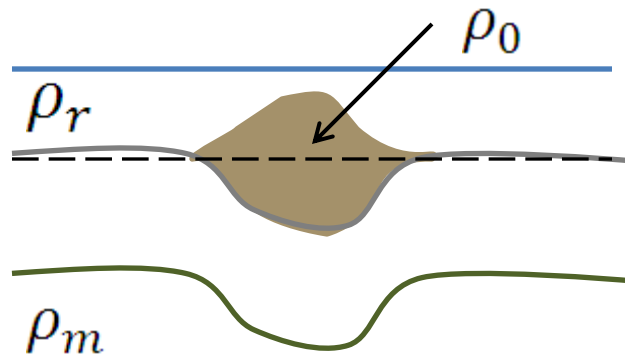


# Flexura de placa elástica por diferenças finitas

Victor Sacek

IAG - USP



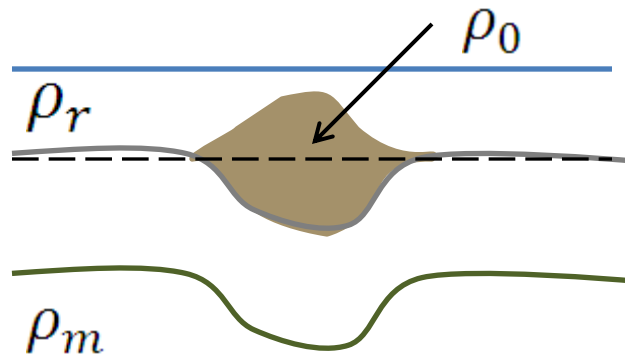
# Comparação

$h$  Espessura total do carregamento:

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_r) g w = (\rho_0 - \rho_r) g h$$

$h'$  Espessura do carregamento acima da paleotopografia/paleobatimetria:

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_0) g w = (\rho_0 - \rho_r) g h'$$



# Comparação

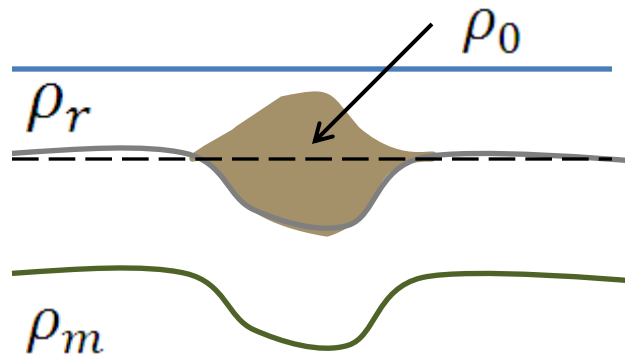
$h$  Espessura total do carregamento:

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_r) g w = (\rho_0 - \rho_r) g h$$

$h'$  Espessura do carregamento acima da paleotopografia/paleobatimetria:

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_0) g w = (\rho_0 - \rho_r) g h'$$

$\Delta\rho$



# Comparação

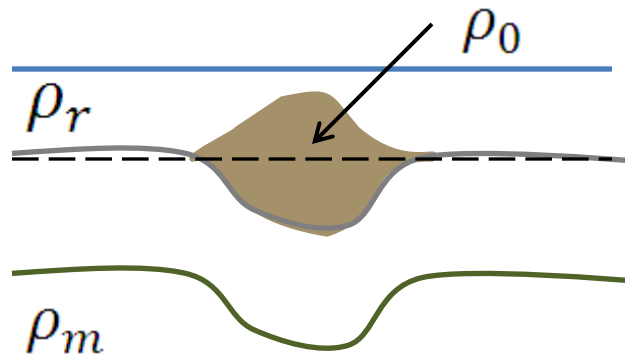
$h$  Espessura total do carregamento:

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_r) g w = (\rho_0 - \rho_r) g h$$

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$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_0) g w = (\rho_0 - \rho_r) g h'$$

$\Delta\rho$   $p$



# Comparação

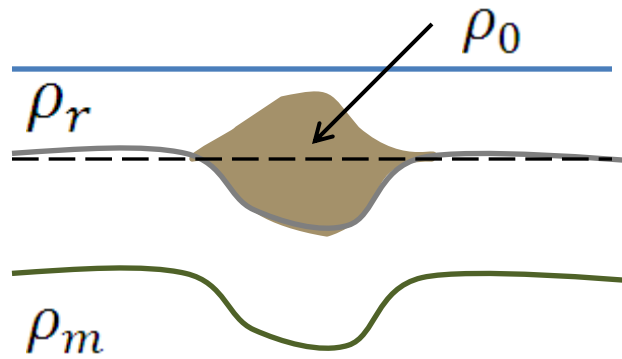
$h$  Espessura total do carregamento:

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_r) g w = (\rho_0 - \rho_r) g h$$

$h'$  Espessura do carregamento acima da paleotopografia/paleobatimetria:

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_0) g w = (\rho_0 - \rho_r) g h'$$

$D$  constante
 $\Delta\rho$ 
 $p$



# Comparação

$h$  Espessura total do carregamento:

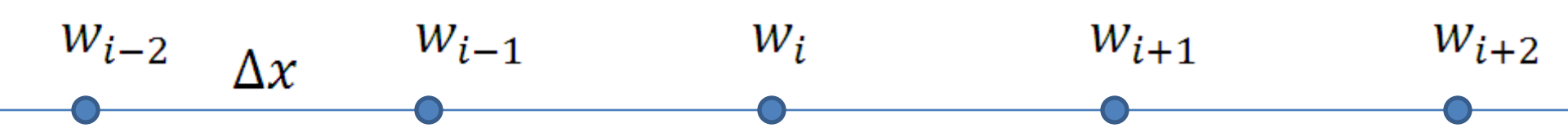
$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_r) g w = (\rho_0 - \rho_r) g h$$

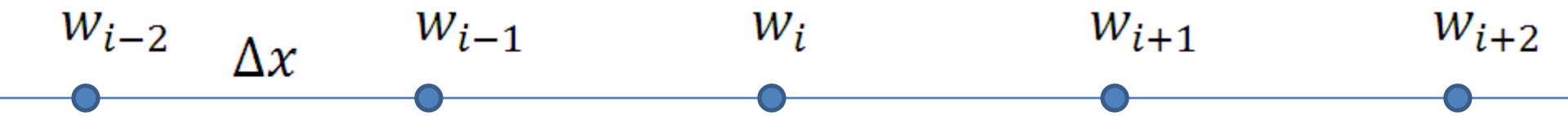
$h'$  Espessura do carregamento acima da paleotopografia/paleobatimetria:

$$\frac{d^2}{dx^2} \left( D \frac{d^2 w}{dx^2} \right) + (\rho_m - \rho_0) g w = (\rho_0 - \rho_r) g h'$$

$D$  constante       $\Delta \rho$        $p$

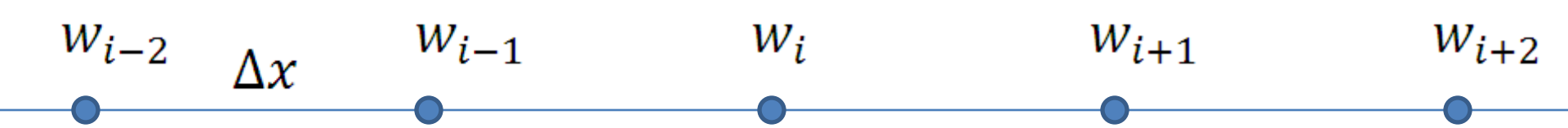
$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p$$





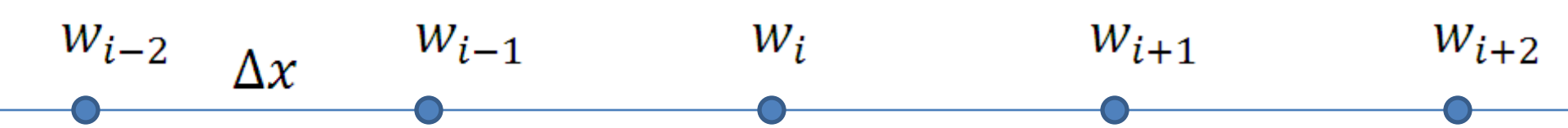
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$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p$$

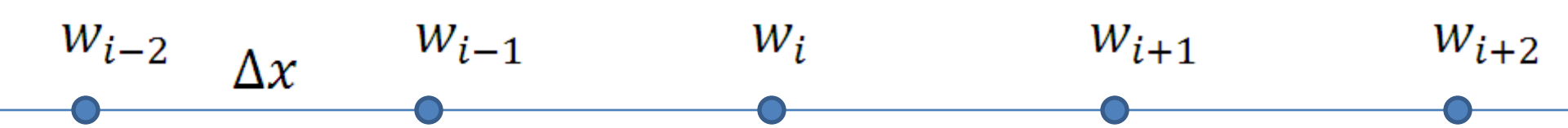




$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p$$



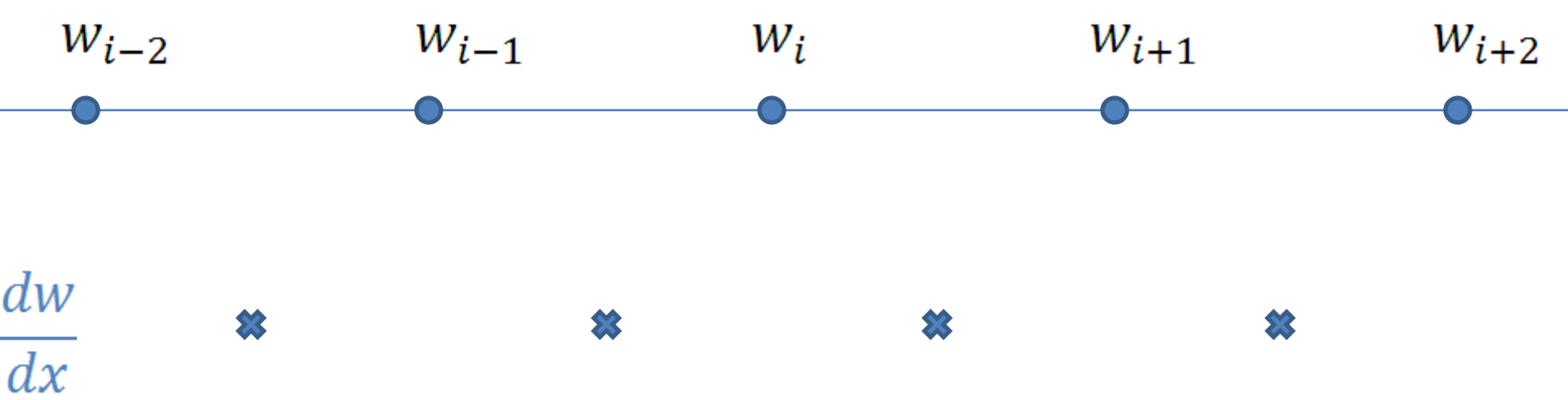
$$+\Delta \rho g w_i = p_i$$

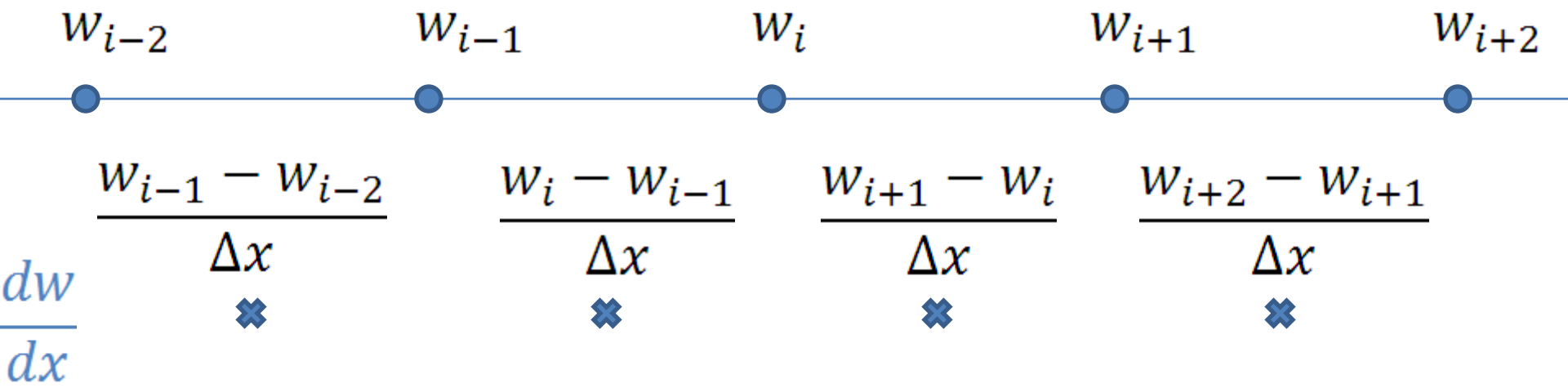


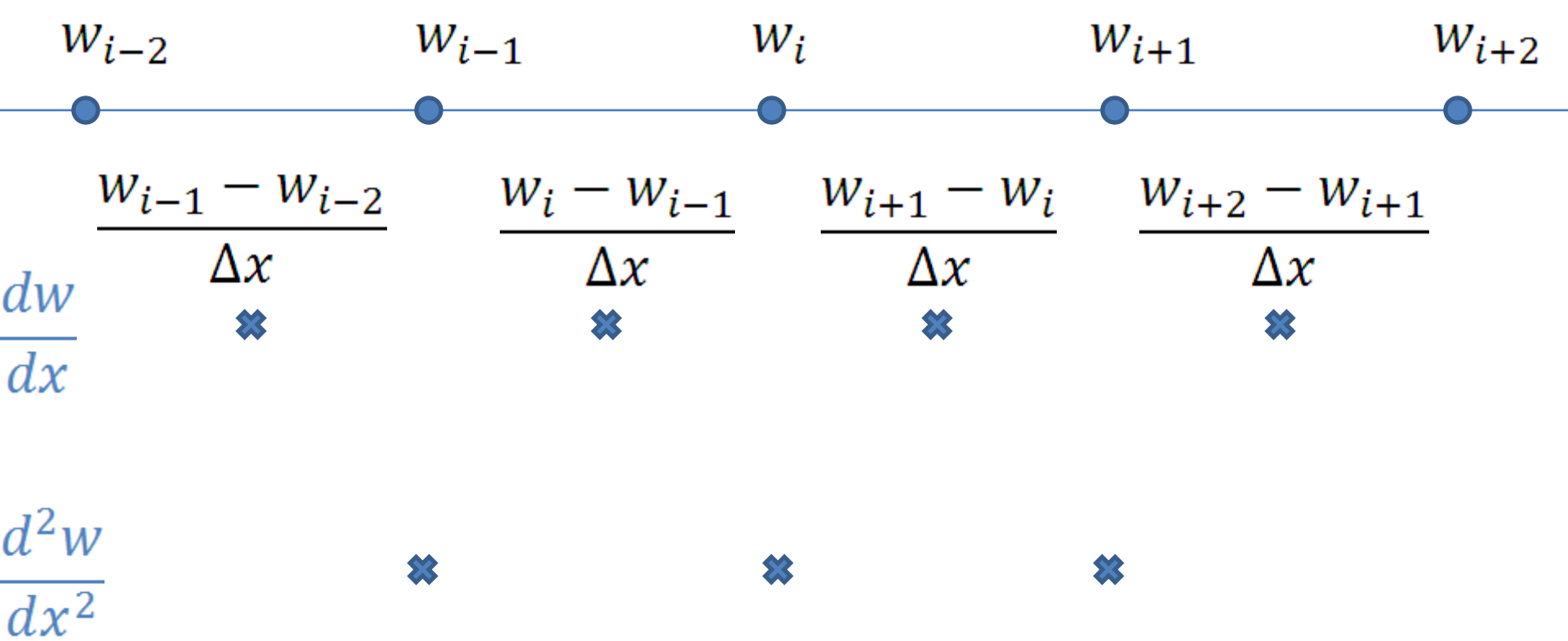
$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p$$

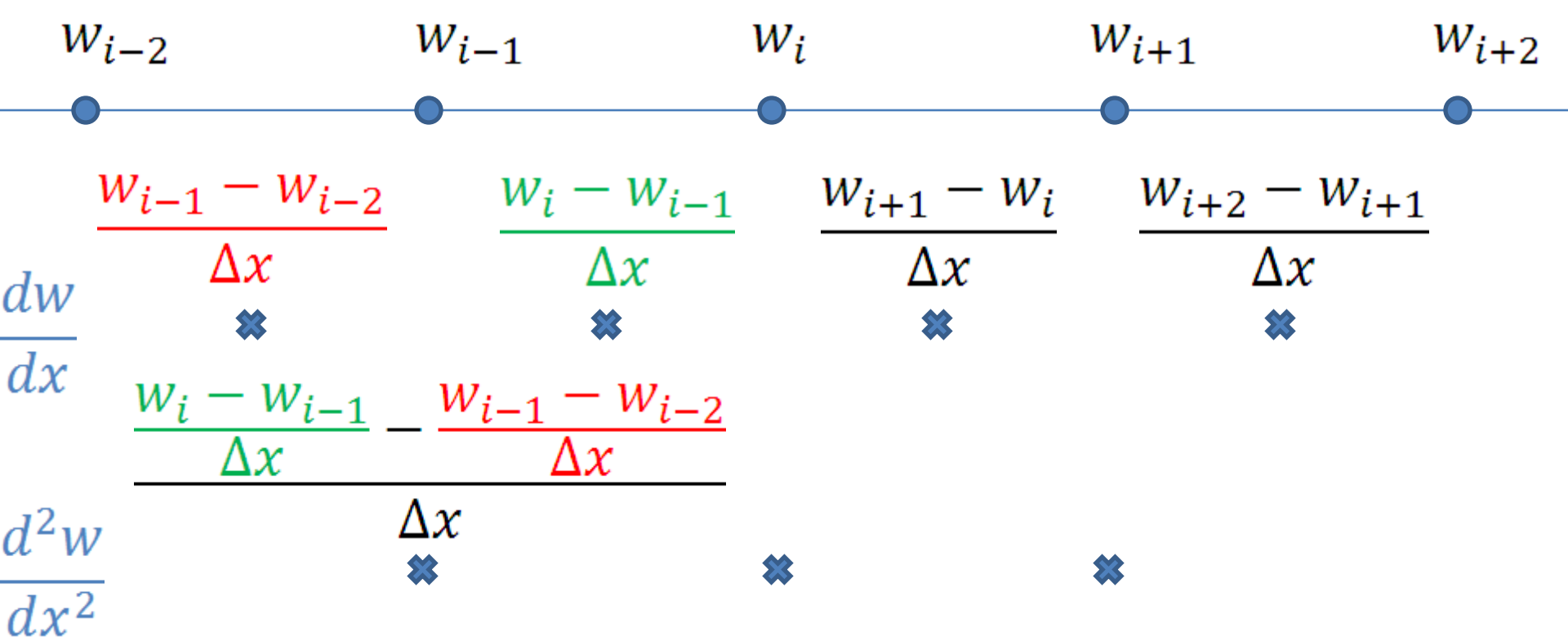


$$? + \Delta \rho g w_i = p_i$$









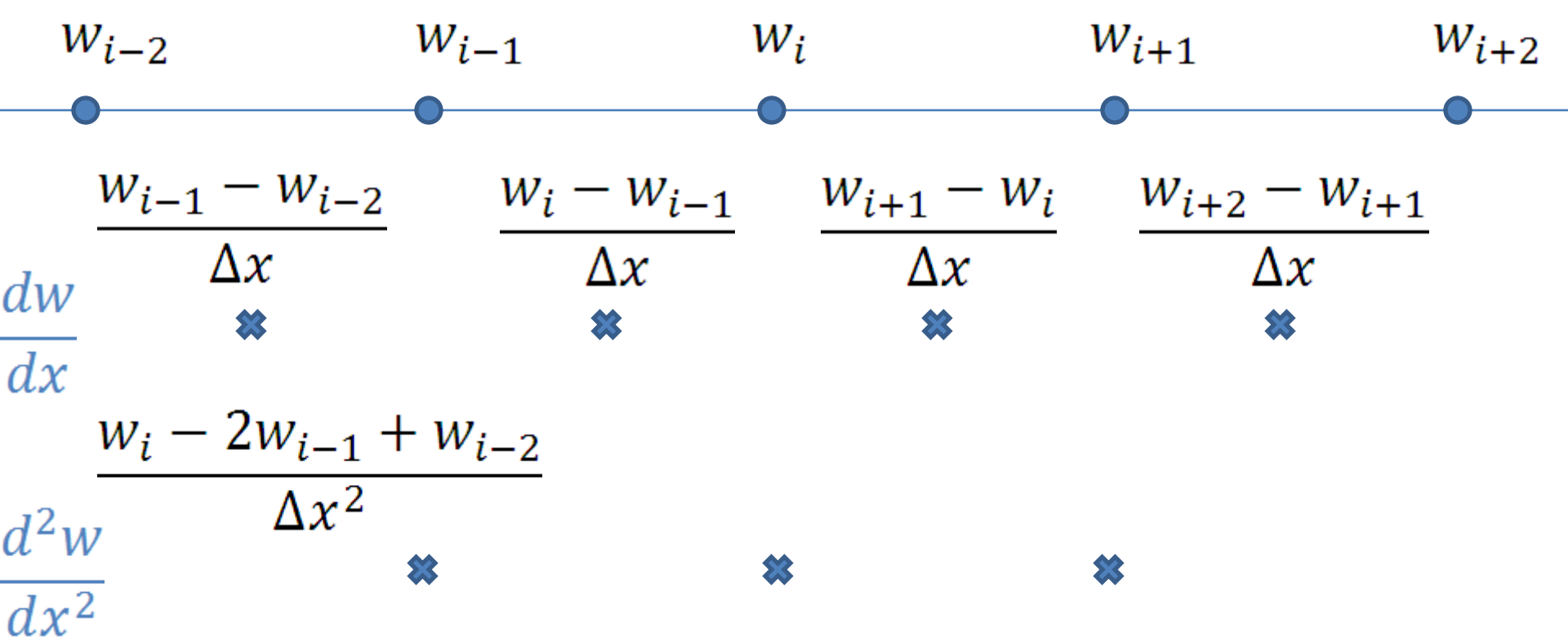




Diagram illustrating the stencil for the first and second order derivatives of  $w$  with respect to  $x$  on a grid.

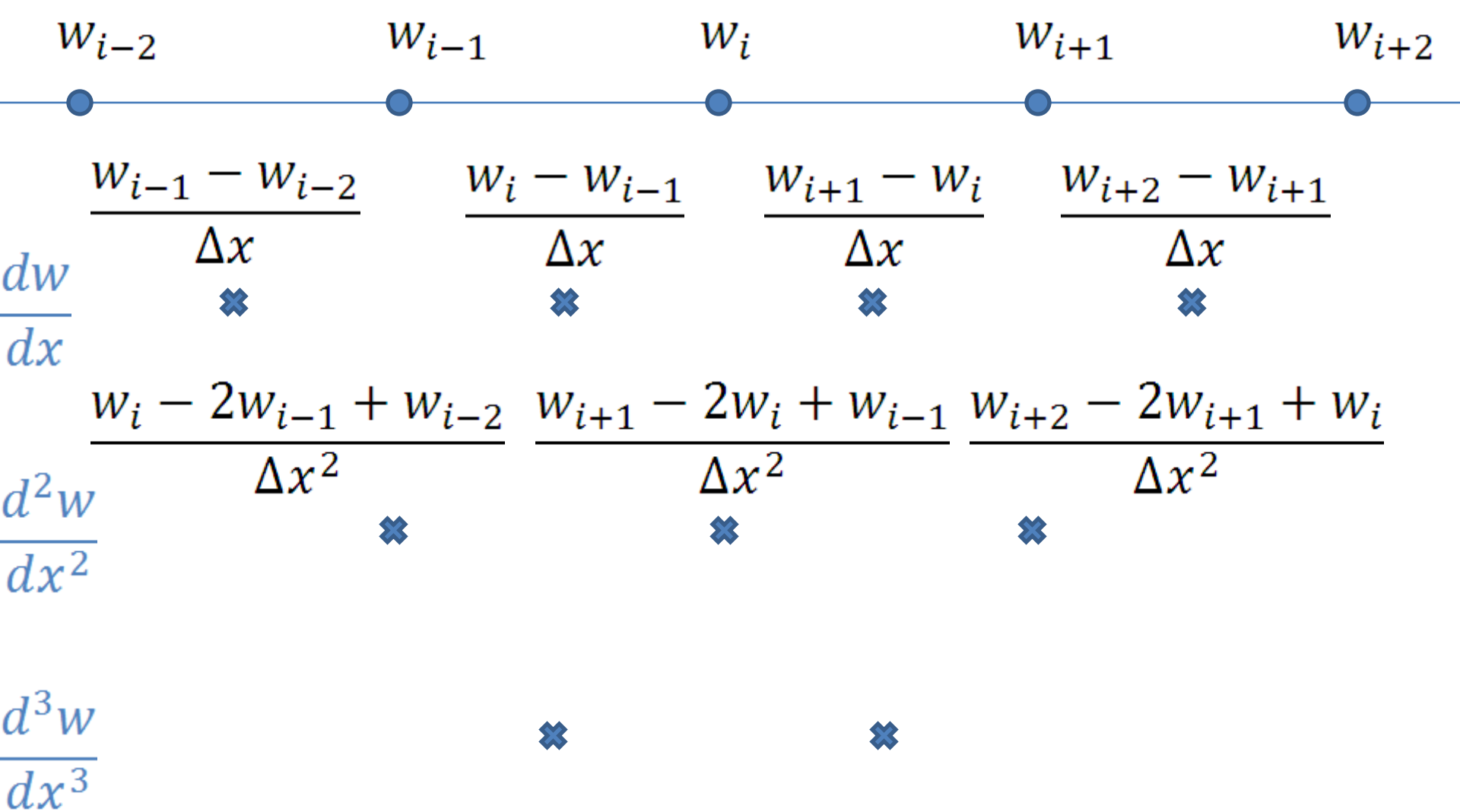
The grid points are labeled  $w_{i-2}$ ,  $w_{i-1}$ ,  $w_i$ ,  $w_{i+1}$ , and  $w_{i+2}$ .















The first order derivative  $\frac{dw}{dx}$  is calculated using the central difference stencil:

$$\frac{dw}{dx} \approx \frac{w_{i-1} - w_{i-2}}{\Delta x} \times \frac{w_i - w_{i-1}}{\Delta x} \times \frac{w_{i+1} - w_i}{\Delta x} \times \frac{w_{i+2} - w_{i+1}}{\Delta x}$$
















The second order derivative  $\frac{d^2w}{dx^2}$  is calculated using the central difference stencil:

$$\frac{d^2w}{dx^2} \approx \frac{w_i - 2w_{i-1} + w_{i-2}}{\Delta x^2} \times \frac{w_{i+1} - 2w_i + w_{i-1}}{\Delta x^2} \times \frac{w_{i+2} - 2w_{i+1} + w_i}{\Delta x^2}$$



	$w_{i-2}$	$w_{i-1}$	$w_i$	$w_{i+1}$	$w_{i+2}$
					
	$\frac{w_{i-1} - w_{i-2}}{\Delta x}$	$\frac{w_i - w_{i-1}}{\Delta x}$	$\frac{w_{i+1} - w_i}{\Delta x}$	$\frac{w_{i+2} - w_{i+1}}{\Delta x}$	
$\frac{dw}{dx}$					
	$\frac{w_i - 2w_{i-1} + w_{i-2}}{\Delta x^2}$	$\frac{w_{i+1} - 2w_i + w_{i-1}}{\Delta x^2}$	$\frac{w_{i+2} - 2w_{i+1} + w_i}{\Delta x^2}$		
$\frac{d^2w}{dx^2}$					
	$\frac{w_{i+1} - 3w_i + 3w_{i-1} - w_{i-2}}{\Delta x^3}$	$\frac{w_{i+2} - 3w_{i+1} + 3w_i - w_{i-1}}{\Delta x^3}$			
$\frac{d^3w}{dx^3}$					

	$w_{i-2}$	$w_{i-1}$	$w_i$	$w_{i+1}$	$w_{i+2}$
	●	●	●	●	●
	$\frac{w_{i-1} - w_{i-2}}{\Delta x}$	$\frac{w_i - w_{i-1}}{\Delta x}$	$\frac{w_{i+1} - w_i}{\Delta x}$	$\frac{w_{i+2} - w_{i+1}}{\Delta x}$	
$\frac{dw}{dx}$	×	×	×	×	
	$\frac{w_i - 2w_{i-1} + w_{i-2}}{\Delta x^2}$	$\frac{w_{i+1} - 2w_i + w_{i-1}}{\Delta x^2}$	$\frac{w_{i+2} - 2w_{i+1} + w_i}{\Delta x^2}$		
$\frac{d^2w}{dx^2}$		×	×	×	
	$\frac{w_{i+1} - 3w_i + 3w_{i-1} - w_{i-2}}{\Delta x^3}$			$\frac{w_{i+2} - 3w_{i+1} + 3w_i - w_{i-1}}{\Delta x^3}$	
$\frac{d^3w}{dx^3}$				×	×
$\frac{d^4w}{dx^4}$			×		

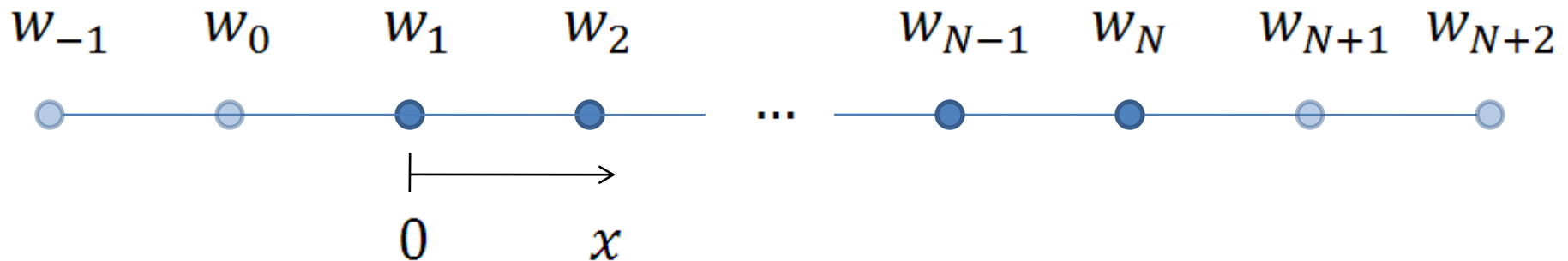
	$w_{i-2}$	$w_{i-1}$	$w_i$	$w_{i+1}$	$w_{i+2}$
					
$\frac{dw}{dx}$	$\frac{w_{i-1} - w_{i-2}}{\Delta x}$	$\frac{w_i - w_{i-1}}{\Delta x}$	$\frac{w_{i+1} - w_i}{\Delta x}$	$\frac{w_{i+2} - w_{i+1}}{\Delta x}$	
					
$\frac{d^2w}{dx^2}$	$\frac{w_i - 2w_{i-1} + w_{i-2}}{\Delta x^2}$	$\frac{w_{i+1} - 2w_i + w_{i-1}}{\Delta x^2}$	$\frac{w_{i+2} - 2w_{i+1} + w_i}{\Delta x^2}$		
					
$\frac{d^3w}{dx^3}$	$\frac{w_{i+1} - 3w_i + 3w_{i-1} - w_{i-2}}{\Delta x^3}$	$\frac{w_{i+2} - 3w_{i+1} + 3w_i - w_{i-1}}{\Delta x^3}$			
					
$\frac{d^4w}{dx^4}$	$\frac{w_{i+2} - 4w_{i+1} + 6w_i - 4w_{i-1} + w_{i-2}}{\Delta x^4}$				
					

# Condições de contorno

- Placa contínua:

$$w \rightarrow 0 \text{ para } x \rightarrow 0$$

$$w \rightarrow 0 \text{ para } x \rightarrow x_n$$



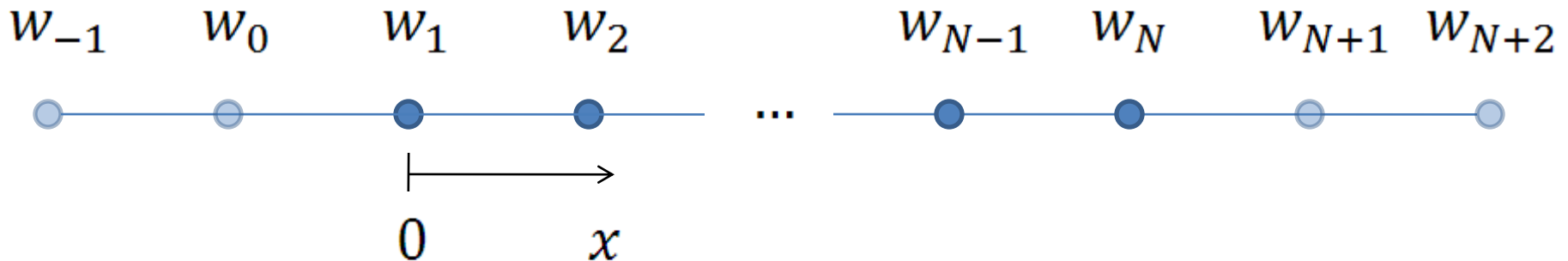
# Condições de contorno

- Placa contínua:

$$w \rightarrow 0 \text{ para } x \rightarrow 0$$

$$w \rightarrow 0 \text{ para } x \rightarrow x_n$$

$$w_{-1}, w_0, w_{N+1}, w_{N+2} = 0$$



$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p$$



$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p$$

$$D \frac{w_{i+2} - 4w_{i+1} + 6w_i - 4w_{i-1} + w_{i-2}}{\Delta x^4} + \Delta \rho g w_i = p_i$$

$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p$$

$$D \frac{w_{i+2} - 4w_{i+1} + 6w_i - 4w_{i-1} + w_{i-2}}{\Delta x^4} + \Delta \rho g w_i = p_i$$

$$D[w_{i+2} - 4w_{i+1} + 6w_i - 4w_{i-1} + w_{i-2}] + \Delta x^4 \Delta \rho g w_i = \Delta x^4 p_i$$

$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p$$

$$D \frac{w_{i+2} - 4w_{i+1} + 6w_i - 4w_{i-1} + w_{i-2}}{\Delta x^4} + \Delta \rho g w_i = p_i$$

$$D[w_{i+2} - 4w_{i+1} + \textcircled{6w_i} - 4w_{i-1} + w_{i-2}] + \textcircled{\Delta x^4 \Delta \rho g w_i} = \Delta x^4 p_i$$

$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p$$

$$D \frac{w_{i+2} - 4w_{i+1} + 6w_i - 4w_{i-1} + w_{i-2}}{\Delta x^4} + \Delta \rho g w_i = p_i$$

$$D[w_{i+2} - 4w_{i+1} + \textcircled{6w_i} - 4w_{i-1} + w_{i-2}] + \textcircled{\Delta x^4 \Delta \rho g w_i} = \Delta x^4 p_i$$

$$\begin{aligned} Dw_{i-2} - 4Dw_{i-1} + [6D + \Delta x^4 \Delta \rho g]w_i - 4Dw_{i+1} + Dw_{i+2} &= \\ &= \Delta x^4 p_i \end{aligned}$$

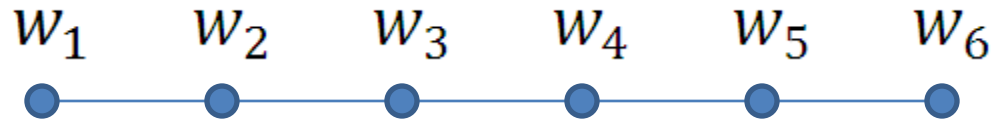
$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p$$

$$D \frac{w_{i+2} - 4w_{i+1} + 6w_i - 4w_{i-1} + w_{i-2}}{\Delta x^4} + \Delta \rho g w_i = p_i$$

$$D[w_{i+2} - 4w_{i+1} + \textcircled{6w_i} - 4w_{i-1} + w_{i-2}] + \textcircled{\Delta x^4 \Delta \rho g w_i} = \Delta x^4 p_i$$

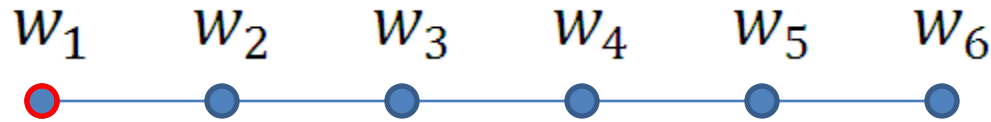
$$\begin{aligned} Dw_{i-2} - 4Dw_{i-1} + [6D + \Delta x^4 \Delta \rho g]w_i - 4Dw_{i+1} + Dw_{i+2} &= \\ &= \Delta x^4 p_i \end{aligned}$$

# Exemplo



$$Dw_{i-2} - 4Dw_{i-1} + [6D + \Delta x^4 \Delta \rho g]w_i - 4Dw_{i+1} + Dw_{i+2} = \Delta x^4 p_i$$

# Exemplo

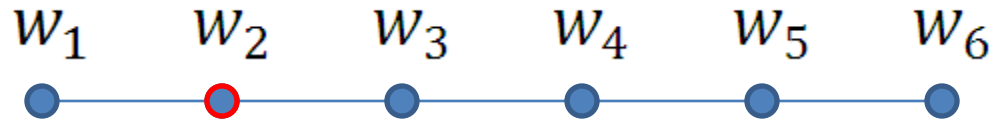


$w_1 :$

$$[6D + \Delta x^4 \Delta \rho g]w_1 - 4Dw_2 + Dw_3 = \Delta x^4 p_1$$

$$Dw_{i-2} - 4Dw_{i-1} + [6D + \Delta x^4 \Delta \rho g]w_i - 4Dw_{i+1} + Dw_{i+2} = \Delta x^4 p_i$$

# Exemplo



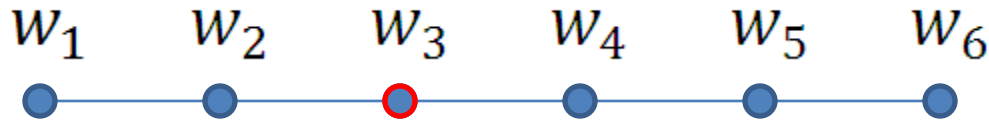
$$w_1 : \quad [6D + \Delta x^4 \Delta \rho g] w_1 - 4D w_2 + D w_3 = \Delta x^4 p_1$$

$$w_2 : \quad -4D w_1 + [6D + \Delta x^4 \Delta \rho g] w_2 - 4D w_3 + D w_4 = \Delta x^4 p_2$$

$$\begin{aligned} Dw_{i-2} - 4Dw_{i-1} + [6D + \Delta x^4 \Delta \rho g] w_i - 4Dw_{i+1} + Dw_{i+2} = \\ = \Delta x^4 p_i \end{aligned}$$



# Exemplo



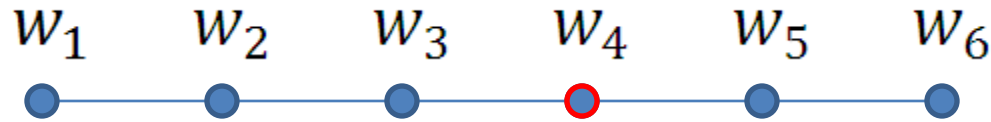
$$w_1 : \quad [6D + \Delta x^4 \Delta \rho g] w_1 - 4D w_2 + D w_3 = \Delta x^4 p_1$$

$$w_2 : \quad -4D w_1 + [6D + \Delta x^4 \Delta \rho g] w_2 - 4D w_3 + D w_4 = \Delta x^4 p_2$$

$$w_3 : \quad D w_1 - 4D w_2 + [6D + \Delta x^4 \Delta \rho g] w_3 - 4D w_4 + D w_5 = \Delta x^4 p_3$$

$$\begin{aligned} D w_{i-2} - 4D w_{i-1} + [6D + \Delta x^4 \Delta \rho g] w_i - 4D w_{i+1} + D w_{i+2} = \\ = \Delta x^4 p_i \end{aligned}$$

# Exemplo



$$w_1 : \quad [6D + \Delta x^4 \Delta \rho g] w_1 - 4Dw_2 + Dw_3 = \Delta x^4 p_1$$

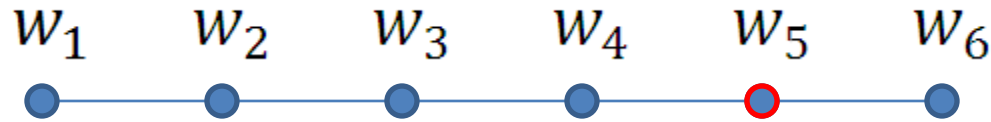
$$w_2 : \quad -4Dw_1 + [6D + \Delta x^4 \Delta \rho g] w_2 - 4Dw_3 + Dw_4 = \Delta x^4 p_2$$

$$w_3 : \quad Dw_1 - 4Dw_2 + [6D + \Delta x^4 \Delta \rho g] w_3 - 4Dw_4 + Dw_5 = \Delta x^4 p_3$$

$$w_4 : \quad Dw_2 - 4Dw_3 + [6D + \Delta x^4 \Delta \rho g] w_4 - 4Dw_5 + Dw_6 = \Delta x^4 p_4$$

$$\begin{aligned} Dw_{i-2} - 4Dw_{i-1} + [6D + \Delta x^4 \Delta \rho g] w_i - 4Dw_{i+1} + Dw_{i+2} &= \\ &= \Delta x^4 p_i \end{aligned}$$

# Exemplo



$$w_1 : \quad [6D + \Delta x^4 \Delta \rho g] w_1 - 4Dw_2 + Dw_3 = \Delta x^4 p_1$$

$$w_2 : \quad -4Dw_1 + [6D + \Delta x^4 \Delta \rho g] w_2 - 4Dw_3 + Dw_4 = \Delta x^4 p_2$$

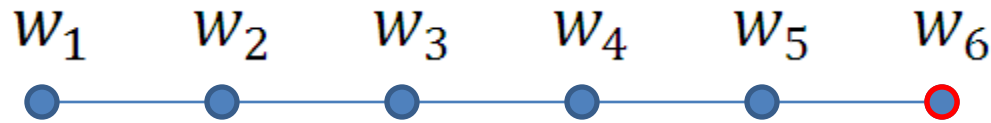
$$w_3 : \quad Dw_1 - 4Dw_2 + [6D + \Delta x^4 \Delta \rho g] w_3 - 4Dw_4 + Dw_5 = \Delta x^4 p_3$$

$$w_4 : \quad Dw_2 - 4Dw_3 + [6D + \Delta x^4 \Delta \rho g] w_4 - 4Dw_5 + Dw_6 = \Delta x^4 p_4$$

$$w_5 : \quad Dw_3 - 4Dw_4 + [6D + \Delta x^4 \Delta \rho g] w_5 - 4Dw_6 = \Delta x^4 p_5$$

$$Dw_{i-2} - 4Dw_{i-1} + [6D + \Delta x^4 \Delta \rho g] w_i - 4Dw_{i+1} + Dw_{i+2} = \Delta x^4 p_i$$

# Exemplo



$$w_1 : \quad [6D + \Delta x^4 \Delta \rho g]w_1 - 4Dw_2 + Dw_3 = \Delta x^4 p_1$$

$$w_2 : \quad -4Dw_1 + [6D + \Delta x^4 \Delta \rho g]w_2 - 4Dw_3 + Dw_4 = \Delta x^4 p_2$$

$$w_3 : \quad Dw_1 - 4Dw_2 + [6D + \Delta x^4 \Delta \rho g]w_3 - 4Dw_4 + Dw_5 = \Delta x^4 p_3$$

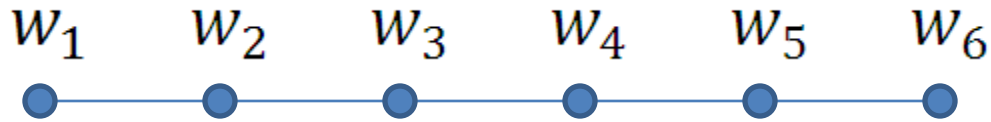
$$w_4 : \quad Dw_2 - 4Dw_3 + [6D + \Delta x^4 \Delta \rho g]w_4 - 4Dw_5 + Dw_6 = \Delta x^4 p_4$$

$$w_5 : \quad Dw_3 - 4Dw_4 + [6D + \Delta x^4 \Delta \rho g]w_5 - 4Dw_6 = \Delta x^4 p_5$$

$$w_6 : \quad Dw_4 - 4Dw_5 + [6D + \Delta x^4 \Delta \rho g]w_6 = \Delta x^4 p_6$$

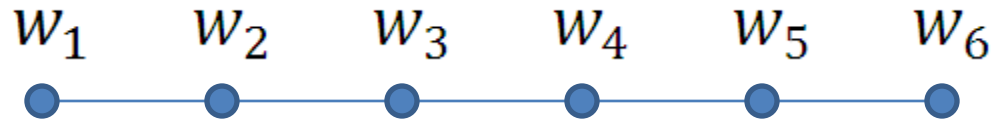
$$\begin{aligned} Dw_{i-2} - 4Dw_{i-1} + [6D + \Delta x^4 \Delta \rho g]w_i - 4Dw_{i+1} + Dw_{i+2} &= \\ &= \Delta x^4 p_i \end{aligned}$$

# Exemplo



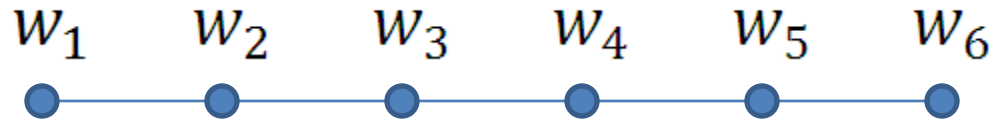
$$\begin{bmatrix} 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 & 0 & 0 \\ -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 & 0 \\ D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 \\ 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D \\ 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D \\ 0 & 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ w_4 \\ w_5 \\ w_6 \end{bmatrix} = \Delta x^4 \begin{bmatrix} p_1 \\ p_2 \\ p_3 \\ p_4 \\ p_5 \\ p_6 \end{bmatrix}$$

# Exemplo



$$\begin{bmatrix}
 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 & 0 & 0 \\
 -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 & 0 \\
 D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 \\
 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D \\
 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D \\
 0 & 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g
 \end{bmatrix}
 \begin{bmatrix}
 w_1 \\
 w_2 \\
 w_3 \\
 w_4 \\
 w_5 \\
 w_6
 \end{bmatrix}
 = \Delta x^4
 \begin{bmatrix}
 p_1 \\
 p_2 \\
 p_3 \\
 p_4 \\
 p_5 \\
 p_6
 \end{bmatrix}$$

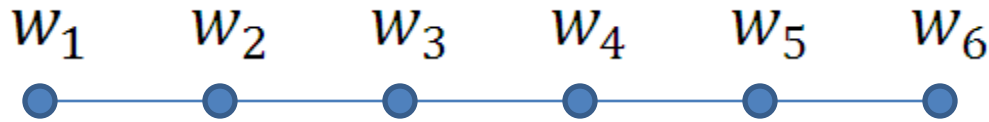
# Exemplo



$$\begin{bmatrix}
 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 & 0 & 0 \\
 -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 & 0 \\
 D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 \\
 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D \\
 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D \\
 0 & 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g
 \end{bmatrix}
 \begin{bmatrix}
 w_1 \\
 w_2 \\
 w_3 \\
 w_4 \\
 w_5 \\
 w_6
 \end{bmatrix}
 = \Delta x^4
 \begin{bmatrix}
 p_1 \\
 p_2 \\
 p_3 \\
 p_4 \\
 p_5 \\
 p_6
 \end{bmatrix}$$

$$\mathbf{Aw} = \mathbf{p}$$

# Exemplo



$$\begin{bmatrix}
 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 & 0 & 0 \\
 -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 & 0 \\
 D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 \\
 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D \\
 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D \\
 0 & 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g
 \end{bmatrix}
 \begin{bmatrix}
 w_1 \\
 w_2 \\
 w_3 \\
 w_4 \\
 w_5 \\
 w_6
 \end{bmatrix}
 = \Delta x^4
 \begin{bmatrix}
 p_1 \\
 p_2 \\
 p_3 \\
 p_4 \\
 p_5 \\
 p_6
 \end{bmatrix}$$

$$\mathbf{A} \mathbf{w} = \mathbf{p}$$

$$A(i, j = i - 2) = D$$

$$A(i, j = i - 1) = -4D$$

$$A(i, j = i) = 6D + \Delta x^4 \Delta \rho g$$

$$A(i, j = i + 1) = -4D$$

$$A(i, j = i + 2) = D$$



# Condições de contorno

- Placa rompida:

$$\frac{d^2 w}{dx^2} = 0 \text{ para } x = x_1$$



# Condições de contorno

- Placa rompida:

$$\frac{d^2 w}{dx^2} = 0 \text{ para } x = x_1$$

$$\frac{w_2 - 2w_1 + w_0}{\Delta x^2} = 0$$

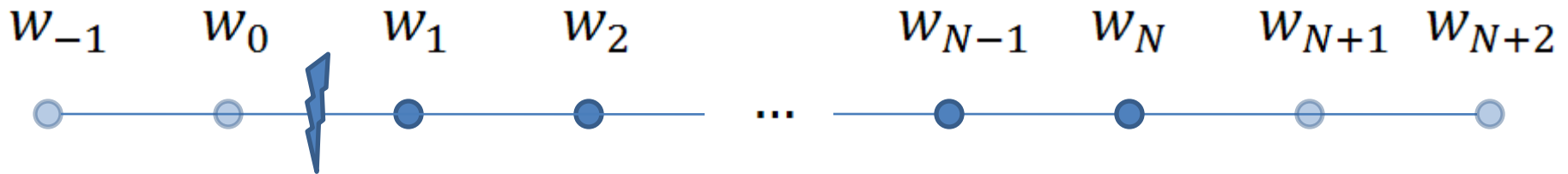


# Condições de contorno

- Placa rompida:

$$\frac{d^2 w}{dx^2} = 0 \text{ para } x = x_1$$

$$\frac{w_2 - 2w_1 + w_0}{\Delta x^2} = 0 \rightarrow w_0 = 2w_1 - w_2$$



# Condições de contorno

- Placa rompida:  $\int_0^\infty \Delta \rho g w \, dx = \int_0^\infty p \, dx$



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- Placa rompida:  $\int_0^\infty \Delta \rho g w \, dx = \int_0^\infty p \, dx$

$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p$$



# Condições de contorno

- Placa rompida:  $\int_0^\infty \Delta \rho g w \, dx = \int_0^\infty p \, dx$

$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p \rightarrow \int_0^\infty D \frac{d^4 w}{dx^4} \, dx + \int_0^\infty \Delta \rho g w \, dx = \int_0^\infty p \, dx$$



# Condições de contorno

- Placa rompida:  $\int_0^\infty \Delta \rho g w \, dx = \int_0^\infty p \, dx$

$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p \rightarrow \int_0^\infty D \frac{d^4 w}{dx^4} \, dx + \int_0^\infty \Delta \rho g w \, dx = \int_0^\infty p \, dx$$



# Condições de contorno

- Placa rompida:  $\int_0^\infty \Delta \rho g w \, dx = \int_0^\infty p \, dx$

$$D \frac{d^4 w}{dx^4} + \Delta \rho g w = p \rightarrow \int_0^\infty D \frac{d^4 w}{dx^4} \, dx + \int_0^\infty \Delta \rho g w \, dx = \int_0^\infty p \, dx$$

$$\int_0^\infty D \frac{d^4 w}{dx^4} \, dx = 0$$





# Condições de contorno

- Placa rompida:

$$\int_0^{\infty} D \frac{d^4 w}{dx^4} dx = 0$$



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- Placa rompida:

$$\int_0^\infty D \frac{d^4 w}{dx^4} dx = 0 \rightarrow D \frac{d^3 w}{dx^3} \Big|_0^\infty = 0$$



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Placa semi-infinita

$x \rightarrow \infty$  temos  $w \rightarrow 0 \therefore \frac{d^3 w}{dx^3} \rightarrow 0$



# Condições de contorno

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# Condições de contorno

- Placa rompida:

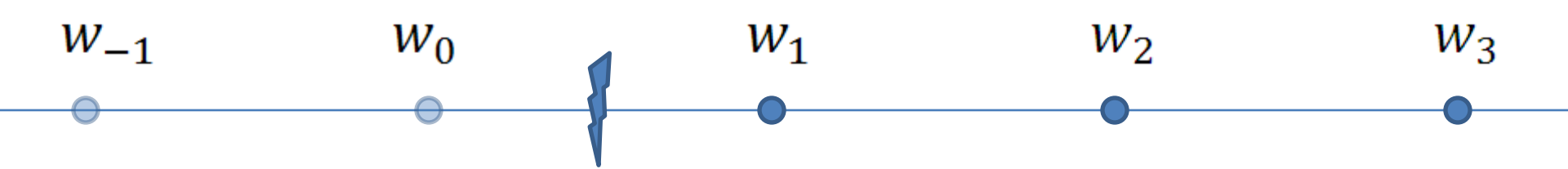
$$\int_0^{\infty} D \frac{d^4 w}{dx^4} dx = 0 \rightarrow D \frac{d^3 w}{dx^3} \Big|_0^{\infty} = 0 \rightarrow D \frac{d^3 w}{dx^3} \Big|_0 = 0$$

Placa semi-infinita

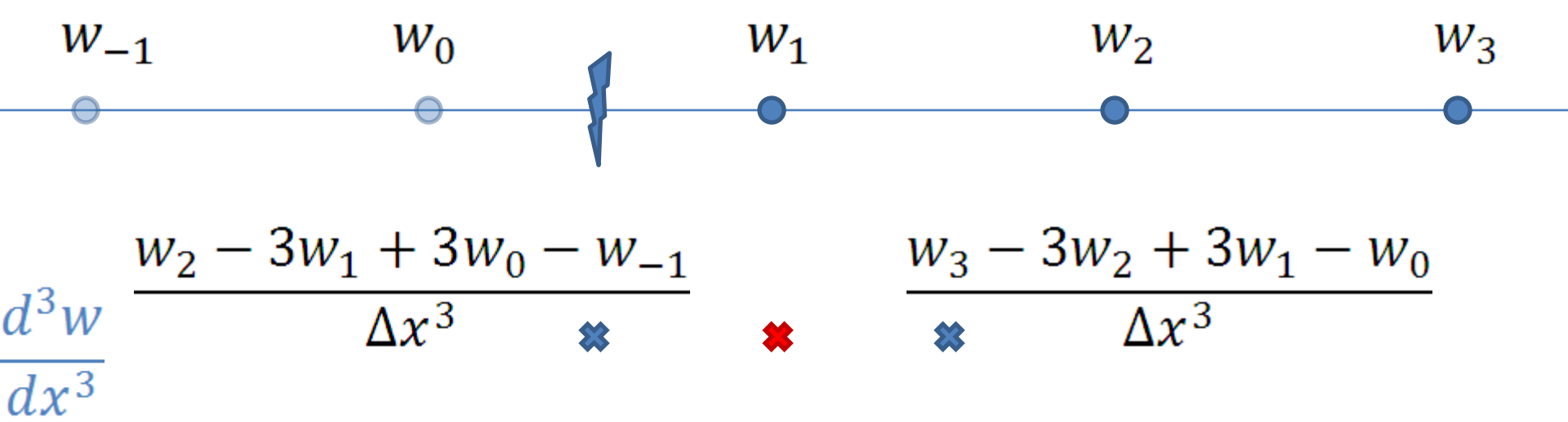
$x \rightarrow \infty$  temos  $w \rightarrow 0 \therefore \frac{d^3 w}{dx^3} \rightarrow 0$

$$\frac{d^3 w}{dx^3} \Big|_0 = 0$$

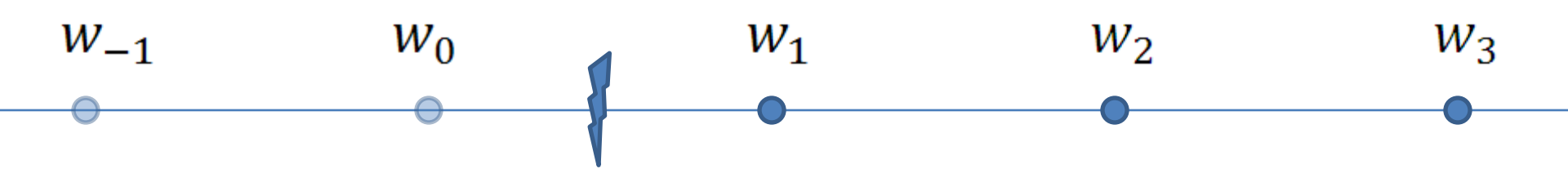




$$\frac{d^3 w}{dx^3} \quad \frac{w_2 - 3w_1 + 3w_0 - w_{-1}}{\Delta x^3} \quad \times \quad \times \quad \frac{w_3 - 3w_2 + 3w_1 - w_0}{\Delta x^3}$$

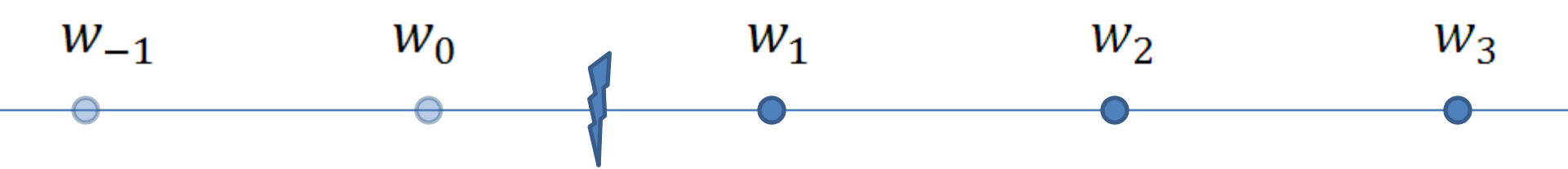






$$\frac{d^3 w}{dx^3} \quad \frac{w_2 - 3w_1 + 3w_0 - w_{-1}}{\Delta x^3} \quad \times \quad \times \quad \times \quad \frac{w_3 - 3w_2 + 3w_1 - w_0}{\Delta x^3}$$

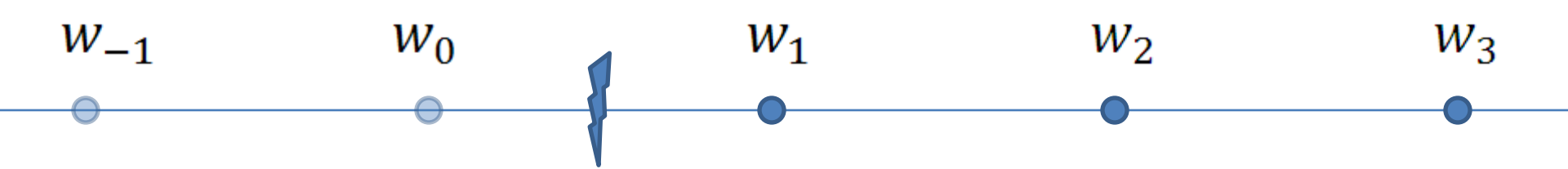
$$\frac{w_3 - 2w_2 + 2w_0 - w_{-1}}{2\Delta x^3}$$



$$\frac{d^3 w}{dx^3} \quad \frac{w_2 - 3w_1 + 3w_0 - w_{-1}}{\Delta x^3} \quad \times \quad \times \quad \times \quad \frac{w_3 - 3w_2 + 3w_1 - w_0}{\Delta x^3}$$

$$\frac{w_3 - 2w_2 + 2w_0 - w_{-1}}{2\Delta x^3}$$

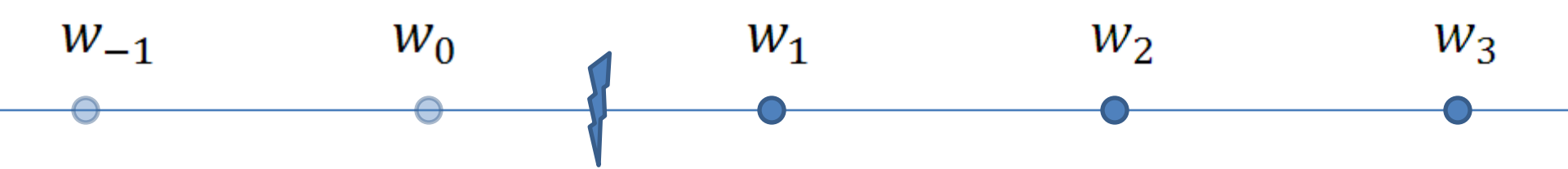
$$\left. \frac{d^3 w}{dx^3} \right|_0 = 0$$



$$\frac{d^3 w}{dx^3} \quad \frac{w_2 - 3w_1 + 3w_0 - w_{-1}}{\Delta x^3} \quad \times \quad \times \quad \times \quad \frac{w_3 - 3w_2 + 3w_1 - w_0}{\Delta x^3}$$

$$\frac{w_3 - 2w_2 + 2w_0 - w_{-1}}{2\Delta x^3}$$

$$\left. \frac{d^3 w}{dx^3} \right|_0 = 0 \rightarrow \frac{w_3 - 2w_2 + 2w_0 - w_{-1}}{2\Delta x^3} = 0$$

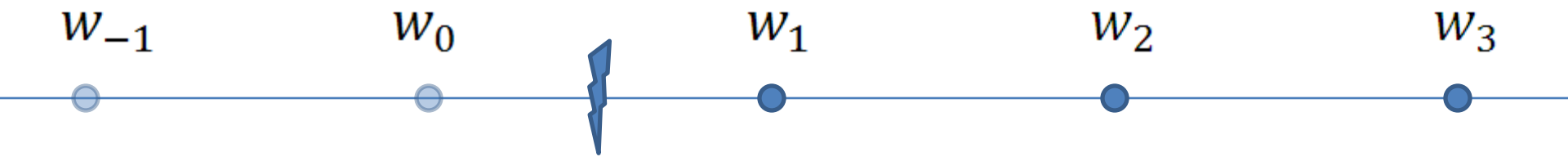


$$\frac{d^3 w}{dx^3} \quad \frac{w_2 - 3w_1 + 3w_0 - w_{-1}}{\Delta x^3} \quad \times \quad \times \quad \times \quad \frac{w_3 - 3w_2 + 3w_1 - w_0}{\Delta x^3}$$

$$\frac{w_3 - 2w_2 + 2w_0 - w_{-1}}{2\Delta x^3}$$

$$\left. \frac{d^3 w}{dx^3} \right|_0 = 0 \rightarrow \frac{w_3 - 2w_2 + 2w_0 - w_{-1}}{2\Delta x^3} = 0$$

$$\rightarrow w_{-1} = w_3 - 2w_2 + 2w_0$$

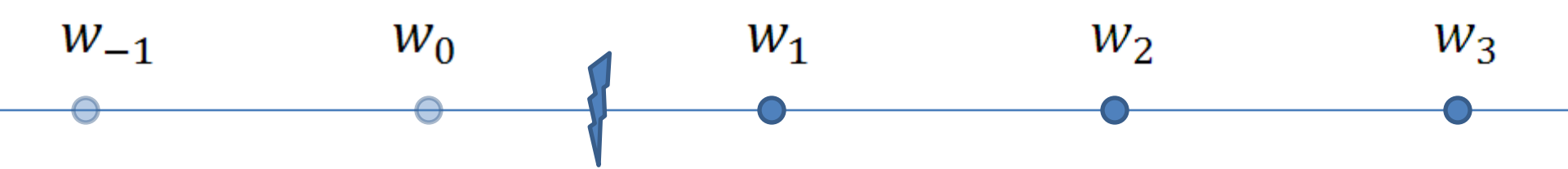


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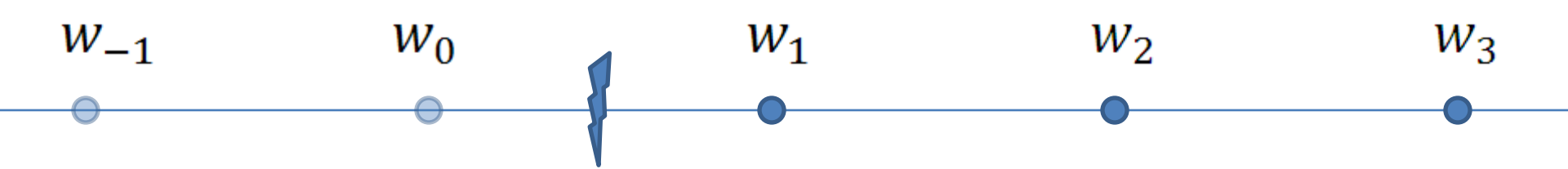


$$\frac{d^3 w}{dx^3} \quad \frac{w_2 - 3w_1 + 3w_0 - w_{-1}}{\Delta x^3} \quad \times \quad \times \quad \times \quad \frac{w_3 - 3w_2 + 3w_1 - w_0}{\Delta x^3}$$

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$$\rightarrow w_{-1} = w_3 - 2w_2 + 2w_0 \quad \text{with } w_0 = 2w_1 - w_2$$



$$\frac{d^3 w}{dx^3} \quad \frac{w_2 - 3w_1 + 3w_0 - w_{-1}}{\Delta x^3} \quad \times \quad \times \quad \times \quad \frac{w_3 - 3w_2 + 3w_1 - w_0}{\Delta x^3}$$

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$$\rightarrow w_{-1} = w_3 - 2w_2 + 2w_0 \quad \text{with a red arrow pointing to } w_0 \text{ and the equation } w_0 = 2w_1 - w_2$$

$$\rightarrow w_{-1} = w_3 - 4w_2 + 4w_1$$

# Modificação da matriz **A** para placa rompida

$$A(1,1) = 2D + \Delta x^4 \Delta \rho g$$

$$A(1,2) = -4D$$

$$A(1,3) = 2D$$

$$A(2,1) = -2D$$

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$$\begin{bmatrix} 2D + \Delta x^4 \Delta \rho g & -4D & 2D & 0 & 0 & 0 \\ -2D & 5D + \Delta x^4 \Delta \rho g & -4D & D & 0 & 0 \\ D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 \\ 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D \\ 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D \\ 0 & 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g \end{bmatrix}$$

# Condições de contorno

- Placa contínua II:

$$\left. \frac{dw}{dx} \right|_0 = 0$$



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- Placa contínua II:  $\int_0^\infty \Delta \rho g w \, dx = \int_0^\infty p \, dx$



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# Condições de contorno

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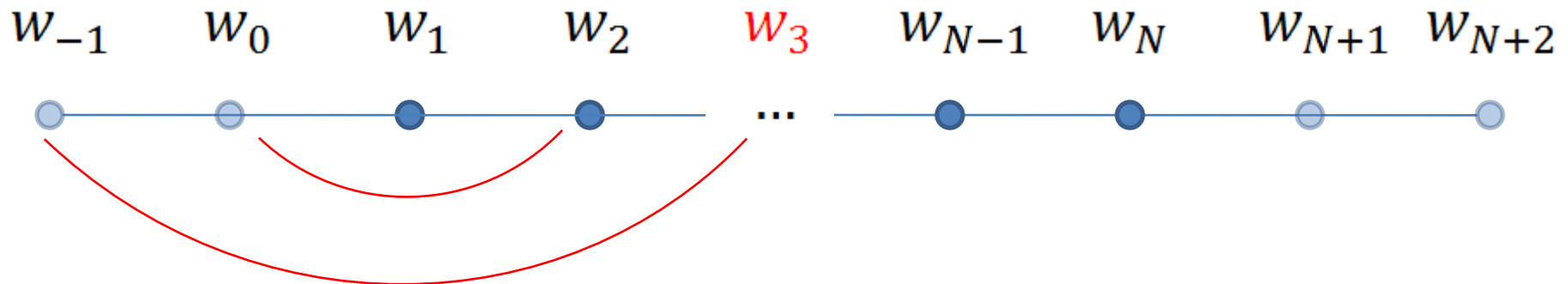
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# Modificação da matriz **A** para placa contínua II

$$A(1,2) = -8D$$

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$$\begin{bmatrix} 6D + \Delta x^4 \Delta \rho g & -8D & 2D & 0 & 0 & 0 \\ -4D & 7D + \Delta x^4 \Delta \rho g & -4D & D & 0 & 0 \\ D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D & 0 \\ 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D & D \\ 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g & -4D \\ 0 & 0 & 0 & D & -4D & 6D + \Delta x^4 \Delta \rho g \end{bmatrix}$$