# Getting Started with Computer Vision Proposal

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# Introduction

The field of computer vision has a deceptively simple mission: build up information from images to make conclusions about the world. In a time when we're more and more surrounded by increasingly high resolution cameras hooked up to powerful computers (cf. the More Pixels Law) and huge online databases of images (the world's largest photo libraries), computer vision is taking its place as one of the foundational skills necessary to invent the next generation of technology: from user interfaces, to mobile applications, to search engines, to social networks.

Until now, computer vision has mainly been the domain of academic researchers, computer science

wizards, and a few adventurous interactive artists and designers. However the tools of the field have never been easier to use. Specifically, OpenCV, a huge open source project implementing a tremendous range of computer vision algorithms and techniques, has reached an advanced level of maturity where it is widely available (including on both iOS and Android) and integrated into creative coding toolkits that are accessible to beginners. This book attempts to create an easy entry point for a much broader set of people to get started with

computer vision. It introduces the code and concepts necessary to build computer vision projects with the Processing creative coding environment. It is designed to be accessible to a beginner audience, but also to instill the fundamental concepts of the field, enabling readers to not just follow recipes, but build their own projects. To achieve these goals, this book is organized around the six stages that constitute most computer

Filter Calibrate

- Track
- Train

vision applications:

Capture

- Combine
- The plan for this book is to integrate these techniques into fun and motivating projects such as:

A Caroonifier

Object tracking for a simple game

 Augmented Reality Identifying toys

- Recognizing faces
- Note: Due to the inherently rich multi-media nature of computer vision applications, this book is a prime candidate to use O'Reilly's new web-based publishing tools that include video and interactive pieces. It
- should be planned for that format from the start with the appropriate modules designed as scripts for videos, interactive pieces, quizzes, etc. at the writing stage rather than waiting for a written book to be

completed first. **Timing and Code Development** A brief note about some practical issues related to timing of the book's release and the development process. I am currently negotiating with the Processing Foundation to work for them on updating the

Processing OpenCV library for Processing 2.0. This work will pair very well with this project as I'll be

#### able to include all the necessary functions in the library for the projects here and this book will act as comprehensive documentation for that project which can be maintained along with the project going forward.

publicly available to draft on the attention from those announcements.

possibly even participation and collaboration from other core Processing members who teach with OpenCV. The release of Processing 2.0 (probably this summer) will be the target release date for this new OpenCV library and would also be a good target for having at least the first components of this project

Given the goals of producing rich online multi-media content for this project, I believe that the individual

pieces should be released as they are completed so we can get feedback from the community and

**Chapter Outline** 1. First steps: Cartoonifier

This first chapter introduces the basics of how to work with OpenCV in Processing. We'll learn how to access images and live camera feeds as well as how to do the basic filtering on these images that

## makes all other applications possible.

### Install OpenCV for Processing Access camera, load still images

Face detection with HAAR finder

Filter image: brightness, contrast, convert to grayscale, blur, invert, etc. Background subtraction with remember() and absDiff() Contour finders (canny, scharr, sobel)

with computers. In this chapter we'll explore one of the most basic and reliable ways to track objects: based on their color. We'll start with the simplest possible color tracker and then we'll improve it to

flood fill

Project: build an application that renders a person's face in a cartoon-y style.

The ability to locate and track objects in images enables all kinds of new ways for people to interact

2. Tracking an Object

template matching

make it more robust. Finally, we'll explore some other, more complex ways of tracking objects.

Connected components with cvBlob

Adaptive color tracking using mean-shift/cam-shift

 preview the idea of image features from AR chapter 3. Augmented Reality

Augmented Reality has been a hot area of interaction design research and experimentation for the last few years. Creating AR interfaces involves adding computer graphics to live camera input so that those graphics match the perspective of the scene, creating the illusion that they are actually present. In order to accomplish this, we must track an object in the scene (as in the previous chapter) and also determine

find their orientation. They also frequently contain information uniquely identifying each marker. There are standard AR marker sets with accompanying code that makes them relatively easy to work with. We'll explore the basic OpenCV functions used to detect and identify these markers. Then we'll learn

how to use the ARToolkit, which makes it easy to work with a particular set of markers.

There are two main approaches to AR: using markers and markerless. "AR markers" are flat objects with visible patterns that are designed make it easy to detect them and to

its size and orientation so we know how to position our graphics.

Basic color tracking: inRange, mixerRGBGray, thresholding, blobs

polygon approximation marker detection pose estimation **ARToolkit** 

multiple images even as the object moves and rotates. We'll see how to track such an object in an AR

All recognition applications are based on machine learning: the process of training an algorithm based

### markers or because you want to track some pre-existing markerless object. OpenCV enables markerless object tracking using "image features", unique parts of objects that can be reliably found in

application.

**Markerless** 

specific toys.

- pose estimation 4. Object and Face Recognition with Machine Learning
- on data. In this chapter we'll use OpenCV techniques to extract data from images, we'll use its machine learning tools to train classifiers based on this data, and then we'll use these classifiers to recognizes, faces, toys, and hand gestures.
  - Using SVM for matching Militarizing your backyard with Python example (video) Histogram of Oriented Gradients feature vector

  - Windowed search Eigenfaces

Toy detection and hand gesture detection

Building a feature vector: color histogram

- Manual
  - Contour detection

Camera Calibration: creation and loading

Install NyARToolkit (or SimpleARToolkit)

Display 3D cube, display 3D model

Sometimes, you don't want to or can't use an AR marker, either to avoid the appearance of the ugly

Determine orientation

Detect markers

image binarization

 Find image features (using corner detection) in a source image FLANN search for similar features

outlier filtering with RANSAC

- Recognition is the task of identifying a person or an object in a never-before-seen image using data extracted from a pre-processed set of images of many people or objects. Face recognition is how Facebook can automatically tag you in new photos. Recognition can let us detect hand gestures and

Training a Support Vector Machine (libsvm vs OpenCV implementation)