

# Concentration Inequalities and Multi-Armed Bandits

Nan Jiang

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## 【强化学习理论 59】Statistical RL 3



张楚珩

清华大学 交叉信息院博士在读

5 人赞同了该文章

这是UIUC姜楠老师开设的CS598统计强化学习（理论）课程的第二讲。

原文传送门

CS598 Note2

nanjiang.cs.illinois.edu



### 一、Hoeffding's Inequality

初等的统计学过中心极限定理，它们告诉我们当i.i.d.样本很多的时候，在sample上的统计量就会趋向于真实的统计量。这里就更定量化的告诉我们sample上的统计量以怎样的程度趋向于真实的统计量，即concentration inequalities。Hoeffding's inequality就是其中最常用的一种。

**Theorem 1.** Let  $X_1, \dots, X_n$  be independent random variables on  $\mathbb{R}$  such that  $X_i$  is bounded in the interval  $[a_i, b_i]$ . Let  $S_n = \sum_{i=1}^n X_i$ . Then for all  $t > 0$ ,

$$\Pr[S_n - \mathbb{E}[S_n] \geq t] \leq e^{-2t^2 / \sum_{i=1}^n (b_i - a_i)^2}, \quad (1)$$

$$\Pr[S_n - \mathbb{E}[S_n] \leq -t] \leq e^{-2t^2 / \sum_{i=1}^n (b_i - a_i)^2}. \quad (2)$$

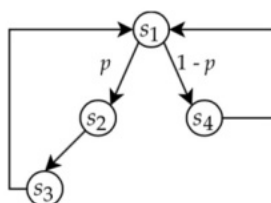
Remarks:

- By union bound, we have  $\Pr[|S_n - \mathbb{E}[S_n]| \geq t] \leq 2e^{-2t^2 / \sum_{i=1}^n (b_i - a_i)^2}$ .
- We often care about the convergence of the empirical mean to the true average, so we can divide  $S_n$  by  $n$ :  $\Pr\left[\left|\frac{S_n}{n} - \frac{\mathbb{E}[S_n]}{n}\right| \geq t\right] \leq 2e^{-2n^2 t^2 / \sum_{i=1}^n (b_i - a_i)^2}$ .
- A useful rephrase of the result when all variables share the same support  $[a, b]$ : with probability at least  $1 - \delta$ ,  $\left|\frac{S_n}{n} - \frac{\mathbb{E}[S_n]}{n}\right| \leq (b - a) \sqrt{\frac{1}{2n} \ln \frac{2}{\delta}}$ .
- $X_1, \dots, X_n$  are not necessarily identically distributed; they just have to be independent.
- The number of variables,  $n$ , is a constant in the theorem statement. When  $n$  is random, as is the case in bandits, for Hoeffding's inequality to apply,  $n$  cannot depend on the realization of  $X_1, \dots, X_n$ .

个人认为最好理解的就是红圈里面的不等式，即sample mean是如何趋向于true mean的。

为了说明最后一点，Note中给了一个例子。

Example: Consider the following Markov chain:



Say we start at  $s_1$  and sample a path of length  $T$  ( $T$  is a constant). Let  $n$  be the number of times we visit  $s_1$ , and we can use the transitions from  $s_1$  to estimate  $p$ .

1. Can we directly apply Hoeffding's inequality here with  $n$  as the number of coin tosses? If you want to derive a concentration bound for this problem, look up Azuma's inequality.

2. What if we sample a path until we visit  $s_1$   $N$  times for some constant  $N$ ? Can we apply Hoeffding's inequality with  $N$  as the number of random variables?

对于第二种情况来说， $N$  固定，然后给定  $N$  个随机变量  $x_i$ ，每个随机变量要么是3（走左边的环路）要么是2（走右边的环路），直接应用Hoeffding's inequality，就能得到该随机变量的样本上平均值距离真是平均值的界。

对于第一种情况需要用另一种concentration inequality, Azuma's inequality。它是对于鞅的concentration inequality，在这个问题上具体的用法我不太确定。这里简述一下。第一种情况下走的步数  $T$  是固定的，构建一个随机变量  $x_i$  表示新增访问  $s_1$  的次数，随机变量  $x_i = x_i - \frac{1}{2+p}$ ， $Z_i = \sum_{j=1}^i x_j$  就是鞅，然后应用Azuma's inequality，注意到随机变量  $\sum_{i=1}^T x_i = n$ ，可以得到关于  $p$  和  $n$  的

concentration inequality由此来估算  $p$ 。

In probability theory, the **Azuma–Hoeffding inequality** (named after Kazuoki Azuma and Wassily Hoeffding) gives a concentration result for the values of martingales that have bounded differences.

Suppose  $\{X_k : k = 0, 1, 2, 3, \dots\}$  is a martingale (or super-martingale) and

$$|X_k - X_{k-1}| \leq c_k,$$

almost surely. Then for all positive integers  $N$  and all positive reals  $t$ ,

$$P(X_N - X_0 \geq t) \leq \exp\left(\frac{-t^2}{2 \sum_{k=1}^N c_k^2}\right).$$

And symmetrically (when  $X_k$  is a sub-martingale):

$$P(X_N - X_0 \leq -t) \leq \exp\left(\frac{-t^2}{2 \sum_{k=1}^N c_k^2}\right).$$

If  $X$  is a martingale, using both inequalities above and applying the union bound allows one to obtain a two-sided bound:

$$P(|X_N - X_0| \geq t) \leq 2 \exp\left(\frac{-t^2}{2 \sum_{k=1}^N c_k^2}\right).$$

Azuma's inequality applied to the Doob martingale gives McDiarmid's inequality which is common in the analysis of randomized algorithms.

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## 二、Multi-Armed Bandits (MAB)

### 2.1. 问题描述

A MAB problem is specified by  $K$  distributions over  $\mathbb{R}$ ,  $\{R_i\}_{i=1}^K$ . Each  $R_i$  has bounded supported  $[0, 1]$  and mean  $\mu_i$ . Let  $\mu^* = \max_{i \in [K]} \mu_i$ . For round  $t = 1, 2, \dots, T$ , the learner

1. Chooses arm  $i_t \in [K]$ .
2. Receives reward  $r_t \sim R_{i_t}$ .

A popular objective for MAB is the pseudo-regret, which poses the *exploration-exploitation* challenge:

$$\text{Regret}_T = \sum_{t=1}^T (\mu^* - \mu_{i_t}).$$

Another important objective is the simple regret:

$$\mu^* - \mu_{\hat{i}},$$

where  $\hat{i}$  is the arm that the learner picks after  $T$  rounds of interactions. This poses the “pure exploration” challenge, since all it matters is to make a good final guess and the regret incurred within the  $T$  rounds does not matter. A related objective is called Best-Arm Identification, which asks whether  $\hat{i} \in \arg \max_{i \in [K]} \mu_i$ ; Best-Arm Identification results often require additional gap conditions.

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MAB问题的目标主要有几种

- Pseudo-regret: 希望在  $T$  轮内总的 regret 最小，即目标是一边探索一边利用；
- Simple regret: 希望在  $T$  轮之后找到的那个 arm 的 regret 小，即目标是在  $T$  轮内尽可能做探索；

- Best-arm identification: 希望在 T 轮之后以最大的概率找到最好的 arm，这也是一个鼓励探索的目标。

## 2.2. 均匀采样

这里我们的目标是 minimize simple regret，方式是在 T 轮中对于每个 arm 都 play 一样多的次数，然后我们推导出一个 simple regret 关于 T 的上界。这也可以看做一个 Hoeffding 不等式的应用。

We consider the simplest algorithm that chooses each arm the same number of times, and after T rounds selects the arm with the highest empirical mean. For simplicity let's assume that  $T/K$  is an integer. We will prove a high-probability bound on the simple regret. The analysis gives an example of the application of Hoeffding's inequality to a learning problem; the algorithm itself is likely to be suboptimal.

For simplicity let's assume that  $T/K$  is an integer. After T rounds, each arm is chosen  $T/K$  times, and let  $\hat{\mu}_i$  be the empirical average reward associated with arm  $i$ . By Hoeffding's inequality, we have:

$$\Pr[|\hat{\mu}_i - \mu_i| \geq \epsilon] \leq 2e^{-2T\epsilon^2/K}.$$

Now we want accurate estimation for *all* arms simultaneously. That is, we want to bound the probability of the event that *any*  $\hat{\mu}_i$  deviating from  $\mu_i$  too much. This is where union bound is useful:

$$\begin{aligned} \Pr\left[\bigcup_{i=1}^K \{|\hat{\mu}_i - \mu_i| \geq \epsilon\}\right] & \quad (\text{the event that estimation is } \epsilon\text{-inaccurate for at least 1 arm}) \\ & \leq \sum_{i=1}^K \Pr[|\hat{\mu}_i - \mu_i| \geq \epsilon] \leq 2Ke^{-2T\epsilon^2/K}. \quad (\text{union bound, then Hoeffding's inequality}) \end{aligned}$$

注意这里使用了 union bound，讲的是（K 个事件中任意一个事件发生）的概率小于 K 个事件（每个事件独立发生）的概率的和。

To rephrase this result: with probability at least  $1 - \delta$ ,  $|\hat{\mu}_i - \mu_i| \leq \sqrt{\frac{K}{2T} \ln \frac{2K}{\delta}}$  holds for all  $i$  simultaneously.

Finally, we use the estimation error to bound the decision loss: recall that  $\hat{i} = \arg \max_{i \in [K]} \hat{\mu}_i$ , and let  $i^* = \arg \max_{i \in [K]} \mu_i$ .

$$\begin{aligned} \mu^* - \mu_{\hat{i}} &= \mu_{i^*} - \hat{\mu}_{i^*} + \hat{\mu}_{i^*} - \mu_{\hat{i}} \\ &\leq \mu_{i^*} - \hat{\mu}_{i^*} + \hat{\mu}_{\hat{i}} - \mu_{\hat{i}} \leq 2\sqrt{\frac{K}{2T} \ln \frac{2K}{\delta}}. \end{aligned}$$

We can rephrase this result as a sample complexity statement: in order to guarantee that  $\mu^* - \mu_{\hat{i}} \leq \epsilon$  with probability at least  $1 - \delta$ , we need  $T = O\left(\frac{K}{\epsilon^2} \ln \frac{K}{\delta}\right)$ .

## 2.3. 下界

这里讲的是对于所有的用来解决 MAB 问题的算法而言，性能都不可能超过一个什么样的界。概括说起来就是，如果最优的 arm 的均值比次优的 arm 的均值没有大太多，这样我们就很难在较少的次数内以较高精度来分辨谁是最优的，因此找一个最优的 arm 成功率就不会太高。

The linear dependence of the sample complexity on  $K$  makes a lot of sense, as to choose a arm with high reward we have to try each arm at least once. Below we will see how to mathematically formalize this idea and prove a lower bound on the sample complexity of MAB.

**Theorem 2.** For any  $K \geq 2$ ,  $\epsilon \leq \sqrt{1/8}$ , and any MAB algorithm, there exists an MAB instance where  $\mu^*$  is  $\epsilon$  better than other arms, yet the algorithm identifies the best arm with no more than  $2/3$  probability unless  $T \geq \frac{K}{72\epsilon^2}$ .

The theorem itself is stated as a best-arm identification lower bound, but it is also a lower bound for simple regret minimization. This is because all arms except the best one is  $\epsilon$  worse than  $\mu^*$ , so missing the optimal arm means a simple regret of at least  $\epsilon$ .

See the proof in [1] (Theorem 2); the technique is due to [2] and can be also used to prove the lower bound on the regret of MAB.

另外，我导师前年的高等理论计算机课程也讲过这个问题，证明了 upper

confidence bound (UCB) 算法在此问题上的性能。参见 [ATCS Note4](#)。

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