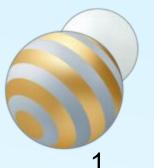


Computer Organization

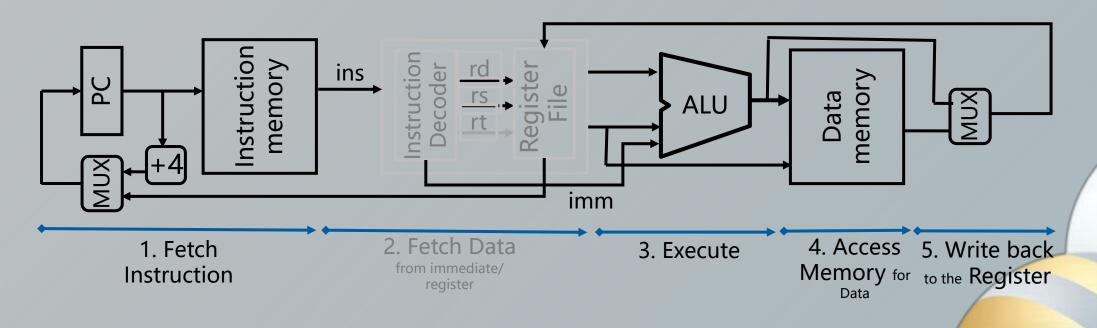
Lab10 CPU Design(2)

Data Path(2) IFetch, Dmemory, ALU





- CPU(2) -DataPath (2)
 - Data-Memory
 - > IFetch
 - > ALU





Von Neumann structure vs Harvard structure

	Dxffffffff	memory map limit address		
	Dxffffffff	kernel space high address		
	0xffff0000	MMIO base address		
	Dxfffeffff	kernel data segment limit address		
	0x90000000	.kdata base address		
	Dx8ffffffc	kernel text limit address		
	0x80000180	exception handler address		
	0x80000000	kernel space base address		
Configuration —	0x80000000	.ktext base address		
Default	Dx7fffffff	user space high address		
Compact, Data at Address 0	Dx7fffffff	data segment limit address		
Compact, Text at Address 0	Dx7ffffffc	stack base address		
	Dx7fffeffc	stack pointer \$sp		
	0x10040000	stack limit address		
	0x10040000	heap base address		
	0x10010000	.data base address		
	0x10008000	global pointer \$gp		
	0x10000000	data segment base address		
	0x10000000	.extern base address		

Von Neumann architecture: data and instruction share the same memory.

The **Von Neumann architecture**, also known as the **Princeton** architecture, is centered around the fact that data and instructions are mixed and addressed together, meaning that their data and instructions are stored at different addresses in the same memory, and their widths must be the same. When transmitting instructions and data, both **share the** same program bus and data bus, so instructions and data cannot be operated simultaneously, and they can only be executed **sequentially**.

The data and instruction memory implemented in **Mars**(a simulator of MIPS32) is **Von Neumann architecture** (data and instruction share the same memory)

The characteristic of the **Harvard architecture** is that data and instructions are stored separately in two different memories: data memory and program memory.

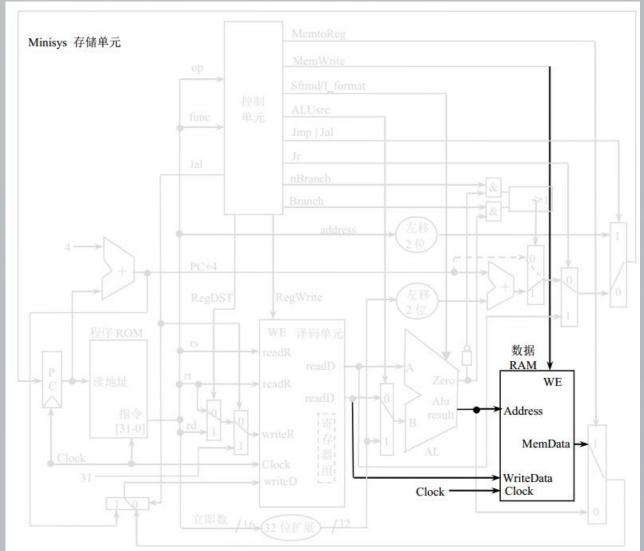
The buses of the two are used separately, and the buses are divided into data bus and address bus of program memory, as well as data bus and address bus of data memory. And the width of instructions and data can be different, while instructions and data can work in **parallel**.

In the next few pages of the courseware, we will introduce the implementation of the **Harvard architecture**.

TIPS: Harvard architecture here is just a refernece, not requirement!



Data-Memory



module **dmemory32**(readData,address, writedata,memWrite,clock);

input clock; // 'Clock' signal

/* used to determine to write the memory unit or not, in the left screenshot its name is 'WE' */

input **memWrite**;

// the 'Address' of memory unit which is tobe read/writen

input[31:0] address;

// data tobe wirten to the memory unit

input[31:0] writeData;

/*data to be read from the memory unit, in the lef

screenshot its name is 'MemData' */

output[31:0] readData;



Using IP core: Block Memory

Using the **IP core** 'Block Memory' of Xilinx to implement the Data-memory.



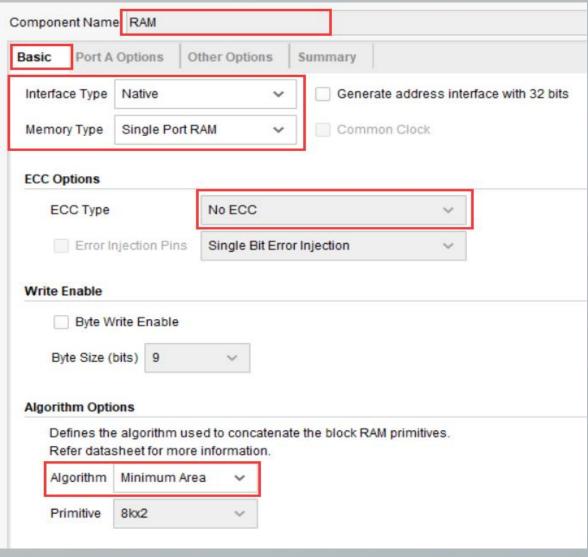
Import the **IP core** in vivado project

1) in "PROJECT MANAGER" window click "IP Catalog"

- 2) in "IP Catalog" window
 - > Vivado Repository
 - > Memories & Storage Elements
 - > RAMs & ROMs & BRAM
 - > Block Memory Generator



Customize Memory IP core

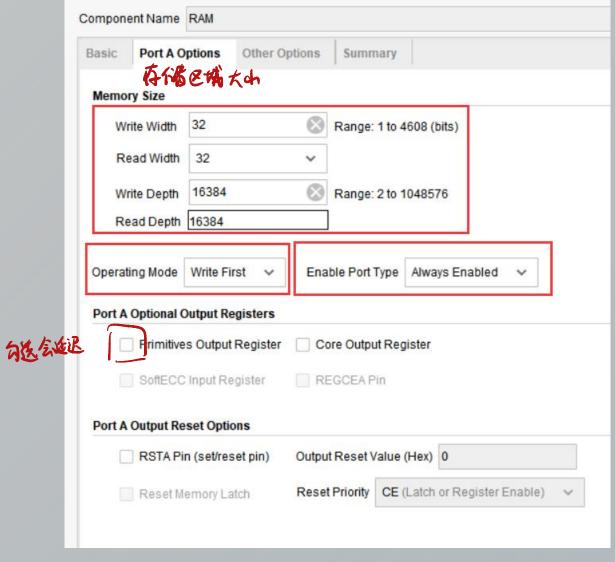


Customize memory IP core

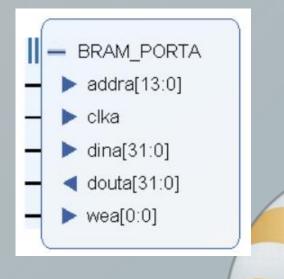
- **▶1)** Component Name: RAM
- **▶2)** Basic settings:
 - ➤ Interface Type: Native
 - ➤ Memory Type: Single-port RAM
 - **▶** ECC options: **no ECC check**
 - ➤ Algorithm options: Minimum area



Customize Memory IP core continued



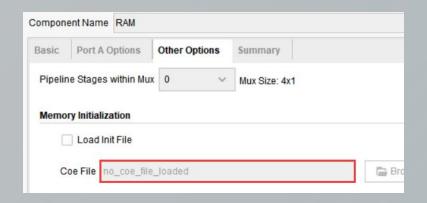
- 3) PortA Options settings:
 - > Data read and write bit width:
 - 32 bits (4Byte)
 - Write/Read Depth: 16384 (64KB)
 - ➤ Operating Mode: Write First
 - > Enable Port Type: Always Enabled
 - ➤ PortA Optional Output Registers: **NOT SET**

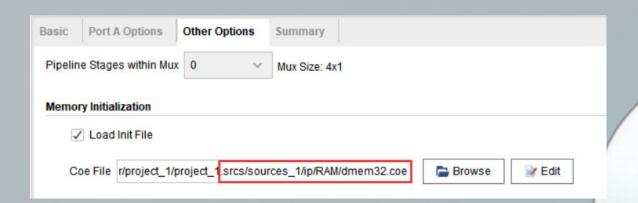


Customize Memory IP core continued

- 4) Other Options settings:
 - > 1. When specifying the initialization file for customize the RAM on the 1st time, the IP core RAM just customized WITHOUT initial file and corresponding path, so set it to no initial file when creating RAM.
 - > 2. After the RAM IP core created
 - > 2-1. COPY the initialization file dmem32.coe to projectName.srcs/sources_1/ip/ComponentName.

 ("projectName.srcs" is under the project folder, "componentName" here is 'RAM')
 - > 2-2. Double-click the newly created RAM IP core, **RESET** it with the **initialization file**, select the dmem32.coe file that has been in the directory of projectName.srcs/sources_1/ip/RAM.





Tips: "dmem32.coe" file could be found in the directory "labs/lab10" of course blackboard site



Design Module With Memory IP Instanced

```
BRAM PORTA
RAM ram (
                                                                            addra[13:0]
    .clka(clk),
                                                                            clka
    .wea(memWrite),
                                                                            ▶ dina[31:0]
    .addra(address[15:2]),
                                                                            douta[31:0]
    .dina(writeData),
                                                                            wea[0:0]
    .douta(readData)
);
assign clk = !clock;
```

Q: In the five stages of instruction processing, what operations must be arranged on the edge of the clock? What's your design for a one-cycle CPU?



Function Verification by simulation

```
module ramTb( );
reg clock = 1'b0;
reg memWrite = 1'b0;
reg [31:0] addr = 32'h0000 0010;
reg [31:0] writeData = 32'ha000 0000;
wire [31:0] readData;
dmemory32 uram
            (clock,memWrite,addr,writeData,readData);
always #50 clock = ~clock;
initial fork
  #120 memWrite = 1'b1;
  #200
     writeData = 32'h0000 00f5;
  #400
    memWrite = 1'b0;
join
endmodule
```

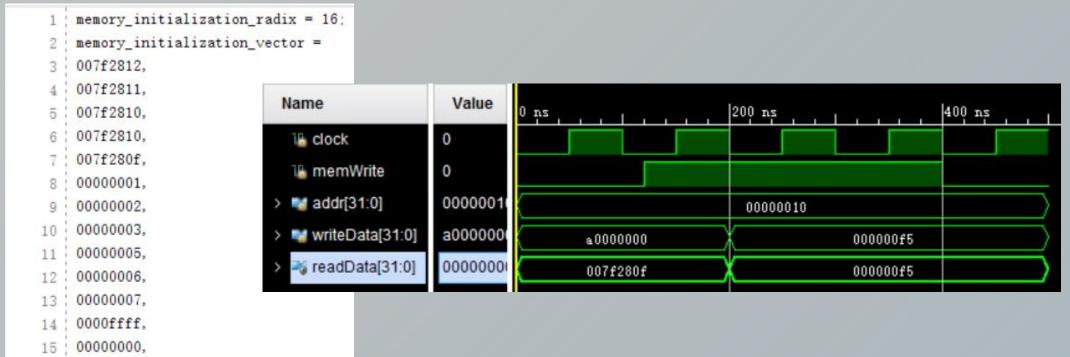
NOTE:

Using bind port with name is Suggested!!

- 1) Set "memWrite" to 1'b0 means to read the data from the RAM unit identified by "addr".
- 2) Set "memWrite" to 1'b1 and "writeData" to 0x0000_00f5 which means to write data 0xa000_00f5 to the RAM unit identified by "addr".
- Q1. While instance the module on page 4(module dmemory32(readData,address,writedata,memWrite,clock)) and using sequential binding as the testbench on the left hand, What will hanppen?
- **Q2.** While the data has been written to the RAM unit, would it be recorded to the initial data file(dmem32.coe)?



Function Verification by simulation continued



Q1: On which edge of clock does the read and write operations occur? posedge or negedge?

Q2: What's value will be get while read the memory according to the "addr" 0x0000_0020?

how about "addr" 0x0000_0016?

000000000.

Tips: "dmem32.coe" file could be found in the directory "labs/lab10" of course blackboard site



- 1. Build the data memory module.
- 2. Verify its function by simulation

(NOTE: The testbench on page 9 is JUST a reference)

- > Read the values one by one from memory unit where are specified in the red box of the screenshot on the right hand.
- > Write a word(value is 0x1000_0000) to the memory unit where is specified in the blue box of the screeshot on the right hand, then read it out.
- 3. List all the signals which are needed for data-memory module

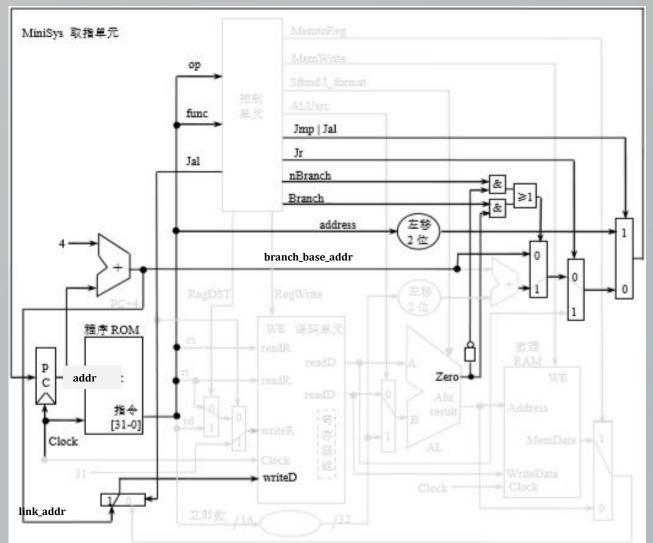
1	<pre>memory_initialization_radix = 16;</pre>
2	<pre>memory_initialization_vector =</pre>
3	007f2812,
4	007f2811,
5	007f2810,
6	007f2810,
7	007f280f,
8	00000001, read these initial
9	00000002, value
10	00000003,
11	00000005,
12	00000006,
13	00000007,
14	0000ffff,
15	00000000,
16	00000000, write this word
17	00000000, Write this word
18	ooooooo, with 0x1000 0000
19	00000000,
20	then read it
21	0000000,

name	from	to	bits	function
clock	CPU-TOP	Data Memory	1	data memory write is sensitive with its negedge
rdata	Data Memory	Decoder	32	the word read from the data memory and send to decoder
memoryWrite	Controller	Data Memory	1	1'b1 means to write the memory unit, else means not to write
address	ALU	Data Memory	32	the address which is used to identify the memory unit tobe read or written

Tips: "dmem32.coe" file could be found in the directory "labs/lab10" of course blackboard site



Instruction Fetch



The function of Instruction Fetch module

- 1. **Store** the instructions(machine-code)
- 2. **Update** the value of the PC register
 - Reset 人口位置
 - PC+4
 - Update the value of the PC register according to the jump instructions
 - branch(beq,bne) [I-type]
 - jal, j [J-type]
 - jr [R-type]
- 3. Fetch the instructions according to the value of the PC register



Using IP core As Instruction Memory

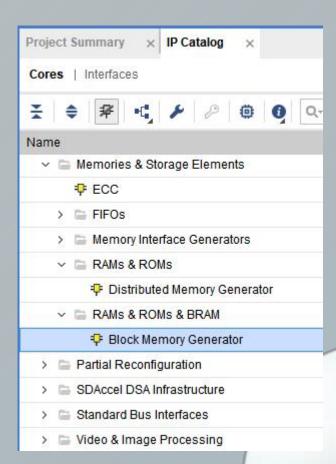
Step1: Find the IP core(Block Memory Generator) in IP Catalog

Step2: Customize the IP core

- set name(component name), type(ROM)
- set features of the ROM(width and depth), operation mode and register output
- set initial file

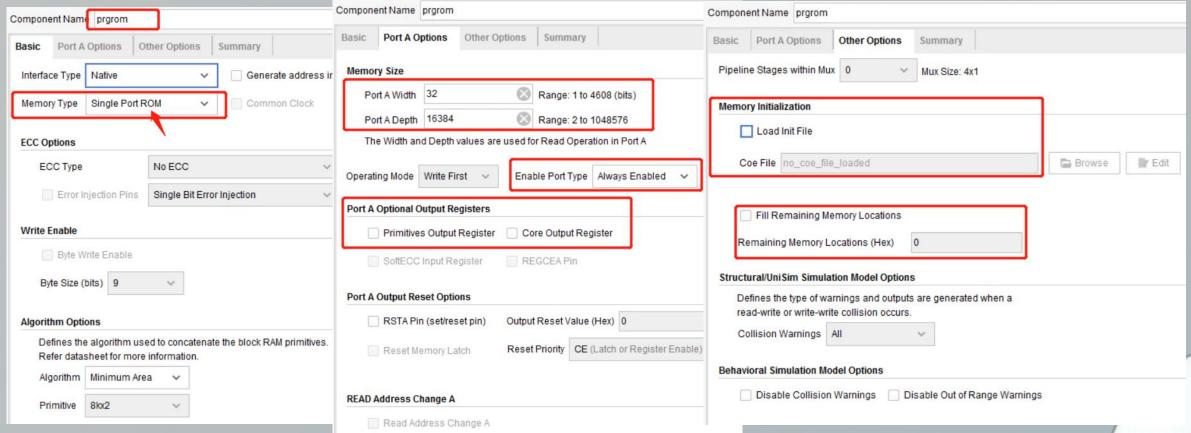
Step3: **Generate** the IP core, then it will be added to vivado project automatically

Tips: The setting steps of ROM IP core are almost same as which of the RAM IP core in Data-memory except the type is





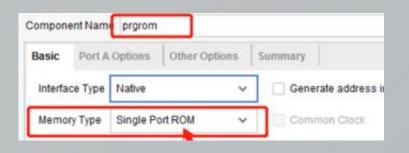
Customize the IP core

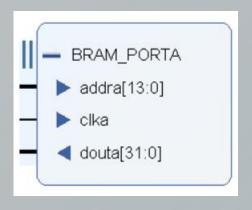


NOTE: set the init file of prgrom after this IP core has been added into vivado project. Same steps as the RAM IP core used in Data-memory.



Instance the IP core





```
prgrom instmem(
    .clka(clock),
    .addra(PC[15:2]),
    .douta(Instruction)
);
```

In One Cycle CPU, the process of **geting instrcution** should **happen** on the **posedge** of the clock. At this moment, IFetch module gets the instruction which is store at "**addra**" from the instruction memory "Instmem"

Q: Why using PC[15:2] instead of PC[13:0] to bind with port "addra"?

TIPS: The same reason as the address bus used in Data-memory



The Function Verification of "prgrom"

🔚 prgmip32.coe🛛 memory initialization radix = 16; memory initialization vector = 34010001, 34020002, 34030003, 34040004, 34050005, 34060006, 34070007, 34080008, 34090009, 340a000a, 340b000b,

340c000c,

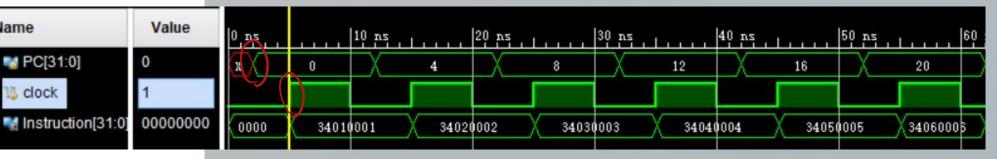
Name

PC[31:0]

15 clock

Tips: "prgmip32.coe" file could be found in the directory "labs/lab10" of course blackboard site

的序、换出和以上升沿同步



```
module prgrom_tb( );
                        //a reference for the testbench?
 reg[31:0] PC;
 reg clock=1'b0;
 wire [31:0] Instruction;
  prgrom instmem(.clka(clock),.addra(PC[15:2]),.douta(Instruction));
 always #5 clock = \simclock;
 initial begin
   clock = 1'b0;
   #2 PC = 32'h0000 0000;
   repeat(5) begin
   #10 PC = PC+4:
   #10 $finish;
   end
 end
endmodule
```

- Read the "Instruction" from "douta" port of Instruction memory "prgrom" on every posedge of the "clock".
- In this tescase, the value of 'PC' is added with 4 each time.
- Q: How many instructions would be fetched in this testbench?



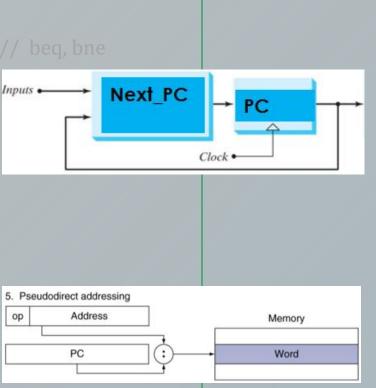
IFetch Module

```
module IFetc32(Instruction, branch_base_addr, link_addr,
clock, reset.
Addr_result, Read_data_1, Branch, nBranch, Jmp, Jal, Jr, Zero);
  output[31:0] Instruction;
                                      // the instruction fetched from this module to Decoder and Controller
  output[31:0] branch_base_addr; // (pc+4) to ALU which is used by branch type instruction
  output[31:0] link_addr;
                                     // (pc+4) to Decoder which is used by jal instruction
//from CPU TOP
               clock, reset:
                                          // Clock and reset
 input
// from ALU
 input[31:0] Addr_result;
                                    // the calculated address from ALU
 input
              Zero:
                                    // while Zero is 1, it means the ALUresult is zero
// from Decoder
                                    // the address of instruction used by jr instruction
 input[31:0] Read_data_1;
// from Controller
                                    // while Branch is 1,it means current instruction is beq
           Branch;
 input
                                    // while nBranch is 1,it means current instruction is bnq
 input
           nBranch;
 input
                                    // while Jmp 1, it means current instruction is jump
           Jmp;
           Jal;
                                    // while Jal is 1, it means current instruction is jal
 input
                                    // while Ir is 1, it means current instruction is ir
 input
           Jr;
```



Update the Value of the PC register

```
Q1: Complete the code to update 'Next PC'
                                Q2: Could be 'PC' ready while read the 'prgrom'? Determine when to update the value of the PC register.
reg[31:0] PC, Next_PC;
                                Q3: Is this Minisys ISA a Harvard structure or Von Neumann structure(take a look at the initial value of PC)
always @* begin
    if((Branch == 1) \&\& (Zero == 1)) || ((nBranch == 1) \&\& (Zero == 0))) // beg, but
      Next_PC = ... // the calculated new value for PC
    else if(Jr == 1)
      Next_PC = ... // the value of $31 register
    else Next_PC = ... // PC+4
  end
 always @(... clock) begin
  if(reset == 1)
       PC <= 32'h0000 0000;
  else begin
                                                                                      Address
   if((Imp == 1) || (Ial == 1)) begin
       PC <= ...:
   end
  else PC <= ...;
end
```



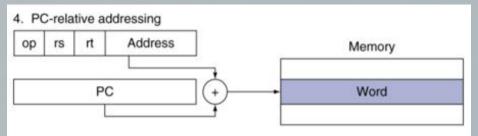
NOTES: The code here is JUST refence, NOT request.



Outputs of IFetch: Prepare for Decoder and ALU

```
output[31:0] branch_base_addr; // (pc+4) to ALU which is used by branch type instruction output[31:0] link_addr; // (pc+4) to Decoder which is used by 'jal' instruction
```

Here for "pc+4", the value of 'pc' is the address of current processing instruction.



NOTES:

Don't forget to instance instruction memory, complete the port binding.

TIPS: The design here is for reference ONLY, NOT request.



Practice2

- 1. Make a Minisys source file with j, jal, jr, beq,bne and other NON-jumping instructions included.
- 2. Using the Minisys1AssemblerV2.2 to assembler the source file on step 1, get the coe files .
- 3. Using the "prgmip32.coe" generated on step 2 as the initial file for the ROM in IFetch submodule to verify the its funciton:
- 3-1) What's the value of register PC while the reset is valid.
- 3-2) While reset is invalid, on which edge of clock would the value of register PC be updated?
- 3-3) What's the updated value to register PC while the current instruction is j, jal, jr, beq,bne and other NON-jumping instructions.
- 3-4) On which edge of clock would the instruction be fetched out?
- 3-5) Is there any difference between the two output ports ("branch_base_addr" and "link_addr")

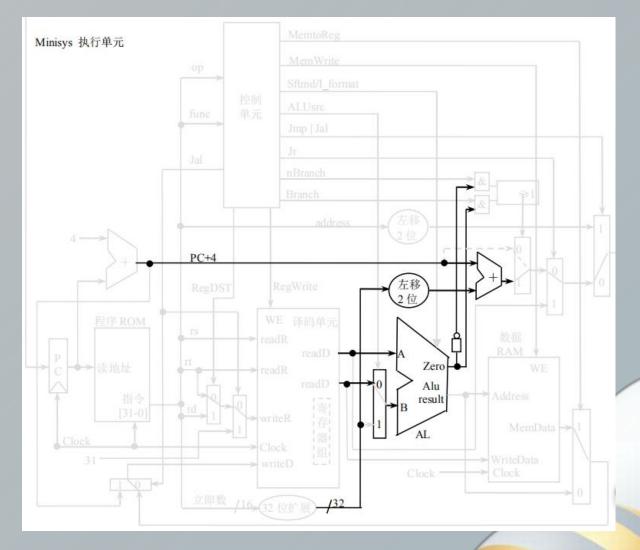
Tips:1) There are j, jal, jr, beq,bne and other NON-jumping instructions in cputest.asm(which is in the Minisys1AssemblerV2.2.rar), you can modify it as an alternative to the 1st step.

2) "Minisys1AssemblerV2.2.rar" could be found in the directory "labs" of course blackboard site



- Determine the function and the inputs and outputs of ALU
 - > A MUX for operand selection
 - `ALU_control'
 - ➤ Operation
 - Arithmetic and Logic calculation
 - > Shift calculation
 - > Special calculation (slt,lui)
 - > Address calculation

Q: Is the ALU a commbinatorial logic and sequential logic?



Tips: follow design is a reference ONLY, not required.



Minisys - A subset of MIPS32

Туре	Name	funC(ins[5:0])
R	sII	00_0000
	srl	00_0 010
	sllv	00_0 100
	srlv	00_0 110
	sra	00_0 011
	srav	00_0111
	jr	00_1 000
	add	10_000 0
	addu	10_0001
	sub	10_001 0
	subu	10_0011
	and	10_01 00
	or	10_01 01
	xor	10_01 10
	nor	10_0111
	slt	10_1 010
	sltu	10_1 011

Туре	Name	opC(Ins[31:26])
1	beq	00 _0100
	bne	00 _0101
	lw	10 _0011
	sw	10 _1011
		/ / //
	addi	00_1 000
	addiu	00_1 001
	slti	00_1 010
	sItiu	00_1 011
	and i	00_1 100
	ori	00_1 101
	xori	00_1 110
	lui	00_1111

Type Name		opC(Ins[31:26])
/	jump	00_001 0
J	jal	00_0011



NOTE:

Minisys is a subset of MIPS32.

The opC of R-Type instruction is 6'b00_0000

BASIC INSTRUCTION FORMATS

R	opc	ode	rs	rt	ro	d	shamt	funct
	31	26 25	21	20	16 15	11 10	6.5	0
I	opc	ode	rs	rt			immediate	
	31	26 25	21	20	16 15			0
J	opc	ode			add	lress		
	31	26 25	t.					0



Inputs Of ALU

```
module Executs32 ();
// from Decoder
  input[31:0] Read_data_1;
                                      //the source of Ainput
  input[31:0] Read_data_2;
                                       //one of the sources of Binput
  input[31:0] Sign_extend;
                                      //one of the sources of Binput
// from IFetch
  input[5:0] Opcode;
                                       //instruction[31:26]
  input[5:0] Function_opcode;
                                       //instructions[5:0]
                                       //instruction[10:6], the amount of shift bits
  input[4:0] Shamt;
  input[31:0] PC plus 4;
                                       //pc+4
// from Controller
  input[1:0] ALUOp;
                             //{ (R format || I format), (Branch || nBranch) }
             ALUSrc;
                             // 1 means the 2nd operand is an immediate (except beg,bne)
  input
                             // 1 means I-Type instruction except beq, bne, LW, SW
  input
             I format;
                             // 1 means this is a shift instruction
             Sftmd;
  input
```



Outputs And Variable of ALU

Q1: Who needs the calculation result of ALU?

```
output[31:0] reg ALU_Result; // the ALU calculation result
output Zero; // 1 means the ALU_reslut is zero, 0 otherwise
output[31:0] Addr_Result; // the calculated instruction address
```

Q2: How to determine the data type of following variable?

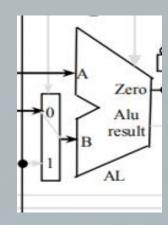
```
wire[31:0]
             Ainput, Binput;
                                          // two operands for calculation
wire[5:0]
              Exe code; // use to generate ALU_ctrl. (I_format==0) ? Function_opcode : { 3'b000 , Opcode[2:0] };
                         // the control signals which affact operation in ALU directely
             ALU ctl;
wire[2:0]
wire[2:0]
             Sftm;
             Shift Result;
                                     // the result of shift operation
reg[31:0]
reg[31:0]
             ALU output mux;
                                      // the result of arithmetic or logic calculation
                                // the calculated address of the instruction, Addr Result is Branch Addr[31:0]
wire[32:0]
             Branch Addr;
```



The Selection On Operand2

Two operands of ALU: Ainput and Binput.

- Ainput is from the output port "Read_data_1" of Decoder
- Binput is the output of 2-1 MUX:
 - "Sign_extend" and "Read_data_2" are from Decoder.
 - The output of the MUX is determined by "ALUSrc" which comes from Controller.





ALU_ctrl generation

- ➤ Design:
 - > lots of operations need to be processed in ALU
 - ➤ To reduce the burden of the Controller, the Controller and ALU produce control signals which affect the ALU operation together

Opcode

Function code

Exe code

ALUOp

ALU ctrl

- > Implements(1):
 - ALUOp(1st level control signal):

generated by Controller (the basic relationship between instruction and operation)

- > bit1 to identify if the instruction is R_format/ I_format, otherwise means neither
- > bit0 to identify if the instruction is beg/bne, otherwise means neither
- ALUOp = { (R_format || I_format) , (Branch || nBranch) }

```
// R_format = (0pcode = = 6'b000000)? 1'b1:1'b0;
```

// "I_format" is used to identify if the instruction is I_type(except for beq, bne, lw and sw).



ALU_ctrl generation continued

- > Implements(2):
 - Exe_code(2nd level control signal): according to the instruction type(I-format or not):

Tips

- I_format is 1 means this is the I-type instruction
 except beq,bne,lw and sw.
- 2) Opcode is instruction[31:26]
- 3) function_opcode is instruction[5:0]
- **Q.** Could the 'Exe_code' be generated by Controller or by ALU? What's your choice?

Type	Name	funC(ins[5:0])
R	sll	00_0000
	srl	00_0 010
	sllv	00_0100
	srlv	00_0 110
	sra	00_0 011
	srav	00_0111
	jr	00_1000
	add	10_000 0
	addu	10_0001
	sub	10_0010
	subu	10_0011
	and	10_0100
	or	10_01 01
	xor	10_01 10
	nor	10_0111
	slt	10_1 010
	sltu	10_1 011

Туре	Name	opC(Ins[31:26])			
1	beq	00 _0100				
	bne	00 _0101				
	lw	10 _0011				
	sw	<mark>10</mark> _1011				
		I-Format				
		1				
	addi	00_1 000				
	addiu	00_1 001				
	slti	00_1 010	Г			
	sltiu	00_1 011				
	and i	00_1 100	Г			
	ori	00_1 101				
	xori	00_1 110				
	lui	00_1111	Г			



ALU_ctrl generation continued

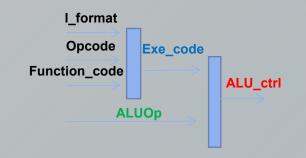
Exe_code[30]	ALUOp[10]	ALU_ct1[20]	指令助记符
0100	10	000	and,andi
0101	10	001	or,ori
0000	10	010	add,addi
xxxx	00	010	lw, sw
0001	10	011	addu, addiu
0110	10	100	xor,xori
0111	10	101	nor,lui
0010	10	110	sub, slti
xxxx	01	110	beq, bne
0011	10	111	subu, sltiu
1010	10	111	slt
1011	10	111	sltu

```
Implements(3)
ALU_ctrl: based on ALUOp and Exe_code,
specify most of the operation details in ALU
```

```
ALUOp =
{ (R_format || I_format) , (Branch || nBranch) }

Exe_code = (I_format==0) ?

Function_opcode :
{ 3'b000 , Opcode[2:0] };
```



```
assign ALU_ctl[0] = (Exe_code[0] | Exe_code[3]) & ALUOp[1];
assign ALU_ctl[1] = ((!Exe_code[2]) | (!ALUOp[1]));
assign ALU_ctl[2] = (Exe_code[1] & ALUOp[1]) | ALUOp[0];
```



ALU_ctrl usage

> Type1: The same operation in ALU with different operand source sometimes the instructions share the same calculation operation but with different operand source, such as "and" and "andi", "addu" and "addui".

The same operation but different operand source: **ALU_ctrl** is same

- add vs addi
- addu vs addiu
- and vs andi
- or vs ori
- xor vs xori
- slt vs sltu vs sltiu

Exe_code[30]	ALUOp[10]	ALU_ctl[20]	指令助记符	
0100	10	000	and,andi	
0101	10	001	or,ori	
0000	10	010	add,addi	
XXXX	00	010	lw, sw	
0001	10	011	addu, addiu	
0110	10	100	xor,xori	
0111	10	101	nor,lui	
0010	10	110	sub, slti	
XXXX	01	110	beq, bne	
0011	10	111	subu sltiu	
1010	10	111	slt	
1011	10	111	sltu	



ALU_ctrl usage continued

> Type2: The same operation in ALU with different destination

The ALU_ctrl code is same(3'b010) for both "Iw", "sw", "add" and "andi":

• the operation of "Iw" and "sw" in ALU is calcuation the address based on the base address and offset which is same as in "add" operation.

Exe_code[30]	ALUOp[10]	ALU_ctl[20]	指令助记符	
0100	10	000	and,andi	
0101	10	001	or,ori	
0000	10	010	add,addi	
XXXX	00	010	lw, sw	
0001	10	011	addu, addiu	
0110	10	100	xor,xori	
0111	10	101	nor,lui	
0010	10	110	sub, slti	
XXXX	01	110	beq, bne	
0011	10	111	subu, sltiu	
1010	10	111	slt	
1011	10	111	sltu	



ALU_ctrl usage continued

- > Type2 continued: The same operation in ALU with different destination
 - "beq", "bne" vs "sub" (destionation):
 - "beq" and "bne": Addr_reslut
 - "sub": "ALU reslut"
 - "subu" vs "slt", "sltu" (destionation)
 - "slti" and "sltiu": Zero.

I_format is used here to distinguish these two types

• "sub" vs "slti", "subu" vs "sltiu":

same as upper instructions,
Function_opcode(3)=1 of slt and sltu
could be used as distinguishment

Exe_code[30]	ALUOp[10]	ALU_ctl[20]	指令助记符	
0100	10	000	and,andi	
0101	10	001	or,ori	
0000	10	010	add,addi	
XXXX	00	010	lw, sw	
0001	10	011	addu, addiu	
0110	10	100	xor,xori	
0111	10	101	nor,lui	
0010	10	110	sub, slti	
XXXX	01	110	beq, bne	
0011	10	111	subu, sltiu	
1010	10	111	slt	
1011	10	111	sltu	



ALU_ctrl usage continued

> Type3: Some instructions' ALU_ctrl code is the same as others, but with different operation in ALU.

For these instructions, make sure they can be identified to avoid wrong operations:

- shift instrucitons: could be identified by the input port "sftmd"
- lui: whose ALU_ctrl code is the same as "nor", but could be identified by "I_format"
- jr: could be identified by the input port "jr", not excute in ALU
- j : could be identified by the input port "jmp", not excute in ALU
- jal: could be identified by the input port "jal", not excute in ALU



end

Practice3-1: Arithmatic and Logic calculation

Complete the following code according to the table on the right hand

```
reg[31:0] ALU output mux;
always @ (ALU ctl or Ainput or Binput)
begin
case (ALU ctl)
    3'b000:ALU output mux =? ? ?
    3'b001:ALU output mux =? ? ?
    3'b010:ALU output mux =? ? ?
    3'b011:ALU output mux =? ? ?
    3'b100:ALU output mux =? ? ?
    3'b101:ALU output mux =? ? ?
    3'b110:ALU output mux =? ? ?
    3'b111:ALU output mux =? ? ?
    default:ALU output mux = 32'h00000000;
endcase
```

Exe_code[30]	ALUOp[10]	ALU_ctl[2()]	指令助记符	
0100	10	000	and,andi	
0101	10	001	or,ori	
0000	10	010	add,addi	
XXXX	00	010	lw, sw	
0001	10	011	addu, addiu	
0110	10	100	xor,xori	
0111	10	101	nor,lui	
0010	10	110	sub, slti	
xxxx 01		110	beq, bne	
0011 10		111	subu, sltiu	
1010	10	111	slt	
1011	10	111	sltu	

Tips: While ALU_ctrl is 3'b101, One of the implements is to execute only 'nor', make other procedure do the 'lui'



Shift Operation

Type	Name	funC(ins[5:0])
R	sII	00_0000
- 11	srl	00_0 010
	sllv	00_0100
	srlv	00_0 110
	sra	00_0011
	srav	00_0111

There are 6 shift instructions, listed in the table on the left hand.

Ainput, Binput/shamt are the operand of shift operation

R	opc	ode	rs	rt		rd	shamt	funct
	31	26 25	21	20	16	15 11	10 6	5 (

```
      sftm[2:0] process

      3'b000
      sll rd, rt, shamt

      3'b010
      srl rd, rt, shamt

      3'b100
      sllv rd, rt, rs

      3'b110
      srlv rd, rt, rs

      3'b011
      sra rd, rt, shamt

      3'b111
      srav rd, rt, rs

      other
      not shift
```



Practice3-2: Shift Operation

Complete the following code, taking the table on the left hand as reference

sftm[2:0]	process
3'b000	sll rd, rt, shamt
3'b010	srl rd, rt, shamt
3'b100	sllv rd, rt, rs
3'b110	srlv rd, rt, rs
3'b011	sra rd, rt, shamt
3'b111	srav rd, rt, rs
other	not shift

```
always @* begin
   if(Sftmd)
         case(Sftm[2:0])
           3'b000:Shift_Result = Binput << Shamt;
           3'b010:Shift_Result = ???;
           3'b100:Shift_Result = Binput << Ainput;
           3'b110:Shift_Result = ???;
           3'b011:Shift Result = ???;
           3'b111:Shift_Result = ???;
           default:Shift_Result = Binput;
         endcase
   else
         Shift_Result = Binput;
  end
```



Get the Output of ALU

The operations of ALU include:

- 1) execute the **setting** type instructions (**slt, sltu, slti** and **sltiu**)
 - get ALU_output_mux, and set the value of the output port "ALU_result"
- 2) execute the lui operation
 - get result of "lui" execution, and set the value to the output port "ALU_result"
- 3) execute the **shift** operation
 - > get "Shift_Result", set its value to the output port "ALU_result"
- 4) do the basic arithmetic and logic calculation
 - > get ALU_output_mux, set its value to the output port "ALU_result"

Tips: Exe_code[3..0], ALUOp[1..0] and ALU_ctl[2..0] are used to identify the types of operation



Practice 3-3: the output "ALU_Result"

Complete the following code according to the code annotation

```
always @* begin
    //set type operation (slt, slti, sltu, sltiu)
    if( ((ALU_ctl==3'b111) && (Exe_code[3]==1)) || /*to be completed*/ )
              ALU_Result = (Ainput-Binput<0)?1:0;
   //lui operation
   else if((ALU_ctl==3'b101) && (I_format==1))
              ALU_Result[31:0] = /*to be completed*/;
   //shift operation
   else if(Sftmd==1)
              ALU_Result = Shift_Result ;
    //other types of operation in ALU (arithmatic or logic calculation)
    else
              ALU_Result = ALU_output_mux[31:0];
 end
```

Exe_code[30]	ALUOp[10]	ALU_ctl[20]	指令助记符	
0100	10	000	and,andi	
0101	10	001	or,ori	
0000	10	010	add,addi	
XXXX	00	010	lw, sw	
0001	10	011	addu, addiu	
0110	10	100	xor,xori	
0111	10	101	nor,lui	
0010	10	110	sub, slti	
xxxx	01	110	beq, bne	
0011	10	111	subu, sitiu	
1010	10	111	slt	
1011	10	111	sltu	



Practice 3-4: the output "Addr_result" and "Zero"

The values of "Addr_result" and "Zero" are still not determined.

```
output[31:0] reg ALU Result; // the ALU calculation result
output Zero; // 1 means the ALU_reslut is zero, 0 otherwise
output[31:0] Addr_Result; // the calculated instruction address
```

"Zero" is a signal used by "IFetch" to determine whether to use the value of "Addr_reslut" to update PC register or not.

TIPS: Minisys only support "beq" and "bne" in the conditional jump instruction.

> "Addr_result" is calculated by ALU when the instruction is "beq" or "bne".

TIPS: Addr_reslut should be the sum of pc+4(could be get from PC_plus_4) and the immediate in the instruction.



Practice 3-5: Function Verification on ALU

Build a testbench to verify the function of ALU.

Take the testcases described in bellow table as reference, More testcases are suggested for function verification.

Time (ns)	Instruction	A input	B input	Results(includes 'Zero')	
0	add	0x5	0x6	ALU_Result = 0x0000_000b, Zero=1'b0	
200	addi	0xffff_ff40	0x3	ALU_Result = 0xffff_ff43, Zero=1'b0	
400	and	0x0000_00ff	0x0000_0ff0	ALU_Result = 0x0000_00f0, Zero=1'b0	
600	sll	0x0000_0002	0x3	ALU_Result = 0x0000_0010, Zero=1'b0	
800	lui	0x0000_0040	0x10 (16)	ALU_Result = 0x0040_0000, Zero=1'b0	
1000	beq	The value of Ainput is same with that of Binput. Zero = 1'b1 Depends on your design Addr_Result: should be the sum of pc+4(could be get from PC_plus_4) and the immediate in the instruction			