

Participez à la conception d'une voiture autonome



Future Vision Transport



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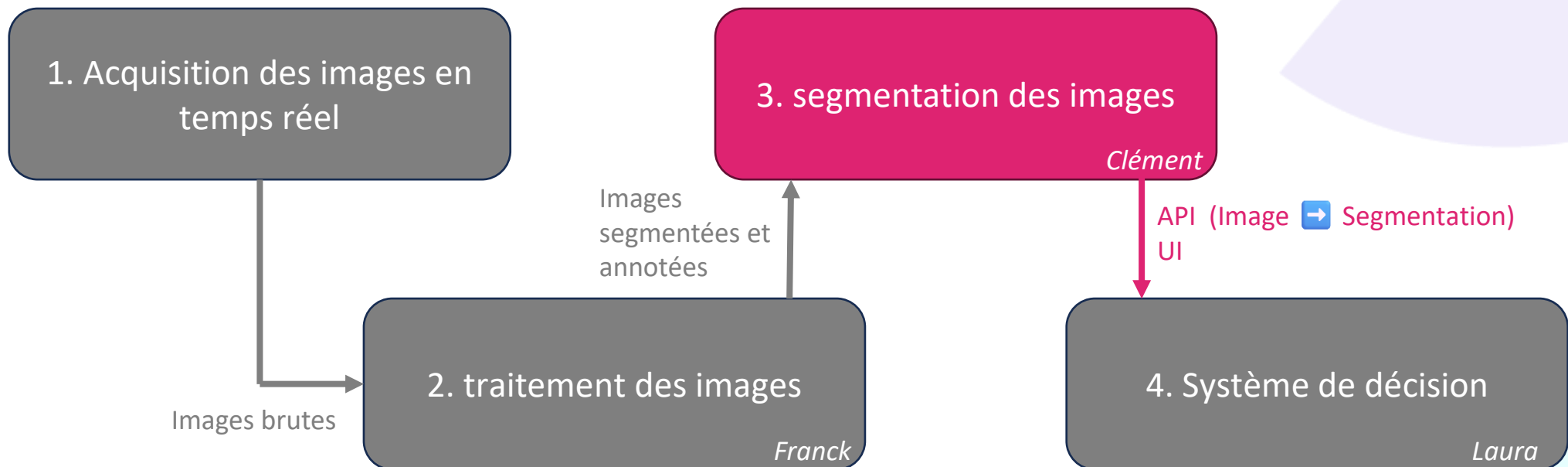
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CONCLUSION

PARTIE 1 – INTRODUCTION

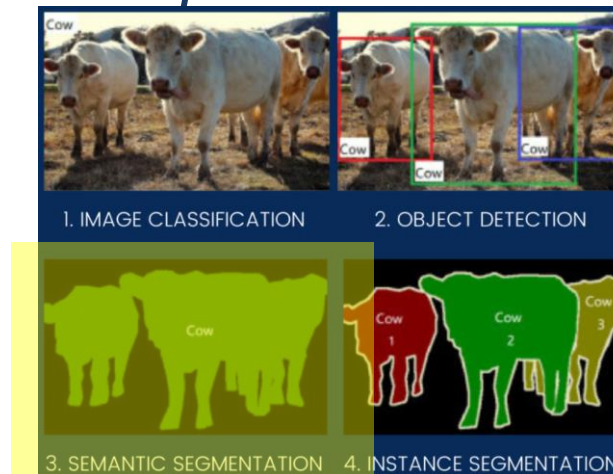
Le projet de l'entreprise

- Conception systèmes embarqués de computer vision
- Cible : véhicules autonomes
- Équipe projet divisée en plusieurs parties :

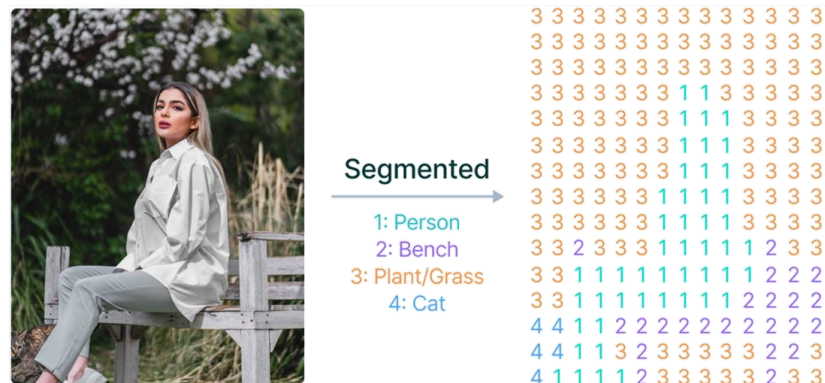


Qu'est-ce que la segmentation ?

- Intégrée au champ de la *Computer Vision* :



- Classification à l'échelle du pixel :



Fonctionnement général

Architecture :

Encoder

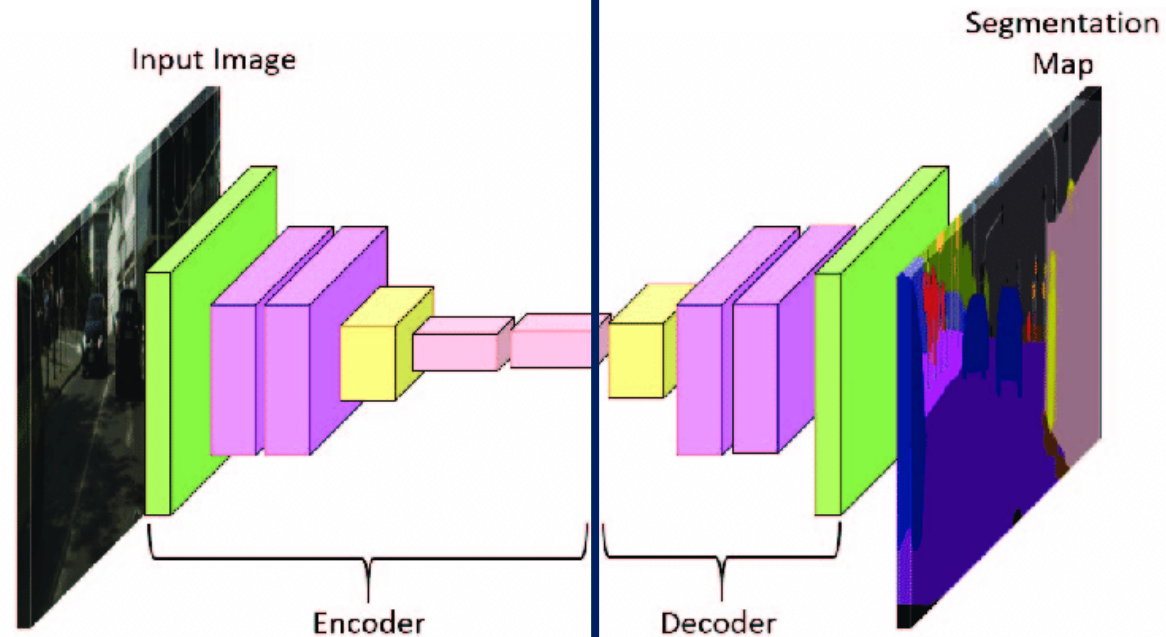
Decoder

Extraire les features importantes

Basé sur des modèles connus sur la classification d'image (sans les couches de décision)

→ *Backbone*

Downsampling



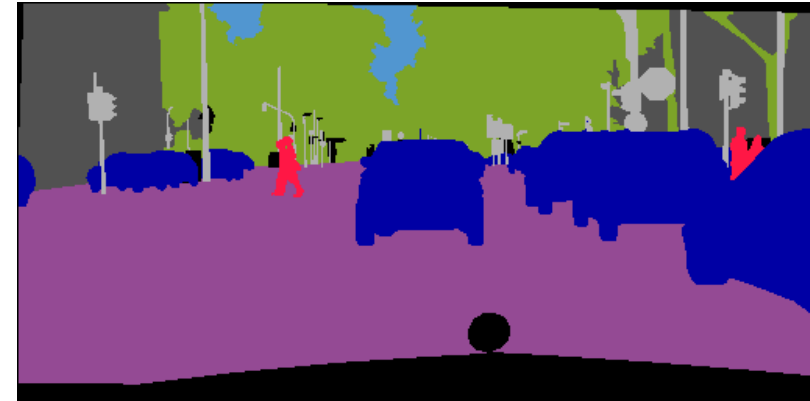
Upsampling

Revenir aux dimensions initiales

Autant de canaux que de classes à détecter

Les données à notre disposition

- Images : P8_Cityscapes_leftImg8bit_trainvaltest
- Masks : P8_Cityscapes_gtFine_trainvaltest














- Prédécoupage :
 - Entraînement : 2975 images / masks
 - Validation : 500 images / masks
 - Test : 1525 images / masks

Réduire le nombre de catégories

name	id	trainId	category	catId
'unlabeled'	, 0 ,	255	'void'	, 0
'ego vehicle'	, 1 ,	255	'void'	, 0
'rectification border'	, 2 ,	255	'void'	, 0
'out of roi'	, 3 ,	255	'void'	, 0
'static'	, 4 ,	255	'void'	, 0
'dynamic'	, 5 ,	255	'void'	, 0
'ground'	, 6 ,	255	'void'	, 0
'road'	, 7 ,	0	'flat'	, 1
'sidewalk'	, 8 ,	1	'flat'	, 1
'parking'	, 9 ,	255	'flat'	, 1
'rail track'	, 10 ,	255	'flat'	, 1
'building'	, 11 ,	2	'construction'	, 2
'wall'	, 12 ,	3	'construction'	, 2
'fence'	, 13 ,	4	'construction'	, 2
'guard rail'	, 14 ,	255	'construction'	, 2
'bridge'	, 15 ,	255	'construction'	, 2
'tunnel'	, 16 ,	255	'construction'	, 2
'pole'	, 17 ,	5	'object'	, 3

name	id	trainId	category	catId
'polegroup'	, 18 ,	255	'object'	, 3
'traffic light'	, 19 ,	6	'object'	, 3
'traffic sign'	, 20 ,	7	'object'	, 3
'vegetation'	, 21 ,	8	'nature'	, 4
'terrain'	, 22 ,	9	'nature'	, 4
'sky'	, 23 ,	10	'sky'	, 5
'person'	, 24 ,	11	'human'	, 6
'rider'	, 25 ,	12	'human'	, 6
'car'	, 26 ,	13	'vehicle'	, 7
'truck'	, 27 ,	14	'vehicle'	, 7
'bus'	, 28 ,	15	'vehicle'	, 7
'caravan'	, 29 ,	255	'vehicle'	, 7
'trailer'	, 30 ,	255	'vehicle'	, 7
'train'	, 31 ,	16	'vehicle'	, 7
'motorcycle'	, 32 ,	17	'vehicle'	, 7
'bicycle'	, 33 ,	18	'vehicle'	, 7
'license plate'	, -1 ,	-1	'vehicle'	, 7

Les outils utilisés

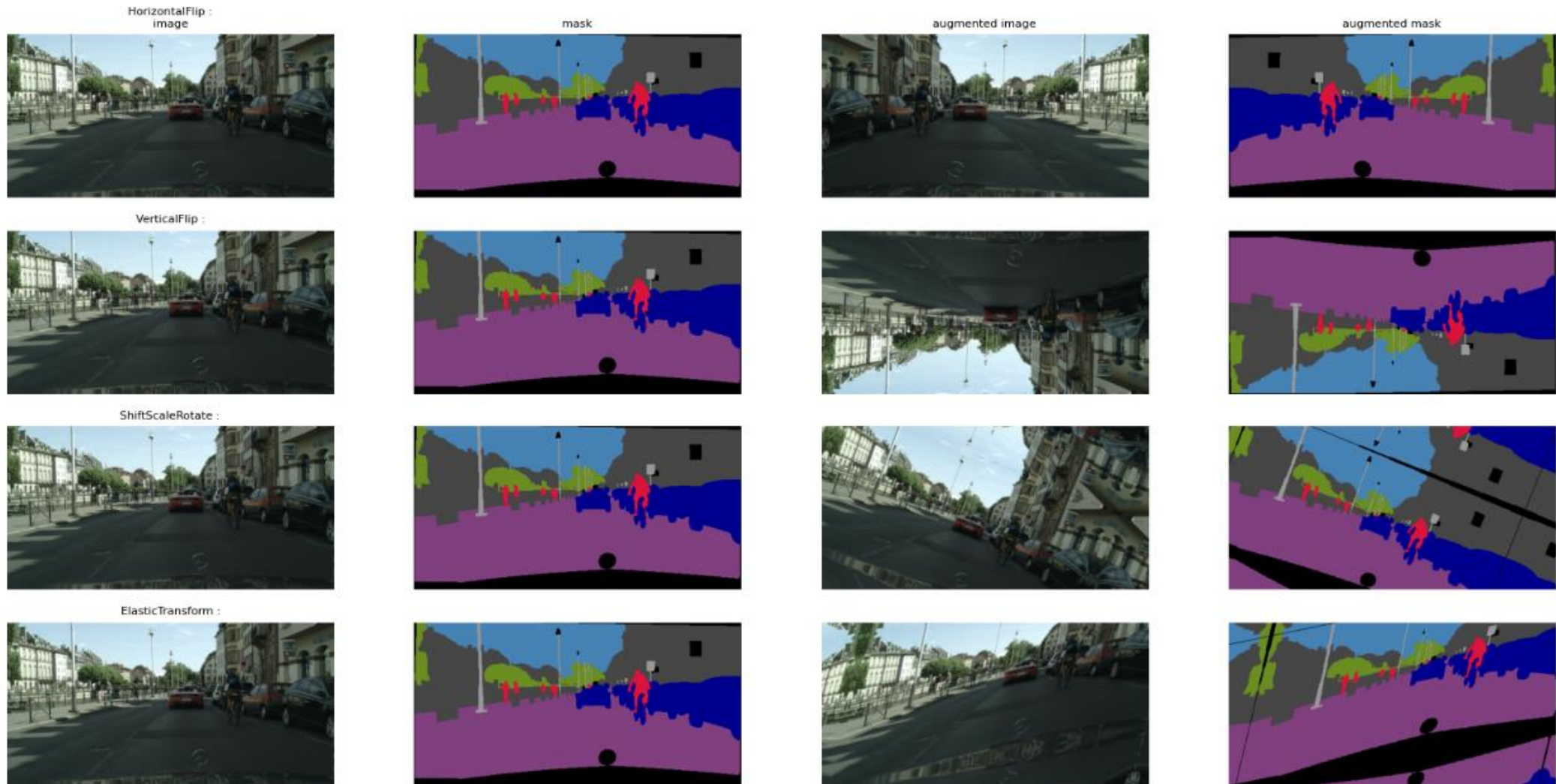
- Mise à disposition des images  Keras
- Export du modèle  TensorFlow
- Modélisation  Segmentation Models
- Augmentation de données  Albumentations
- Création de l'API  FastAPI
- Création de l'UI  Flask
- Conteneurs exécutables  docker
- Déploiement 
- Intégration continue  GitHub
- Déploiement continue  GitHub Actions + 

PARTIE 2 – PREPROCESSING

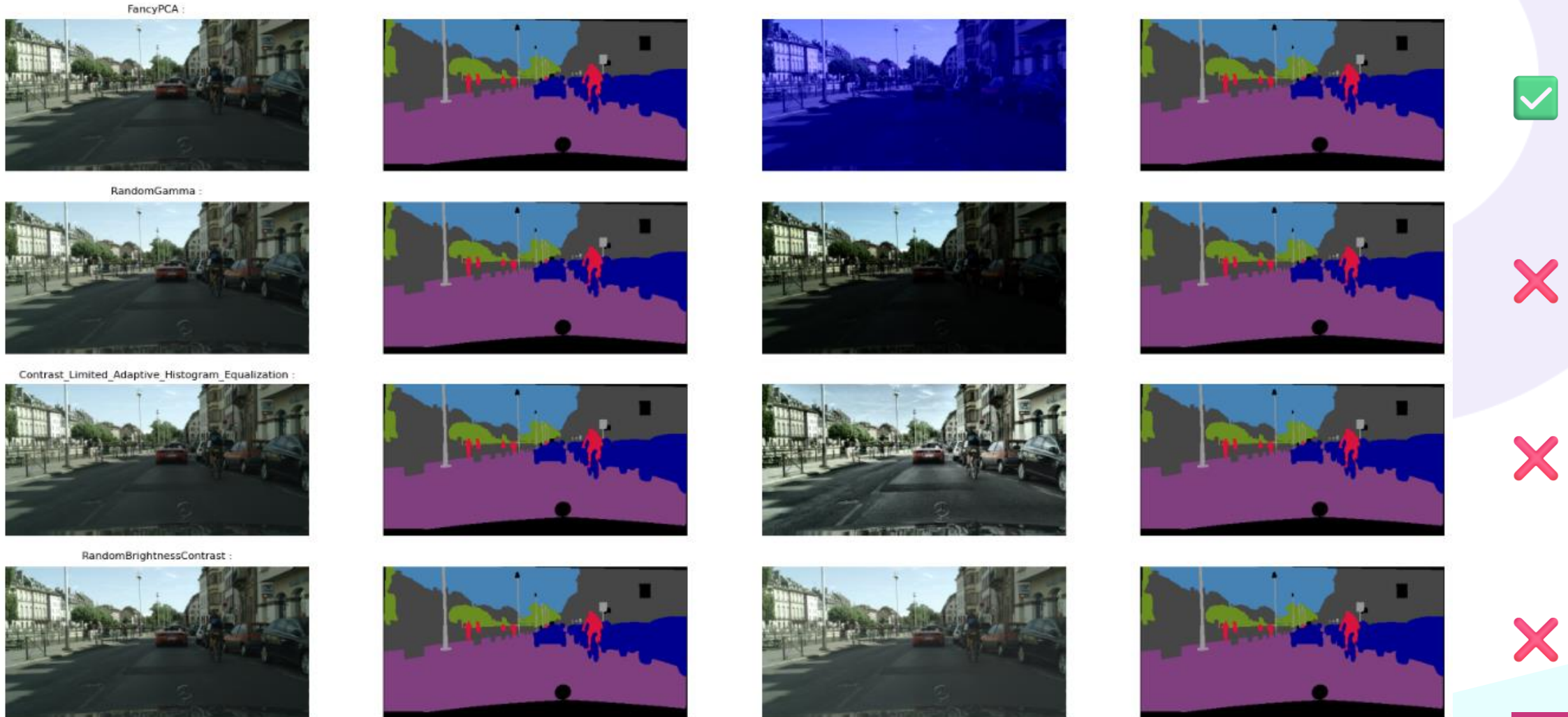
Générateur de données

- Dataset très volumineux (11 Go)
- Sous-classe de `keras.utils.Sequence`
 - ▼ chemins d'accès des images et des masks
 - (facultatif) échantillonnage `n_images`
 - (facultatif) `train_test_split`
 - Lecture images et les masks par lot :
 - à la taille souhaitée `batch_size`
 - aux dimensions souhaitées `image_size`
 - (facultatif) augmentation des données
 - (facultatif) prétraitement images
 - (facultatif) mappage des classes en macro-catégories
 - labels du mask dans leurs propres canaux (256 x 512) → (256 x 512 x 8)
 - mise à disposition du batch créé
 - (facultatif) après chaque `epoch` → mélange les chemins d'accès des images/masks

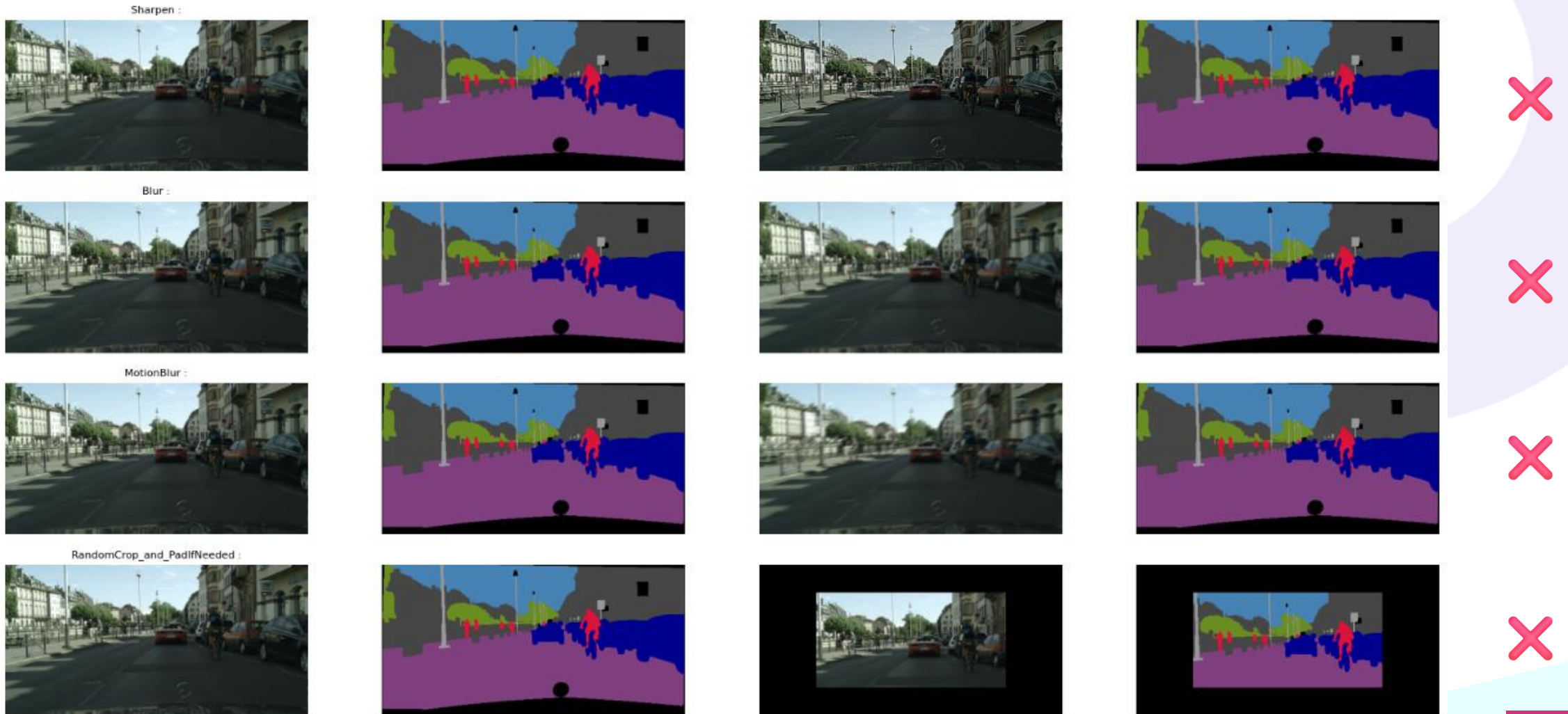
Augmentation des données - exploration



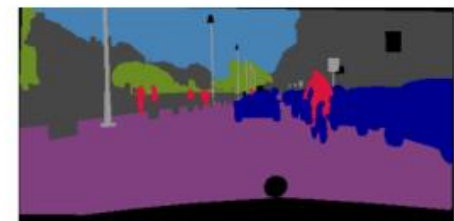
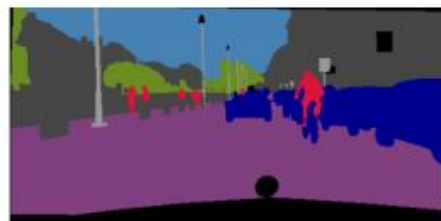
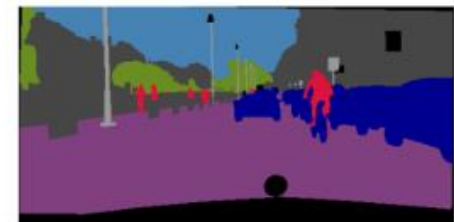
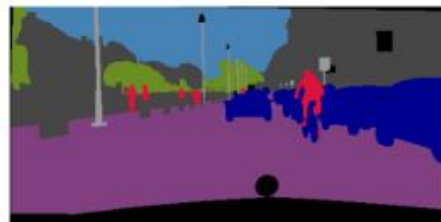
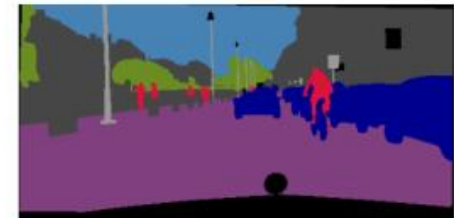
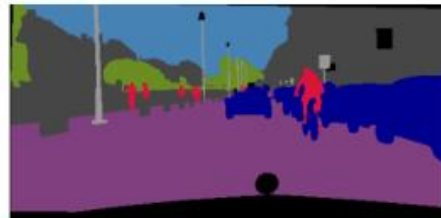
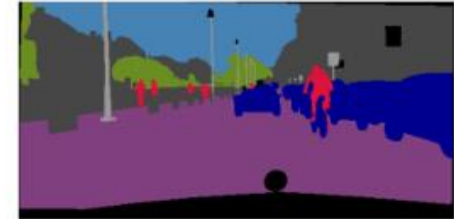
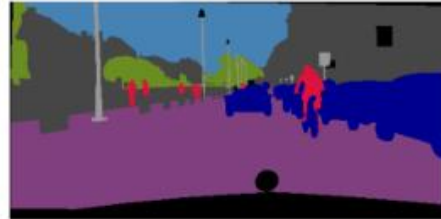
Augmentation des données - exploration



Augmentation des données - exploration



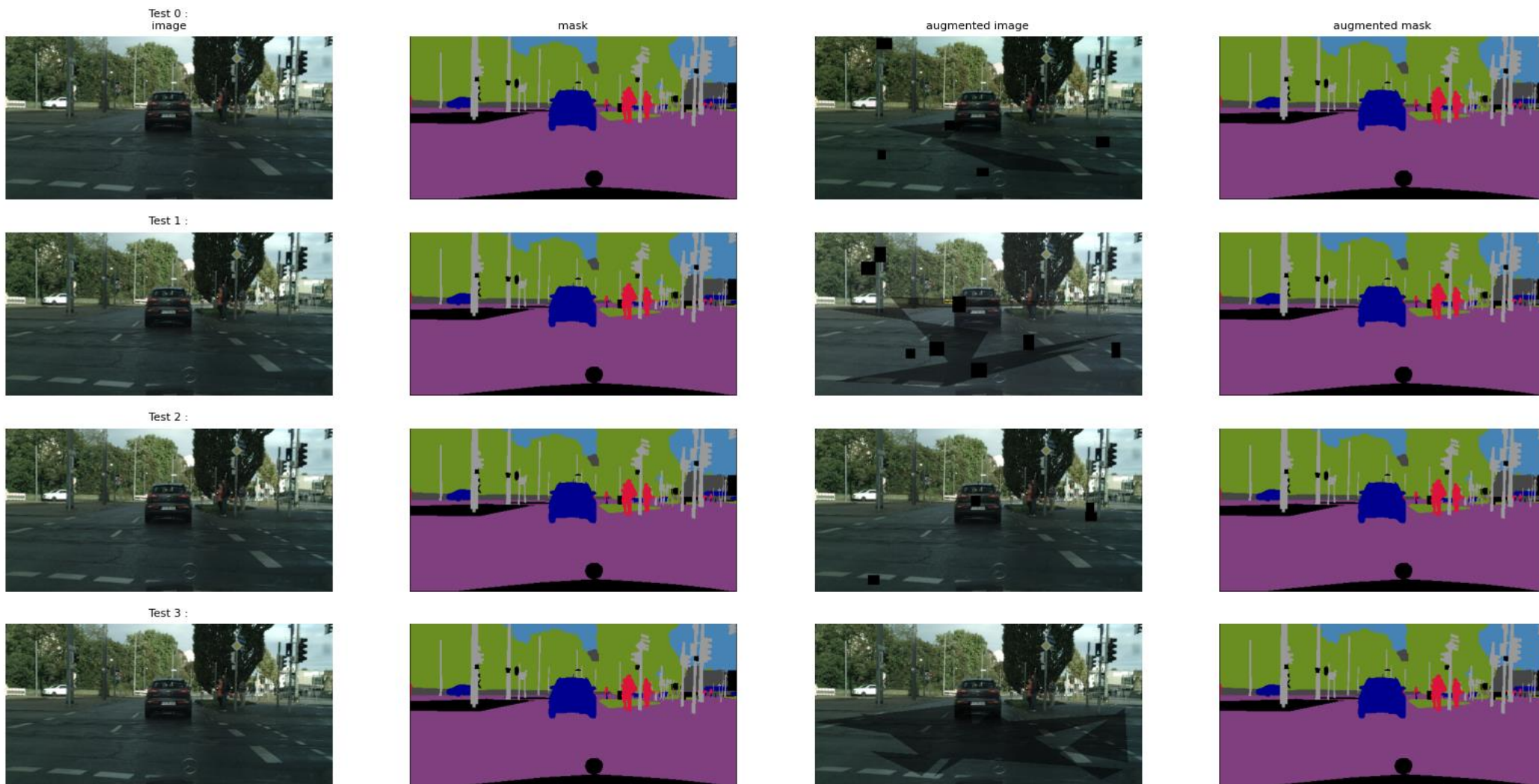
Augmentation des données - exploration



Augmentation des données – solution retenue

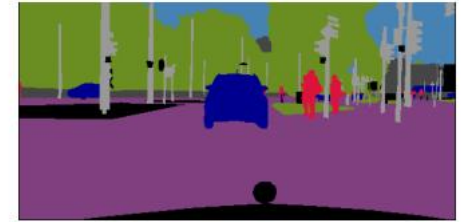
```
# define augmentations for training
list_of_transforms = [
    A.OneOf(
        [
            A.FancyPCA(p=1, alpha=1),
            A.HueSaturationValue(p=1, hue_shift_limit=20, sat_shift_limit=30, val_shift_limit=20),
            A.ColorJitter(p=1, brightness=0.2, contrast=0.2, saturation=0.2),
        ],
        p=0.5
    ),
    A.RandomShadow(
        p=0.5,
        shadow_roi=(
            0, 0.4,
            1, 1
        ),
        num_shadows_lower=1,
        num_shadows_upper=4,
        shadow_dimension=5
    ),
    A.CoarseDropout(
        p=0.5,
        min_holes=2,
        max_holes=8,
        min_height=0.05,
        max_height=0.1,
        min_width=0.025,
        max_width=0.05
    )
]
```

Augmentation des données – solution retenue



Augmentation des données - solution retenue

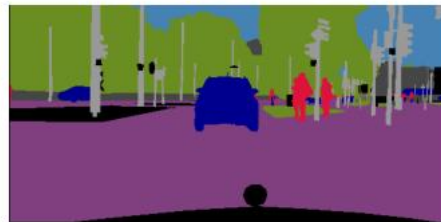
Test 4 :



Test 5 :



Test 6 :



Test 7 :



PARTIE 3 – Modélisation

Métrique d'évaluation

- Mean IoU score (indice de Jaccard) :

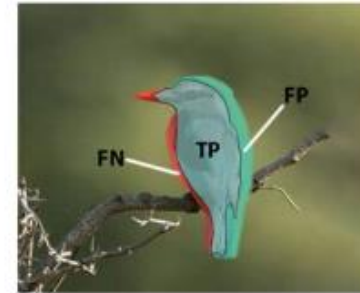
$$IoU = \frac{TP}{(TP + FP + FN)}$$



Ground Truth Mask



Predicted Mask



- Dice score :

$$Dice = \frac{2TP}{2TP + FP + FN}$$

- Training time

Fonction de perte

- Focal Loss

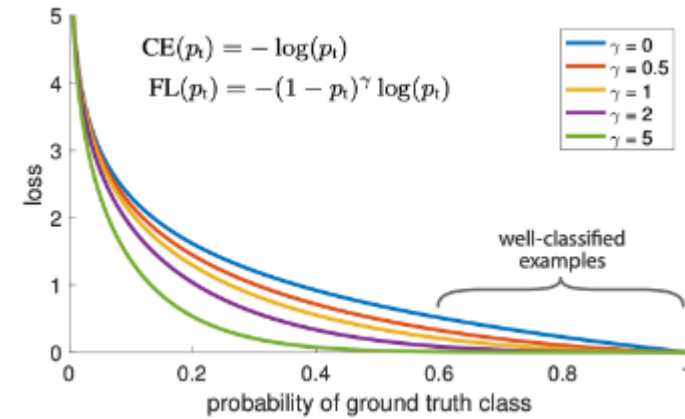
$$\text{CE}(p, \hat{p}) = - (p \log(\hat{p}) + (1-p) \log(1-\hat{p}))$$

$$\text{FL}(p, \hat{p}) = - (\alpha(1-\hat{p})^\gamma p \log(\hat{p}) + (1-\alpha)\hat{p}^\gamma(1-p) \log(1-\hat{p}))$$

+

- Dice Loss

$$\text{DL}(p, \hat{p}) = 1 - \frac{2 \sum p_{h,w} \hat{p}_{h,w}}{\sum p_{h,w} + \sum \hat{p}_{h,w}}$$



Avec ou sans l'argument `class_weights`

Choix pour la modélisation

- Réduire le temps d'apprentissage :
 - Limitation du jeu d'Entraînement : ~~2975~~ → 512 images
 - Limitation de la taille des images : (512 x 1024) → (256 x 512)
- Le nombre d'*epochs*
 - Callback `EarlyStopping`
 - Patience = 3 epochs
 - Warm-up = 10 epochs

Baseline

- Modèle de segmentation sémantique simple :

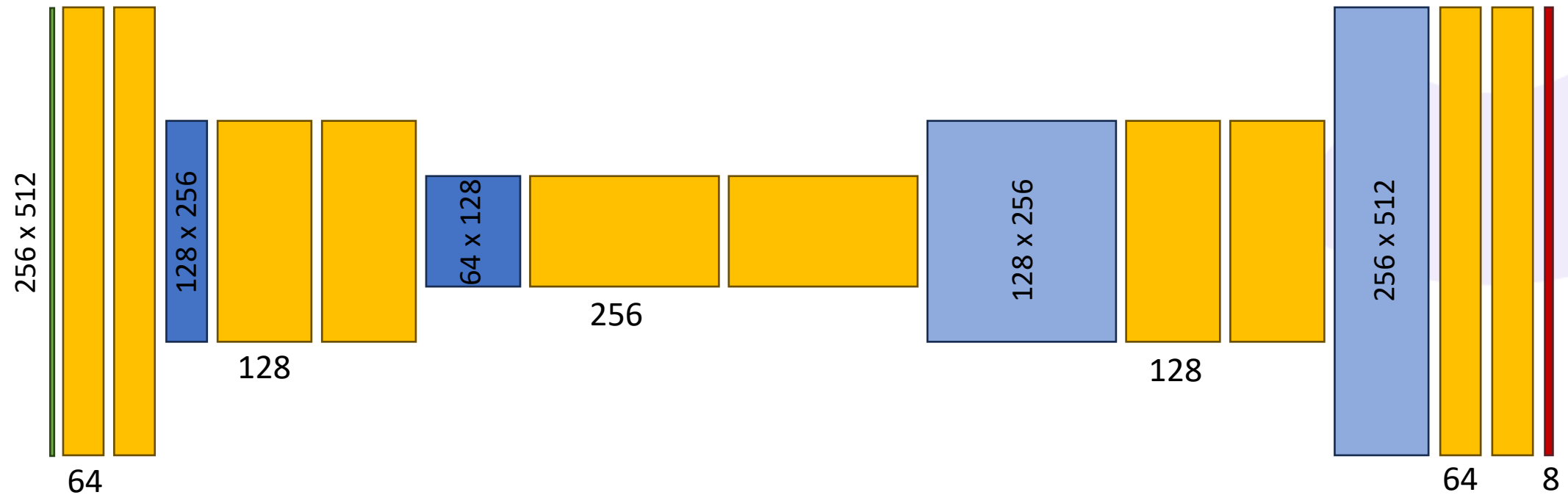


Image 3 canaux



Conv 3x3



MaxPooling 2x2



UpSampling 2x2 nearest



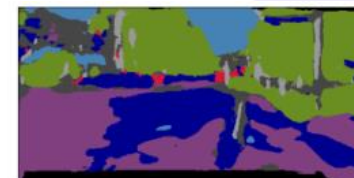
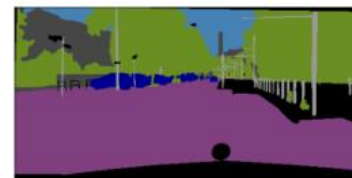
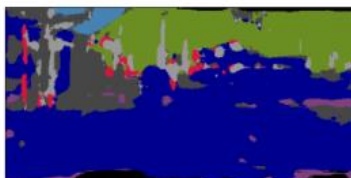
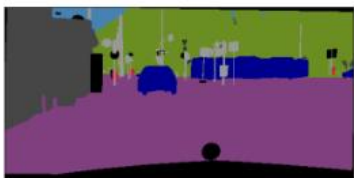
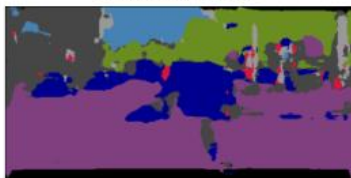
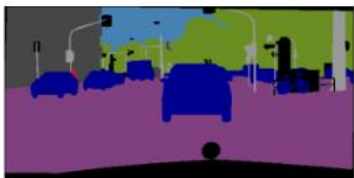
Conv 8 canaux + softmax

Baseline

Images

Masks

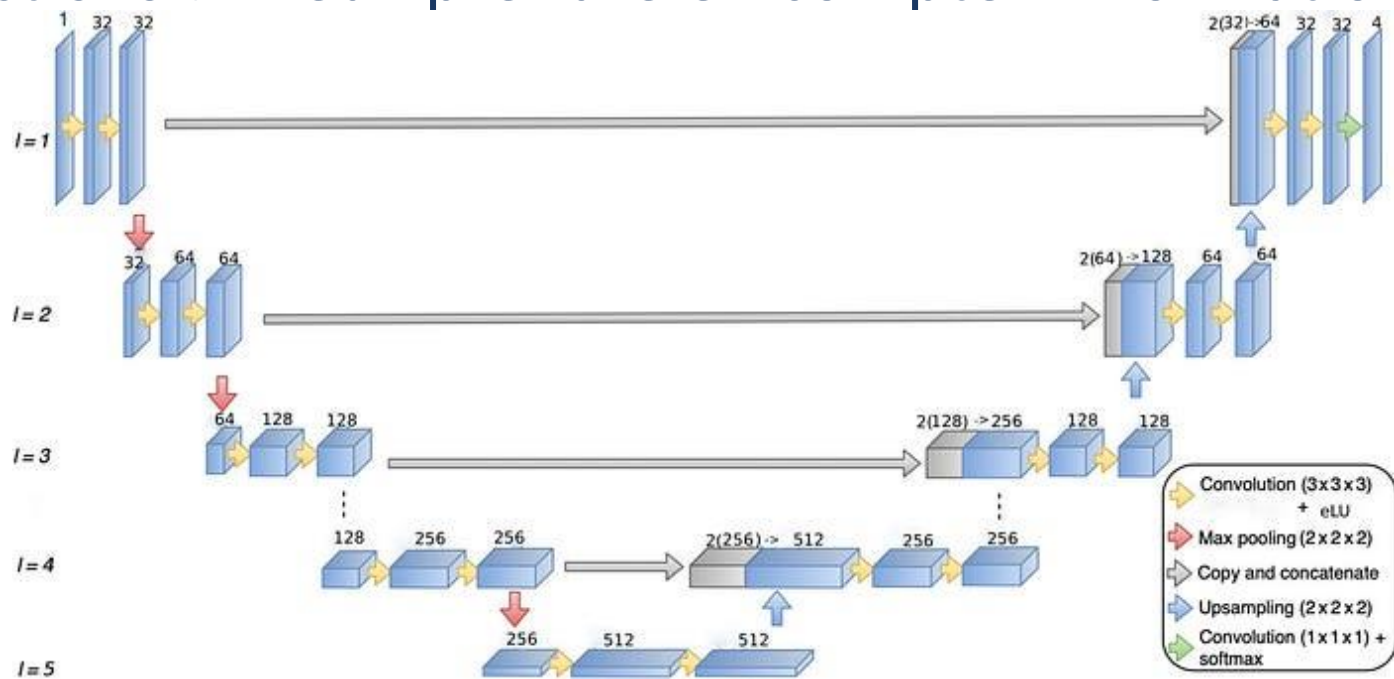
Predicted masks



model	backbone	loss_function	val_iou	val_f_score	training_time	augmentation
baseline		dice+focal	0.388	0.490	259.22 min	No

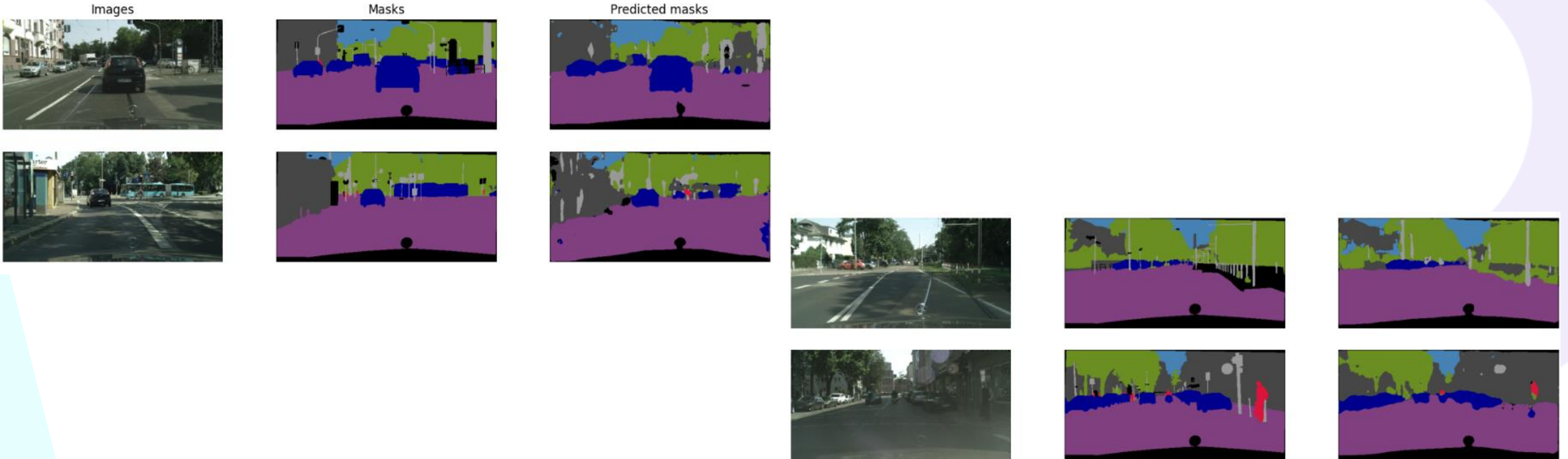
Architecture U-net

- *Skip connections* : mieux prendre en compte l'information spatiale



- *Backbone* : VGG16 et Resnet34

Architecture U-net – Resnet34



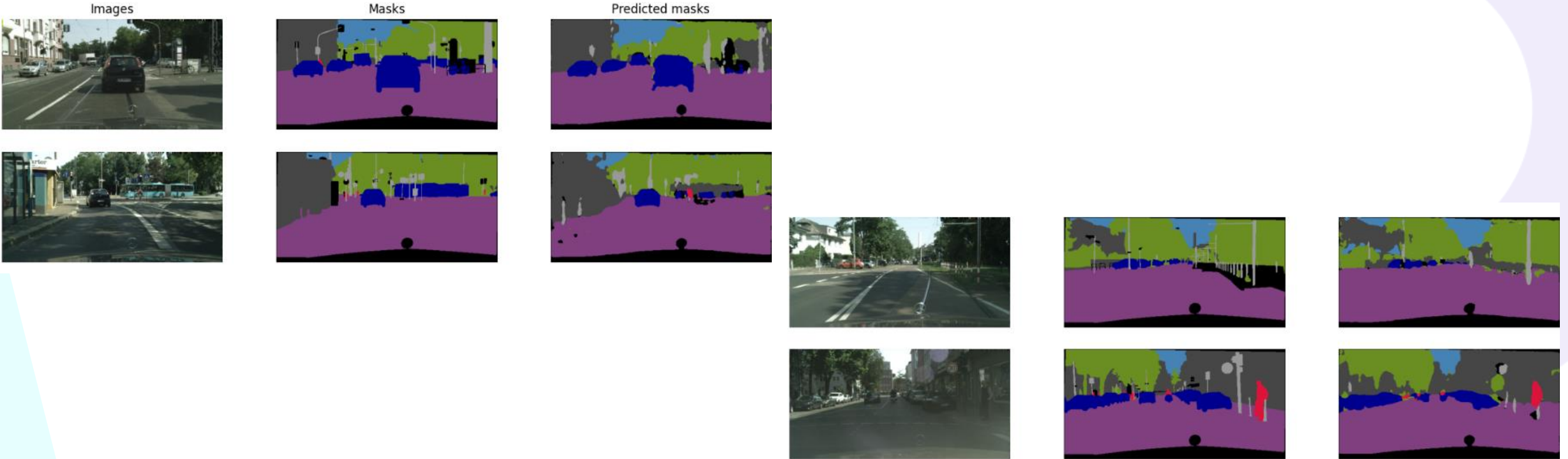
model	backbone	loss_function	val_iou	val_f_score	training_time	augmentation
baseline		dice+focal	0.388	0.490	259.22 min	No
unet	resnet34	dice+focal	0.657	0.702	79.74 min	No

Architecture U-net – VGG16



model	backbone	loss_function	val_iou	val_f_score	training_time	augmentation
baseline		dice+focal	0.388	0.490	259.22 min	No
unet	resnet34	dice+focal	0.657	0.702	79.74 min	No
unet	vgg16	dice+focal	0.302	0.347	179.79 min	No

avec Data Augmentation



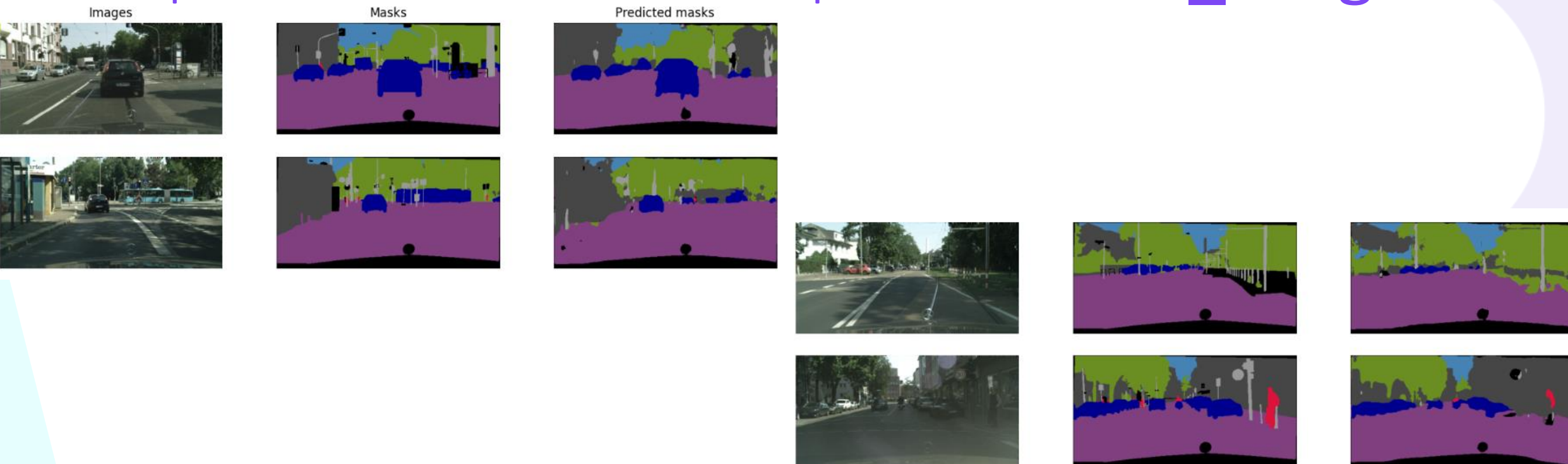
model	backbone	loss_function	val_iou	val_f_score	training_time	augmentation
baseline		dice+focal	0.388	0.490	259.22 min	No
unet	resnet34	dice+focal	0.657	0.702	79.74 min	No
unet	vgg16	dice+focal	0.302	0.347	179.79 min	No
unet	resnet34	dice+focal	0.658	0.722	157.30 min	Yes

Optimisation fonction de perte : `class_weights`

- Loss = Focal loss + Dice loss
- Idée : utiliser l'IoU par classe

	Category	IoU	class_weights
0	void	0.768	0.110
1	flat	0.976	0.086
2	construction	0.921	0.092
3	object	0.359	0.236
4	nature	0.854	0.099
5	sky	0.925	0.091
6	human	0.506	0.167
7	vehicle	0.715	0.118










Optimisation fonction de perte : `class_weights`



model	backbone	loss_function	val_iou	val_f_score	training_time	augmentation
baseline		dice+focal	0.388	0.490	259.22 min	No
unet	resnet34	dice+focal	0.657	0.702	79.74 min	No
unet	vgg16	dice+focal	0.302	0.347	179.79 min	No
unet	resnet34	dice+focal	0.658	0.722	157.30 min	Yes
unet	resnet34	dice_CW+focal	0.664	0.732	147.38 min	Yes

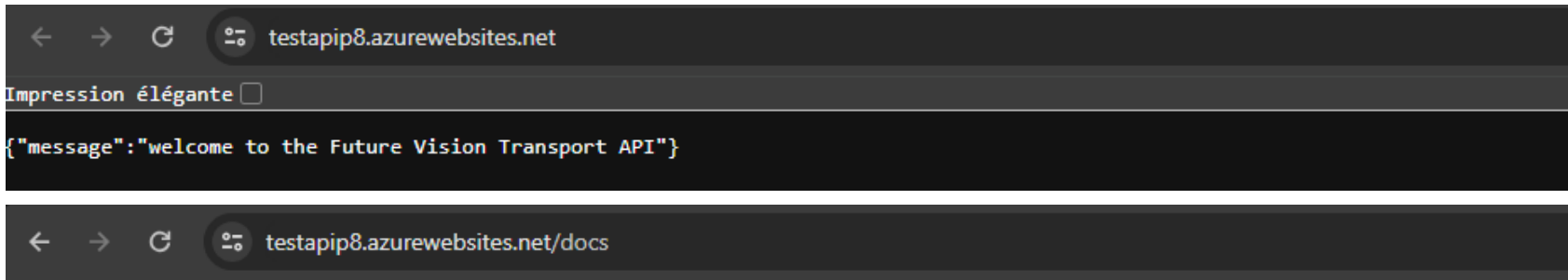
PARTIE 4 – API ET UI

API

- entraîner modèle sur plus de données
- enregistrer  TensorFlow Lite
- `main.py`  FastAPI
- `Dockerfile`  docker
- Construire image docker  docker
- *resource group* 
- *appservice plan* 
- *webapp* 
- Déploiement continu  +  GitHub Actions

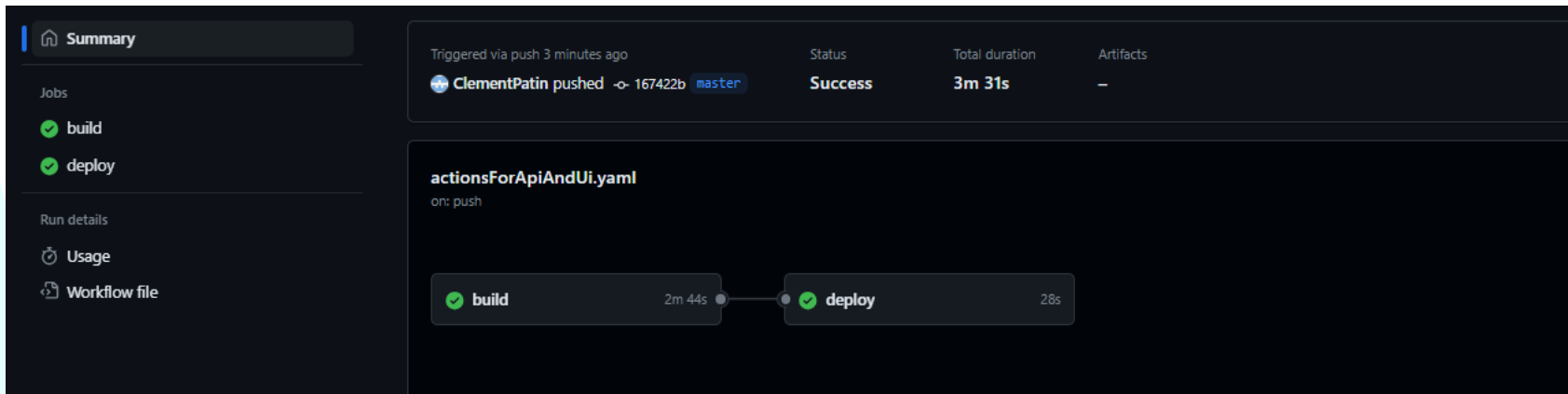
API

API déployée :



FastAPI 0.1.0 OAS 3.1
[/openapi.json](#)









CI/CD:



Fichier YAML  GitHub Actions :

```
! actionsForApiAndUi.yaml
.github > workflows > ! actionsForApiAndUi.yaml
1 name: Build and deploy api and ui containers to Azure Web Apps
2
3 env:
4   AZURE_WEBAPP_NAME_API: testApiP8
5   AZURE_WEBAPP_NAME_UI: testUiP8
6
7 on:
8   push:
9     branches:
10      - master
11
12 permissions:
13   contents: 'read'
14   packages: 'write'
15
16
17
18 jobs:
19   build:
20     runs-on: ubuntu-latest
21
22     steps:
23       - uses: actions/checkout@v4
24
25       - name: Set up Docker Buildx
26         uses: docker/setup-buildx-action@v3
27
28       - name: Log in to GitHub container registry
29         uses: docker/login-action@v3
30         with:
31           registry: ghcr.io
32           username: ${{ github.actor }}
33           password: ${{ secrets.GITHUB_TOKEN }}
34
35       - name: Lowercase the repo name
36         run: echo "REPO=${GITHUB_REPOSITORY,,}" >>${GITHUB_ENV}
37
38       - name: Build and push container image BACKEND to registry
39         uses: docker/build-push-action@v5
40         with:
41           push: true
42           tags: ghcr.io/${env.REPO}:${{ github.sha }}-api
43           context: ./Patin_Clement_2_API_042024
44
45       - name: Build and push container image FRONTEND to registry
46         uses: docker/build-push-action@v5
47         with:
48           push: true
49           tags: ghcr.io/${env.REPO}:${{ github.sha }}-ui
50           context: ./Patin_Clement_3_application_Flask_042024
51
52   deploy:
53     runs-on: ubuntu-latest
54
55     needs: build
56
57     steps:
58       - name: Lowercase the repo name
```

UI

- enregistrer 10 images et 10 masks dans `/static`
- `app.py` / `index.html` / `result.html`  Flask
- Dockerfile  docker
- Construire image docker  docker
- *resource group* 
- *appservice plan* 
- *webapp* 
- Déploiement continu  +  GitHub Actions

UI

app Flask :

```
app.py
Patin_Clement_3_application_Flask_042024 > app.py > ...

8  app = Flask(__name__)
9
10 images_names = [str(i+1) for i in range(10)] # List of image names
11
12 API_URL = "https://testapip8.azurewebsites.net"
13
14 @app.route("/")
15 def index():
16     return render_template("index.html", images_names=images_names)
17
18 @app.route("/show_image/<image_name>")
19 def show_image(image_name):
20     # Validate image name
21     if image_name not in images_names:
22         return "Invalid image name!"
23
24     return render_template("result.html", images_names=images_names)
25
26 @app.route("/predict/<image_name>")
27 def predict(image_name):
28     # check if images are in images
29     if image_name not in images_names:
30         return "Invalid image name!"
31
32     # build url for this image
33     image_path = url_for("static", filename="test_images/"+image_name+".png")
34     mask_path = url_for("static", filename="test_masks/"+image_name+".png")
35
36     # request API
37     headers = {"accept" : "application/json"}
38     files=[
39         ('img',(image_name+".png", open("static/test_images/"+image_name+".png", 'r')
40     ]
41     response = requests.post(url = API_URL+"/predict", headers=headers, files=files)
42
43     # extract image array from response
44     predicted_mask = json.loads(response.json())["mask"]
```

testuip8.azurewebsites.net/predict/1

Future Vision Transport

Testing the image segmentation API

Select an image :

Image 1 Image 2 Image 3 Image 4 Image 5 Image 6 Image 7 Image 8 Image 9 Image 10

Image 1 :



True mask :



Predicted mask :



CONCLUSION

The background image shows a driver's perspective from inside a car. The steering wheel is on the left, and the dashboard features a large, curved digital display. The display shows a navigation map with a highlighted route, a speedometer indicating 46 km/h, and various data visualizations like a bar chart and a line graph. The car is on a multi-lane road with other vehicles visible in the distance. The overall aesthetic is clean and high-tech, representing a vision of autonomous or semi-autonomous driving.

merci