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控制系统仿真与CAD

第六章: 非线性系统的建模与仿真 Chapter 6 Modeling and Simulation of Nonlinear

Systems

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非线性系统的建模与仿真方法

- >前面各章涉及的是线性系统,非线性系统怎么办?
- ▶可以引入Simulink对系统建模、分析
- 〉本章主要内容
 - ➤Simulink简介
 - ▶基于Simulink的框图绘制方法
 - ▶控制系统的建模仿真方法
 - ▶非线性系统的建模与仿真方法
 - ➤Simulink的高级技术——子系统与S-函数
 - >多领域物理建模概述

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控制系统仿真与CAD

第六章 非线性系统的建模与仿真

Simulink简介

An Introduction to Simulink



主讲: 薛定字教授



Simulink建模基础

- ➤ 在Simulink出现之前, MATLAB仿真功能弱
 - ▶借助ACSL等仿真语言进行仿真
 - >接口不好,需要数据文件交互
 - >描述系统采用语言描述,缺乏框图支持,易错
- > Simulink的出现与进展
 - ▶1990年MathWorks推出了SimuLAB,取代ACSL
 - ▶1992年更名Simulink
 - ▶2007年,支持Simscape、多领域物理建模
 - ▶2012年,2012b,全新的建模界面,使用方便,新版本功能更强

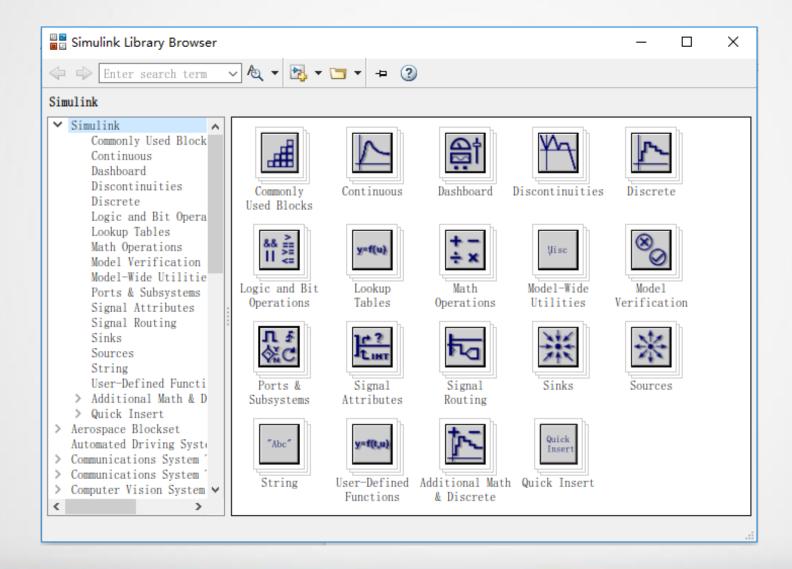
(A)

Simulink的常用模块简介

- > 启动Simulink
 - >命令行式 >> open_system('simulink')
 - ▶双击图标——不同版本的Simulink图标略有不同
- > 相关模块简介
 - ▶輸入模块组、輸出模块组
 - ▶其他相关模块:连续、离散、非线性等
 - ▶专业模块: Simscape、SimMechanics等



现有的模块库





输入模块组 Sources



Band-Limited White Noise



Digital Clock



In Bus Element



Repeating Sequence Interpolated



Step



Chirp Signal



Enumerated Constant



In1



Repeating Sequence Stair



Uniform Random Number



Clock



From File



Pulse Generator



Signal Builder

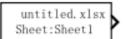




Waveform Generator



Constant



From Spreadsheet



Ramp



Signal Editor



Counter Free-Running



From Workspace



Random Number



Signal Generator



Counter Limited



Ground



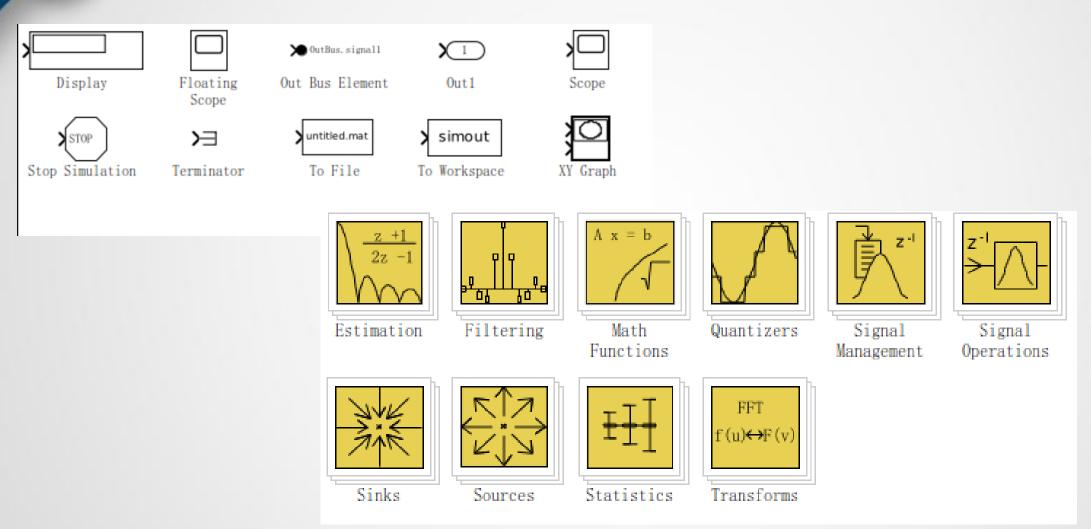
Repeating Sequence



Sine Wave



输出模块组





线性模块组



Derivative



Integrator

PID(s)

PID Controller (2DOF)



Integrator, Second-Order

y = Cx + Du

State-Space



Integrator, Second-Order Limited



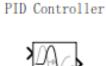
Integrator Limited



Transfer Fcn



Transport Delay



PID(s)

Variable Time Delay



Transport Delay



Zero-Pole



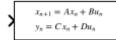
Delay



Discrete PID Controller (2DOF)



Difference



Discrete State-Space



Discrete Derivative

K<u>(z-1</u>) Ts z

Discrete-Time Integrator



Resettable Delay





Variable Integer Delay



Discrete Filter



Discrete Transfer Fcn



Tapped Delay



Zero-Order Hold



Discrete FIR Filter



Discrete Zero-Pole



Transfer Fcn First Order



Discrete PID Controller



Enabled Delay



Transfer Fcn Lead or Lag



Real Zero

First-Order

Hold

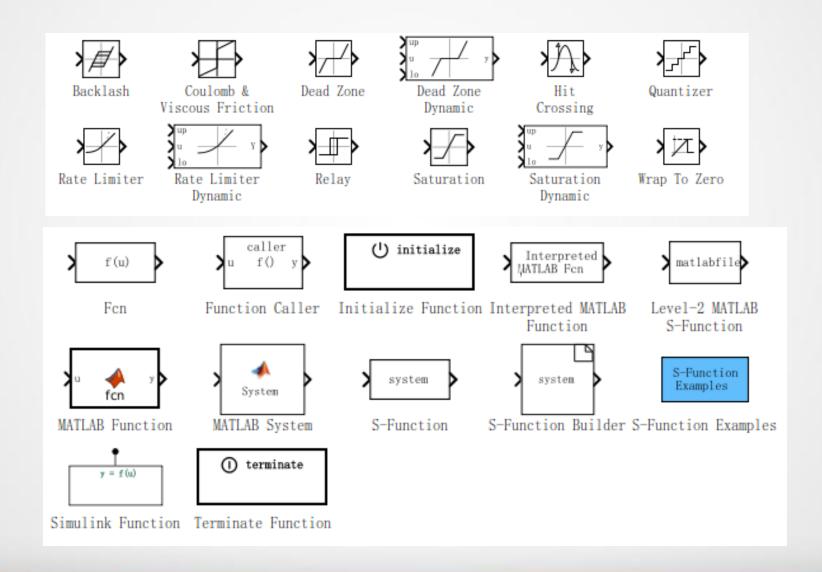


Memory

Unit Delay



非线性模块与自定义模块组





Toolboxes and Blocksets

- Aerospace Blockset Automated Driving System Toolbox
- > Communications System Toolbox
- > Communications System Toolbox HDL Support
- > Computer Vision System Toolbox
- Control System Toolbox Data Acquisition Toolbox
- > DSP System Toolbox
- > DSP System Toolbox HDL Support
- > Embedded Coder
- > Fuzzy Logic Toolbox
- > HDL Coder
- > HDL Verifier Image Acquisition Toolbox Instrument Control Toolbox

MIMO FOTF Toolbox

- > Model Predictive Control Toolbox
- Neural Network Toolbox OPC Toolbox
- > Phased Array System Toolbox
- Powertrain Blockset Report Generator
- > RF Blockset
- Robotics System Toolbox Robust Control Toolbox SimEvents

- > Simscape
- > Simulink 3D Animation
- > Simulink Coder
- > Simulink Control Design
- > Simulink Design Optimization
- > Simulink Design Verifier
- > Simulink Desktop Real-Time
- > Simulink Extras
- Simulink Real-Time Simulink Requirements Simulink Test Stateflow
- > System Identification Toolbox
- > Vehicle Network Toolbox
- Vision HDL Toolbox Recently Used



Foundation Library



Utilities



Driveline



Electronics



Fluids



Multibody



Power Systems

Simscape 4.4 Copyright 2006-2018 The MathWorks, Inc.



Simulink小结

- ► 简单介绍了Simulink发展背景
- > 介绍了一些常用的模块
 - ▶輸入模块
 - ▶輸出模块
 - >线性连续模块、线性离散模块
 - ▶非线性模块

