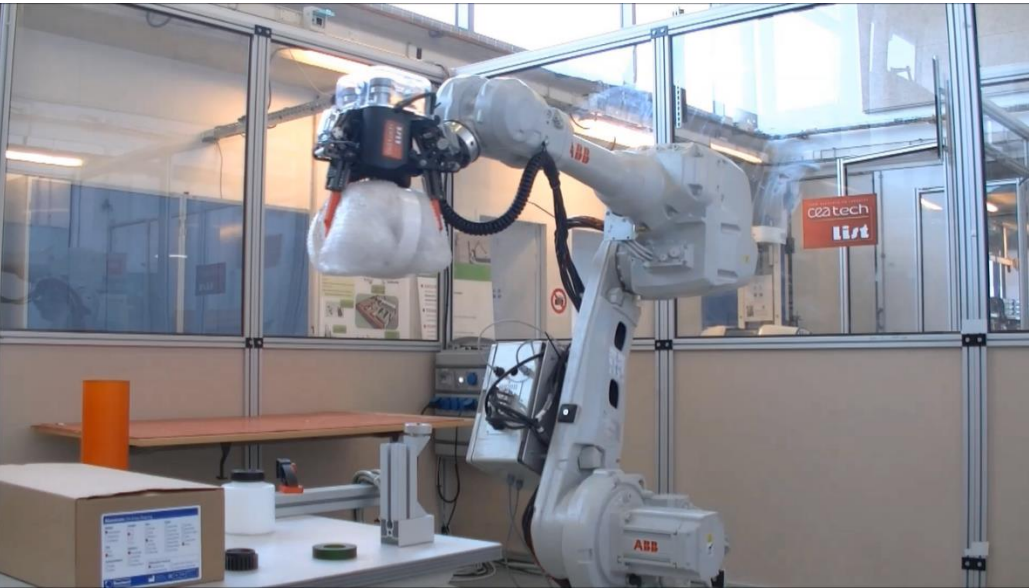


Clément Rolinat, PhD student at CEA (Atomic Energy Commission)



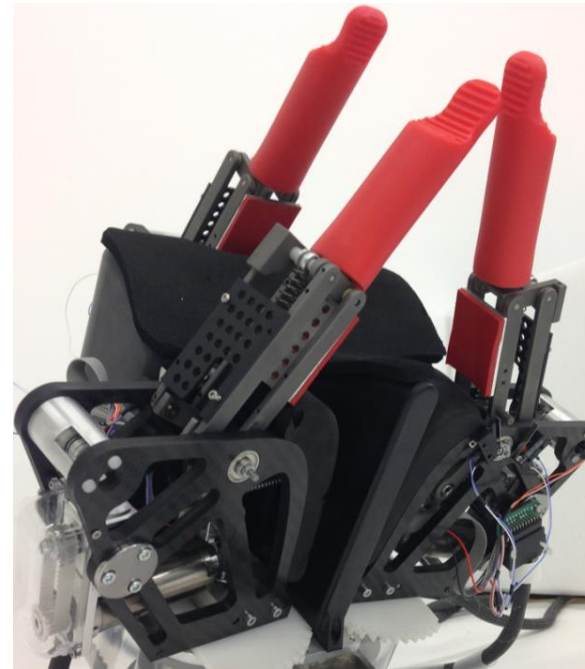
Thesis topic : learning strategies for pluri-digital robotic grasping

Grasping : fundamental task in industrial processes.

Grasp planning algorithm design goal:

- Versatility
- Grasp robustness
- Task compatibility (ex: accessibility)

Hand designed by the CEA
for the European project
H2020 RoMaNS



CEA: French public research institute.

Main research topics:

- Defense
- Renewable, nuclear and low carbon energy
- Technology transfer for industry
- Science of matter and life sciences