

# Pollution Estimation and Prediction of Pittsburgh

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## Abstract

*In modern society, air pollution exerts a critical negative impact on the environment and the health of the human population. The Air Quality Index (AQI), is a dimensionless index that quantitatively describes the air quality condition, and the higher its value, the worse the air quality condition and the greater the negative impact on human health, ecology, and the environment. We use data from U.S. Environmental Protection Agency and macro-trends to predict AQI values in Pittsburgh through  $PM_{2.5}$ ,  $PM_{10}$ ,  $SO_2$ ,  $CO$ , and  $O_3$  concentrations. The mean squared error (MSE) is applied to the experiments in this project to assess the overall performance of the algorithm. To estimate and predict linear AQI regression in Pittsburgh, two simple model, Linear Regression and Deep neural network, are applied to the AQI from the forecasting system. Then we try to take the other pollution sensors' information in to consideration to better predict the AQI of Pittsburgh, so we use the Convolutional Neural Networks (CNN) on filtered 3 days ozone data transformed to a 2D image to predict the Ozone Value of Pittsburgh, Which has a better performance than normal models only using Pittsburgh's Ozone data. It is found that interregional pollutant transportation has a great impact on the air quality of Pittsburgh.*

## 1 Introduction

Poor air quality is one of the greatest public health threats of our time. According to the World Health Organization, more than 90% pollution, which of the world breathes unhealthy air pollution has become the fourth largest risk factor for human health on the planet. Past studies indicate that globally, 8.8 million people die indirectly each year because of poor air quality, and 1 in 8 premature deaths in the world are due to air pollution. The AQI, or Air Quality Index, measures air quality over a given period of time for a given area. The value of the AQI between 1 and 50 is considered satisfactory, and air pollution poses little or no risk. Factors affecting AQI etc. values include the level of ground-level ozone, particle pollution, nitrogen dioxide, carbon monoxide, and sulfur dioxide, etc in the air. Due to the industrialization and urbanization of Pittsburgh, in our study, we focus on the prediction of AQI Value, which generally represent the air quality (and the CNN part is concentrated on Ozone,  $O_3$ ) in the region and inves-

tigate the correlation between pollution parameters and AQI values in the control. This study uses air quality data from Pittsburgh and sensors all across the United States, and uses data engineering and machine learning methods to process and predict air pollutants.

## 2 Related Work

From time to time, various researchers have successfully applied several machine learning models for long and short-term prediction of air quality (Cabaneros et al. 2019, 2017; Lightstone et al. 2017; Ibarra-Berastegi et al. 2008)[1][4][3]. For better prediction results, some research suggested using a vast dataset. Two-hybrid models had been proposed by Zhu et al., which were EMD-intrinsic mode functions (IMF) based hybrid model and empirical mode decomposition (EMD)-SVR based hybrid model. (Zhu et al. 2017)[5]. Jiaxuan Zhang et al [7] used CNN-LSTM multi-model forecast Air Quality Index in Beijing, CNN's efficient feature extraction function was used to extract data features, improved the air quality prediction accuracy (Jiaxuan Zhang et al. 2022). Sarun Duangsuwan used BPNN-CNN model predicted the results of air pollution parameters and generated 3D AQI mapping locations assess air pollution monitoring at 98% accuracy for data assessment in an open burning scenario (Sarun Duangsuwan et al. 2022)[2]. In our study, we propose a CNN network-based model to predict the relationship between air pollutants and AQI considering the influence of the geographical location of the observation sites.

## 3 Data

Our datasets are public data sets from EPA (United States Environmental Protection Agency) pre-Generated Data Files[6]. EPA programs use data standards to provide consistently defined and formatted data elements and sets of data values. These standards improve public access to meaningful environmental data. We used it to obtain data related to air pollution ( $PM_{2.5}$ ,  $PM_{10}$ ,  $SO_2$ ,  $CO$ , and  $O_3$ ) in Pittsburgh and sensors all across United States for 7 years (2015 to 2021), which also contained some labels like units of measure, observation count, observation percent, arithmetic mean, first maximum value, etc. For our prediction, we generally use the daily "Arithmetic Mean" values for all the pollutants. From the original data set (which is composed of thousands of different sensors for 1 year per CSV file, with some null values or no record for certain days), we extracted AQI and the daily average pollutants as labels through data engineering and used

Linear regression is a commonly used method in machine learning that is used to model the relationship between a dependent variable and one or more independent variables. In a linear regression model, the dependent variable is predicted by a linear combination of the independent variables. The mean squared error (MSE) is a common metric used to evaluate the model's performance. It is calculated as the average of the squared differences between the predicted values and the true values, and is a measure of the overall error of the model, which is able to predict the true values of the dependent variable. A lower MSE value indicates that the model is making more accurate predictions, while a higher MSE value indicates that the model is less accurate. So in our project, we use MSE in combination with other metrics together, these metrics can provide a comprehensive evaluation of a linear regression model's performance.

We used a linear regression model, regressed the data linearly with hyperparameter adjustment, and choose the `adGrid(lr.regParam)` is 0.001, 0.01, 0.1, 1; choose the `adGrid(lr.maxIter)` is 100, 200, 500, 1000 when `parallelism=8`, `numFolds=5`, and obtained the value of Train MSE and Test MSE. From the result we choose the best `regParam` as 0.01 and `best maxIter` as 1000.

### 4.3 Deep Neural Network (Keras)

Keras is an open-source deep learning library that is written in Python and is capable of running on top of other popular deep learning libraries, such as TensorFlow, Theano, and CNTK. In Keras, a neural network is represented as a sequence of layers, which are stacked on top of each other to form a deep learning model. Each layer is a modular, self-contained building block that can be combined with other layers to create a deep learning architecture. Keras makes it easy to develop and train neural networks using a variety of different architectures.

In this part, we use TensorFlow and Keras to build our neural network to process the data with linear layers. The learning rate, epochs, loss, and `val_loss` of this data set are calculated and obtained learning rate, epochs, loss, and `val_loss` of the best model. Epoch in our model refers to the one entire passing of training air data through the algorithm. It's a hyperparameter defined as the total number of iterations of all the training data in one cycle for training the machine learning model. The learning rate is also a hyper-parameter that controls how much we are adjusting the weights of our network with respect to the loss gradient. Loss is a number of the penalty for a bad prediction indicating how bad the model's prediction was on a single example. If the model's prediction is perfect, the loss is zero; otherwise, the loss is greater. `val_loss` is the value of the cost function for your cross-validation data and loss is the value of the cost function for your training data. So in our model, we later determine the results of model training by the hyperparameters.

Here we just use a simple Deep Neural Network. (model = `keras.Sequential()`, `keras.layers.Dense(wid, activation='relu')`, `Optimizer= Adam(0.01)`, `epoch=100`). We choose MSE for the loss function and evaluator parameter. And hyperparameter tuned the model for Layers depth in [3,5,7,10] and width in [15,18,20,25].

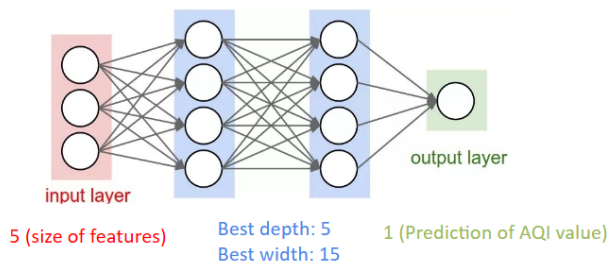


Figure 2: Structure of neural networks

### 4.4 Convolutional Neural Network

We figured that it is not enough to only do analysis based on the pollutants' concentration in Pittsburgh itself, but should lay more emphasis on the location of the monitors and the meteorological data, and thus we are trying to create intensity maps across the United States and train them using CNN to predict the AQI of Pittsburgh.

Convolutional Neural Network (CNN) is a type of deep learning neural network that is designed to automatically and adaptively learn spatial hierarchies of features from input data by using multiple layers of interconnected nodes. CNNs are composed of multiple layers, including an input layer, hidden layers, and an output layer. The hidden layers consist of multiple convolutional layers and pooling layers, which extract features from the input data and reduce its dimensionality; these layers combine the extracted features to make predictions. In this part, we use the CNN model to do predictions. Data-driven models are generally dependent on the size of the dataset. CNN models, like other empirical models, can be applied to datasets of arbitrary size, but the dataset used for training should be large enough to cover all known possible problems in the problem domain.

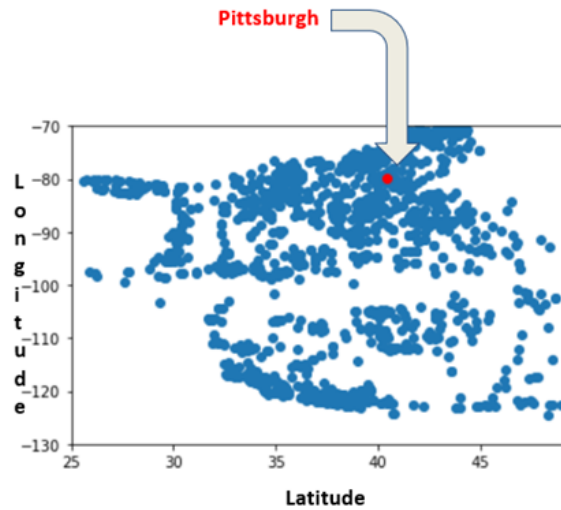


Figure 3: Geographic location of each monitoring station.

The datasets we are using are sensor-based air quality data and geographical location data. Based on the empirical research, the best results are obtained by partitioning the dataset into 7-80% for training and 20-30% for testing. That's why the dataset in this work is bisected as 80% for training and 20% for testing purposes. Our Linear Regression model and Convolutional Neural Network (CNN) model are trained with the training dataset and tested on the testing dataset to evaluate the results for analyzing the performance of the models. For DNN model, the train, validate and test data set is randomly splitted as 80%, 10% and 10%. Further subsections discuss the implementation of the models and the analysis of results.

#### 4.5 Linear Regression Model & DNN Model

We tested both linear regression models and a neural network model for the air quality index estimation. After several trials, we found that this two simple models is not good at predict the air quality index. The MSE is far from ideally closing to 0.

The pre-processed air quality data are provided as input to the models. The training process uses labeled data and allows the machine to learn the relationship between features and labels by comparing the error between the predicted value and the actual label and using a gradient descent algorithm to reduce the loss, tuning the parameters in continuous iterations until the algorithm finds the model parameters with the lowest possible loss or the overall loss stops changing and the optimal model is determined; while the prediction process applies the trained model to the unlabeled data, i.e., mapping the data to the predicted labels. The gradient descent algorithm uses a gradient multiplied by a learning rate to determine the location of the next point in the loss function image. The size of the set learning rate is related to the degree of gradient flatness. Batch size is the total number of data used to compute the gradient in a single iteration, and selecting small batches is usually more effective than whole batches when performing gradient descent on large datasets.

To facilitate multiple hyperparameter tuning of the model, we created functions for building and training the model, and determined hyperparameters such as learning rate and epochs after several tests. The final loss curve shows a steady decline with a slope close to zero, indicating that the model converges. At last, the performance assessment of the Linear Regression model is presented using the MSE method. The obtained MSE values are listed below.

Linear Regression Model	Deep Neural Network Model
(Hyperparameter Tunning)	(Hyperparameter Tunning)
RegParam [0.001, 0.01, 0.1, 1]	Width [15, 18, 20, 25]
MaxIter [100, 200, 500, 1000]	Depth [3, 5, 7, 10]
(Best Parameters)	(Best Parameters)
Learning Rate 0.1	Stimulate Function RELU
RegParam 0.1	Optimizer Adam0.01
MaxIter 1000	Learning Rate 0.01
MSE on train dataset: 122.2905	Epochs 100
MSE on test dataset: 131.5947	Width 15
	Depth 5
	MSE on train dataset: 116.0465
	MSE on validate dataset: 112.2235
	MSE on test dataset: 145.8887

Table 3: MSE values of four prediction models.

Note that the AQI on the next day is predicted using the previous 2-day information.

#### 4.6 Convolutional Neural Network Model

As the normal model (Linear Regression and DNN are not performed well in the prediction task, we keep our eyes on the CNN, since the CNN model has more divisions and may contain the interregional interaction between Pittsburgh and

other cities, which could influence the model performance. To investigate whether interregional pollutant transportation has a relatively large impact on air quality in Pittsburgh, we use CNN to perform complex mathematical calculations on the input time series, identifying useful information and feature extraction. As explained in 4.Methods, the datasets of air pollutant concentrations for Pittsburgh and the surrounding area are available from the EPA website, which includes the geographic location (latitude and longitude) of each monitoring station.

Site Num	Latitude	Longitude	Local Site Name	Address	count
11	34.530717	-86.967536	DECATUR, Alabama	P.O. BOX 2224 WAL...	246
1004	39.166017	-120.148833	Tahoe City-Fairwa...	221 Fairway Drive...	362
1	34.376227	-84.059506	Dawsonville	Georgia Forestry ...	246
3	41.89557	-86.001629	Cassopolis ROSS B...	22721 DIAMOND COV...	266
26	27.832413	-97.555387	Corpus Christi Tu...	9860 La Branch	363
15	43.31551	-89.10889	COLUMBUS	1045 WENDT RD, CO...	209
9997	33.503833	-112.095767	JLG SUPERSITE	4530 N 17TH AVENUE	358
7	35.345607	-118.851825	Edison	JOHNSON FARM, EDI...	364
6	30.130433	-85.731517	ST. ANDREWS STATE ...	4607 STATE PARK L...	365
9991	40.816038	-85.661408	Salamonie Reservoir	Hamilton Rd, Lagr...	365
12	38.06503	-84.49761	LEXINGTON PRIMARY	FAYETTE COUNTY HE...	193
31	39.521933	-119.7954	Reno4	1260-A Stewart St.	363
21	31.796218	-106.584434	62M Desert View	5935A VALLE VISTA...	365
2	35.434767	-83.442133	Bryson City	30 Recreation Par...	238
101	35.964969	-84.22317	Freel's Bend 03 a...	FREELS BEND_STUDY...	241
9001	33.67649	-117.33098	Lake Elsinore	506 W FLINT ST. L...	361
5	40.283092	-74.742613	Rider University	Athletic Fields, ...	361
3	43.873056	-104.191944	null	Newcastle, WARMS ...	346
101	36.508611	-116.847778	Death Valley NP ...	DEATH VALLEY NM, ...	365
5	37.98178	-120.378551	Sonora-Barretta S...	251 S BARRETTA, ...	364

Table 4: Geographic location (latitude and longitude) of each monitoring station.

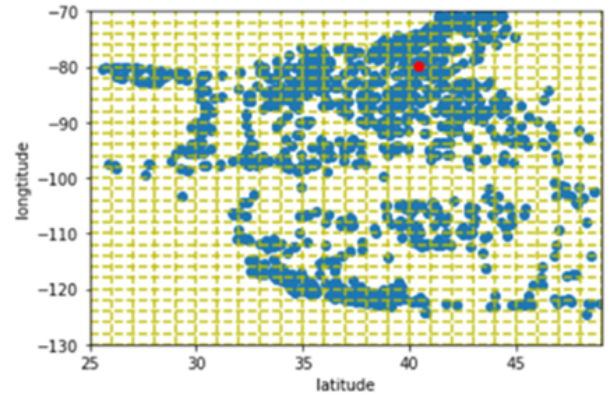


Figure 4: The 2-d map with adjacent sites falling into the same cell.

Since CNN has internal structures that are designed to operate upon three-dimensional image data, a 40x50 map is created for everyday data and maps for every three days are stacked to form an "image". The map is bounded by the maximum and minimum of the coordinates, with the input of daily ozone concentrations. If multiple locations are assigned to the same point, their input would be averaged. The ozone concentrations in Pittsburgh are the target values (except that of the first three days). These intensity maps are generated using OpenCV and then provided as input to the CNN model. The CNN model is run using Adam optimizer with a learning rate



of  $1e-5$ , and the batch size is set to 1 for better convergence.

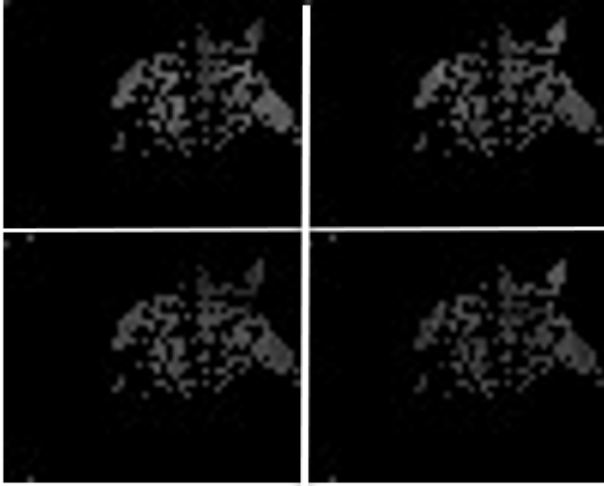


Figure 5: Intensity maps generated using OpenCV.

The losses of the training and testing process are calculated and shown below. As we can see, the train and test loss for CNN model is less than 0.1, and the plots of loss cross to iterations show that changes in pollutant concentrations in Pittsburgh are significantly influenced by air pollution in the surrounding area.

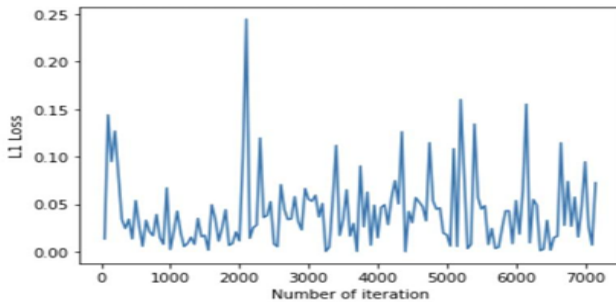


Figure 6: Train loss vs. number of iterations.

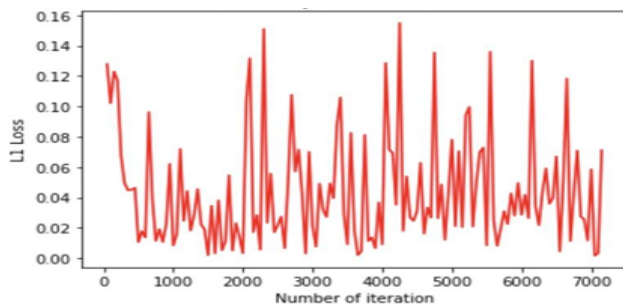


Figure 7: Test loss vs. number of iterations.

## 5 Conclusion

The results of the prediction evaluation show that linear regression and DNN are not a good model for predicting Pittsburgh's air quality, while our CNN model performs very well in the prediction, and the loss curve of our CNN model may indicate that interregional pollutant transportation can have a great impact on the air quality of Pittsburgh.

However, since the monitor/sensor sites are not exactly same for different Pollutants, our CNN model only use Ozone and it's AQI as input features, the conclusion that CNN model performs better for AQI prediction may change if all pollutants are take into consideration.

In the future, our work could be extended in the following aspects. First, we will consider more data related to air quality, e.g., various urban big data related to air quality (meteorology, traffic, factory air pollutant emissions, road network distribution, etc.) Second, other approaches, such as semi-supervised learning and Long Short Term Memory (LSTM) could be introduced to improve the accuracy and practicability of the model. Third, we could evaluate our method in more cities to make the results more convincing.

## 6 Labor division

The members of our team are Wenyan Zheng, Haineng Huang, JianFeng Su, and Kaixin Song. Our TA advisor is Linji Wang. Our tasks mainly include data processing, model development and evaluation. These were evenly distributed to each member.

Data processing and model development: all team members

Final report write-up and presentation slides: all team members

## References

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