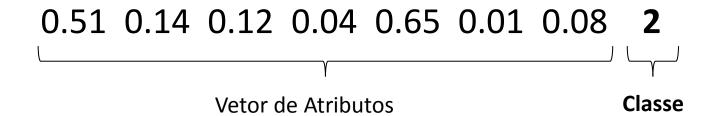
# Aprendizagem não supervisonada

• No aprendizado **supervisionado**, todas os exemplos de treinamento eram **rotulados**.



 Estes exemplos são ditos "supervisionados", pois, contém tanto a entrada (atributos), quanto a saída (classe).

 Porém, muitas vezes temos que lidar com exemplos "não-supervisionados", isto é, exemplos não rotulados.

#### Por que?

 Coletar e rotular um grande conjunto de exemplos pode custar muito tempo, esforço, dinheiro...

- Entretanto, podemos utilizar grandes quantidades de dados não rotulados para encontrar padrões existentes nestes dados. E somente depois supervisionar a rotulação dos agrupamentos encontrados.
- Esta abordagem é bastante utilizada em aplicações de mineração de dados (datamining), onde o conteúdo de grandes bases de dados não é conhecido antecipadamente.

 O principal interesse do aprendizado nãosupervisionado é desvendar a organização dos padrões existentes nos dados através de clusters (agrupamentos) consistentes.

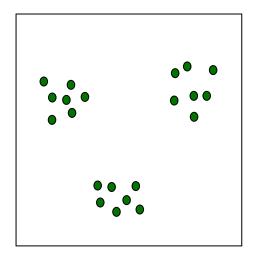
 Com isso, é possível descobrir similaridades e diferenças entre os padrões existentes, assim como derivar conclusões úteis a respeito deles.

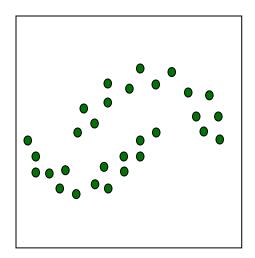
# Clusterização

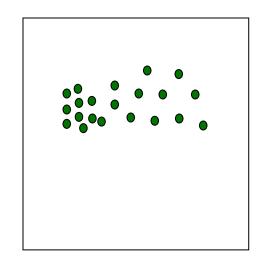
 A clusterização é o processo de agrupar um conjunto de objetos físicos ou abstratos em classes de objetos similares.

 Um cluster é uma coleção de objetos que são similares uns aos outros (de acordo com algum critério de similaridade pré-definido) e dissimilares a objetos pertencentes a outros clusters.

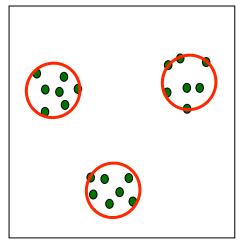
- Clustering describes data by "groups"
- The meaning of "groups" may vary by data!
- Examples

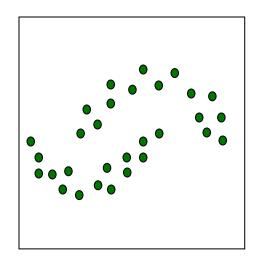


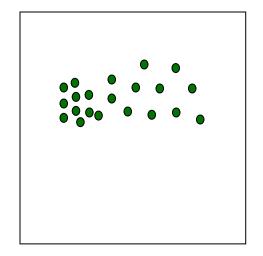




- Clustering describes data by "groups"
- The meaning of "groups" may vary by data!
- Examples

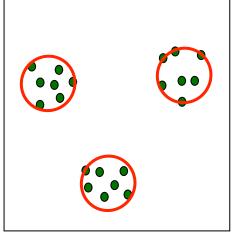




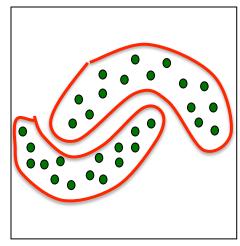


Location

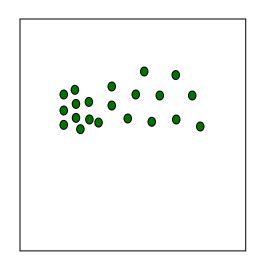
- Clustering describes data by "groups"
- The meaning of "groups" may vary by data!
- Examples



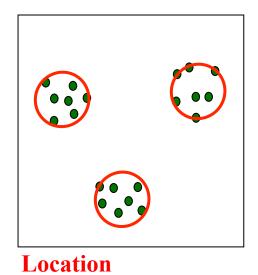


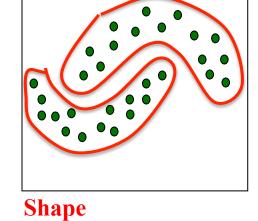


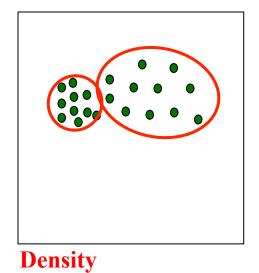
**Shape** 



- Clustering describes data by "groups"
- The meaning of "groups" may vary by data!
- Examples







## Critério de Similaridade

• A similaridade é difícil de ser definida...



# Algoritmos de Clustering

 Os algoritmos de clusterização buscam identificar padrões existentes em conjuntos de dados.

- Os algoritmos de clusterização podem ser divididos em varias categorias:
  - Sequenciais;
  - Hierárquicos;
  - Baseados na otimização de funções custo;
  - Outros: Fuzzy, SOM, LVQ...

# Algoritmos Sequenciais

São algoritmos diretos e rápidos.

 Geralmente, todos os vetores de características são apresentados ao algoritmo uma ou várias vezes.

• O resultado final geralmente depende da ordem de apresentação dos vetores de características.

# Algoritmos Sequenciais

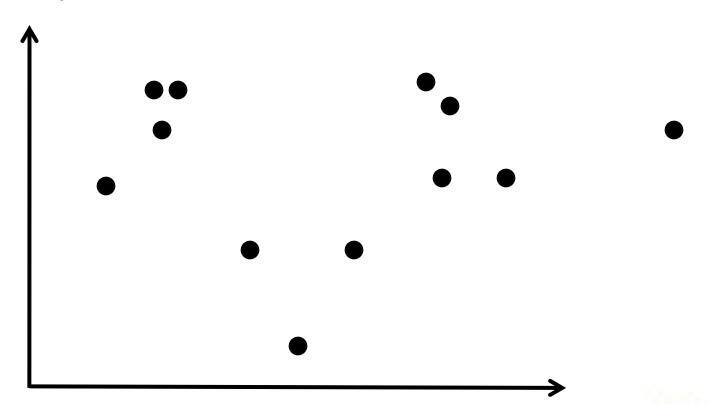
- Basic Sequential Algorithmic Scheme (BSAS)
  - Todos os vetores s\(\tilde{a}\) apresentados uma \(\tilde{u}\) nica vez ao algoritmo.
  - Número de clusters não é conhecido inicialmente.
  - Novos clusters são criados enquanto o algoritmo evolui.

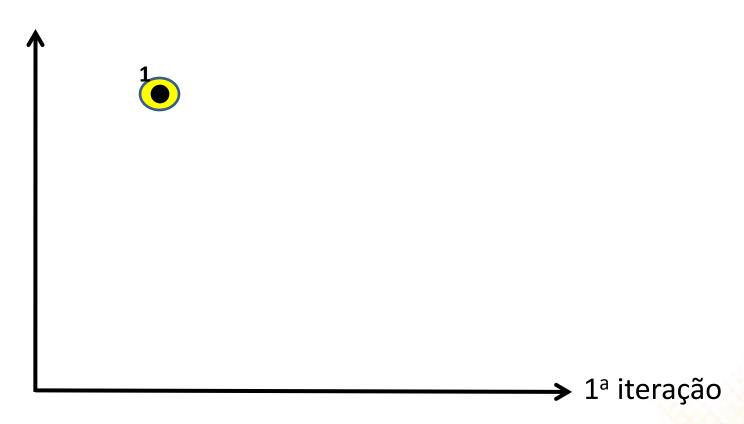
#### Parâmetros do BSAS:

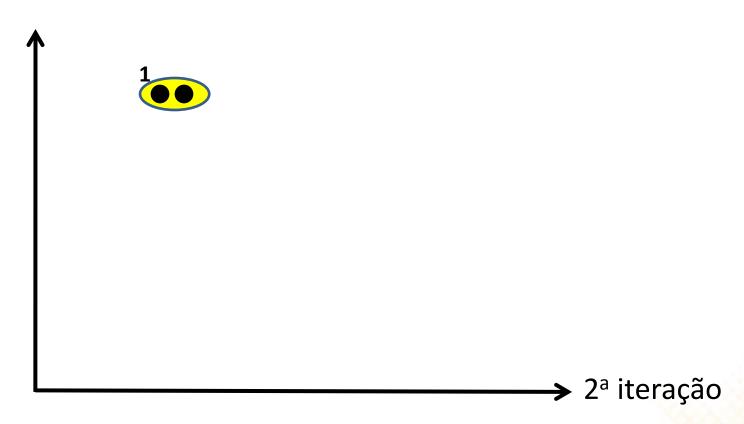
- d(x, C): métrica de distância entre um vetor de características x e um cluster C.
- Θ: limiar de dissimilaridade.
- q: número máximo de clusters.

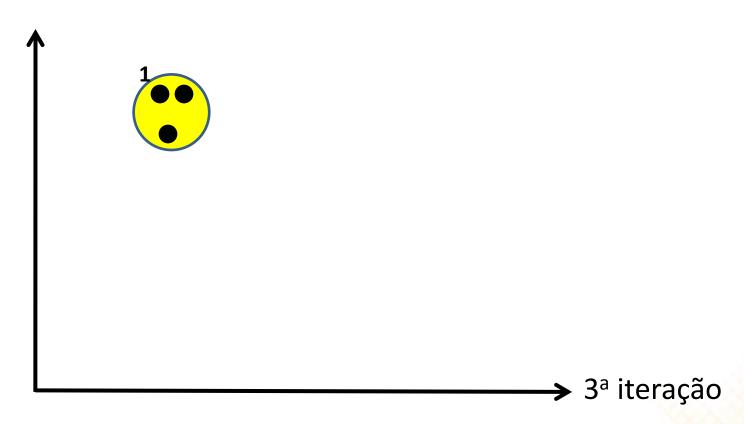
#### Ideia Geral do Algoritmo:

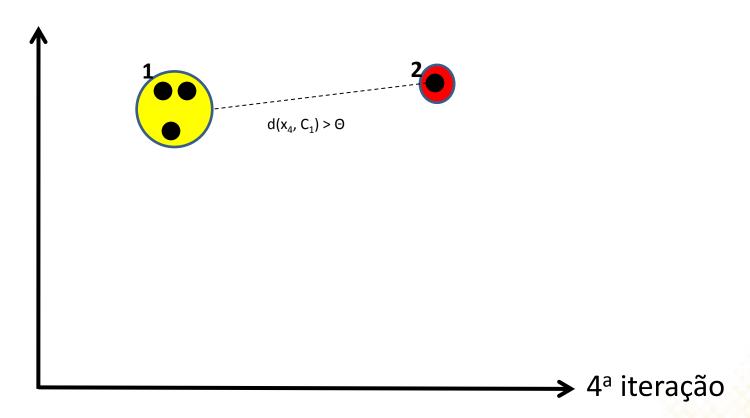
 Para um dado vetor de características, designá-lo para um cluster existente ou criar um novo cluster (depende da distância entre o vetor e os clusters já formados).

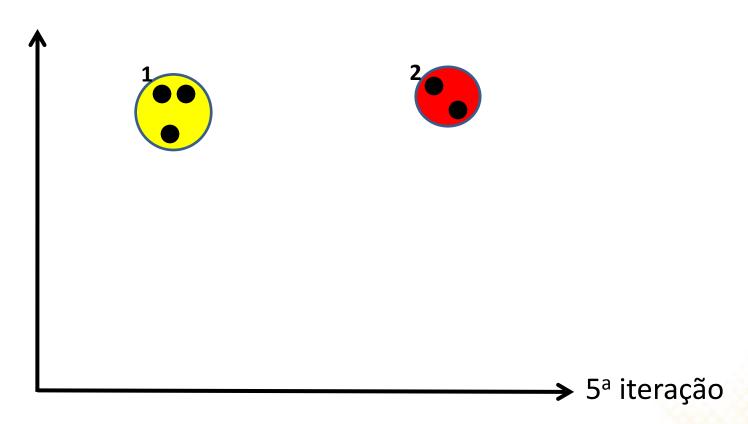


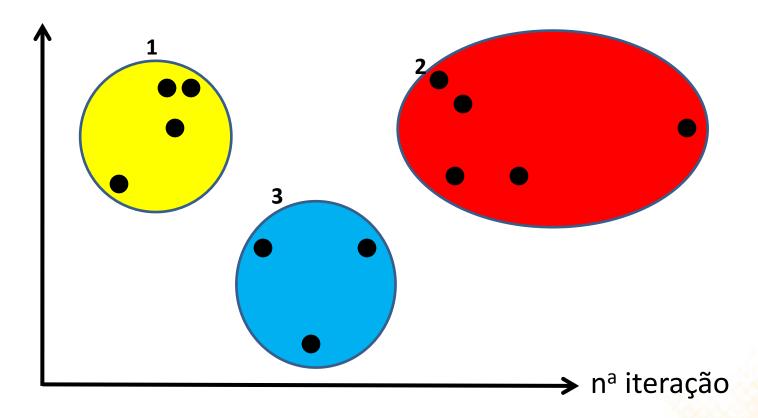












 Os algoritmos de clusterização hierárquica pode ser divididos em 2 subcategorias:

#### Aglomerativos:

- Produzem uma sequência de agrupamentos com um número decrescente de clusters a cada passo.
- Os agrupamentos produzidos em cada passo resultam da fusão de dois clusters em um.

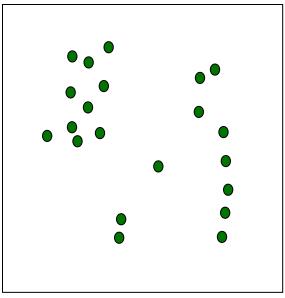
#### Divisivos:

- Atuam na direção oposta, isto é, eles produzem uma sequência de agrupamentos com um número crescente de clusters a cada passo.
- Os agrupamentos produzidos em cada passo resultam da partição de um único cluster em dois.

## Hierarchical Agglomerative Clustering

Initially, every datum is a cluster

#### Data:

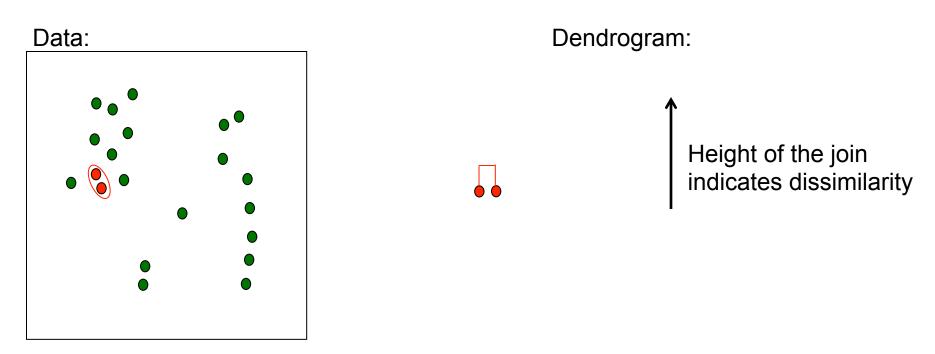


- A simple clustering algorithm
- Define a distance (or dissimilarity)
   between clusters (we'll return to this)
- Initialize: every example is a cluster
- Iterate:
  - Compute distances between all clusters (store for efficiency)
  - Merge two closest clusters
- Save both clustering and sequence of cluster operations
- "Dendrogram"

Algorithmic Complexity: O(m<sup>2</sup> log m) +

#### Iteration 1

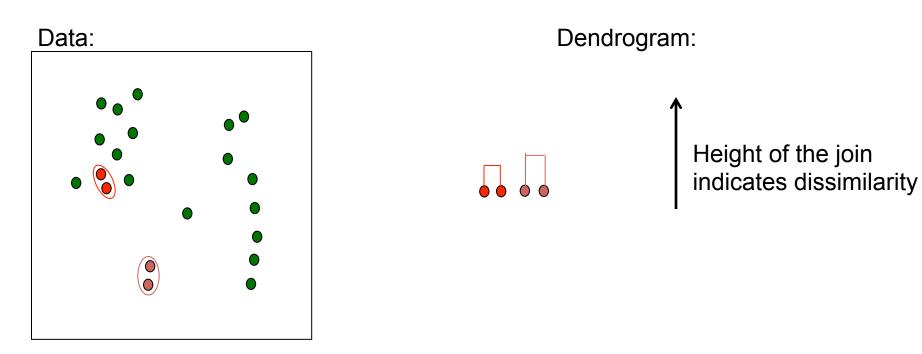
Builds up a sequence of clusters ("hierarchical")



Algorithmic Complexity:  $O(m^2 \log m) + O(m \log m) +$ 

#### Iteration 2

Builds up a sequence of clusters ("hierarchical")



Algorithmic Complexity:  $O(m^2 \log m) + 2*O(m \log m) +$ 

#### Iteration 3

Builds up a sequence of clusters ("hierarchical")

Data:

Dendrogram:

Height of the join indicates dissimilarity

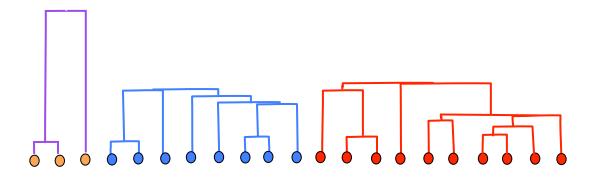
Algorithmic Complexity:  $O(m^2 \log m) + 3*O(m \log m) +$ 

#### Iteration m-3

Builds up a sequence of clusters ("hierarchical")

Data:

Dendrogram:

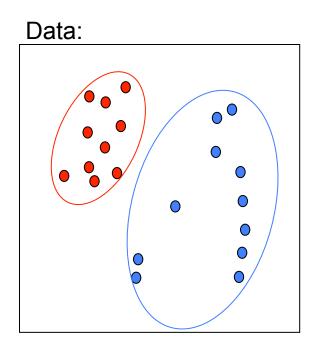


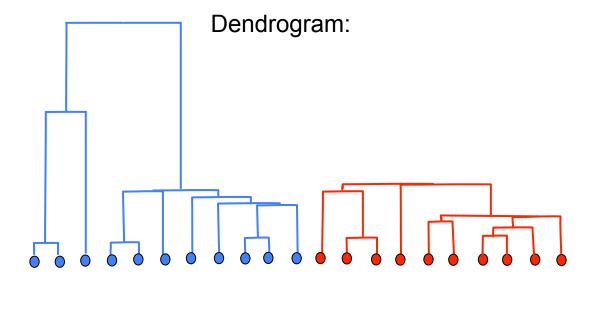
In matlab: "linkage" function (stats toolbox)

Algorithmic Complexity:  $O(m^2 \log m) + (m-3)*O(m \log m) +$ 

#### Iteration m-2

Builds up a sequence of clusters ("hierarchical")





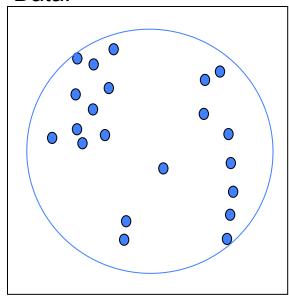
In matlab: "linkage" function (stats toolbox)

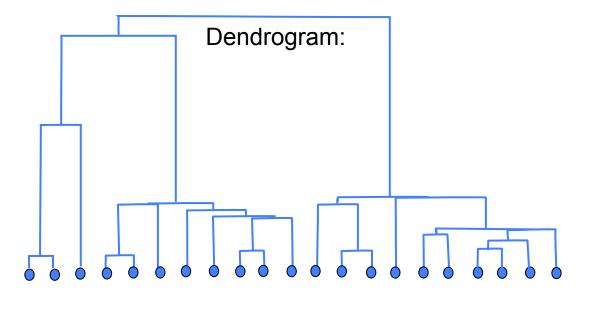
Algorithmic Complexity:  $O(m^2 \log m) + (m-2)*O(m \log m) +$ 

#### Iteration m-1

Builds up a sequence of clusters ("hierarchical")





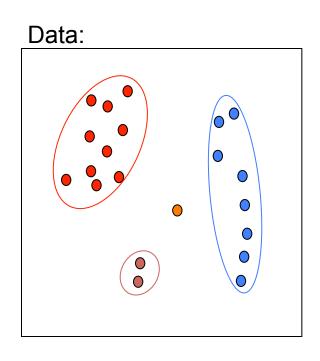


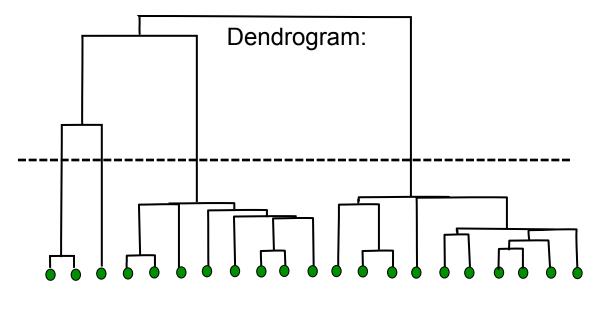
In matlab: "linkage" function (stats toolbox)

Algorithmic Complexity:  $O(m^2 \log m) + (m-1)*O(m \log m) = O(m^2 \log m)$ 

## From dendrogram to clusters

Given the sequence, can select a number of clusters or a dissimilarity threshold:

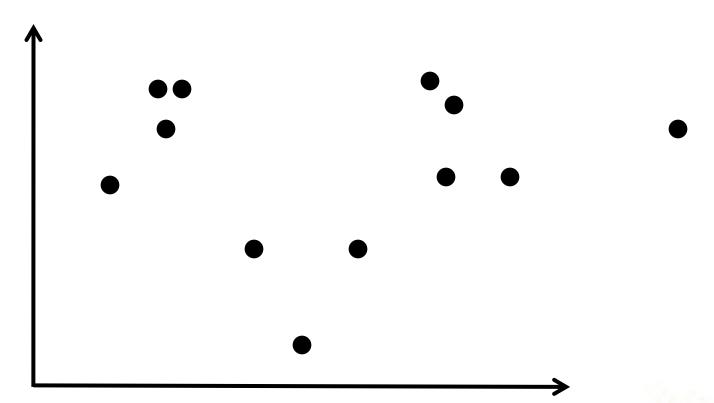


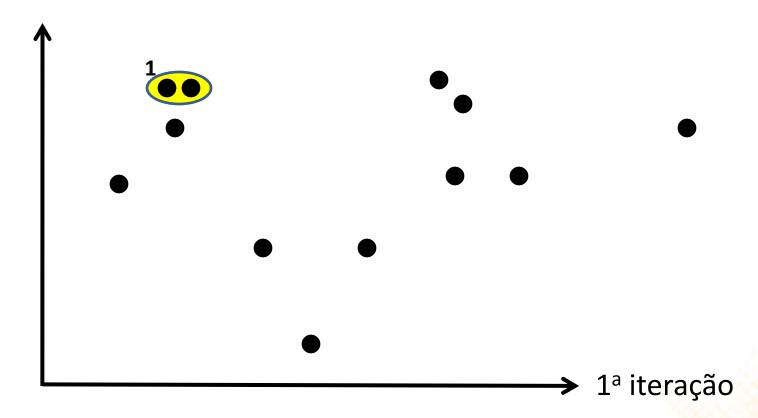


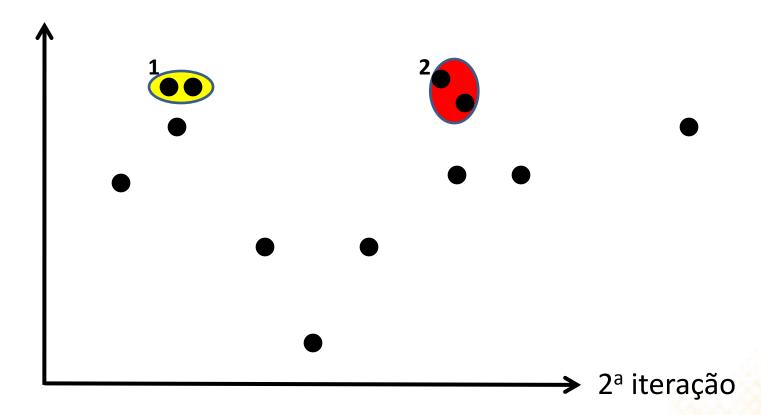
In matlab: "linkage" function (stats toolbox)

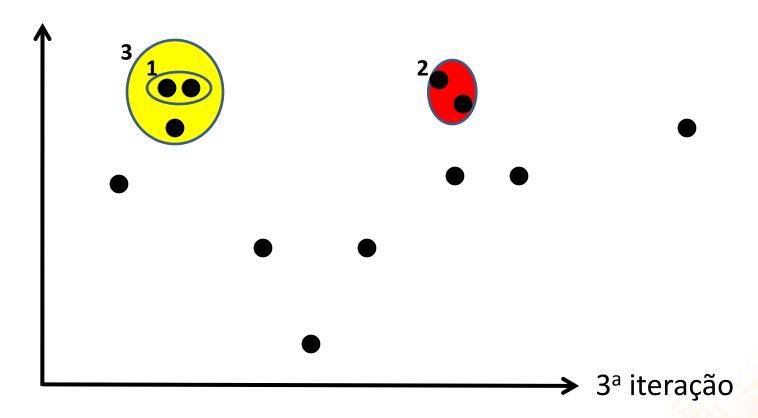
Algorithmic Complexity:  $O(m^2 \log m) + (m-1)*O(m \log m) = O(m^2 \log m)$ 

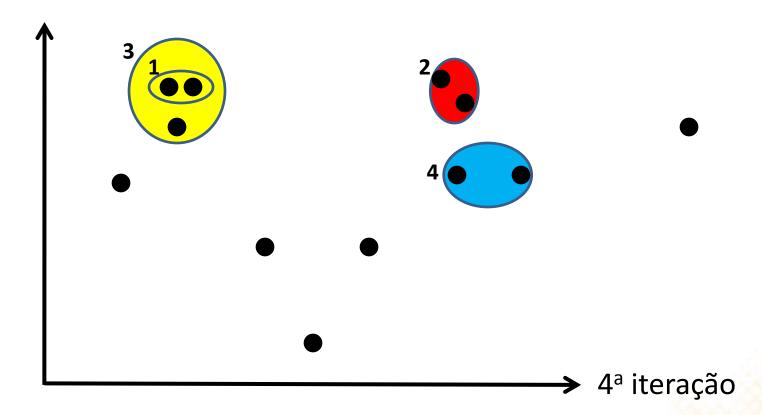
# Clusterização Hierárquica (outro exemplo)





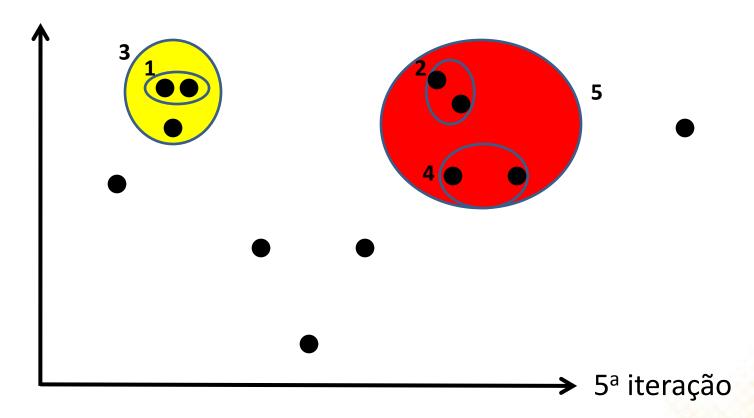






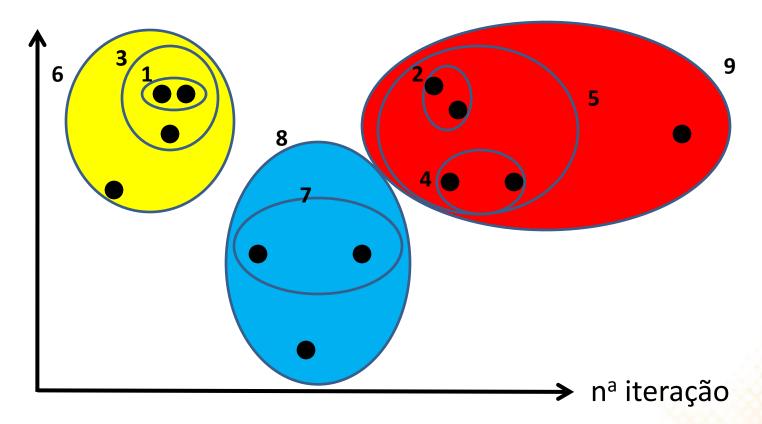
# Clusterização Hierárquica

Exemplo 1 – Aglomerativo:



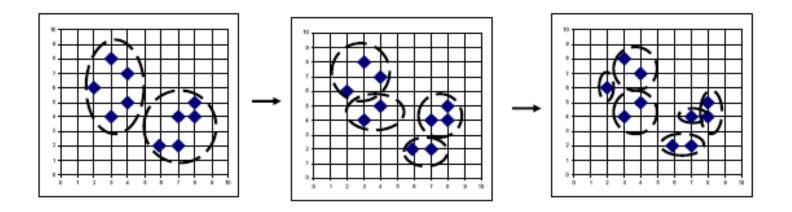
# Clusterização Hierárquica

• Exemplo 1 – Aglomerativo:



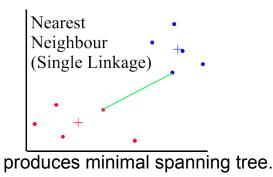
# Clusterização Hierárquica

Exemplo 2 – Divisivo:



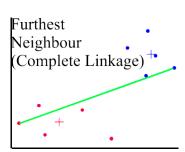
Processo inverso.

### Cluster distances



$$D_{\max}(C_i, C_j) = \max_{x \in C_i, \ y \in C_j} ||x - y||^2$$

$$D_{\text{avg}}(C_i, C_j) = \frac{1}{|C_i||C_j|} \sum_{x \in C_i, y \in C_j} ||x - y||^2$$

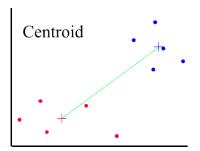


avoids elongated clusters.

$$D_{\text{means}}(C_i, C_j) = \|\mu_i - \mu_j\|^2$$

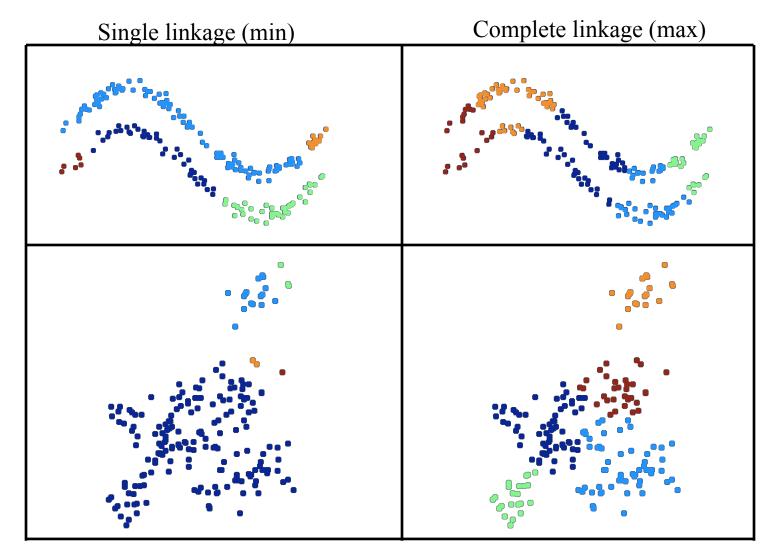
Need:

$$D(A,C) \rightarrow D(A+B,C)$$



### Cluster distances

Dissimilarity choice will affect clusters created

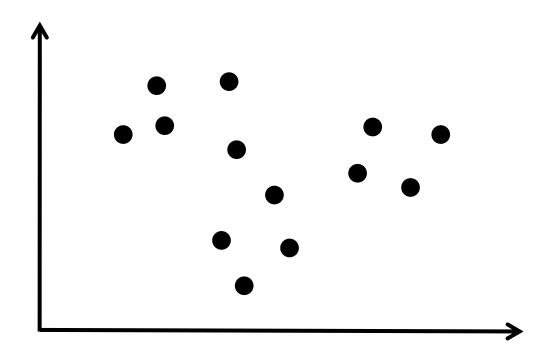


### K-Means

- É a técnica mais simples de aprendizagem não supervisionada.
- Consiste em fixar k centróides (de maneira aleatória), um para cada grupo (clusters).
- Associar cada indivíduo ao seu centróide mais próximo.
- Recalcular os centróides com base nos indivíduos classificados.

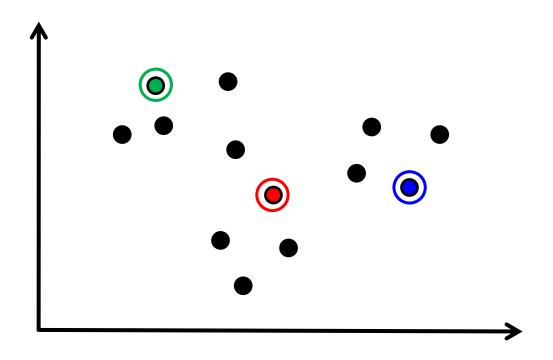
- (1) Selecione k centróides iniciais.
  - (2) Forme k clusters associando cada exemplo ao seu centróide mais próximo.
  - (3) Recalcule a posição dos centróides com base no centro de gravidade do cluster.
- (4) Repita os passos 2 e 3 até que os centróides não sejam mais movimentados.

• Exemplo:



Exemplo:

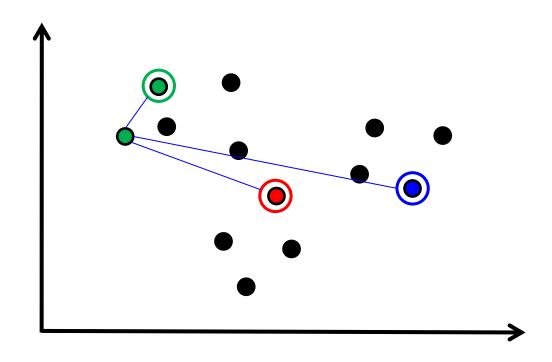
k = 3



Seleciona-se k centróides iniciais.

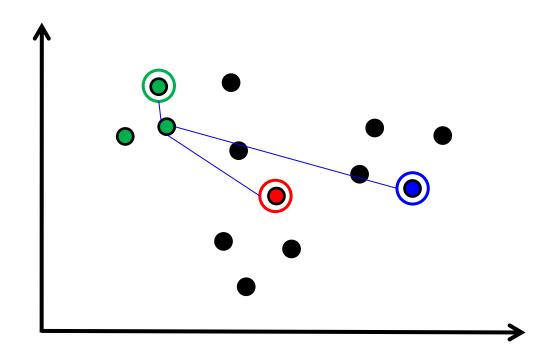
• Exemplo:

k = 3



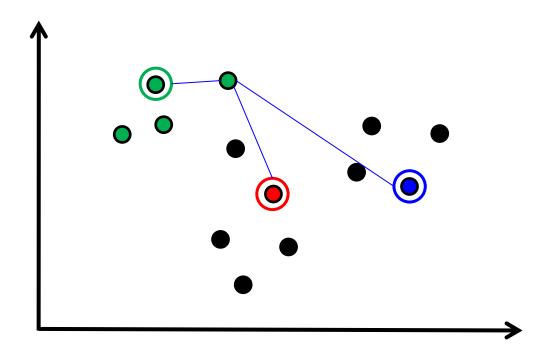
Exemplo:

k = 3



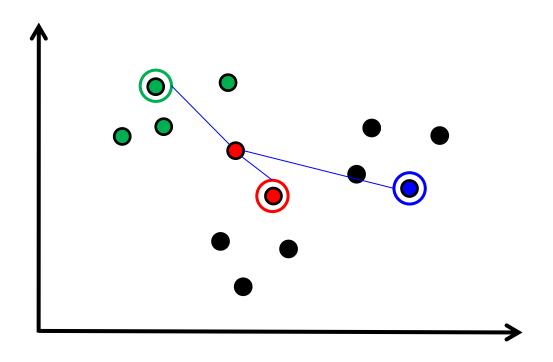
Exemplo:

k = 3



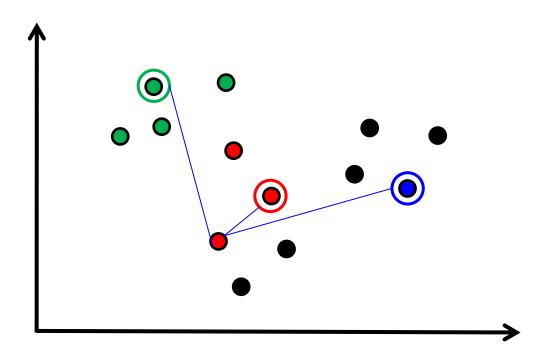
Exemplo:

k = 3



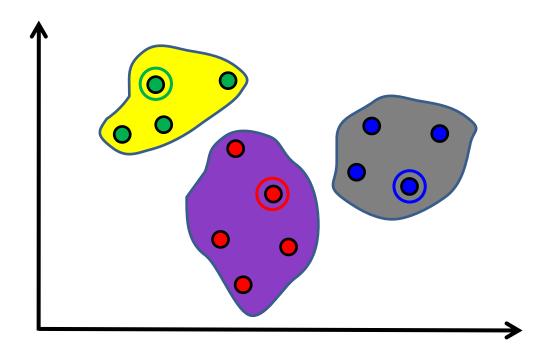
Exemplo:

k = 3



Exemplo:

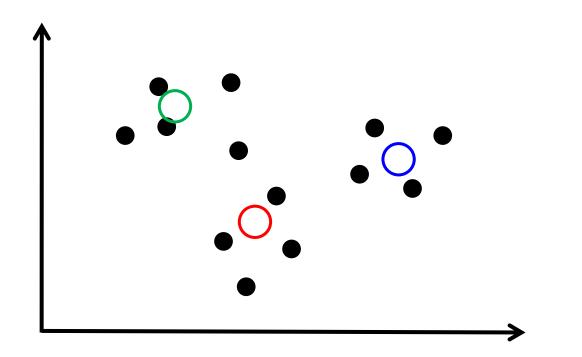
k = 3



n<sup>a</sup> iteração

Exemplo:

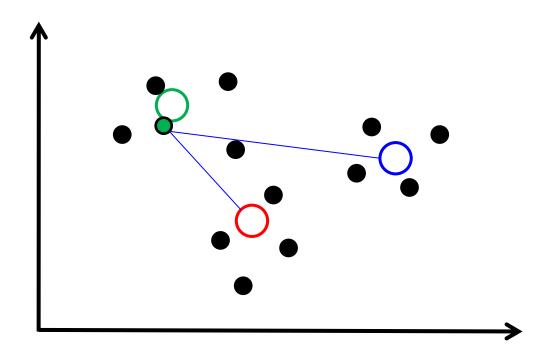
k = 3



Repite-se os passos anteriores até que os centróides não se movam mais.

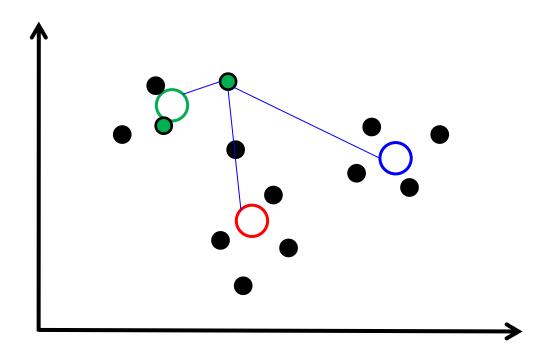
Exemplo:

k = 3



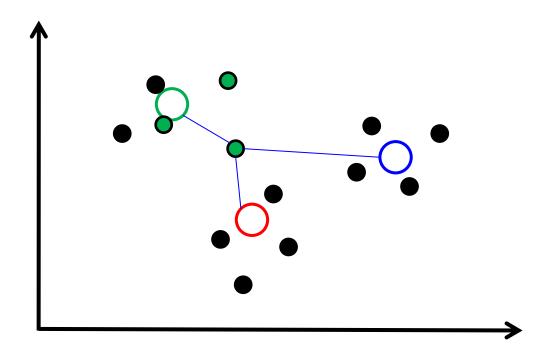
Exemplo:

k = 3



Exemplo:

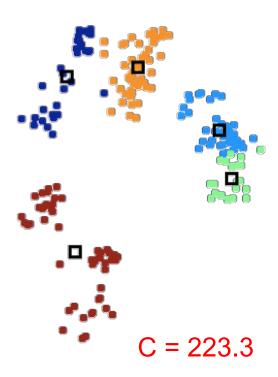
k = 3



### Initialization

- Multiple local optima, depending on initialization
- Try different (randomized) initializations
- Can use cost C to decide which we prefer

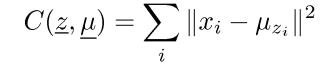
$$C(\underline{z},\underline{\mu}) = \sum_{i} ||x_i - \mu_{z_i}||^2$$



### Initialization

- Multiple local optima, depending on initialization
- Try different (randomized) initializations
- Can use cost C to decide which we prefer

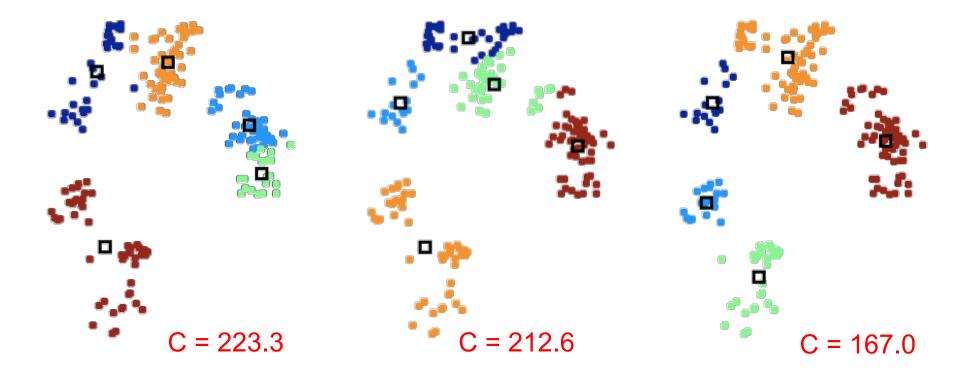
= 223.3



### Initialization

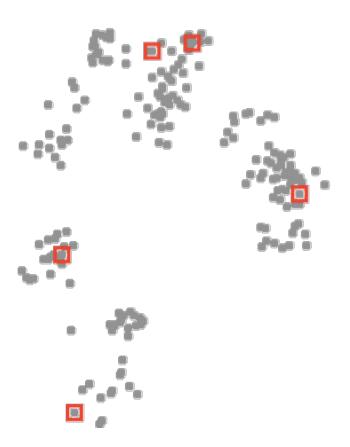
- Multiple local optima, depending on initialization
- Try different (randomized) initializations
- Can use cost C to decide which we prefer

$$C(\underline{z},\underline{\mu}) = \sum_{i} \|x_i - \mu_{z_i}\|^2$$



### Initialization methods

- Random
  - Usually, choose random data index
  - Ensures centers are near some data
  - Issue: may choose nearby points



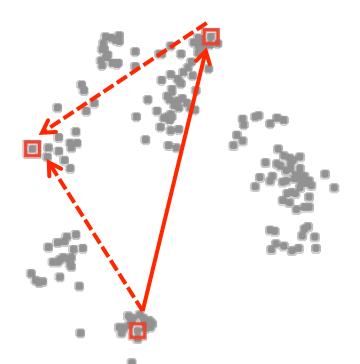
### Initialization methods

#### Random

- Usually, choose random data index
- Ensures centers are near some data
- Issue: may choose nearby points

#### Distance-based

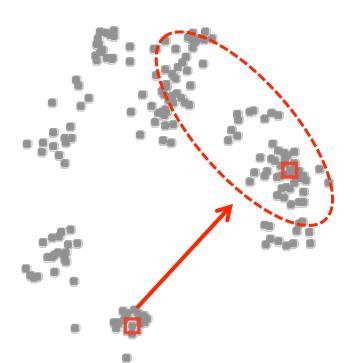
- Start with one random data point
- Find the point farthest from the clusters chosen so far
- Issue: may choose outliers



#### Initialization methods

#### Random

- Usually, choose random data index
- Ensures centers are near some data
- Issue: may choose nearby points
- Distance-based
  - Start with one random data point
  - Find the point farthest from the clusters chosen so far
  - Issue: may choose outliers
- Random + distance ("k-means++") (Arthur & Vassilvitskii, 2007)
  - Choose next points "far but randomly"
      $p(x) \propto$  squared distance from x to current centers
  - Likely to put a cluster far away, in a region with lots of data



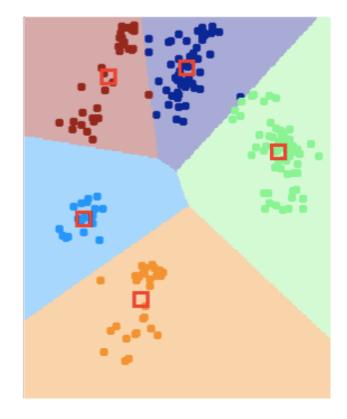
## Out-of-sample points

- Often want to use clustering on new data
- Easy for k-means: choose nearest cluster center

```
% perform clustering
[Z, mu] = kmeans(X, K);

% cluster id = nearest center
L = knnClassify(mu, (1:K)', 1);

% assign in- or out-of-sample points
Z = predict(L, X);
```



With cost function

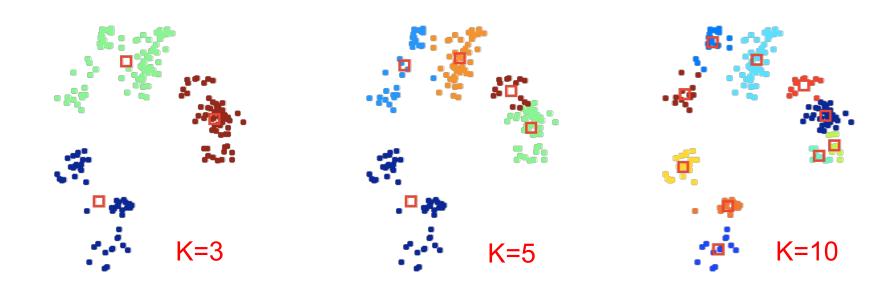
$$C(\underline{z},\underline{\mu}) = \sum ||x_i - \mu_{z_i}||^2$$

 $C(\underline{z},\underline{\mu}) = \sum_i \|x_i - \mu_{z_i}\|^2$  what is the optimal value of k?

With cost function

$$C(\underline{z},\underline{\mu}) = \sum_{i} \|x_i - \mu_{z_i}\|^2$$

what is the optimal value of k?

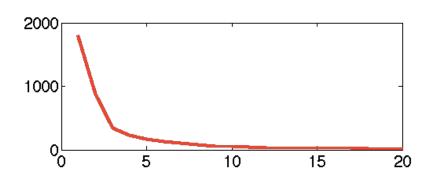


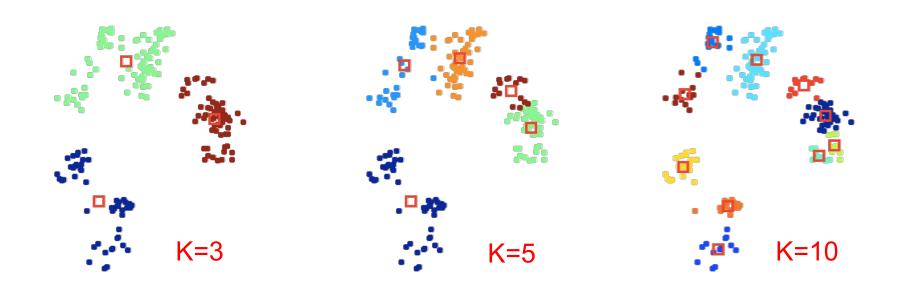
With cost function

$$C(\underline{z},\underline{\mu}) = \sum \|x_i - \mu_{z_i}\|^2$$

what is the optimal value of k?

Cost always decreases with k!



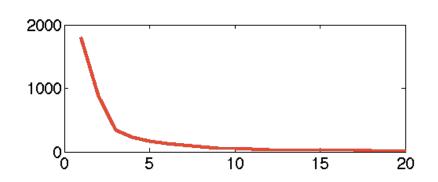


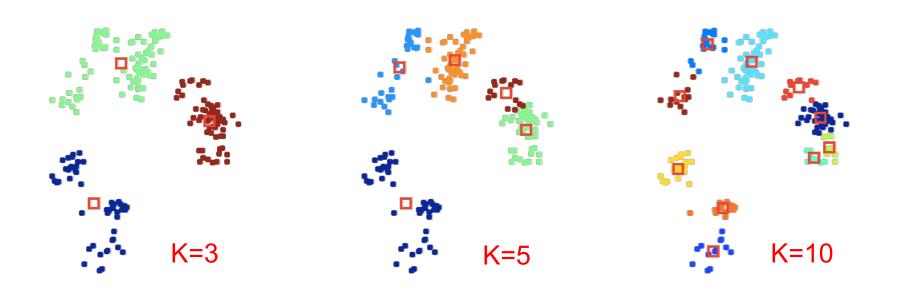
With cost function

$$C(\underline{z},\underline{\mu}) = \sum \|x_i - \mu_{z_i}\|^2$$

what is the optimal value of k?

- Cost always decreases with k!
- A model complexity issue...

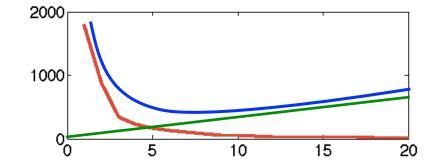




With cost function

$$C(\underline{z},\underline{\mu}) = \sum \|x_i - \mu_{z_i}\|^2$$

what is the optimal value of k?



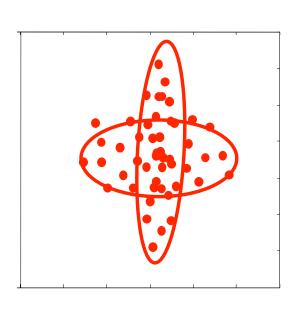
- Cost always decreases with k!
- A model complexity issue...
- One solution is to penalize for complexity
  - Add penalty: Total = Error + Complexity
  - Now more clusters can increase cost, if they don't help "enough"
  - Ex: simplified BIC penalty

$$J(\underline{z}, \underline{\mu}) = \log \left[ \frac{1}{m d} \sum_{i} ||x_i - \mu_{z_i}||^2 \right] + k \frac{\log m}{m}$$

More precise version: see e.g. "X-means" (Pelleg & Moore 2000)

#### Mixtures of Gaussians

- K-means algorithm
  - Assigned each example to exactly one cluster
  - What if clusters are overlapping?
    - Hard to tell which cluster is right
    - Maybe we should try to remain uncertain
  - Used Euclidean distance
  - What if cluster has a non-circular shape?
- Gaussian mixture models
  - Clusters modeled as Gaussians
    - Not just by their mean
  - EM algorithm: assign data to cluster with some probability
  - Gives probability model of x! ("generative")



- Observations  $x_1 \dots x_n$ 
  - $^-$  K=2 Gaussians with unknown  $\mu,\,\sigma^2$
  - estimation trivial if we know the source of each observation

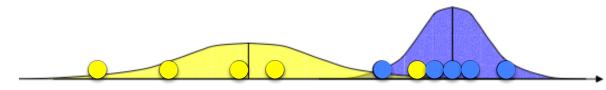


Observations  $x_1 \dots x_n$ 

K=2 Gaussīans with unknown  $\mu$ ,  $\sigma^2$  estimation trivial if we know the source of each observation

$$\mu_b = \frac{x_1 + x_2 + \dots + x_{n_b}}{n_b}$$

$$\sigma_b^2 = \frac{(x_1 - \mu_1)^2 + \dots + (x_n - \mu_n)^2}{n_b}$$

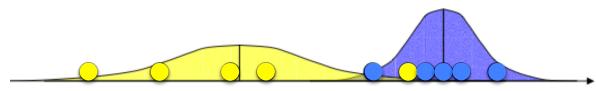


#### Observations $x_1 \dots x_n$

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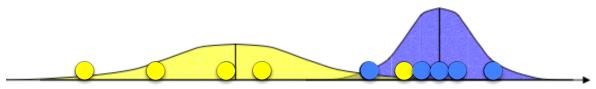
• What if we don't know the source?

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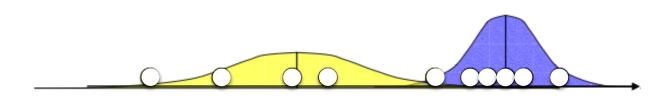
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- If we knew parameters of the Gaussians ( $\mu$ ,  $\sigma^2$ )
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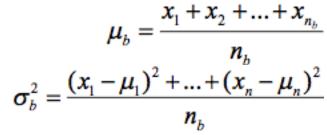


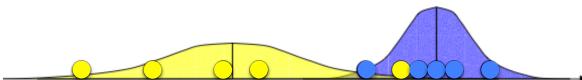
#### Mixture models in 1-d

#### Observations x<sub>1</sub> ... x<sub>n</sub>

K=2 Gaussians with unknown  $\mu$ ,  $\sigma^2$ 

κ=2 Gaussians with unknown μ, σ<sup>2</sup>
 estimation trivial if we know the source of each observation

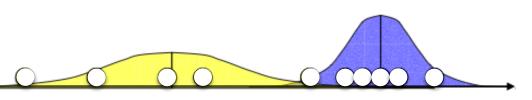




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$$P(b | x_i) = \frac{P(x_i | b)P(b)}{P(x_i | b)P(b) + P(x_i | a)P(a)}$$

$$P(x_i \mid b) = \frac{1}{\sqrt{2\pi\sigma_b^2}} \exp\left(-\frac{(x_i - \mu_b)^2}{2\sigma_b^2}\right)$$



# **Expectation Maximization (EM)**

- Chicken and egg problem
  - need ( $\mu_a$ ,  $\sigma_a^2$ ) and ( $\mu_b$ ,  $\sigma_b^2$ ) to guess source of points
  - need to know source to estimate  $(\mu_a, \sigma_a^2)$  and  $(\mu_b, \sigma_b^2)$

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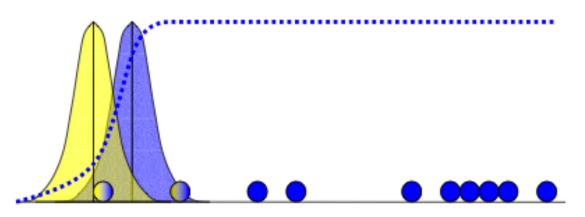
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- E-step: for each point:  $P(b|x_i) = does it look like it came from b?$
- M-step: adjust  $(\mu_a, \sigma_a^2)$  and  $(\mu_b, \sigma_b^2)$  to fit points assigned to them
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EM: 1-d example



# EM: 1-d example



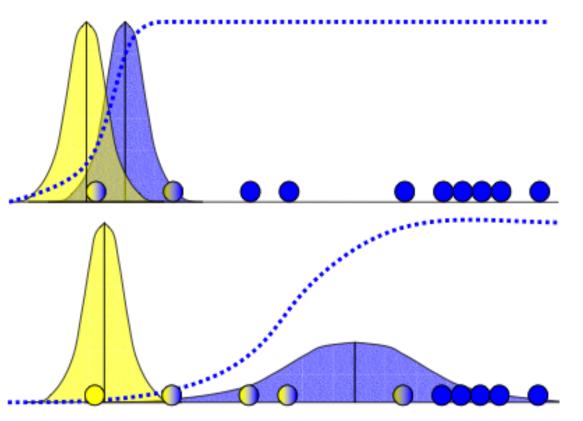
$$P(blue|x) \ll P(yellow|x)$$

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$$b_{i} = P(b | x_{i}) = \frac{P(x_{i} | b)P(b)}{P(x_{i} | b)P(b) + P(x_{i} | a)P(a)}$$

$$a_{i} = P(a | x_{i}) = 1 - b_{i}$$

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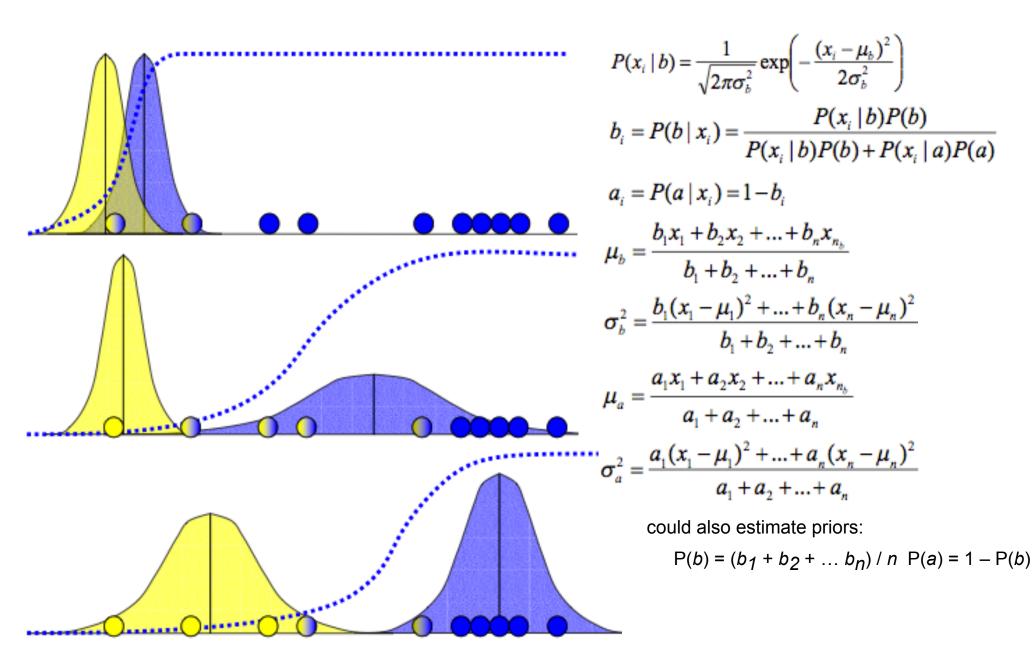
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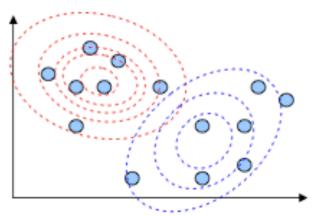
$$\mu_{b} = \frac{b_{1}x_{1} + b_{2}x_{2} + \dots + b_{n}x_{n_{b}}}{b_{1} + b_{2} + \dots + b_{n}}$$

$$\sigma_{b}^{2} = \frac{b_{1}(x_{1} - \mu_{1})^{2} + \dots + b_{n}(x_{n} - \mu_{n})^{2}}{b_{1} + b_{2} + \dots + b_{n}}$$

## EM: 1-d example

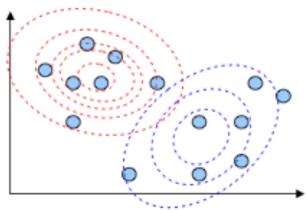


- Data with d attributes, from k sources
- Each source c is a Gaussian
- Iteratively estimate parameters:
  - prior: what % of instances came from source c?



$$P(c) = \frac{1}{n} \sum_{i=1}^{n} P(c \mid \vec{x}_i)$$

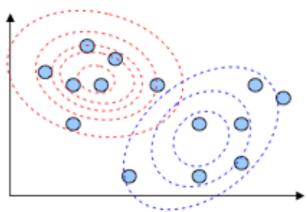
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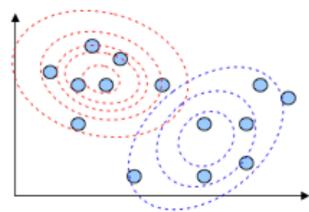


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based on: our guess of the source for each instance

$$P(c \mid \vec{x}_i) = \frac{P(\vec{x}_i \mid c)P(c)}{\sum_{c'=1}^{k} P(\vec{x}_i \mid c')P(c')}$$

$$P(\vec{x}_{i} \mid c) = \frac{1}{\sqrt{2\pi |\Sigma_{c}|}} \exp\left(-\frac{1}{2} \left(\vec{x}_{i} - \vec{\mu}_{c}\right)^{T} \Sigma_{c}^{-1} \left(\vec{x}_{i} - \vec{\mu}_{c}\right)\right)$$

$$\sum_{i=1}^{d} \sum_{k=1}^{d} \left(x_{i,j} - \mu_{c,j}\right) \left(\Sigma_{c}^{-1}\right)_{j,k} \left(x_{i,k} - \mu_{c,k}\right)$$

Probabilistic model

$$L = \log P(x_1...x_n) = \sum_{i=1}^n \log \sum_{k=1}^K P(x_i \mid k) P(k)$$

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- Occam's razor: pick "simplest" of all models that fit
  - Bayes Inf. Criterion (BIC):  $\max_{p} \{ L \frac{1}{2} p \log n \}$
  - Akaike Inf. Criterion (AIC):  $\min_{p} \{ 2p L \}$

L ... likelihood, how well

our model fits the data p ...

number of parameters

how "simple" is the model

