

Clea Lin

clealin.rs@gmail.com | (+61) 421 180 529

Gate 2 High Street, Kensington, Sydney, NSW 2033, Australia

EDUCATION

The University of New South Wales

Sydney, Australia

Incoming Student, Master of Engineering Science in Robotics

Sep. 2022 – Aug. 2024

National Tsing Hua University

Hsinchu, Taiwan

Bachelor of Science in Power Mechanical Engineering

Sep. 2015 – Jun. 2019

- ♦ Coursework: Control System, Electric Circuits, Electronics, Digital Control System

Nanyang Technological University

Singapore

Full-time Exchange in Mechanical and Aerospace Engineering

Jan. 2019 – May 2019

WORK EXPERIENCES

Institute of Information Science, Academia Sinica

Taipei, Taiwan

Natural Language Processing and Sentiment Analysis Lab, Research Assistant

Feb. 2022 – Jun. 2022

- ♦ Research topic: AI-Automated Training System for Figure Skating
- ♦ Constructed an AI-automated training system that performs pose tracking for the learner's practice video and provides real-time instructions.
- ♦ Trained a frame embedding space model where two similar video sequences can be aligned temporally.
- ♦ Generated a pose comparison video between the learner and the trainer automatically.

Center for Artificial Intelligence and Advanced Robotics, National Taiwan University

Taipei, Taiwan

Intelligent Robot Laboratory, Research Assistant

May 2021 – Feb. 2022

- ♦ Research topic: AI Companion Healthcare Aid Robot
- ♦ Develop a behaviour recognition warning system for the elderly by training a random forest classifier based on human skeleton data and object detection.
- ♦ Upgrade a reminiscence chatting function using natural language processing techniques and AI-based image understanding to proactively drive the reminiscence process in social interactions with elderly users.

IC Design Technology Center, National Tsing Hua University

Hsinchu, Taiwan

Neuromorphic and Biomedical Engineering Laboratory, Research Assistant

Aug. 2020 – Apr 2021

- ♦ Research topic: Neuromorphic Intelligent Vision System-on-Chip
- ♦ Programmed in Python for preprocessing frame data by OpenCV and implementing CNN model.
- ♦ Built a bioinspired object recognition system with an event-based camera and neuromorphic chips on Field Programmable Gate Array (FPGA).
- ♦ Demonstrated real-time object detection and recognition and reduced 26% of transition delay.

PEGATRON Corporation**Taipei, Taiwan***Software Research and Development Department, Firmware Engineer*

Aug. 2019 – Jul. 2020

- ♦ Analyzed issues related to Microsoft products UEFI and improved runtime performance.
- ♦ Developed testing system to improve issue reproducing efficiency, reducing 70% of testing time.
- ♦ Certification of WinDBG Kernel Debugging, Power Analysis, and ETW from Microsoft.

Porite Taiwan Co., Ltd.**Miaoli, Taiwan***Manufacturing Process Engineer Intern*

Jul. 2018 – Aug. 2018

- ♦ Generated ideas of importing robotic arms before the sintering process for manufacturing automation.
- ♦ Redesigned the collecting procedure of sintered powder metallurgy parts to enhance yield rate.

RESEARCH EXPERIENCES

Customized Assistive Device Power System for Lower Extremities

Feb. 2018 – Dec. 2018

- ♦ Demonstrated real-time human body posture recognition by STM32F446 board and IMU sensors.
- ♦ Accelerated data transmission speed between IMU sensors and master device by converting SPI to I2C protocol.

Hand-eye Coordination Training System

Jul. 2021 – Aug. 2021

- ♦ Implemented pose detection API and received real-time skeletal and facial landmarks.
- ♦ Built the system for seniors and improved their hand-eye coordination in an engaging way.

DC Motor Design for Rotational Speed Control System

Feb. 2018 – Jun. 2018

- ♦ Built a DC motor from scratch and designed a proportional controller with an electric circuit.
- ♦ Analyzed the rotational speed and adjusted proportional gain to get the optimum performance.

Vacuum Robot Navigation and Battery Level Tracking

Feb. 2018 – Jun. 2018

- ♦ Developed path planning algorithm which performed 100% floor coverage.
- ♦ Created low-battery alarm and function of auto-return to charging base by battery level tracking.

Damping System Design on Building Structure

Feb. 2018 – Jun. 2018

- ♦ Constructed a pendulum tuned mass damper and a pounding tuned mass damper.
- ♦ Applied the dampers on a mock building and analyzed damping ratios for each structure.

Electric Scooter Two-Speed Gearbox Structure Design and Stress Analysis

Sep. 2017 – Jan. 2018

- ♦ Reduced 45% of required input by evaluating the radius and rotational speed of planetary gears.
- ♦ Adjusted speed reduction ratio to reach a 17° hill climb performance with a speed of 30km/h.

AWARD

2021 National Innovation Award — Academic Research Innovation Award**Taiwan**

- ♦ Research topic: CHARM: Companion Healthcare Aid Robot Manager
- ♦ Given in recognition of outstanding contribution to AI and robotics in healthcare services for the elderly and mild cognitive impairment (MCI) patients.

SKILLS

Programming Language

C, C++, C#, Python, Java, Pytorch, OpenCV, PowerShell, Batch script, MATLAB, Git

Software and Tool

Jupyter Notebook, TensorFlow, Visual Studio, Android Studio, AutoCAD, Inventor, MS Office

Operating System

Linux, Ubuntu, Windows

Language

Fluent in English (TOEFL iBT 104)

EXTRACURRICULAR ACTIVITIES

Volunteer

Sep. 2020

Yilan County Animal Shelter, Taiwan

- ♦ Took care of stray dogs and updated their health records.
- ♦ Helped the shelter increase adoptions so that the dogs can find a new home.

Student Representative

Oct. 2018

Innovation Open House: Democratizing Personal Experience

- ♦ Represented the Department of Power Mechanical Engineering, NTHU.
- ♦ Gave a 45-minute online speech about a combination of work, school, and life experiences.

Vocalist, Guitarist

Aug. 2016 – Jan. 2017

Guitar Club, National Tsing Hua University

- ♦ Started a 5-person acoustic guitar band and scheduled weekly practice.
- ♦ Gave performances in the midterm concert.