

# Concentration Inequalities and Multi-Armed Bandits

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## 【强化学习理论 59】StatisticalRL 3



这是UIUC姜楠老师开设的CS598统计强化学习(理论)课程的第二讲。

#### 原文传送门



## 一、Hoeffding's Inequality

初等的统计学过中心极限定理,它们告诉我们当i.i.d.样本很多的时候,在sample上的统计量就会趋向于真实的统计量。这里就更定量化的告诉我们sample上的统计量以怎样的程度趋向于真实的统计量,即concentration inequalities。Hoeffding's inequality就是其中最常用的一种。

**Theorem 1.** Let  $X_1, \ldots, X_n$  be independent random variables on  $\mathbb{R}$  such that  $X_i$  is bounded in the interval  $[a_i, b_i]$ . Let  $S_n = \sum_{i=1}^n X_i$ . Then for all t > 0,

$$\Pr[S_n - \mathbb{E}[S_n] \ge t] \le e^{-2t^2/\sum_{i=1}^n (b_i - a_i)^2},$$
 (1)

$$\Pr[S_n - \mathbb{E}[S_n] \le -t] \le e^{-2t^2/\sum_{i=1}^n (b_i - a_i)^2}.$$
 (2)

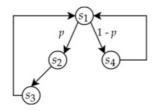
### Remarks:

- By union bound, we have  $\Pr[|S_n \mathbb{E}[S_n]| \ge t] \le 2e^{-2t^2/\sum_{i=1}^n (b_i a_i)^2}$ .
- We often care about the convergence of the empirical mean to the true average, so we can devide  $S_n$  by n:  $\Pr\left[\left|\frac{S_n}{n} \frac{\mathbb{E}[S_n]}{n}\right| \ge t\right] \le 2e^{-2n^2t^2/\sum_{i=1}^n(b_i a_i)^2}$ .
- A useful rephrase of the result when all variables share the same support [a,b]: with probability at least  $1-\delta$ ,  $\left|\frac{S_n}{n}-\frac{\mathbb{E}[S_n]}{n}\right| \leq (b-a)\sqrt{\frac{1}{2n}\ln\frac{2}{\delta}}$ .
- $X_1, \ldots, X_n$  are not necessarily identically distributed; they just have to be independent.
- The number of variables, n, is a constant in the theorem statement. When n is n = n itself, for Hoeffding's inequality to apply, n cannot depend on the realization of  $X_1, \ldots, X_n$ .

个人认为最好理解的就是红圈里面的不等式,即sample mean是如何趋向于true mean的。

为了说明最后一点, Note中给了一个例子。

Example: Consider the following Markov chain:



Say we start at  $s_1$  and sample a path of length T (T is a constant). Let n be the number of times we visit  $s_1$ , and we can use the transitions from  $s_1$  to estimate p.

1. Can we directly apply Hoeffding's inequality here with n as the number of coin the set of you want to derive a concentration bound for this problem, look up Azuma's inequality.

2. What if we sample a path until we visit  $s_1$  N times for some constant N? Can we apply Hoeffding's inequality with N as the number of random variables?

对于第二种情况来说, $_N$  固定,然后给定  $_N$  个随机变量  $_X$  ,每个随机变量要么是3(走左边的环路)要么是2(走右边的环路),直接应用Hoeffding's inequality,就能得到该随机变量的样本上平均值距离真是平均值的界。

对于第一种情况需要用另一种concentration inequality,Azuma's inequality。它是对于鞅的 concentration inequality,在这个问题上具体的用法我不太确定。这里简述一下。第一种情况下走的 步数  $_{\mathbf{r}}$  是固定的,构建一个随机变量  $_{\mathbf{x}_i}$  表示新增访问  $_{\mathbf{r}}$  的次数,随机变量  $_{\mathbf{x}_i=\mathbf{x}_i-\frac{1}{2+p}}$  ,  $_{\mathbf{x}_i=\sum_{j=1}^{L}\mathbf{x}_i}$  就是鞅,然后应用Azuma's inequality,注意到随机变量  $_{\mathbf{x}_i=\mathbf{x}_i}^{\mathbf{r}}$  ,可以得到关于  $_{\mathbf{r}}$  和  $_{\mathbf{r}}$  的

In probability theory, the Azuma-Hoeffding inequality (named after Kazuoki Azuma and Wassily Hoeffding) gives a concentration result for the values of martingales that have bounded differences. Suppose { X<sub>k</sub> : k = 0, 1, 2, 3, ... } is a martingale (or super-martingale) and

$$|X_k - X_{k-1}| < c_k$$
,

almost surely. Then for all positive integers N and all positive reals t,

$$P(X_N - X_0 \ge t) \le \exp\left(\frac{-t^2}{2\sum_{k=1}^N c_k^2}\right)$$

And symmetrically (when X<sub>c</sub> is a sub-martingale):

$$P(X_N-X_0 \leq -t) \leq \exp\biggl(\frac{-t^2}{2\sum_{k=1}^N c_k^2}\biggr)$$

If X is a martingale, using both inequalities above and applying the union bound allows one to obtain a two-sided bound

$$P(|X_N-X_0|\geq t)\leq 2\exp\Biggl(rac{-t^2}{2\sum_{k=1}^N c_k^2}\Biggr).$$

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Azuma's inequality applied to the Doob martingale gives McDiarmid's inequality which is common in the analysis of randomized algorithms

## 二、Multi-Aramed Bandits (MAB)

## 2.1. 问题描述

A MAB problem is specified by K distributions over  $\mathbb{R}$ ,  $\{R_i\}_{i=1}^K$ . Each  $R_i$  has bounded supported [0,1] and mean  $\mu_i$ . Let  $\mu^\star = \max_{i \in [K]} \mu_i$ . For round  $t=1,2,\ldots,T$ , the learner

- 1. Chooses arm  $i_t \in [K]$ .
- 2. Receives reward  $r_t \sim R_{i_t}$ .

A popular objective for MAB is the pseudo-regret, which poses the exploration-exploitation challenge:

$$\mathrm{Regret}_T = \sum_{t=1}^T (\mu^\star - \mu_{i_t}).$$

Another important objective is the simple regret:

$$\mu^* - \mu_2$$
,

where  $\hat{i}$  is the arm that the learner picks after T rounds of interactions. This poses the "pure exploration" challenge, since all it matters is to make a good final guess and the regret incurred within the T rounds does not matter. A related objective is called Best-Arm Identification, which are  $\hat{i} \in \arg\max_{i \in [K]} \mu_{ii}$ . Best-Arm Identification results often require additional gap conditions.

## MAB问题的目标主要有几种

- Pseudo-regret: 希望在 T 轮内总的 reget 最小,即目标是一边探索一边利用;
- Simple regret: 希望在 T 轮之后找到的那个 arm 的 regret 小,即目标是在 T 轮内尽可能做探索;

• Best-arm identification: 希望在 T 轮之后以最大的概率找到最好的 arm,这也是一个鼓励探索的目标。

### 2.2. 均匀采样

这里我们的目标是最小化 simple regret,方式是在 T 轮中对于每个 arm 都 play 一样多的次数,然后我们推导出一个 simple regret 关于 T 的上界。这也可以看做一个Hoeffding不等式 的应用。

We consider the simplest algorithm that chooses each arm the same number of times, and after T rounds selects the arm with the highest empirical mean. For simplicity let's assume that T/K is an integer. We will prove a high-probability bound on the simple regret. The analysis gives an example of the application of Hoeffiding's inequiaity to a learning problem; the algorithm itself is likely to be suboptimal.

For simplicity let's assume that T/K is an integer. After T rounds, each arm is chosen T/K times, and let  $\hat{\mu}_i$  be the empirical average reward associated with arm i. By Hoeffding's inequality, we have:

$$\Pr[|\hat{\mu}_i - \mu_i| \ge \epsilon] \le 2e^{-2T\epsilon^2/K}$$
.

Now we want accurate estimation for *all* arms simultaneously. That is, we want to bound the probability of the event that *any*  $\hat{\mu}_i$  deviating from  $\mu_i$  too much. This is where union bound is useful:

$$\begin{split} &\Pr\left[\bigcup_{i=1}^K \{|\hat{\mu}_i - \mu_i| \geq \epsilon\}\right] \qquad \text{(the event that estimation is $\epsilon$-inaccurate for at least 1 arm)} \\ &\leq \sum_{i=1}^K \Pr\left[|\hat{\mu}_i - \mu_i| \geq \epsilon\right] \leq 2Ke^{-2T\epsilon^2/K}. \qquad \text{(union bound, then Householder} \end{split}$$

注意这里使用了 union bound,讲的是( K 个事件中任意一个事件发生)的概率小于 K 个事件(每个事件独立发生)的概率的和。

To rephrase this result: with probability at least  $1 - \delta$ ,  $|\hat{\mu}_i - \mu_i| \le \sqrt{\frac{K}{2T} \ln \frac{2K}{\delta}}$  holds for all i simultaneously.

Finally, we use the estimation error to bound the decision loss: recall that  $\hat{i} = \arg\max_{i \in [K]} \hat{\mu}_i$ , and let  $i^{\star} = \arg\max_{i \in [K]} \mu_i$ .

$$\begin{split} \boldsymbol{\mu}^{\star} - \boldsymbol{\mu}_{\hat{i}} &= \boldsymbol{\mu}_{i^{\star}} - \hat{\boldsymbol{\mu}}_{i^{\star}} + \hat{\boldsymbol{\mu}}_{i^{\star}} - \boldsymbol{\mu}_{\hat{i}} \\ &\leq \boldsymbol{\mu}_{i^{\star}} - \hat{\boldsymbol{\mu}}_{i^{\star}} + \hat{\boldsymbol{\mu}}_{\hat{i}} - \boldsymbol{\mu}_{\hat{i}} \leq 2\sqrt{\frac{K}{2T}\ln\frac{2K}{\delta}}. \end{split}$$

We can rephrase this result as a sample complexity statement: in order to guarantee that  $\mu^* - \mu_i \leq \epsilon$  with probability at least  $1 - \delta$ , we need  $T = O\left(\frac{K}{\epsilon^2} \ln \frac{K}{\delta}\right)$ .

## 2.3. 下界

这里讲的是对于所有的用来解决 MAB 问题的算法而言,性能都不可能超过一个什么样的界。概括 说起来就是,如果最优的 arm 的均值比次优的 arm 的均值没有大太多,这样我们就很难在较少的 次数内以较高精度来分辨谁是最优的,因此找一个最优的 arm 成功率就不会太高。

The linear dependence of the sample complexity on K makes a lot of sense, as to choose a arm with high reward we have to try each arm at least once. Below we will see how to mathematically formalize this idea and prove a lower bound on the sample complexity of MAB.

**Theorem 2.** For any  $K \geq 2$ ,  $\epsilon \leq \sqrt{1/8}$ , and any MAB algorithm, there exists an MAB instance where  $\mu^*$  is  $\epsilon$  better than other arms, yet the algorithm identifies the best arm with no more than 2/3 probability unless  $T \geq \frac{K}{72\epsilon^2}$ .

The theorem itself is stated as a best-arm identification lower bound, but it is also a lower bound for simple regret minimization. This is because all arms except the best one is  $\epsilon$  worse than  $\mu^*$ , so missing the optimal arm means a simple regret of at least  $\epsilon$ .

See the proof in [1] (Theorem 2); the technique is due to [2] and can be also use 1 to prove the lawer bound on the regret of MAB.

另外,我导师前年的高等理论计算机课程也讲过这个问题,证明了 upper

confidence bound (UCB) 算法在此问题上的性能。参见ATCS Note4。

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## 文章被以下专栏收录

