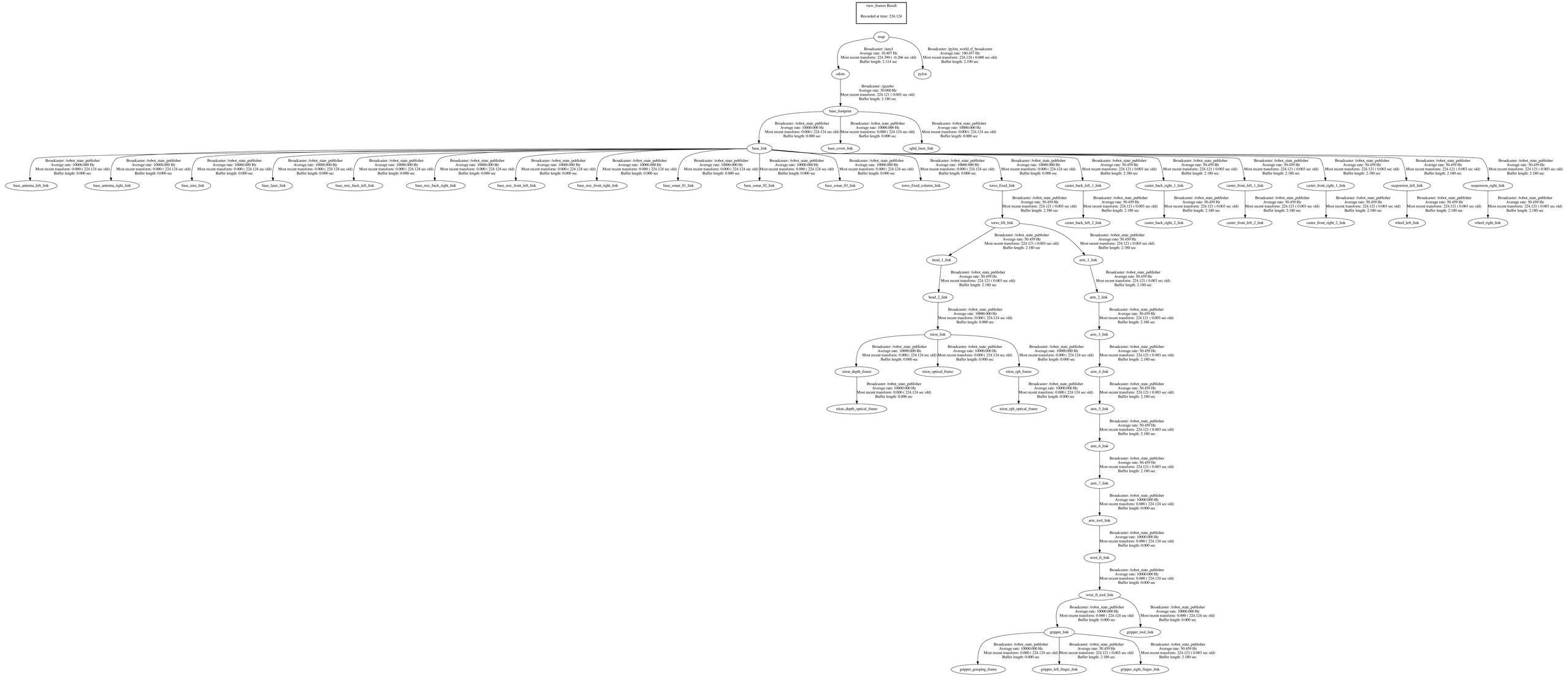
view_frames Result
Recorded at time: 224.124
map
Broadcaster: /amcl
Average rate: 10.407 Hz
Most recent transform: 224.090 (-0.266 sec old)
Buffer length: 2.114 sec
Broadcaster: /pylon_world_tf_broadcaster
Average rate: 100.457 Hz
Most recent transform: 224.124 (0.000 sec old)
Buffer length: 2.190 sec
odom
pylon
Broadcaster: /gazebo
Average rate: 50.000 Hz
Most recent transform: 224.121 (0.003 sec old)
Buffer length: 2.180 sec
base_footprint
Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (224.124 sec old)
Buffer length: 0.000 sec
base_link
base_cover_link
rgbd_laser_link
base_antenna_left_link
base_antenna_right_link
base_imu_link
base_laser_link
base_misc_back_left_link
base_misc_back_right_link
base_misc_front_left_link
base_misc_front_right_link
base_sonar_01_link
base_sonar_02_link
base_sonar_03_link
torso_fixed_column_link
torso_fixed_link
caster_back_left_1_link
caster_back_right_1_link
caster_front_left_1_link
caster_front_right_1_link
suspension_left_link
suspension_right_link
caster_back_left_2_link
caster_back_right_2_link
caster_front_left_2_link
caster_front_right_2_link
wheel_left_link
wheel_right_link
torso_lift_link
head_1_link
arm_1_link
head_2_link
arm_2_link
xtion_link
arm_3_link
xtion_depth_frame
xtion_optical_frame
xtion_rgb_frame
arm_4_link
xtion_depth_optical_frame
xtion_rgb_optical_frame
arm_5_link
arm_6_link
arm_7_link
arm_tool_link
wrist_ft_link
wrist_ft_tool_link
gripper_link
gripper_tool_link
gripper_grasping_frame
gripper_left_finger_link
gripper_right_finger_link