A2Q4

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(a)

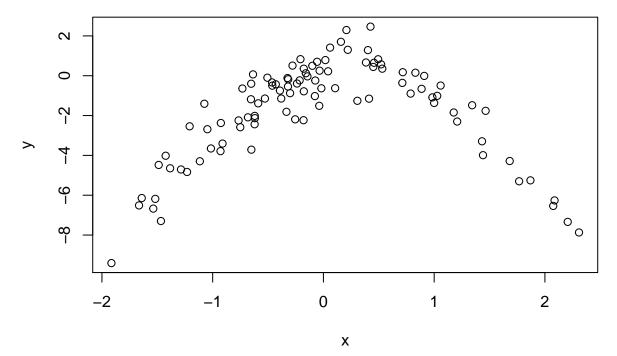
```
set.seed(1)
e = rnorm(100)
x = rnorm(100)
y = x-2*x^2+e
```

Comment: n = 100. p = 1. The equation is: $y = x - 2x^2 + \epsilon$

(b)

```
plot(x, y, main = "y vs x")
```

y vs x



Comment: The plot suggests a quadratic relationship between Y and X since we can see a clear parabolic curve.

(c)

(i)

```
library(boot)
set.seed(1)
data <- data.frame(x, y)</pre>
m1 \leftarrow glm(y\sim x, data = data)
summary(m1)
##
## Call:
## glm(formula = y ~ x, data = data)
## Deviance Residuals:
       Min
                 1Q
                     Median
                                    ЗQ
                                            Max
## -7.1052 -1.0395
                     0.6767
                               1.7058
                                         4.0770
## Coefficients:
               Estimate Std. Error t value Pr(>|t|)
                            0.2456 -7.075 2.25e-10 ***
## (Intercept) -1.7373
## x
                 0.2956
                             0.2575 1.148
                                               0.254
## ---
## Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' 1
## (Dispersion parameter for gaussian family taken to be 6.020807)
       Null deviance: 597.98 on 99 degrees of freedom
## Residual deviance: 590.04 on 98 degrees of freedom
## AIC: 467.29
## Number of Fisher Scoring iterations: 2
cv.glm(data = data, m1)$delta[1]
## [1] 6.351742
(ii)
m2 \leftarrow glm(y\sim poly(x, 2, raw = T), data = data)
summary(m2)
##
## Call:
## glm(formula = y \sim poly(x, 2, raw = T), data = data)
## Deviance Residuals:
##
        Min
                   1Q
                         Median
                                        3Q
                                                 Max
## -2.32473 -0.60440 0.00421
                                 0.58388
                                             2.29127
```

```
##
## Coefficients:
                       Estimate Std. Error t value Pr(>|t|)
##
## (Intercept)
                        0.11081
                                    0.11730
                                            0.945
## poly(x, 2, raw = T)1 0.99981
                                    0.09932 10.066
                                                      <2e-16 ***
## poly(x, 2, raw = T)2 -2.00212
                                    0.08043 -24.892
                                                      <2e-16 ***
## Signif. codes: 0 '***' 0.001 '**' 0.05 '.' 0.1 ' ' 1
##
## (Dispersion parameter for gaussian family taken to be 0.8233896)
##
      Null deviance: 597.976 on 99 degrees of freedom
## Residual deviance: 79.869 on 97 degrees of freedom
## AIC: 269.31
##
## Number of Fisher Scoring iterations: 2
cv.glm(data = data, m2)$delta[1]
## [1] 0.8392001
(iii)
m3 \leftarrow glm(y\sim poly(x, 3, raw = T), data = data)
summary(m3)
##
## Call:
## glm(formula = y \sim poly(x, 3, raw = T), data = data)
##
## Deviance Residuals:
       Min
                  1Q
                        Median
                                       3Q
                                                Max
## -2.25527 -0.62344
                        0.04973
                                  0.51803
                                            2.23692
##
## Coefficients:
##
                        Estimate Std. Error t value Pr(>|t|)
## (Intercept)
                                   0.11784
                                            0.870
                        0.10256
                                                       0.386
## poly(x, 3, raw = T)1 1.14372
                                    0.19403 5.895 5.58e-08 ***
## poly(x, 3, raw = T)2 -1.96707
                                    0.09019 -21.811 < 2e-16 ***
## poly(x, 3, raw = T)3 -0.06382
                                    0.07389 -0.864
                                                       0.390
## ---
## Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' 1
##
## (Dispersion parameter for gaussian family taken to be 0.8255507)
##
      Null deviance: 597.976 on 99 degrees of freedom
## Residual deviance: 79.253 on 96 degrees of freedom
## AIC: 270.54
## Number of Fisher Scoring iterations: 2
```

```
cv.glm(data = data, m3)$delta[1]
## [1] 0.84757
(iv)
m4 \leftarrow glm(y\sim poly(x, 4, raw = T), data = data)
summary(m4)
##
## Call:
## glm(formula = y \sim poly(x, 4, raw = T), data = data)
## Deviance Residuals:
                         Median
##
       Min
                  1Q
                                       3Q
                                                Max
## -2.19661 -0.61381 -0.01333
                                0.52359
                                            2.15799
##
## Coefficients:
##
                        Estimate Std. Error t value Pr(>|t|)
## (Intercept)
                         0.19108 0.13904
                                            1.374
## poly(x, 4, raw = T)1 1.24405
                                    0.21108 5.894 5.73e-08 ***
## poly(x, 4, raw = T)2 -2.24150  0.24704 -9.074 1.58e-14 ***
## poly(x, 4, raw = T)3 -0.13394 0.09429 -1.420
                                                       0.159
## poly(x, 4, raw = T)4 0.08358
                                    0.07006
                                            1.193
                                                       0.236
## ---
## Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' 1
## (Dispersion parameter for gaussian family taken to be 0.8219298)
##
       Null deviance: 597.976 on 99 degrees of freedom
## Residual deviance: 78.083 on 95 degrees of freedom
## AIC: 271.05
## Number of Fisher Scoring iterations: 2
cv.glm(data = data, m4)$delta[1]
## [1] 0.8737288
(d)
(i)
set.seed(3)
e = rnorm(100)
x = rnorm(100)
y = x-2*x^2+e
data <- data.frame(x, y)</pre>
```

```
m1 \leftarrow glm(y\sim x, data = data)
summary(m1)
##
## Call:
## glm(formula = y ~ x, data = data)
## Deviance Residuals:
                        Median
                                      3Q
       Min
                  1Q
                                               Max
## -10.6288 -0.7015 1.0277
                                             4.1024
                                  1.8149
## Coefficients:
              Estimate Std. Error t value Pr(>|t|)
                           0.3065 -7.723 9.85e-12 ***
## (Intercept) -2.3671
                0.3547
                           0.2804
                                    1.265
                                              0.209
## x
## ---
## Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' 1
## (Dispersion parameter for gaussian family taken to be 9.391978)
##
      Null deviance: 935.44 on 99 degrees of freedom
## Residual deviance: 920.41 on 98 degrees of freedom
## AIC: 511.75
##
## Number of Fisher Scoring iterations: 2
cv.glm(data = data, m1)$delta[1]
## [1] 10.05822
(ii)
m2 \leftarrow glm(y\sim poly(x, 2, raw = T), data = data)
summary(m2)
##
## Call:
## glm(formula = y ~ poly(x, 2, raw = T), data = data)
## Deviance Residuals:
                  1Q
                        Median
                                                Max
## -2.19612 -0.74151
                       0.05864
                                0.74586
                                           1.80209
## Coefficients:
                       Estimate Std. Error t value Pr(>|t|)
                       -0.04932 0.10980 -0.449
## (Intercept)
                                                      0.654
## poly(x, 2, raw = T)1 0.93001
                                 0.08041 11.566
                                                      <2e-16 ***
## poly(x, 2, raw = T)2 -1.94839 0.05746 -33.911 <2e-16 ***
## Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' 1
```

```
## (Dispersion parameter for gaussian family taken to be 0.7381454)
##
       Null deviance: 935.44 on 99 degrees of freedom
##
## Residual deviance: 71.60 on 97 degrees of freedom
## AIC: 258.38
## Number of Fisher Scoring iterations: 2
cv.glm(data = data, m2)$delta[1]
## [1] 0.757718
(iii)
m3 \leftarrow glm(y\sim poly(x, 3, raw = T), data = data)
summary(m3)
##
## Call:
## glm(formula = y \sim poly(x, 3, raw = T), data = data)
## Deviance Residuals:
##
       Min
                   1Q
                         Median
                                       3Q
                                                Max
## -2.22225 -0.70730
                        0.05345
                                0.72684
                                            1.78529
##
## Coefficients:
##
                        Estimate Std. Error t value Pr(>|t|)
## (Intercept)
                        -0.06829
                                   0.11206 -0.609
                                                       0.544
## poly(x, 3, raw = T)1 1.03624
                                             7.105 2.11e-10 ***
                                    0.14585
## poly(x, 3, raw = T)2 -1.92285
                                  0.06453 -29.797 < 2e-16 ***
## poly(x, 3, raw = T)3 -0.03614
                                    0.04137 -0.873
                                                       0.385
## ---
## Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' ' 1
## (Dispersion parameter for gaussian family taken to be 0.7399536)
##
       Null deviance: 935.444 on 99 degrees of freedom
## Residual deviance: 71.036 on 96 degrees of freedom
## AIC: 259.59
##
## Number of Fisher Scoring iterations: 2
cv.glm(data = data, m3)$delta[1]
## [1] 0.7592085
(iv)
```

```
m4 \leftarrow glm(y\sim poly(x, 4, raw = T), data = data)
summary(m4)
##
## Call:
   glm(formula = y \sim poly(x, 4, raw = T), data = data)
##
## Deviance Residuals:
##
        Min
                    1Q
                          Median
                                        3Q
                                                  Max
##
  -2.13706
            -0.63797
                         0.02866
                                   0.63651
                                              1.88106
##
  Coefficients:
##
                          Estimate Std. Error t value Pr(>|t|)
                         -0.174582
                                     0.132442
                                                -1.318
## (Intercept)
                                                          0.191
## poly(x, 4, raw = T)1 0.994890
                                     0.147604
                                                 6.740 1.22e-09 ***
## poly(x, 4, raw = T)2 -1.698835
                                     0.164137 -10.350
                                                        < 2e-16 ***
## poly(x, 4, raw = T)3 -0.006862
                                     0.045613
                                                -0.150
                                                          0.881
## poly(x, 4, raw = T)4 -0.045550
                                     0.030722
                                                -1.483
                                                          0.141
##
## Signif. codes: 0 '*** 0.001 '** 0.01 '* 0.05 '.' 0.1 ' 1
##
##
   (Dispersion parameter for gaussian family taken to be 0.7308313)
##
##
       Null deviance: 935.444
                                on 99
                                       degrees of freedom
## Residual deviance:
                       69.429
                                on 95
                                       degrees of freedom
## AIC: 259.3
##
## Number of Fisher Scoring iterations: 2
cv.glm(data = data, m4)$delta[1]
```

[1] 0.7744529

Comments: The MSE in (c) and (d) are different because we set different seeds. However, LOOCV errors of models iii and iv increases in both (c) and (d) comparing to i and ii.

(e)

Since from the cubic term, the LOOCV errors begin to increase. We conclude that the second model in (c) has the smallest LOOCV error. This is expected because we can see a quadratic pattern in scatterplot. Naturally, we will prefer to use quadratic equation to fit the data.

(f)

Yes. From model i and model ii we can see that the p-values of linear and quadratic terms are significant smaller than 0.05. This means that they are statistically significant in the model. When we looking at model iii and iv, we found that both cubic term and fourth power term have p-value greater than 0.05. There is strong evidence that the null hypothesis is prefered. Therefore, cubic term and fourth power term can be eliminated in the model. The results exactly match the conclusion in (e).