

Report of Data Structure

Graph Theory

Name: Linfeng Liu

No.: 519261910040

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SHANGHAI JIAOTONG UNIVERSITY SJTU-Paris Elite Institute of Technology

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1 Task1: Graph Class

As a preparation of all works later, we try to describe a graph in two ways: Adjacency List and Adjacency Matrix. We design two class, named as **Graphmatrix** and **Graphlist** respectively. We demonstrate this two class in this part. Before the design of these two classed, we design a class **Edge** with class members: **depart**, **destin** and **weight**, which represent respectively the start point, end point and the weight of the edge. In order to visit the private members of edge conveniently, we set **Graphmatrix** and **Graphlist** the friend class of **Edge**.

1.1 AM

In the class **Graphmatrix**, we can construct an arbitrary graph and its adjacency matrix with an array of the edges and an array of vertices. (The array of vertices can be generated by function **Edges2Nodes**. The adjacency matrix of the graph is demonstrated in Figure:1. We override the output operation to print this matrix.

	WL	LZ	LS	XA	CD	KM	ВЈ	WH	GZ	SY	TJ	SH	FZ
۸L	0	130	120	N	N	N	N	N	N	N	N	N	N
LZ	130	0	111	84	85	N	N	N	N	N	N	N	N
LS	120	111	0	N	110	N	N	N	N	N	N	N	N
XA	N	84	N	0	87	N	90	94	N	N	N	N	N
CD	N	85	110	87	0	86	N	99	102	N	N	N	N
KM	N	N	N	N	86	0	N	N	101	N	N	N	N
ВЈ	N	N	N	90	N	N	0	100	N	88	9	N	N
WH	N	N	N	94	99	N	100	0	98	N	97	96	95
GZ	N	N	N	N	102	101	N	98	0	N	N	N	91
SY	N	N	N	N	N	N	88	N	N	0	89	N	N
TJ	N	N	N	N	N	N	9	97	N	89	0	93	N
SH	N	N	N	N	N	N	N	96	N	N	93	0	92
FZ	N	N	N	N	N	N	N	95	91	N	N	92	0

Figure 1: Adjacency Matrix

1.2 AL

In the class **Graphlist**, we can construct an arbitrary graph and its adjacency list with an array of the edges and an array of vertices. (The array of vertices can be generated by function **Edges2Nodes**. The adjacency list of the graph is demonstrated in Figure:1. We override the output operation to print this list.

```
LZ
LS
XA
CD
KM
BJ
WH
GZ
SY
TJ
SH
FZ
                                             --->CD (85)
                                                             --->XA (84)
                                             --->CD (110)
                                            -->BJ (90)
                                                            -->WH (94)
                                                                            --->KM (86) --->GZ (102)
                                              ->CD (99)
                                                               ->GZ (98)
                                    (101)
                                                ->WH (98)
                                                             --->FZ (91)
                                                         --->SY (89)
                                           --->BJ (9)
                              >WH (97)
                                           --->TJ (93)
                                              ->SH (92)
```

Figure 2: Adjacency List

2 Task2: Sorting

In this part, we study the sorting methods in order to sort the array of edges in the graph. First of all, we design a **GetEdgeAM** to get an array of edges from an instance of **Graphmatrix**.

2.1 Heapsort

We design a class **MinHeap**, which can maintain an array according to the properties of a heap. We remove the minimal element of the heap each time and put it in the target array(used to restore the sorted array). The intermediate configuration of the heap and the result of the sorting are all demonstrated in Figure 3. The complexity of heapsort is O(mlog(m)) where m the number of edges in the array we sort. Because we remove all m element in the array and the complexity of remove the root of a heap is O(nlog(m)). That is why the total complexity of heapsort is O(mlog(m)).

Figure 3: process of heapsort

2.2 Mergesort

In order to demonstrate the intermediate sequences of edges during mergesort, we abandon the recursive implementation of mergesort and implement it with two loops. The outer loop determine the size of the merging part(1, 2, 4, 8...), and we merge the array partially in the inner loop. The intermediate sequences of edges during mergesort and the result of the sorting are all demonstrated in Figure 4. The complexity of mergesort is $\mathbf{O}(mlog(m))$ where m the number of edges in the array we sort. Because the complexity of the outer loop is log(m) (for $2^{len} = m$). The complexity of the inner loop is m, we traverse all the element in the array in order to merge them partially. That is why the total complexity of mergesort is $\mathbf{O}(mlog(m))$.



Figure 4: process of mergesort

3 Task3: MST

3.1 Two algorithms

We implement algorithm Prim and algorithm Krustal and get the same MST. The details of the implementation of these two methods are notated in the code. The pseudo code of these two alorithms are as below: the step to check if the two ends of the edge are in the same MST are implemented by

Algorithm 1 MST-Prim

```
Initialization: \mathbf{Heap} (heap of edges) of size 0, \mathbf{MST} (vector of edges in MST) empty, n the number of vertexs in the graph \mathbf{for}\ i=1 to n (n step to build the tree) \mathbf{do} for vertex in the non-traversed neighbors of the current vertex \mathbf{do} Push the vertex to \mathbf{Heap} end for pop the root of the heap and put it in \mathbf{MST} set the destination of the edge as current node end for
```

Union-Find.

Algorithm 2 MST-Krustal

```
Initialization: Heap (heap of edges) that contain all the edges in the graph, MST (vector of edges in MST) empty, n the number of vertexs in the graph for i=1 to n (n step to build the tree) do pop the minimal edge of the heap and take it as the current edge while the two ends of the current edge are in the same MST do pop the minimal edge of the heap and take it as the current edge end while put the current edge to MST end for
```

3.2 Result Demo

- 1. There are 12 routes (i.e. edges) in the MST of the map graph.
- 2. The minimal total distance of routes that keep all cites connected is 1042.
- 3. The MST is demonstrated in Figure 5.
- 4. Regarding WH as root, the tree is a binary tree which is demonstrated in Figure 5.

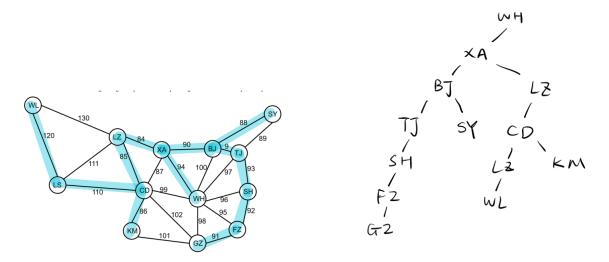


Figure 5: MST

5. The preorder traversal: WH-XA-BJ-TJ-SH-FZ-GZ-SY-LZ-CD-LZ-WL-KM.

6. The postorder traversal: GZ-FZ-SH-TJ-SY-BJ-WL-LZ-KM-CD-LZ-XA-WH.

7. The inorder traversal: GZ-FZ-SH-TJ-BJ-SY-XA-WL-LZ-CD-KM-LZ-WH.

4 Task4: Minimal Distance Path

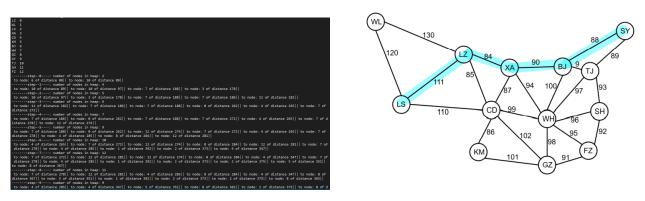


Figure 6: mininal cost path

In this part, we design a class **Node**, which have member variables: **node**, **distance**(the current minimal distance from the starting point to this node.) and **chemin**(the edge lead to this node). We change the pseudo algorithm a little and write it as below: The minimal distance from the city **SY** to city **LS** is **373**. The result is demonstrated in Figure 6

Algorithm 3 Minimal Cost Path

```
Initialization: \mathbf{NH} (heap of nodes) of size 1 with the start point in it, end point p_n, \mathbf{Path} (vector of edges) empty.

while p_n is not visited \mathbf{do}
pop the minimal vertex which have not been visited from NH.
add the chemin of this vertex to \mathbf{Path}.

for vertex in the non-traversed neighbors of the popped vertex \mathbf{do}
Push the vertex to \mathbf{NH} (with its current distance to S).
end for
end while
```

5 Summary

In this project, we design two main classes **Graphmatrix** and **Graphlist** and study some problems in graph theory: sort the edges by heapsort and mergesort, find the MST(minimal spending tree of the graph), find the minimal cost path to pass the given start point the end point.