```
import numpy as np
def func(eq, t0, tx, y0, h):
   n = int((tx-t0)/h)
   t = [t0]
   y = [y0]
   for i in range (0,n,1):
      k1 = eq(t[i], y[i])
      k2 = eq(t[i]+h, y[i] * h+k1)
      yn1 = y[i] + (h/2)*(k1 + k2)
      tn1 = t[i] + h
      y.append(yn1)
      t.append(tn1)
      print('%d\t%.2f\t%.4f'% (i+1,tn1,yn1) )
      print('----')
   return (t, y) #tuple containing two arrays (t,y)
def eq(t, y):
   return np.exp(t)-y
ans = func(eq, 0, 5, 10, 0.5)
       0.50 9.1622
      1.00 8.6965
    -----
          1.50 8.7298
    _____
          2.00 9.4859
    5 2.50 11.3458
          3.00 14.9489
    -----
          3.50 21.3592
       4.00 32.3388
          ______
          4.50 50.8007
    -----
          5.00 81.5539
    _____
def euler_method(f, t_initial, t_final, y_initial, h):
   Solves the ordinary differential equation y' = f(t, y) using Euler's method w
   Returns arrays of time and y values at each step.
   11 11 11
   num steps = int((t final - t initial) / h)
   t_values = [t_initial]
   y_values = [y_initial]
   print('\n-----')
   print('----')
   print('#\ttn\tvn')
```

```
.-- .-, ,
   print('----')
   for i in range(num steps):
       slope = f(t_values[i], y_values[i])
       y new = y values[i] + h * slope
       t new = t values[i] + h
       y_values.append(y_new)
       t_values.append(t_new)
       print('%d\t%.2f\t%.4f'% (i+1,t_new,y_new) )
       print('----')
   return t_values,y_values
def RK4 method(f, t initial, t final, y initial, h):
   Solves the ordinary differential equation y' = f(t, y) using Euler's method with step
   Returns arrays of time and y values at each step.
   num_steps = int((t_final - t_initial) / h)
   t values = [t initial]
   y_values = [y_initial]
   print('\n-----')
   print('----')
   print('#\ttn\tyn')
   print('----')
   for i in range(num_steps):
       k1 = f(t_values[i], y_values[i])
       k2 = f(t_values[i]+0.5*h, y_values[i]+0.5*k1)
       k3 = f(t_values[i]+h/2, y_values[i]+k2/2)
       k4 = f(t values[i]+h, y values[i]+k3)
       y_{new} = y_{values}[i] + (h/6) * (k1+2*k2+2*k3+k4)
       t_{new} = t_{values}[i] + h
       y values.append(y new)
       t_values.append(t_new)
       print('%d\t%.2f\t%.4f'% (i+1,t_new,y_new) )
       print('----')
   return t values, y values
from tabulate import tabulate
import numpy as np
from scipy.integrate import solve_ivp
import numpy as np
def compareFunc(f, t0, tx, y0, h):
 n = int((tx - t0) / h)
 data=[]
 sol = solve ivp(f, [0, 1], [1], t eval=np.array(np.linspace(t0+h, tx, n)))
 va=sol.v.flatten()
 yl=np.insert(ya,0,y0)
 te, ye=euler_method(f, t0, tx, y0, h)
 th, yh=func(f, t0, tx, y0, h)
 trk4,yrk4=RK4\_method(f, t0, tx, y0, h)
```

```
error1 = abs(yl - ye)
error2 = abs(yl - yh)
error3 = abs(yl - yrk4)
print('\n\t\tERRORS')
print('-----')
print('n\tStep\tEuler\t\tHeun\t\tRK4')
print('----')
for i in range(len(te)):
    print('%d\t%.2f\t%.6f\t%.6f' % (i+1, te[i], error1[i], error2[i], error3[i])
    print('-----')
if(error1.all()<error2.all() and error1.all()<error3.all()):</pre>
 print("Method with least error is Euler")
elif(error2.all()<error1.all() and error2.all()<error3.all()):</pre>
 print("Method with least error is Hueuns")
else:
 print("Method with least error is RK4")
```

compareFunc(eq, 0, 1, 1, 0.5)

SOLUTION		
#	tn	yn
1	0.50	1.0000
2	1.00	1.3244
1	0.50	1.2872
2	1.00	1.8059
	SOLUTION	
#	tn	yn
1	0.50	1.1132
2	1.00	1.4673

ERRORS

	Step	 Euler	Heun	 RK4
	эсер			
1	0.00	0.000000	0.000000	0.000000
2	0.50	0.127213	0.159968	0.013981
3	1.00	0.218965	0.262528	0.076065

Method with least error is RK4

```
def eq1(t, y):
```

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```

```
return y**2-t-1

def eq2(t, y):
    return y-t

def eq3(t, y):
    return (t-1)**2-y
```

compareFunc(eq1, 0, 1, 1, 0.25)
compareFunc(eq2, 0, 1, 1, 0.25)
compareFunc(eq3, 0, 1, 1, 0.25)

:	SOLUTION	
#	tn	yn
1	0.25	1.0000
2	0.50	0.9375
3	0.75	0.7822
4	1.00	0.4977
1	0.25	0.8516
2	0.50	0.6106
3	0.75	0.3697
4	1.00	0.2072
	SOLUTION	
#	tn 	yn
1	0.25	0.9407
2	0.50	0.7069
3	0.75	0.3602
4	1.00	0.0017

ERRORS

n	Step	Euler	Heun	RK4
1	0.00	0.000000	0.000000	0.000000
2	0.25	0.036566	0.111872	0.022760
3	0.50	0.113942	0.212937	0.116680
4	0.75	0.243228	0.169316	0.178816
5	1.00	0.395960	0.105427	0.099998

Method with least error is RK4

	SOLUTION	
#	tn	yn
1	0.25	1.2500
_		

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