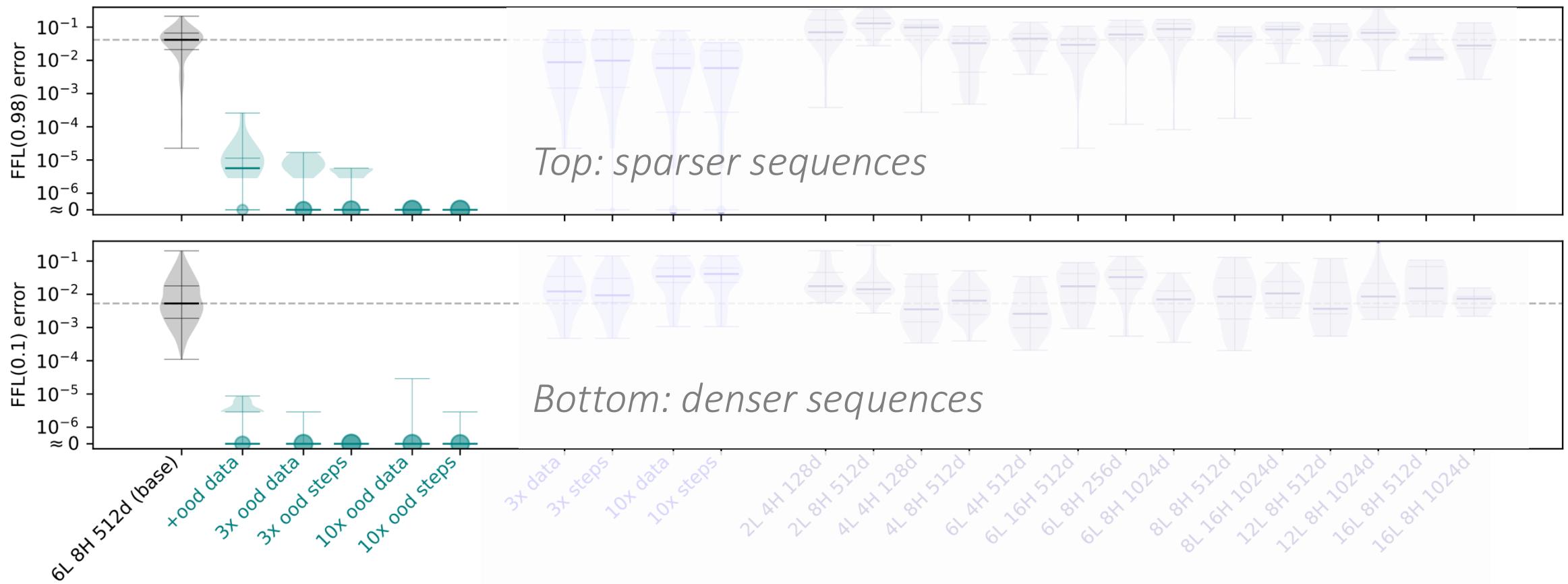
- Compute prefix sums $z_t := \sum_{\tau=1}^t \sigma_{1:\tau}$ (ignoring boundaries);
- At each t , find most recent $t_{\text{uniq}} < t$ such that $z_{t_{\text{uniq}}:t}$ has $n(\# \text{states})$ unique values;
- Then $t_{\text{final}} := \max(\operatorname{argmax}_{t_{\text{uniq}} \leq \tau \leq t} z_\tau, \operatorname{argmin}_{t_{\text{uniq}} \leq \tau \leq t} z_\tau)$ is last boundary collision.



Direct mitigations

(R4) Incorporating OOD data (“priming”) works the best, by far.

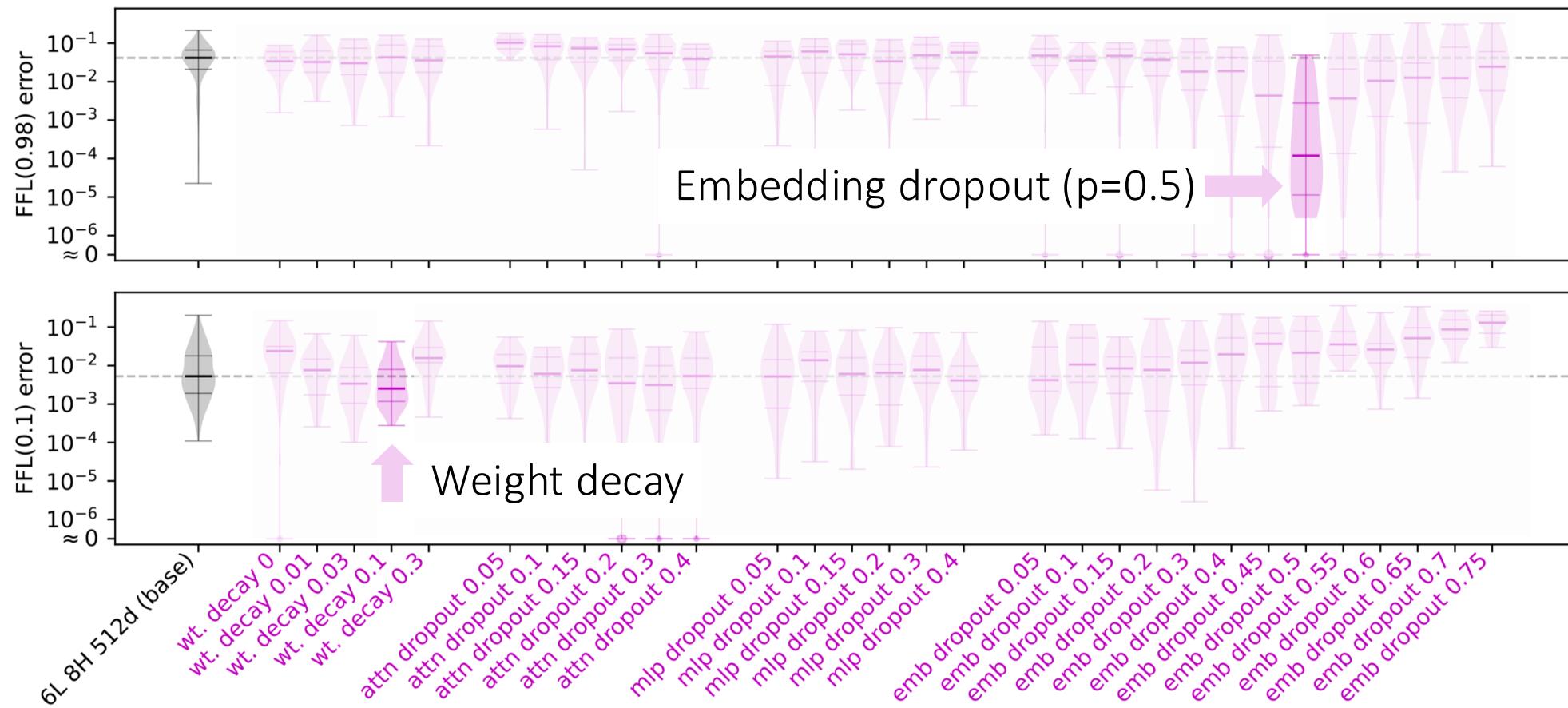
[Jelassi 23]



Indirect mitigations

- Weight decay
- Dropout (attention, MLP, embedding)

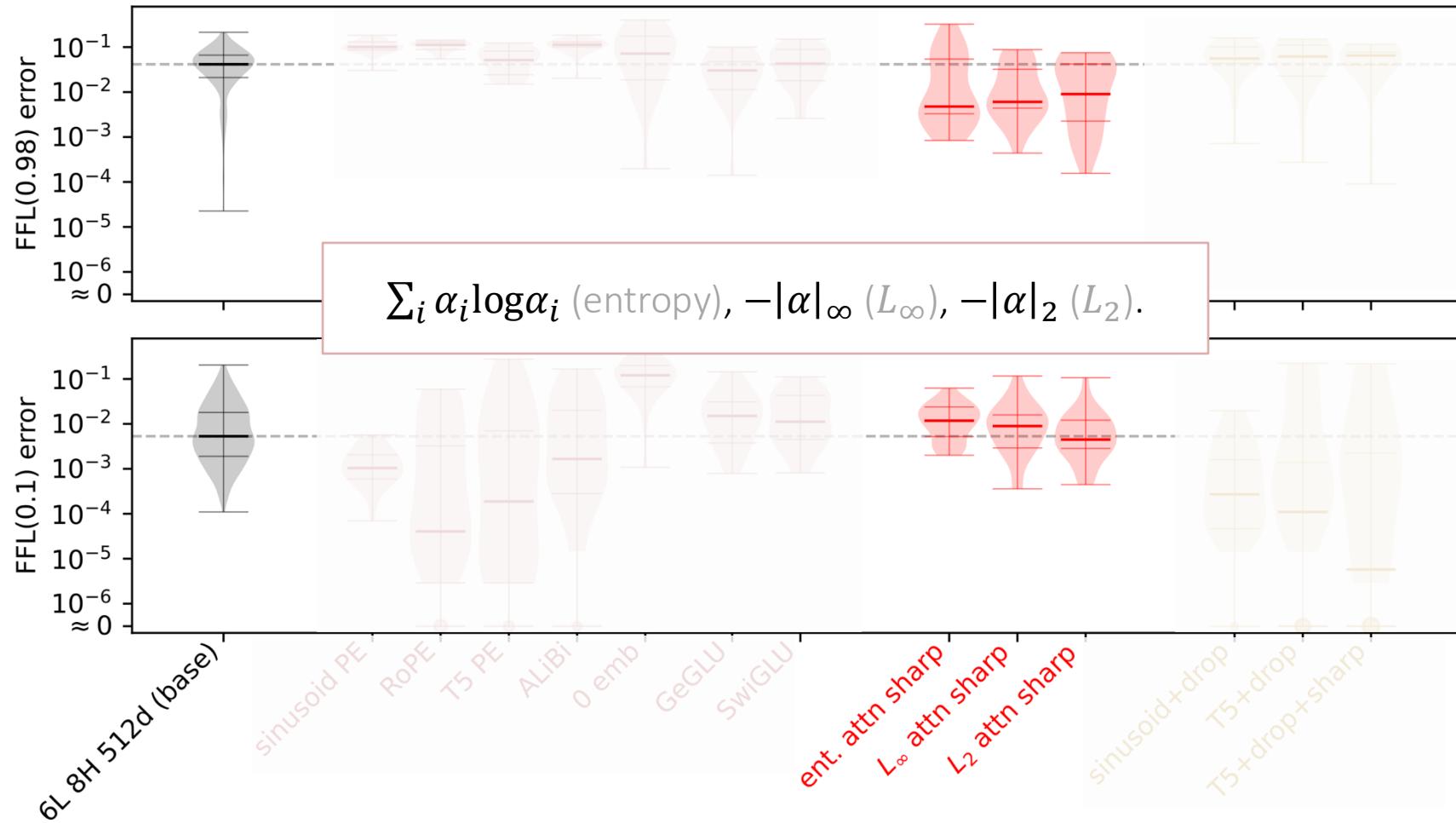
(R6) Standard regularizations have various influences.



Indirect mitigations

Attention-sharpening regularization

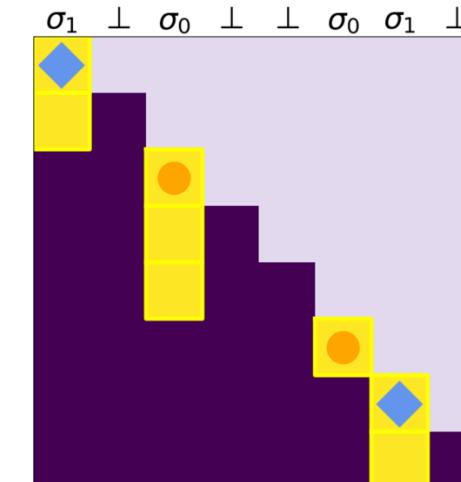
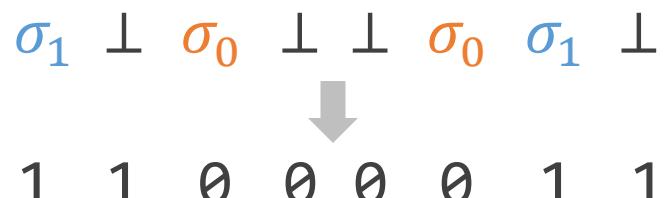
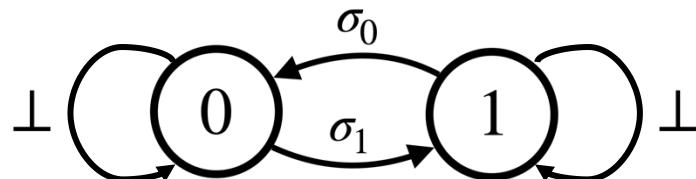
(R6) Standard regularizations have various influences.



Preliminary interpretability results

Simpler setup: flip-flop monoid

- $w\theta = \sigma_0, w1 = \sigma_1, i = \perp$; read at each step.

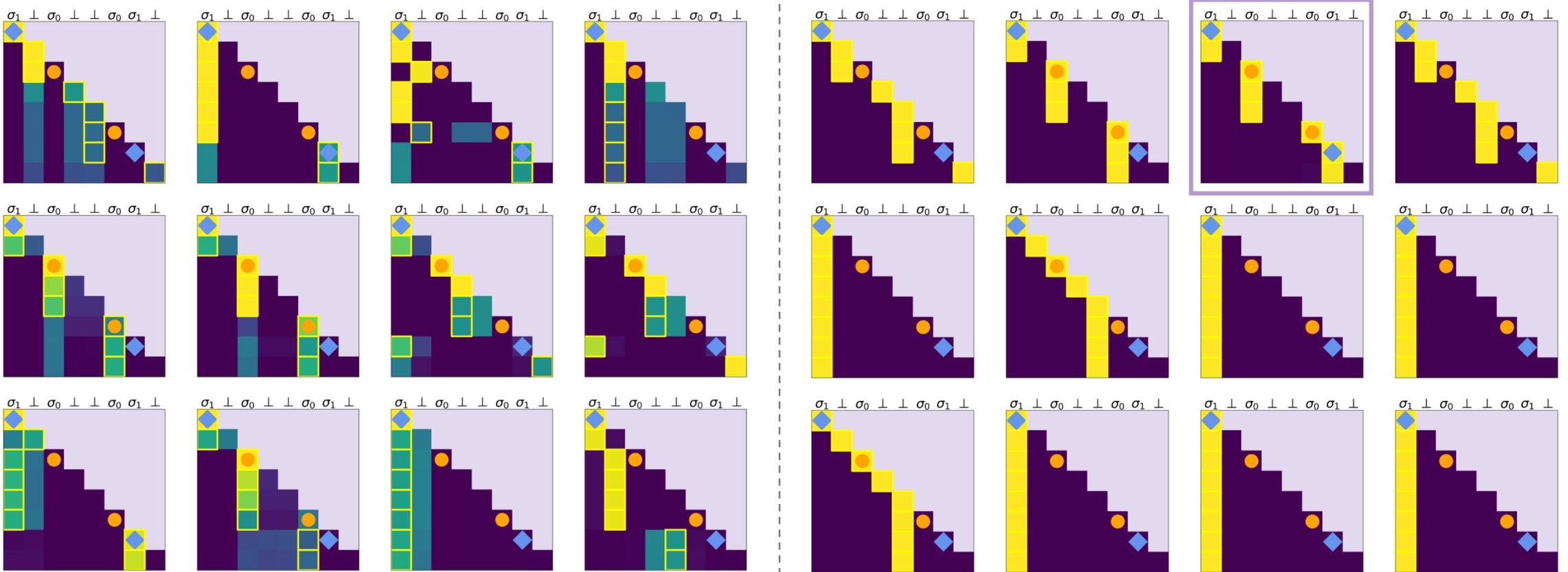


Solvable by 1-layer 1-head Transformers.

- 1-sparse attention: on the closest 0,1.

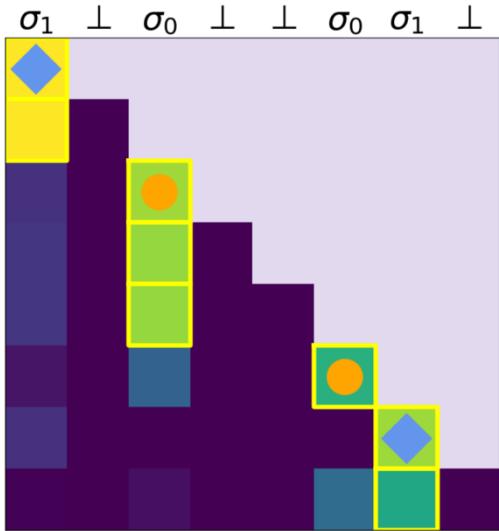
What solutions are found?

6-layer 8-head ... normal (left) vs attention-sharpened (right)

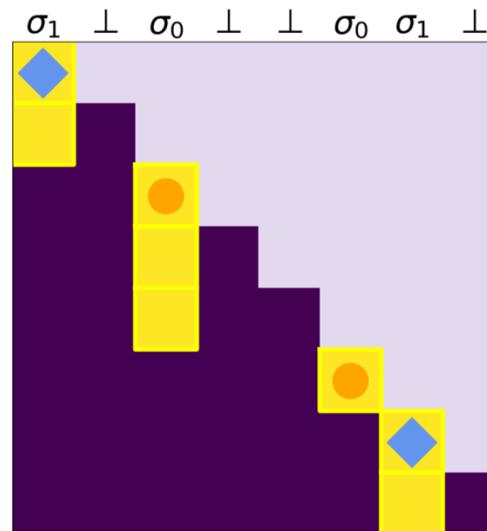


What solutions are found?

1-layer 1-head: normal vs attention-sharpened.

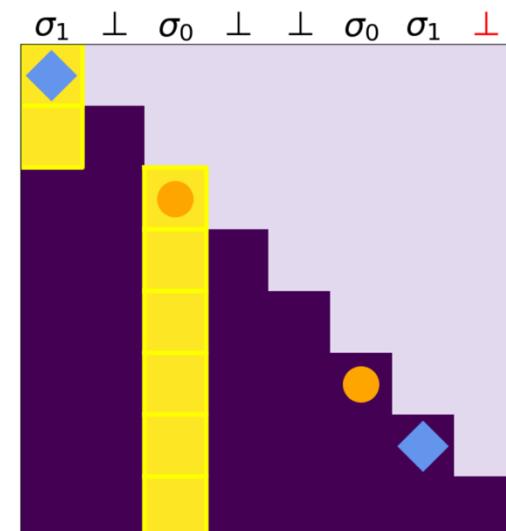


(a) normal



(b) sharpened 1

other dense/sparse patterns exist



(c) sharpened 2

wrong prediction!