

Algorithm Design and Analysis (H) cs216

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(slides edited from Prof. Shiqi Yu)



Dynamic Programming



Algorithmic Paradigms

• Greedy. Process the input in some order, and myopically making irrevocable decisions to optimize some underlying criterion.

• Divide-and-conquer. Break up a problem into independent subproblems, solve each subproblem, and combine solution to subproblems to form solution to original problem.

fancy name for caching intermediate results for later use

• Dynamic programming. Break up a problem into a series of overlapping subproblems, combine solutions to smaller subproblems to form solution to large subproblem.





Dynamic Programming History

 Richard Bellman. Pioneered the systematic study of dynamic programming in 1950s.



- Etymology of "dynamic programming".
 - Dynamic programming = planning over time.
 - Secretary of Defense had pathological fear to mathematical research.
 - > Bellman sought a "dynamic" adjective to avoid conflict.

"...it's impossible to use the word dynamic in a pejorative sense...
Thus, I thought dynamic programming was a good name. It was something not even a Congressman could object to."

Reference: Bellman, R. E. Eye of the Hurricane, An Autobiography.





Dynamic Programming Applications

Application areas.

- Bioinformatics.
- Control theory.
- Information theory.
- Operations research.
- Computer science: theory, graphics, AI, compilers, systems,

Some famous dynamic programming algorithms.

- Unix diff for comparing two files.
- Viterbi for hidden Markov models.
- Needleman-Wunsch/Smith-Waterman for sequence alignment.
- Bellman-Ford-Moore for shortest path routing in networks.





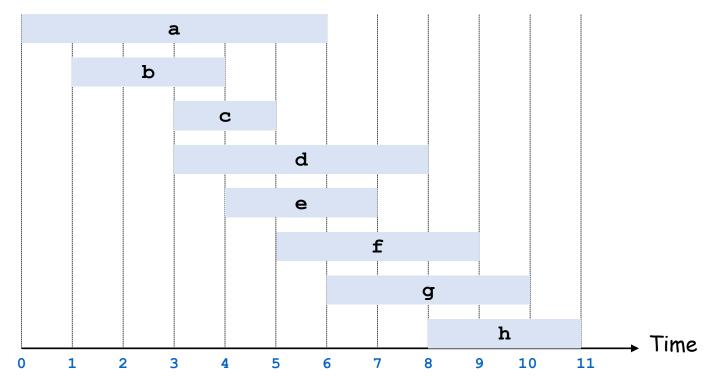
1. Weighted Interval Scheduling



Weighted Interval Scheduling

Weighted interval scheduling problem.

- \triangleright Job j starts at s_i, finishes at f_i, and has weight/value v_i.
- Two jobs compatible if they don't overlap.
- Goal: find maximum weight subset of mutually compatible jobs.



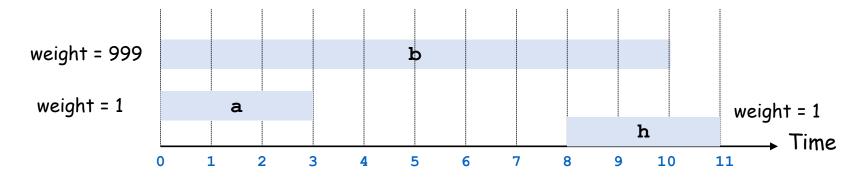




Recall: Unweighted Interval Scheduling

- Recall. Greedy algorithm works if all weights are 1.
 - Consider jobs in ascending order of finish time.
 - Add job to subset if it is compatible with previously chosen jobs.

Observation. Greedy algorithm fails spectacularly for weighted version.

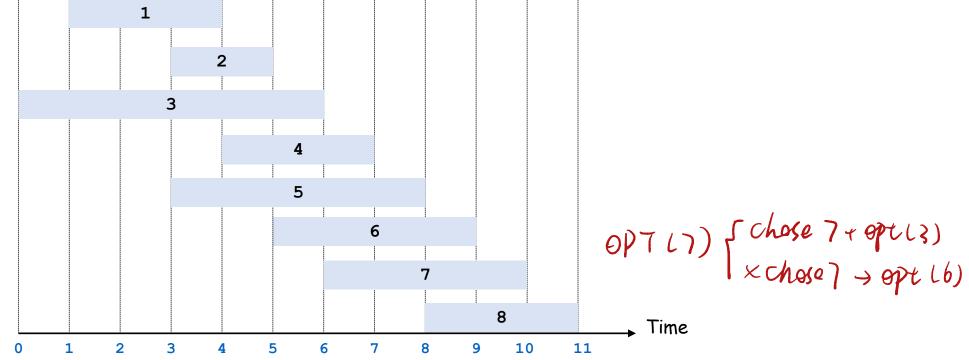






Weighted Interval Scheduling

- Convention. Order jobs by finish time: $f_1 \le f_2 \le ... \le f_n$.
- Def. p(j) = largest index i < j such that job i is compatible with j.
- Ex: p(8) = 5, p(7) = 3, p(2) = 0.







Dynamic Programming: Binary Choice

- **Def.** OPT(j) = max weight of any subset of mutually compatible jobs for subproblem consisting only of jobs 1, 2, ..., j.
- Goal. OPT(n) = max weight of any subset of mutually compatible jobs.

$$OPT(j) = \begin{cases} 0 & \text{if } j = 0\\ \max\{OPT(j-1), w_j + OPT(p(j))\} & \text{if } j > 0 \end{cases}$$

- > Case 1. OPT(j) does not select job j.
 - ✓ Must be optimal solution to problem consisting of remaining jobs 1, 2, ..., j 1.
- > Case 2. OPT(j) selects job j.
 - ✓ Collect weight v_i . (Can't use incompatible jobs p(j) + 1, p(j) + 2, ..., j 1.)
 - ✓ Must include optimal solution to problem consisting of remaining compatible jobs 1, 2, ..., p(j).





Weighted Interval Scheduling: Brute Force

Brute force algorithm.

```
Input: n, s_1, ..., s_n, f_1, ..., f_n, v_1, ..., v_n
Sort jobs by finish times and renumber so that f_1 \le f_2 \le \ldots \le f_n.
Compute p(1), p(2), ..., p(n) via binary search
                                                      O (nlogn)
return Compute-Opt(n)
Compute-Opt(j) {
   if (j = 0)
      return 0
   else
      return max{ Compute-Opt(j - 1), v; + Compute-Opt(p(j)) }
```



recursion could be very expensive!

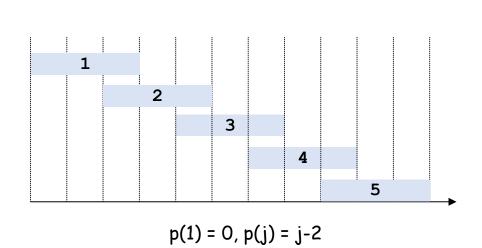


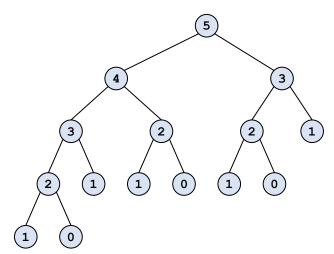
Weighted Interval Scheduling: Brute Force

• Observation. Recursive algorithm could be spectacularly slow due to overlapping subproblems \Rightarrow exponential-time algorithm.

• Ex. For family of "layered" instances, the number of recursive calls grows

like Fibonacci sequence.





depth \approx n, number of recursive calls $\approx 2^n$





Weighted Interval Scheduling: Memorization

- Memorization. Cache results of subproblem j in M[j] to avoid solving the same subproblem more than once.
- Dynamic programming algorithm (top-down).

```
Input: n, s_1, ..., s_n, f_1, ..., f_n, v_1, ..., v_n
Sort jobs by finish times and renumber so that f_1 \leq f_2 \leq \ldots \leq f_n.
Compute p(1), p(2), ..., p(n) via binary search
M[0] = 0 \leftarrow M[] is global array
return M-Compute-Opt(n)
M-Compute-Opt(j) {
   if (M[j] is uninitialized)
       M[j] = max\{ M-Compute-Opt(j-1), v_j + M-Compute-Opt(p(j)) \}
   return M[j]
```





Weighted Interval Scheduling: Running Time

- Claim. Memorized version of algorithm takes $O(n \log n)$ time.
- Pf.
 - \triangleright Sort by finish time: $O(n \log n)$.
 - \triangleright Computing p(·): O(n log n) via binary search.
 - ➤ M-Compute-Opt(j): each invocation takes O(1) time and either
 - ✓ returns an existing value M [j]; or
 - ✓initializes M [j] and makes 2 recursive calls
 - at most *n* uninitialized M [] entries \Rightarrow at most 2n recursive calls.
 - \triangleright Overall running time of M-Compute-Opt(n) is O(n).





Weighted Interval Scheduling: Finding a Solution

- Q. DP algorithm computes optimal value. How to find optimal solution?
- A. Do post-processing by calling Find-Solution(n).

• Running time. O(n), because number of recursive calls $\leq n$.





Weighted Interval Scheduling: Bottom-Up

Dynamic programming algorithm (bottom-up). Unwind recursion.

```
Input: n, s_1,...,s_n, f_1,...,f_n, v_1,...,v_n

Sort jobs by finish times and renumber so that f_1 \le f_2 \le ... \le f_n. Compute p(1), p(2), ..., p(n) via binary search

M[0] = 0

for j = 1 to n

M[j] = max\{ M[j-1], v_j + M[p(j)] \}

return M[n]
```

previously computed M[] values

• Running time. The bottom-up version takes O(n log n) time





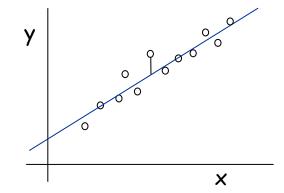
2. Segmented Least Squares



Least Squares

- Least squares. Foundational problem in statistics.
 - \triangleright Given n points in the plane: $(x_1, y_1), (x_2, y_2), ..., (x_n, y_n)$.
 - \triangleright Find a line y = ax + b that minimizes the sum of the squared errors (SSE).

$$SSE = \sum_{i=1}^{n} (y_i - ax_i - b)^2$$



• Solution. Calculus ⇒ min error is achieved when

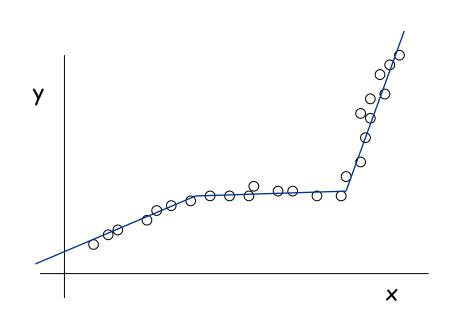
$$a = \frac{n \sum_{i} x_{i} y_{i} - (\sum_{i} x_{i})(\sum_{i} y_{i})}{n \sum_{i} x_{i}^{2} - (\sum_{i} x_{i})^{2}}, \quad b = \frac{\sum_{i} y_{i} - a \sum_{i} x_{i}}{n}$$





Segmented Least Squares

- Segmented least squares.
 - Points lie roughly on a sequence of several line segments.
 - Given n points in the plane (x_1, y_1) , (x_2, y_2) , ..., (x_n, y_n) with $x_1 < x_2 < ... < x_n$, find a sequence of lines that minimizes f(x) (x is the problem input).
- \bullet Q. What's a reasonable choice for f(x) to balance accuracy and parsimony?



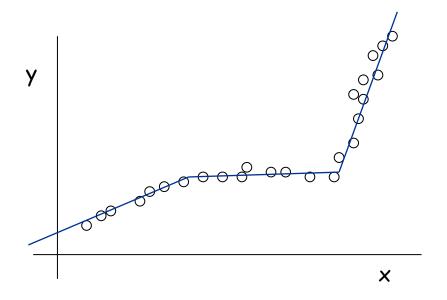
goodness of fit number of lines



Segmented Least Squares

Segmented least squares.

- Points lie roughly on a sequence of several line segments.
- Given n points in the plane (x_1, y_1) , (x_2, y_2) , ..., (x_n, y_n) with $x_1 < x_2 < ... < x_n$, find a sequence of lines that minimizes f(x) = E + cL (for some constant c > 0).
 - ✓ E = sum of the sums of the squared errors (SSEs) in each segment
 - \checkmark L = number of lines







Dynamic Programming: Multiway Choice

Def.

- \triangleright OPT(j) = minimum cost for points p_1, p_2, \ldots, p_j .
- \triangleright e_{ij} = minimum SSE for points p_i, p_{i+1}, . . . , p_j.
- Goal. OPT(n)
- To compute OPT(j):
 - ► Last segment uses points p_i , p_{i+1} , ..., p_i for some $i \le j$.
 - \triangleright Cost = e_{ii} + c + OPT(i 1).
- Bellman equation.

$$OPT(j) = \begin{cases} 0 & \text{if } j = 0\\ \min_{1 \le i \le j} \{ e_{ij} + c + OPT(i - 1) \} & \text{if } j > 0 \end{cases}$$





Segmented Least Squares: Algorithm

Dynamic programming algorithm (bottom-up).

```
INPUT: n, p_1, ..., p_n c
      M[0] = 0
       for j = 1 to n
           for i = 1 to j
                                                                                                  O(n^3)
               Compute the minimum SSE eij for the segment pi,..., pi
       for j = 1 to n
                                                                                                  O(n)
           M[j] = \min_{1 \le i \le j} \{ e_{ij} + c + M[i - 1] \}
       return M[n]
Precompute O(n)

e i_j = combinacion \sum_{k=1}^i x_k, \sum_{k=1}^i y_k, \sum_{k=1}^i x_k^2, \sum_{k=1}^i x_k y_k

• Remark. Can be improved to O(n^2) time.
```

- - \triangleright Compute e_{ii} in O(1) time using precomputed cumulative sums.





3. Knapsack Problem



Knapsack Problem

Knapsack problem.

- Given n objects and a "knapsack".
- \triangleright Item i weighs w_i > 0 kilograms and has value v_i > 0.
- Knapsack has capacity of W kilograms.
- Goal: fill knapsack to maximize total value of items taken.

Greedy approaches fail to work.

- repeatedly add item with maximum v_i.
- repeatedly add item with maximum w_i.
- \triangleright repeatedly add item with maximum ratio v_i / w_i .
- Ex. Optimal subset for W = 11 is { 3, 4 } with value 40.

#	value	weight
1	1	1
2	6	2
3	18	5
4	22	6
5	28	7





Dynamic Programming: False Start

- Def. OPT(i) = maximum value within weight capacity W using items 1, ..., i.
- Goal. OPT(n)
- To compute OPT(i):
 - Case 1: OPT(i) does not select item i.
 - ✓ OPT(i) selects best of { 1, 2, ..., i 1 }
 - > Case 2: OPT(i) selects item i.
 - ✓ not sure which other items should be excluded
 - ✓ not sure how to relate to OPT(j) for j < i

Conclusion. Need more sub-problems!





Dynamic Programming: Adding a Variable

- Def. OPT(i, w) = maximum value within weight limit w using items 1, ..., i.
- Goal. OPT(n, W)
- To compute OPT(i, w):
 - Case 1: OPT(i, w) does not select item i.
 - ✓OPT(i, w) selects best of { 1, 2, ..., i 1 } within weight limit w
 - Case 2: OPT(i) selects item i.
 - ✓ OPT(i, w) collects value v_i
 - ✓OPT(i, w) selects best of { 1, 2, ..., i 1 } within weight limit w w_i

• Bellman equation.
$$OPT(i,w) \ = \begin{cases} 0 & \text{if } i=0 \\ OPT(i-1,w) & \text{if } w_i > w \\ \max \{\ OPT(i-1,w), \ v_i + OPT(i-1,w-w_i)\ \} & \text{otherwise} \end{cases}$$





Knapsack Problem: Algorithm

Dynamic programming algorithm (bottom-up).

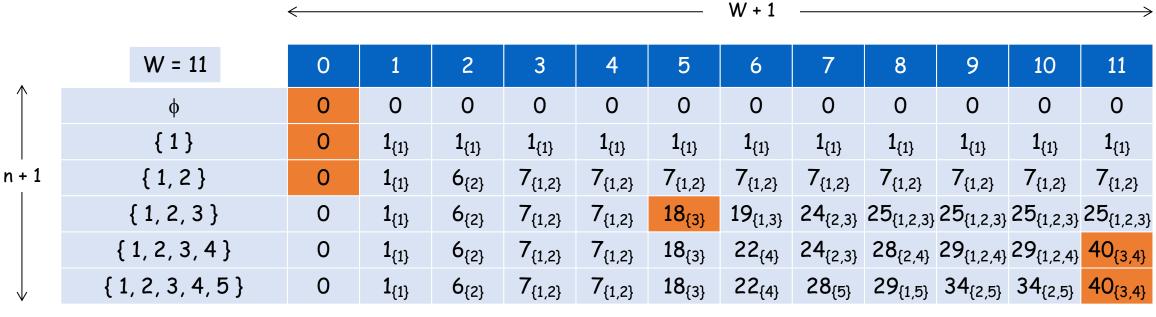
```
Input: n, W, w_1, ..., w_n, v_1, ..., v_n
for w = 0 to W
   M[0, w] = 0
for i = 1 to n
   for w = 1 to W
      if (w_i > w)
         M[i, w] = M[i - 1, w]
      else
          M[i, w] = \max \{ M[i - 1, w], v_i + M[i - 1, w - w_i] \}
return M[n, W]
```

Running time. O(nW)





Knapsack Algorithm: Demo



Item	Value	Weight
1	1	1
2	6	2
3	18	5
4	22	6
5	28	7

$$OPT(i,w) \ = \ egin{cases} 0 & ext{if } i=0 \ OPT(i-1,w) & ext{if } w_i>w \ & ext{max} \left\{ \ OPT(i-1,w), \ v_i+OPT(i-1,w-w_i) \
ight\} & ext{otherwise} \end{cases}$$





Knapsack Problem: Remarks

- DP algorithm depends crucially on assumption that weights are integral.
- Running time O(nW) is not polynomial in input size! "pseudo-polynomial"

- Decision version of Knapsack is NP-complete. [Chapter 8]
 - > Can a value of at least V be achieved under a restriction of a certain capacity W?
- Knapsack approximation algorithm. There exists a polynomial-time algorithm that produces a feasible solution that has value within 0.01% of optimum. [Section 11.8]





Exercise: Coin Changing

- Observation. Greedy algorithm is sub-optimal for US postal denominations: 1, 10, 21, 34, 70, 100, 350, 1225, 1500.
- Counterexample. 140¢.
 - > Greedy: 100, 34, 1, 1, 1, 1, 1, 1.
 - > Optimal: 70, 70.



















- Q. How to solve this problem via DP?
- Problem. Given n coin denominations $\{d_1, d_2, ..., d_n\}$ and a target value V, find the fewest coins needed to make change for V (or report impossible).





Dynamic Programming: Summary

• Outline.

- typically only polynomial number
- Define a collection of subproblems.
- Solution to original problem can be computed from subproblems.
- Natural ordering of subproblems from "smallest" to "largest" that enables determining a solution to a subproblem from solutions to smaller subproblems.

Techniques.

- Binary choice: weighted interval scheduling.
- Multiway choice: segmented least squares.
- Adding a new variable: knapsack problem.
- Top-down vs. bottom-up dynamic programming. Opinions differ.

