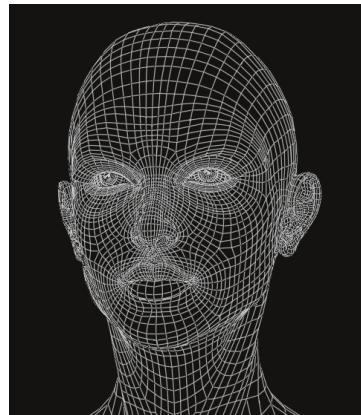
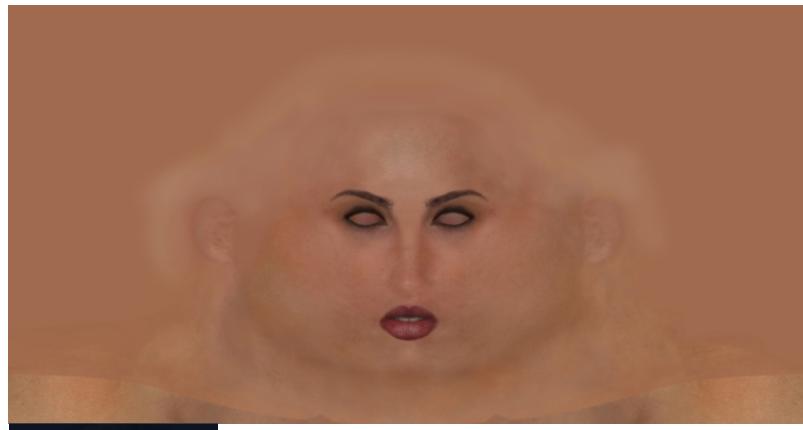


# Texture Mapping

*Pasting textures (2D images) on surfaces*



# Conceptual Steps Involved

## *Texture to Object Mapping*

- User defines where the texture maps onto an object's surface
- In our pipeline this happens at the vertex level

## *Texture to Screen Mapping (through object)*

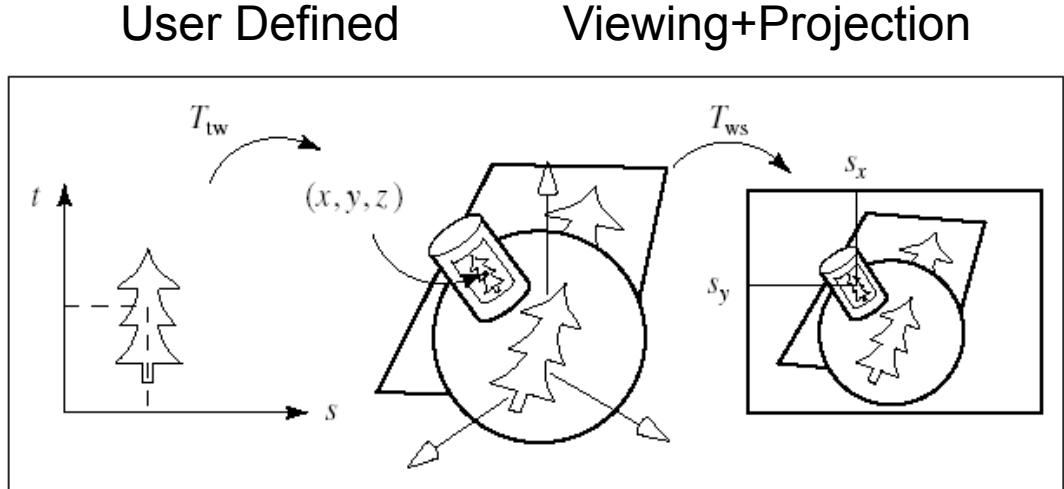
- The rendering system has to project the texture in some way to the screen
- That is, each pixel on the screen has to get the right piece of the texture
- With programmable [Open/Web]GL we can manipulate textures at the fragment level, i.e during the second step

# The two steps as coordinate system transformations

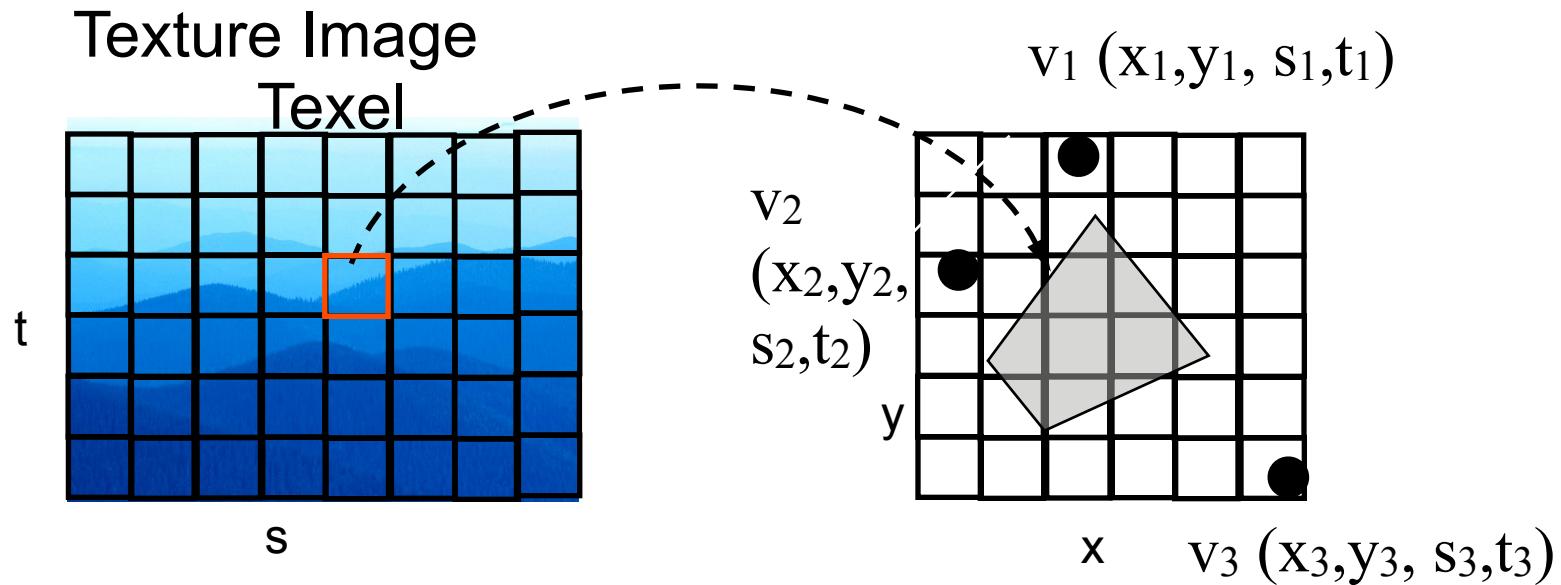
**FIGURE 8.35** Drawing texture on several objects of different shape.

## Systems and transformations involved

- $(s,t)$  : 2D Texture space
- $(s_x, s_y)$  : 2D Screen space 
$$(s_x, s_y) = s T_w(w T_t(s, t))$$
- $s T_w$ : world to screen (viewing and projection)
- $w T_t$ : texture to world



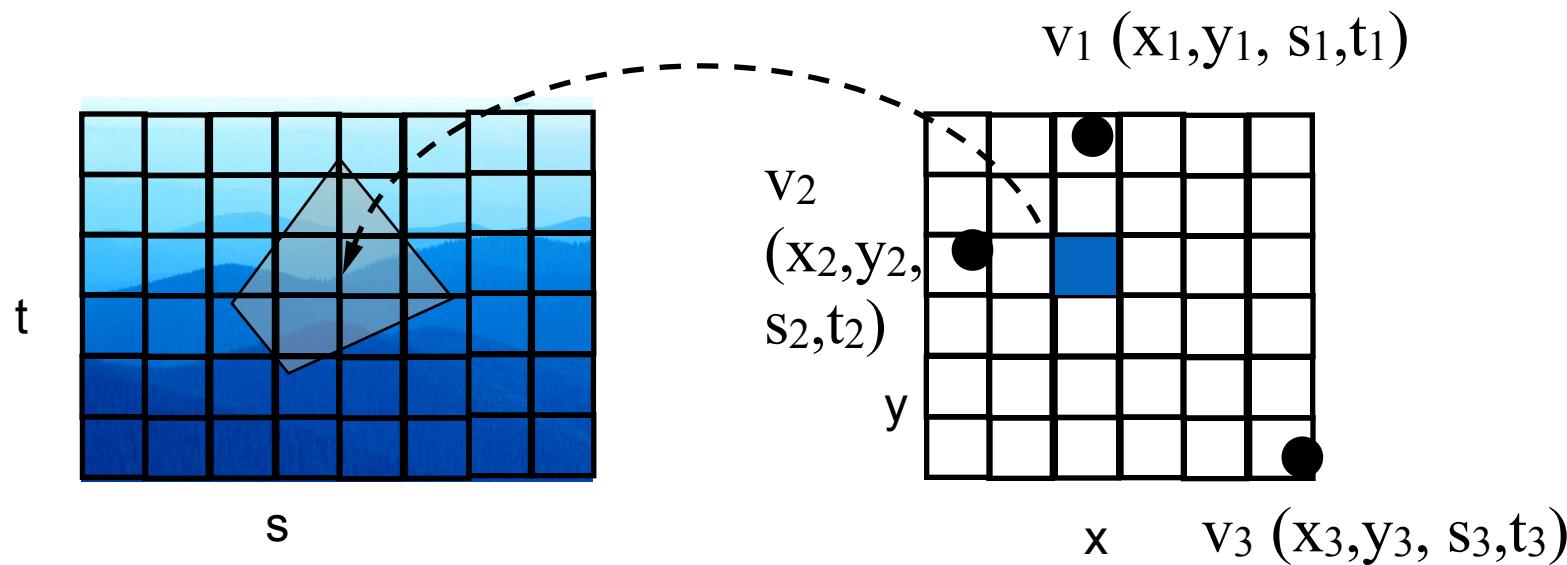
# Approach one: Texture to Screen



$$(s_x, s_y) = {}_s T_w ({}_w T_t(s, t))$$

For each pixel covered by the texture we would have to calculate coverage (overlap)

# Approach two: Screen to texture



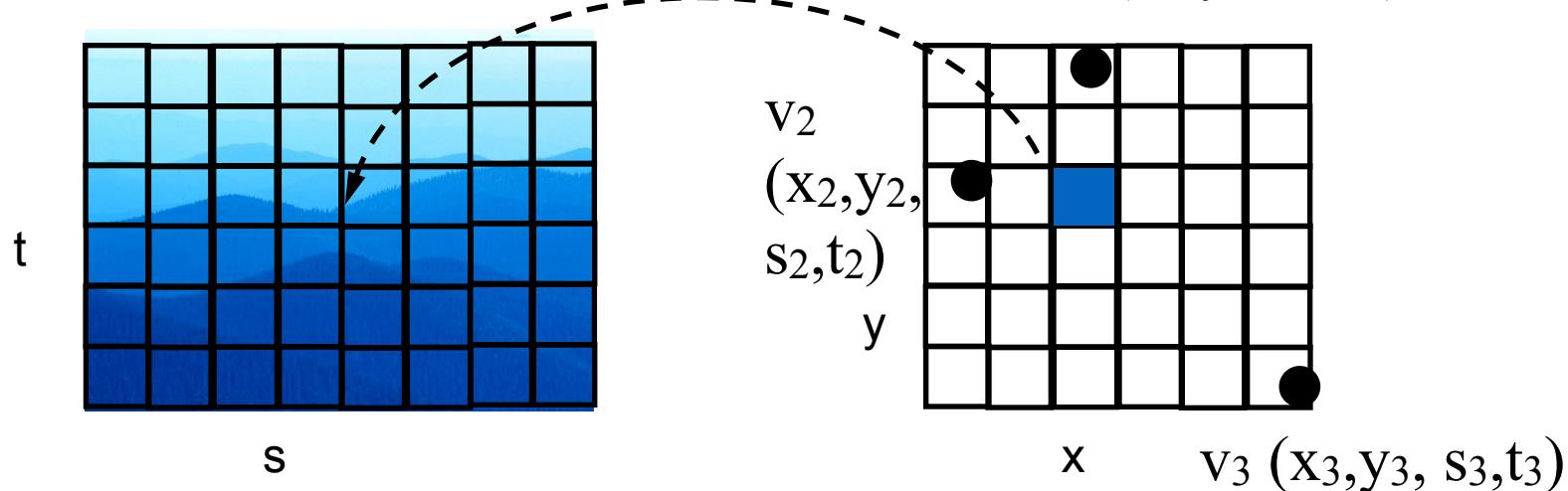
$$(s, t) = {}_t T_w({}_w T_s(s_x, s_y))$$

For each texel covered by the pixel's projection we would have to compute coverage

We also need to invert the projection process

# Web/OpenGL Approach: Screen to texture with mapping sampled at the vertices

*In programmable OpenGL*



For each fragment we compute texture coordinates with which we can fetch texels.

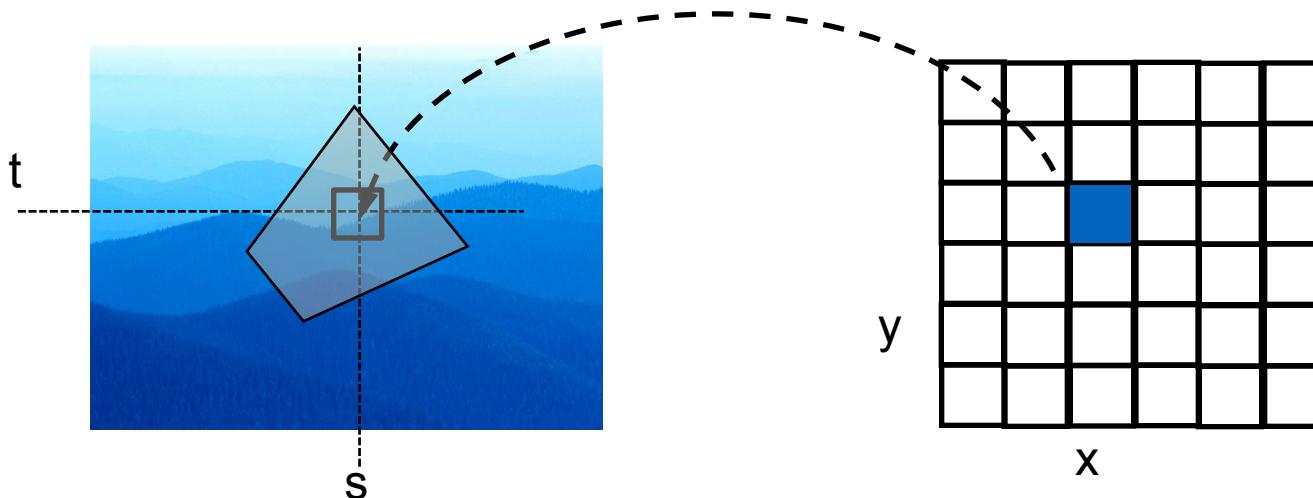
For each fragment we can fetch as many texels as we want (texture lookup). For simple cases, one texture lookup per pixel might be enough.

We keep texture coordinates **per vertex** and the rasterizer **interpolates** them for each fragment  $x, y : (s, t)_{xy} = \text{Interpolate}((s_1, t_1), (s_2, t_2), (s_3, t_3))$  at location  $(x, y)$

Fetching and using a single texel corresponds to what?

# Approach two: Screen to texture

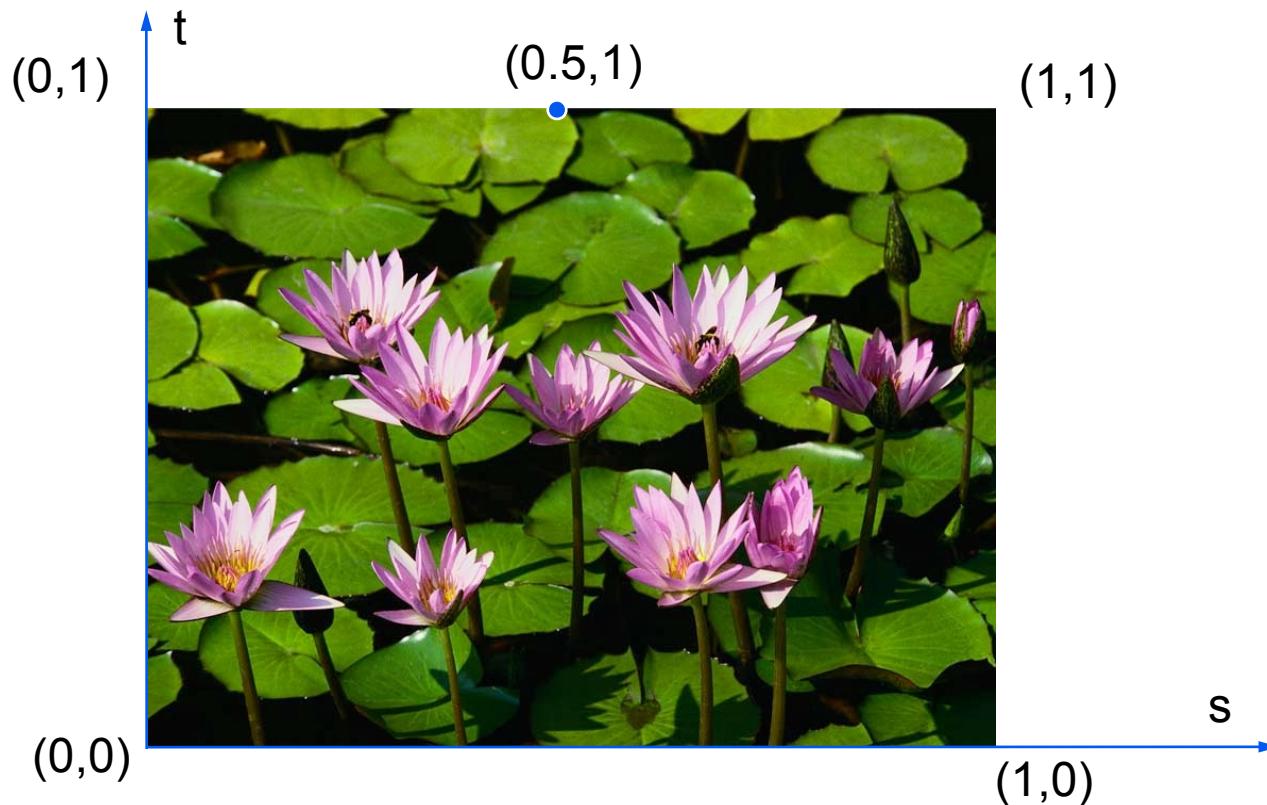
*How do we address texture minification,magnification?*



- Filtering, we will discuss it later

# 2D Textures image abstraction

They are always assigned the shown parametric coordinates (s,t).



# From texture to world (object)

*To apply a texture to an object we have to find a correspondence between  $(s,t)$  and some object coordinate system.*

- Mapping via a parametric representation of the object space (points).
  - By hand.
- 
- Notice: we want to map a 2D image on the surface of the object
  - Most often we need to parametrize the object in 2D

# Mapping from texture to a 2D parametric form of the object space

*Linear transformation*

*Texture space ( $s,t$ ) to object space parameterization ( $u,v$ )*

$$u = u(s,t) = a_u s + b_u t + c_u$$

$$v = v(s,t) = a_v s + b_v t + c_v$$

$s$  in  $[0,1]$

$t$  in  $[0,1]$

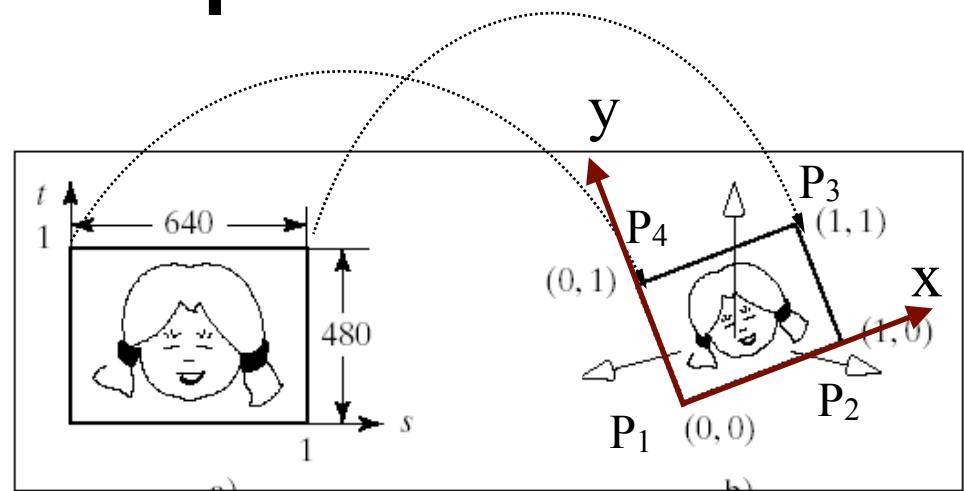
# Example: Image to a quadrilateral

**Choose a convenient  
object 2D system**

Origin  $P_1$

$x$  axis  $P_2-P_1$

$y$  axis  $P_4-P_1$



**Now parameterize it**

A point  $P$  on the object in  $u-v$  coordinates is:

$$P_x(u) = P_{1x}(1-u) + P_{2x}u = P_{1x} + u(P_{2x} - P_{1x})$$

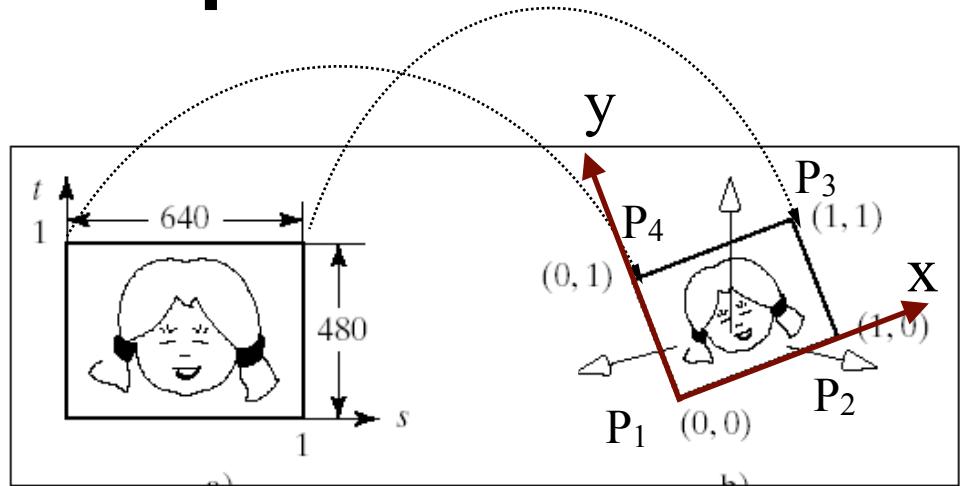
$$P_y(v) = P_{1y}(1-v) + P_{4y}v = P_{1y} + v(P_{4y} - P_{1y})$$

with  $u, v$  in  $[0,1]$

A couple of sanity checks (in  $(P_1, x,y)$  coordinate system) :

$$P(0,0) = P_1, \quad P(1,1) = (P_{2x}, P_{4y}) = P_3, \quad P(1,0) = P_2, \quad P(0,1) = P_4$$

# Example: Image to a quadrilateral



*Then the mapping is simply*

$$u = u(s, t) = s$$

$$v = v(s, t) = t$$

$$s, t \text{ in } [0,1]$$

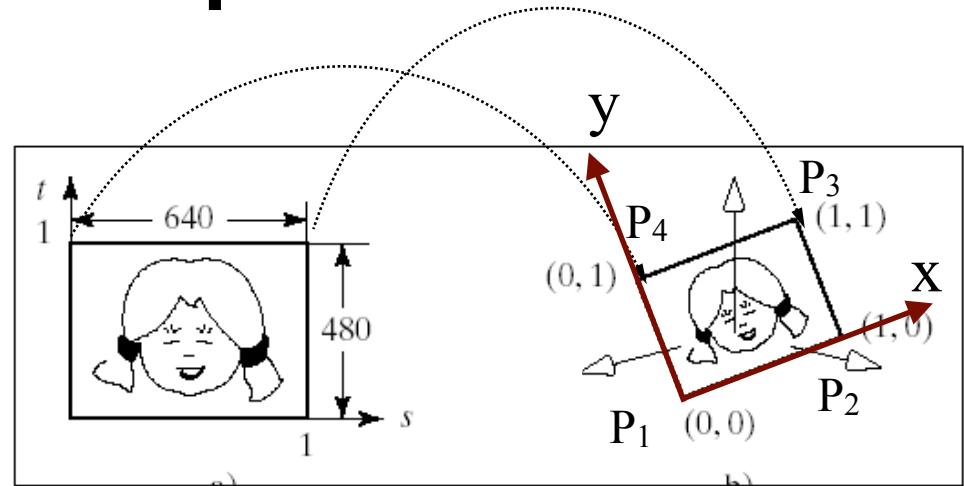
# Example: Image to a quadrilateral

*Then the mapping is  
simply*

$$u = u(s, t) = s$$

$$v = v(s, t) = t$$

$$s, t \text{ in } [0, 1]$$



Using these mapping the vertices are assigned the following texture coordinates as an additional vertex attribute:

$P_1: (0,0)$ ,  $P_2:(1,0)$ ,  $P_3:(1,1)$ ,  $P_4:(0,1)$

For WebGL these four vertices form two triangles. e.g.  
 $(P_1, P_2, P_3)$  and  $(P_1, P_3, P_4)$

## Example 2: Piece of an image to a quadrilateral

**Use only left part**

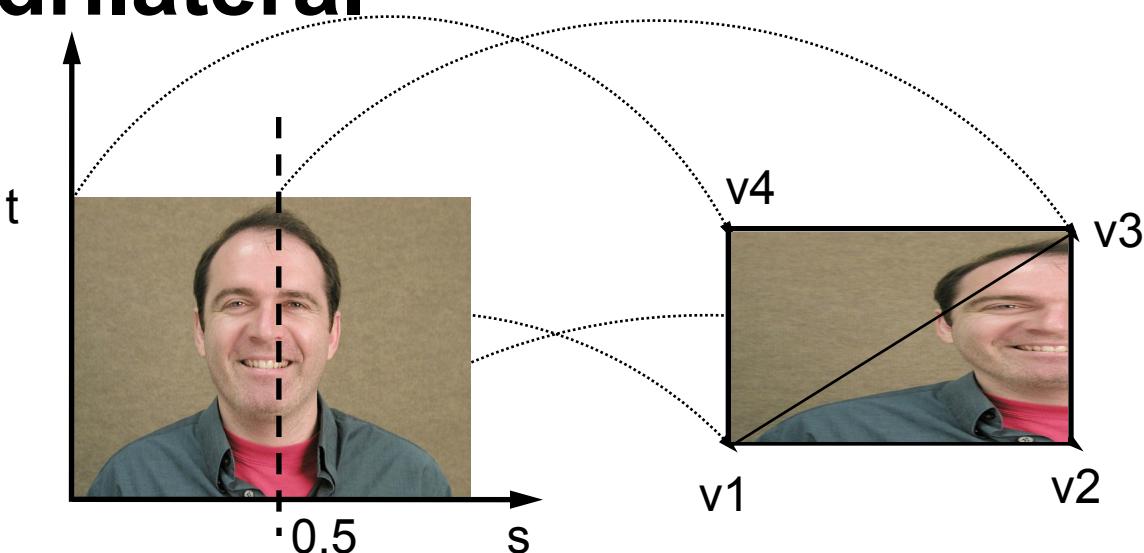
$$s = 0.5u$$

$$t = v$$

$$u, v \text{ in } [0,1]$$

so for

$$v3 = P(u=1, v=1) \text{ the TexCoordinates are } (s, t) = (0.5, 1)$$

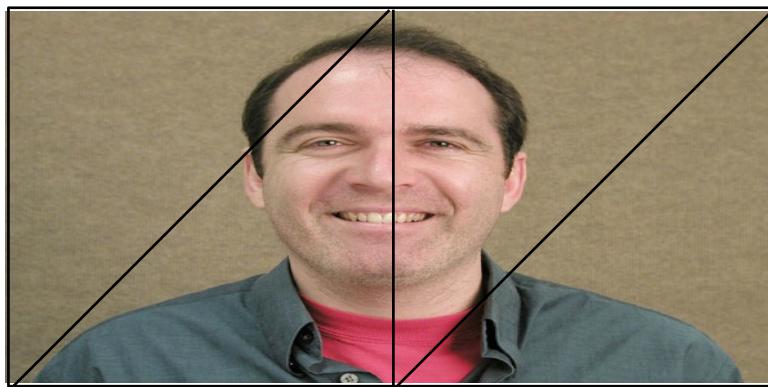
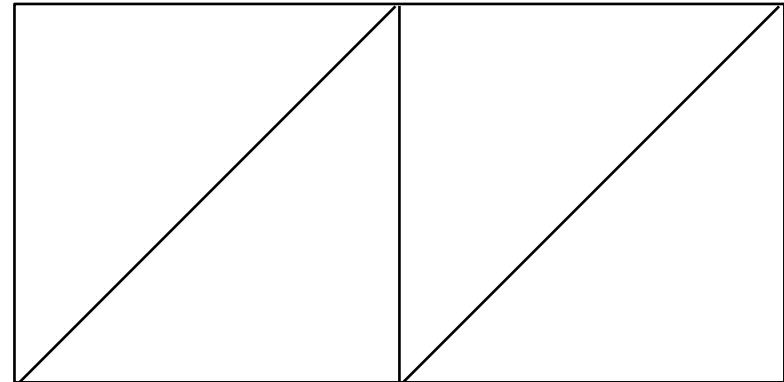


Texture coordinates:

$$V1: (0,0), V2:(0.5,0), V3:(0.5,1), V4:(0,1)$$

# Exercise

- Write out the vertices and the texture coordinates for a quad made out of 4 triangles:



# For non planar objects

## *Similar process*

- Define a mapping
- Sampled it for the vertices

## *Example*

- A quad made of 4 triangles that are not planar but “bent”
- Polygonal representations of curved surfaces (e.g. Sphere)

# Advanced example: 2D Parameterization of a curved surface

## *Parameterizing the Cylinder*

Cylinder has height  $h$ , radius  $r$ , centered at 0

2D parameterization of Object Space

Parametric form :

$$x = r\cos\theta, \quad y = r\sin\theta, \quad z$$

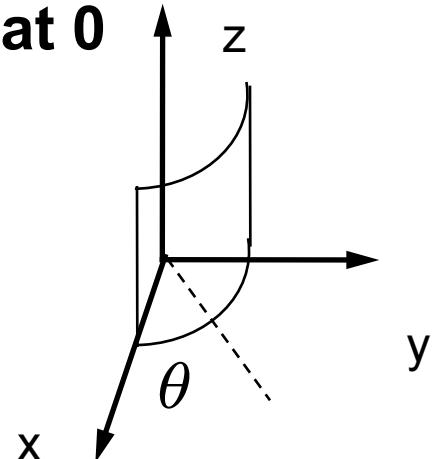
$$\theta \in [0, \pi/2], \quad z \in [0, h]$$

Surface parameters :

$$u = \theta, \quad v = z$$

with

$$0 \leq u \leq \pi/2, \quad 0 \leq v \leq h$$



*In  $(u,v)$  space quarter cylinder is a quad*

# Mapping a square texture to the quarter cylinder

**Now map  $(u, v)$  to  $(s, t)$**

**We chose**

$$(s, t) = (0, 0) \rightarrow (u, v) = (0, 0)$$

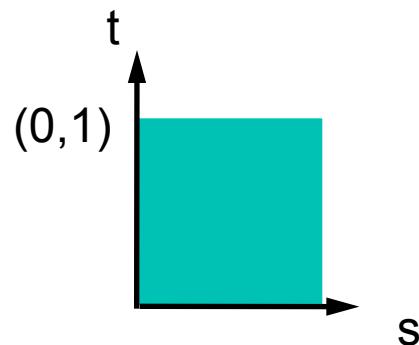
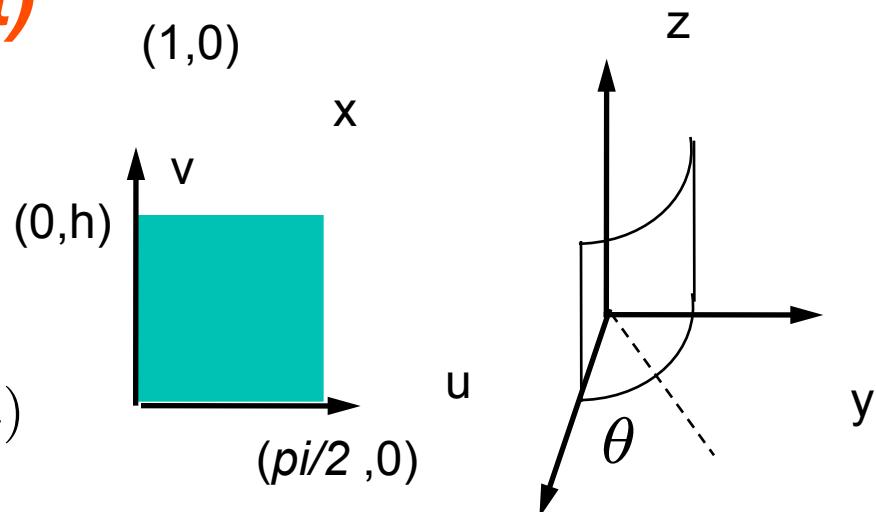
$$(s, t) = (1, 1) \rightarrow (u, v) = (\pi/2, h)$$

that is

$$u = s\pi/2, \quad v = ht$$

or inverted

$$s = 2u/\pi, \quad t = v/h$$



# Example: Wrapping textures on polygonal approximations of curved surfaces

**However, we only have polygons in the graphics pipeline**

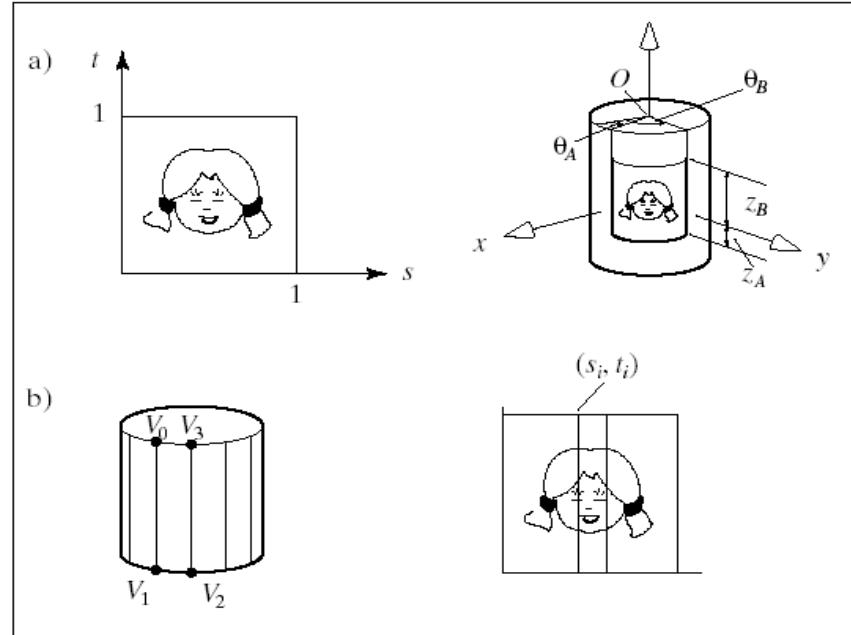
- Tesselate to triangles  
(each quad is two triangles)

$$s = \frac{\theta - \theta_a}{\theta_b - \theta_a}, t = \frac{z - z_a}{z_b - z_a}$$

Cylinder with N faces

Left edge at azimuth  $\theta = 2\pi i / N$

Upper left vertex texture coordinates  $s_i = \frac{2\pi i / N - \theta_a}{\theta_b - \theta_a}, t_i = 1.$



# How does that work with the graphics pipeline?

***Only vertices go down the graphics pipeline.***

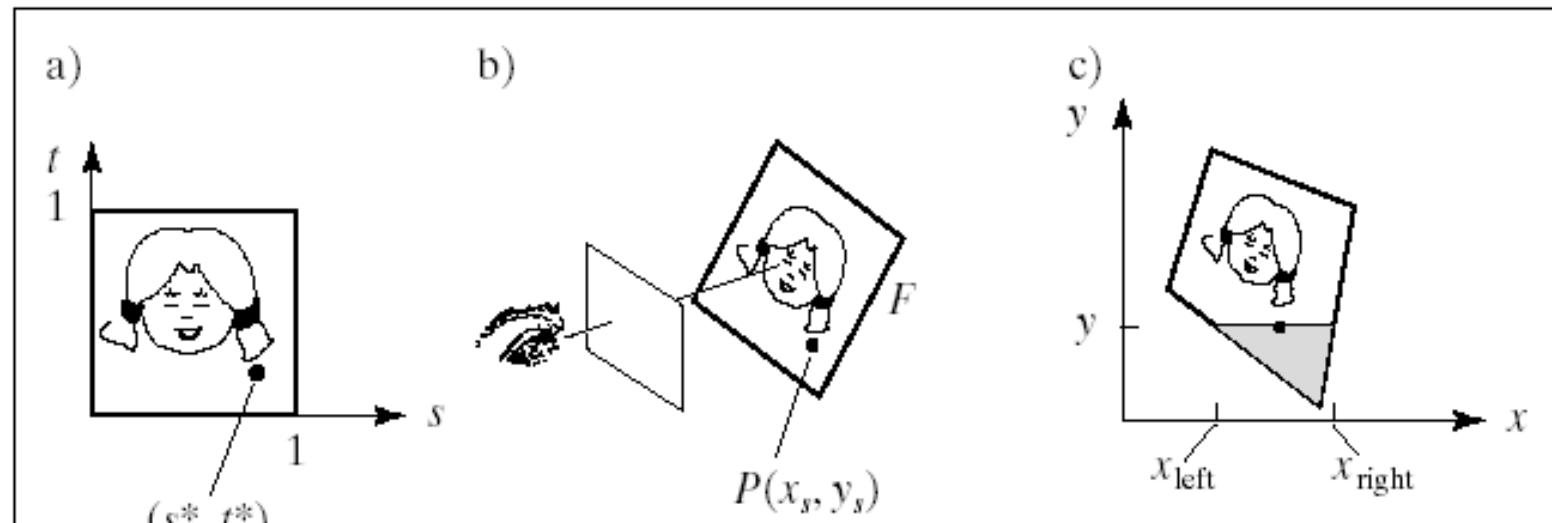
Texture coordinates for interior points of polygons?

*Calculate texture coordinates by interpolation along scanlines.*

# Rendering the texture

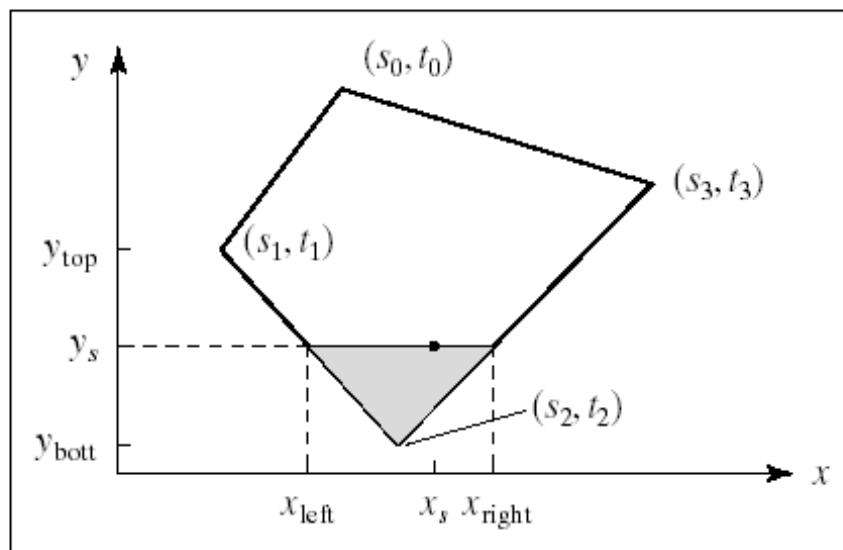
## *Scanline in screen space*

- Generating s,t coordinates for each pixel



**FIGURE 8.39** Rendering a face in a camera snapshot.

# Interpolation of texture coordinates

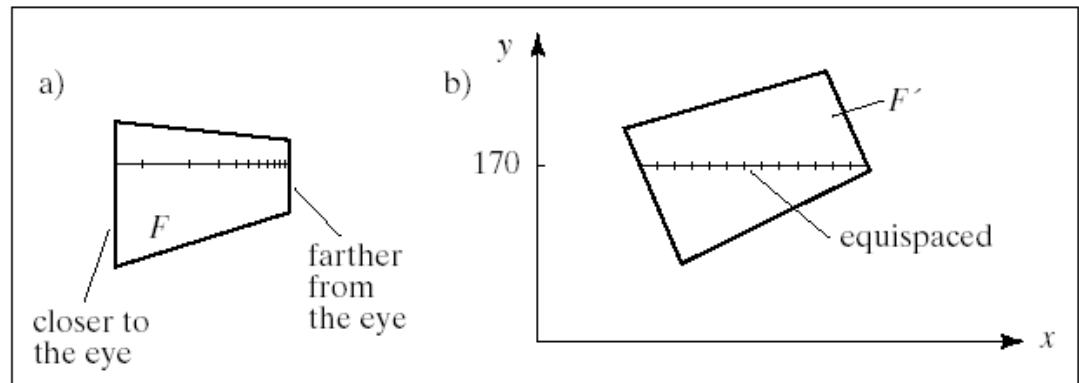
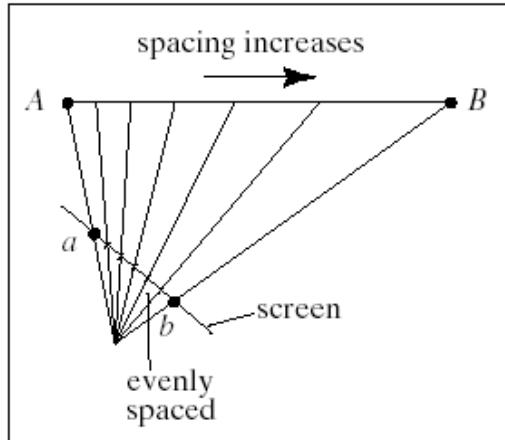


**FIGURE 8.40** Incremental calculation of texture coordinates.

# Problem

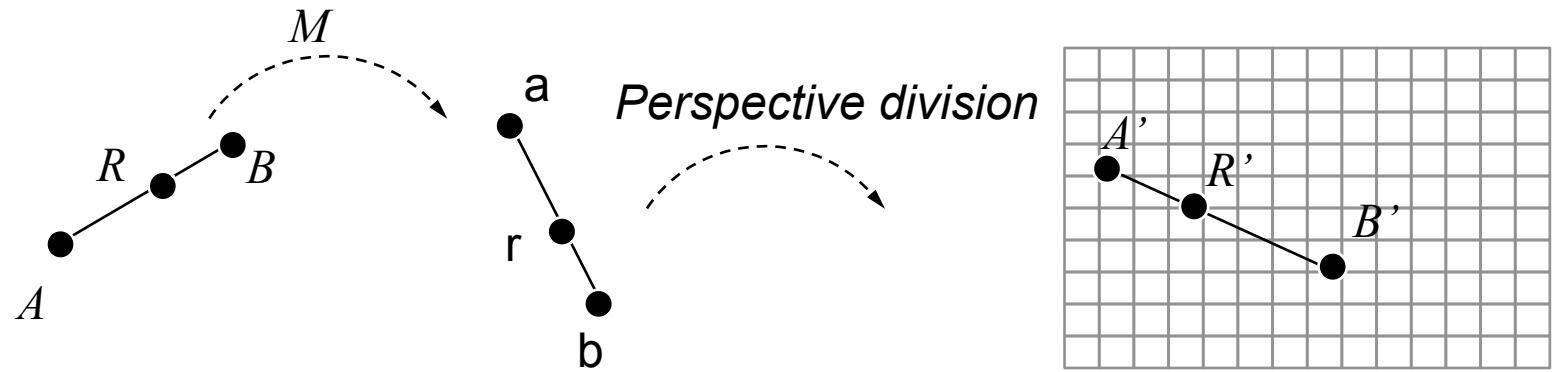
## Perspective foreshortening

- Scanconversion takes equal steps along scanline (screen space), specifically by 1 i.e.  $x, x + 1, x+2, \dots$
- Equal steps in screen space are not equal steps in world space



**FIGURE 8.41** Spacing of samples with linear interpolation.

# Reminder: Inbetween points



$$R(g) = (1 - g)A + gB, \quad g \in \mathbb{R}$$

$r = MR$ , where  $M$  is a WebGL perspective transformation

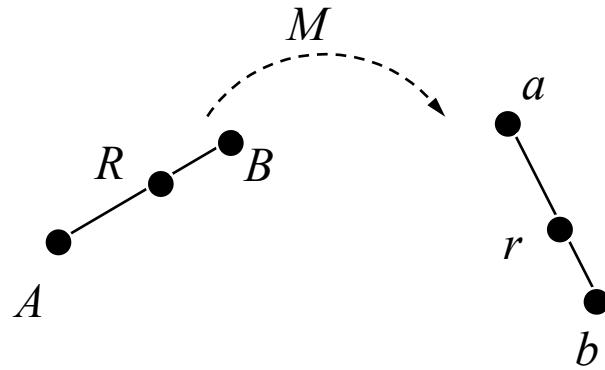
After perspective division (NDCS):

$$R'(f) = (1 - f)A' + fB', \quad f \in \mathbb{R}$$

How do  $g, f$  relate?

# First step

*Viewing to homogeneous space (4D)*



$$R = (1 - g)A + gB$$

$$r = MR = M[(1 - g)A + gB] = (1 - g)MA + gMB \Rightarrow$$

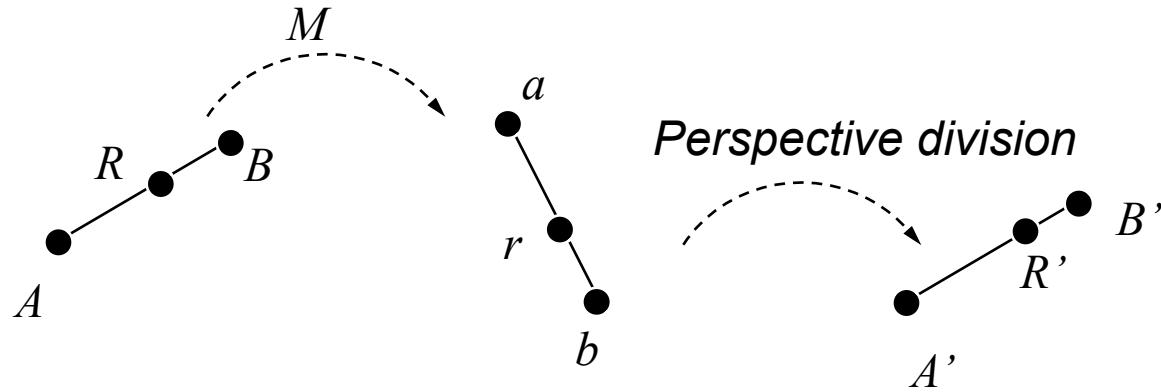
$$r = (1 - g)a + gb$$

$$a = MA = (a_1, a_2, a_3, a_4)$$

$$b = MB = (b_1, b_2, b_3, b_4)$$

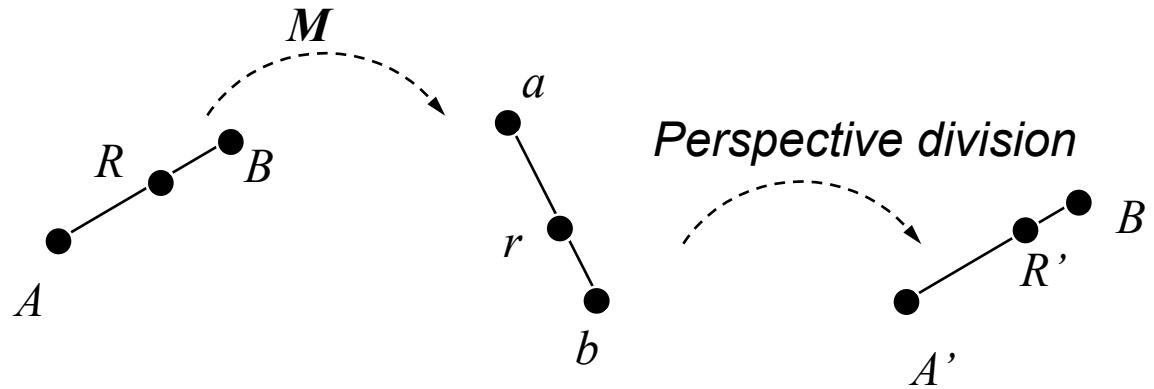
# Second step

## Perspective division



$$\left. \begin{array}{l} r = (1 - g)a + gb \\ r = (r_1, r_2, r_3, r_4) \\ a = (a_1, a_2, a_3, a_4) \\ b = (b_1, b_2, b_3, b_4) \end{array} \right\} \rightarrow R'_1 = \frac{r_1}{r_4} = \frac{(1 - g)a_1 + gb_1}{(1 - g)a_4 + gb_4}$$

# Putting all together



$$R'_1 = \frac{(1-g)a_1 + gb_1}{(1-g)a_4 + gb_4} = \frac{\text{lerp}(a_1, b_1, g)}{\text{lerp}(a_4, b_4, g)}$$

At the same time :

$$R' = (1-f)A' + fB' \Rightarrow R'_1 = (1-f)A'_1 + fB'_1$$

$$R'_1 = (1-f)\frac{a_1}{a_4} + f\frac{b_1}{b_4} = \text{lerp}\left(\frac{a_1}{a_4}, \frac{b_1}{b_4}, f\right)$$

}

# Relation between the fractions

$$\left. \begin{array}{l} R'_1(g) = \frac{\text{lerp}(a_1, b_1, g)}{\text{lerp}(a_4, b_4, g)} \\ R'_1(f) = \text{lerp}\left(\frac{a_1}{a_4}, \frac{b_1}{b_4}, f\right) \end{array} \right\} \rightarrow g = \frac{f}{\text{lerp}\left(\frac{b_4}{a_4}, 1, f\right)}$$

substituting this in  $R(g) = (1 - g)A + gB$  yields

$$R_1 = \frac{\text{lerp}\left(\frac{A_1}{a_4}, \frac{B_1}{b_4}, f\right)}{\text{lerp}\left(\frac{1}{a_4}, \frac{1}{b_4}, f\right)}$$

**THAT MEANS:** For a given  $f$  in **screen space** and  $A, B$  in **viewing space** we can find the corresponding  $R$  (or  $g$ ) in **viewing space** using the above formula.

“A,B” can be texture coordinates, position, color, normal etc.

# Rendering images incrementally

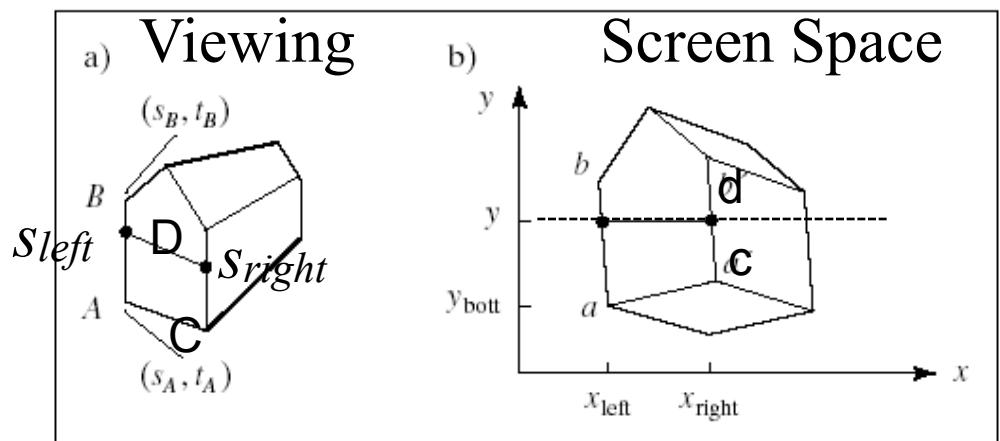
*A maps to a (homogeneous)*

*B maps to b*

*C maps to c*

*D maps to d*

*For scanline y and two edges:*



$f_{edge} = (y - y_{bott}) / (y_{top} - y_{bott})$  so for the left and right edges :

$$s_{left}(y) = \frac{lerp\left(\frac{s_A}{a_4}, \frac{s_B}{b_4}, f_l\right)}{lerp\left(\frac{1}{a_4}, \frac{1}{b_4}, f_l\right)}, s_{right}(y) = \frac{lerp\left(\frac{s_C}{c_4}, \frac{s_D}{d_4}, f_r\right)}{lerp\left(\frac{1}{c_4}, \frac{1}{d_4}, f_r\right)}$$

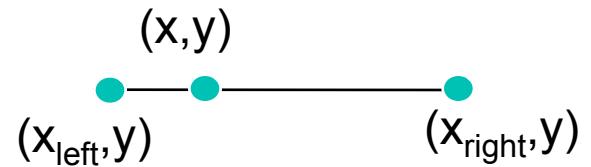
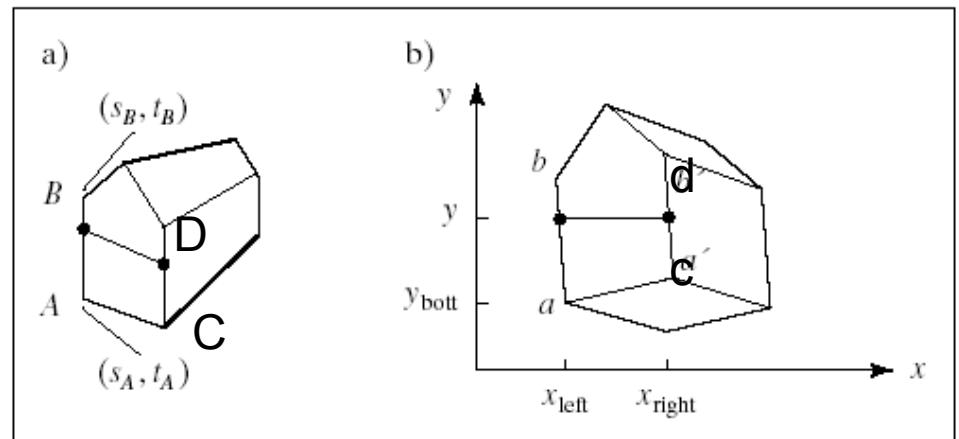
*Once we have  $s_{left}$  and  $s_{right}$  another hyperbolic interpolation fills in the scanline*

# Interpolation along the scanline

$$s_{left}(y) = \frac{lerp(\frac{s_A}{a_4}, \frac{s_B}{b_4}, f_l)}{lerp(\frac{1}{a_4}, \frac{1}{b_4}, f_l)},$$

$$s_{right}(y) = \frac{lerp(\frac{s_C}{c_4}, \frac{s_D}{d_4}, f_r)}{lerp(\frac{1}{c_4}, \frac{1}{d_4}, f_r)}$$

$$s(x, y) = \frac{lerp(\frac{s_{left}}{h_{left}}, \frac{s_{right}}{h_{right}}, f)}{lerp(\frac{1}{h_{left}}, \frac{1}{h_{right}}, f)}$$



What are the f, and h's?

# Interpolation along the scanline

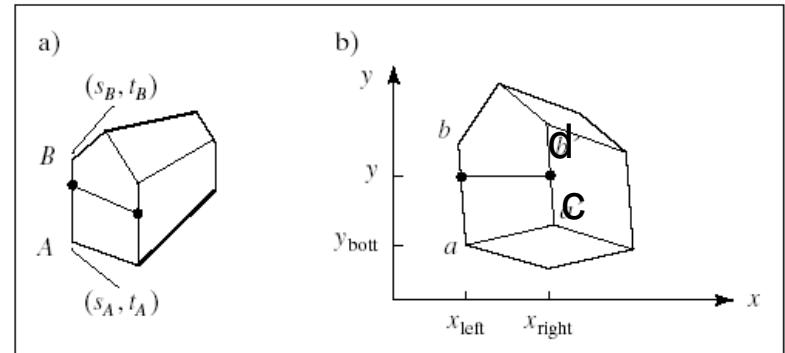
$$s_{left}(y) = \frac{lerp(\frac{s_A}{a_4}, \frac{s_B}{b_4}, f_l)}{lerp(\frac{1}{a_4}, \frac{1}{b_4}, f_l)}, s_{right}(y) = \frac{lerp(\frac{s_C}{c_4}, \frac{s_D}{d_4}, f_r)}{lerp(\frac{1}{c_4}, \frac{1}{d_4}, f_r)}$$

$$s(x, y) = \frac{lerp(\frac{s_{left}}{h_{left}}, \frac{s_{right}}{h_{right}}, f)}{lerp(\frac{1}{h_{left}}, \frac{1}{h_{right}}, f)}$$

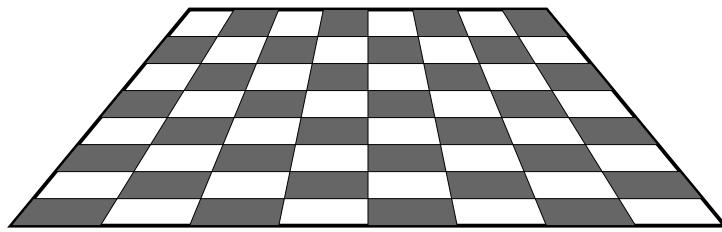
$$h_{left} = lerp(a_4, b_4, f_l)$$

$$h_{right} = lerp(c_4, d_4, f_r)$$

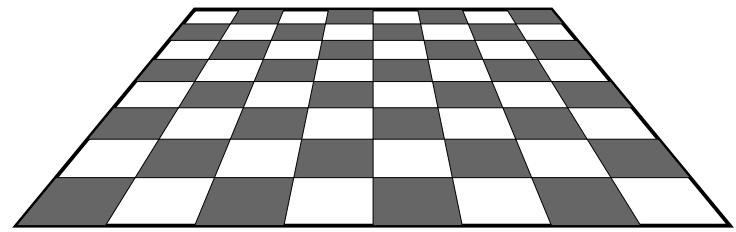
$$f = (x - x_{left}) / (x_{right} - x_{left})$$



# Example: Checkerboard image on a flat quad in the x-y plane



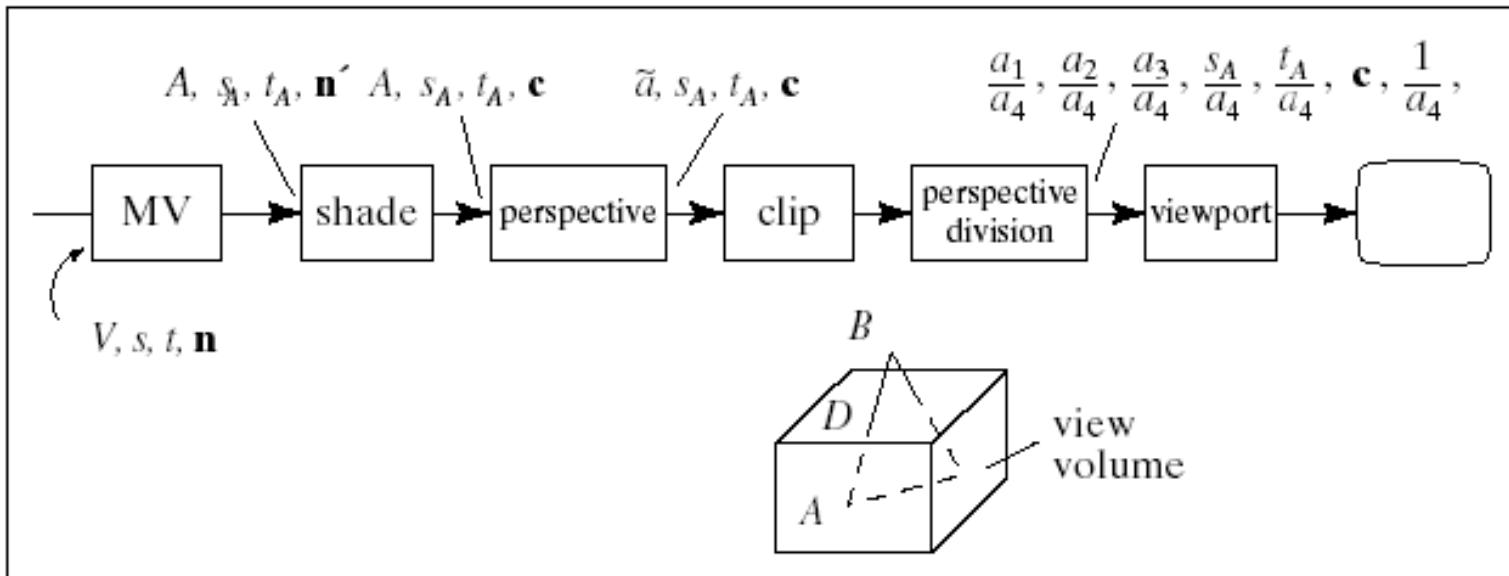
Without hyperbolic interpolation



With hyperbolic interpolation

- Left would be correct for a trapezoid that is parallel to the image plane
- You can think of it as follows:  
Linear interpolation pastes the image on the projected object, hyperbolic pastes the image on the object before the projection

# Pipeline with hyperbolic interpolation



# What does the texture do?

***Textures are accessed in the fragment shader***

- `vec4 texColor = texture(texID, vec2(TexCoord)) ;`
- and we can do what we like them ( assign them as the fragment's color, blended them with other values, anything)

# Texture mapping in WebGL

## *Creating a texture*

```
void gl.texImage2D(  
    GLenum target,    // must be GL_TEXTURE_2D  
    GLint level,  
    GLint internalformat, // e.g. GL_RGB  
    GLsizei width,  
    GLsizei height,  
    GLint border,  
    GLenum format,    // e.g. GL_RGB  
    GLenum type,      // e.g. GL_UNSIGNED_BYTE  
    const GLvoid *pixels // size powers of 2 !!  
);
```

The diagram consists of two black arrows originating from the 'internalformat' and 'format' parameters in the code snippet. Both arrows point towards the bolded text 'MUST MATCH!!' located on the right side of the slide.

Need to load an image. Various libraries exist for that

# Textures Have Many Parameters

*Dealing with out of range tex coordinates*

```
void gl.texParameterf(  
    GLenum target,          // e.g. gl.TEXTURE_2D  
    GLenum pname,           // gl.WRAP_S  
    GLint param             // value e.g. gl.CLAMP  
);
```

e.g.

```
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_S,  
gl.REPEAT);  
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_T,  
gl.REPEAT);
```

# Wrapping/Clamping

CLAMP: If  $s, t > 1.0$  then  $s, t = 1.0$  if  $s, t < -1.0$  then  $s, t = 0$

WRAP: modulo 1.0

```
glBindTexture(GL_TEXTURE_2D, gTexIDs[0]);
```

```
// TexCoord repetition or clamping
```

```
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_S, gl.REPEAT);  
gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_T, gl.REPEAT);
```



GL\_REPEAT



GL\_MIRRORED\_REPEAT



GL\_CLAMP\_TO\_EDGE



GL\_CLAMP\_TO\_BORDER

*Image courtesy of open.gl*

# Texture filtering

***Texture images consist of pixels (texels)***

***Therefore:***

- *Magnification*: a pixel on the screen covers only part of a texel ( a texel stretches to cover multiple pixels)
- *Minification*: a pixel on the screen covers more than one texels ( a texel is squeezed to fit in an area smaller than a pixel)

***Solution: Filtering***

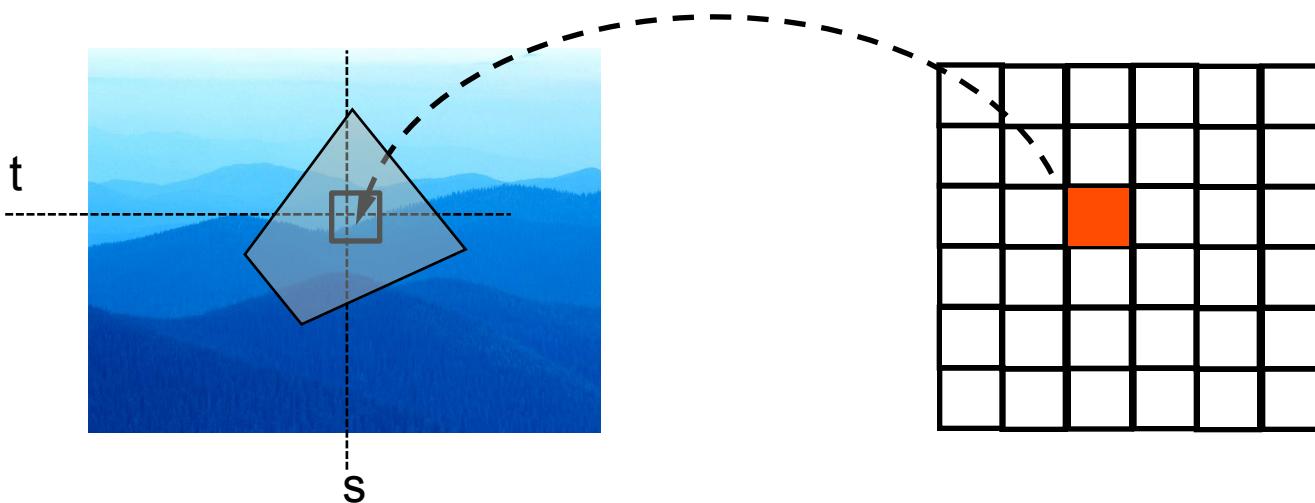
# Texture filtering in OpenGL

```
gl.texParameteri(gl.TEXTURE_2D,  
gl.TEXTURE_MAG_FILTER, gl.NEAREST) ;  
gl.texParameteri(gl.TEXTURE_2D,  
gl.TEXTURE_MIN_FILTER, GL_NEAREST) ;
```

gl.TEXTURE\_MAG\_FILTER: gl.NEAREST or gl.LINEAR  
gl.TEXTURE\_MIN\_FILTER: gl.NEAREST, gl.LINEAR,  
                          gl.NEAREST\_MIPMAP\_NEAREST,  
                          gl.LINEAR\_MIPMAP\_NEAREST,  
                          gl.LINEAR\_MIPMAP\_LINEAR,

# Filtering textures

***Addresses texture minification,magnification***



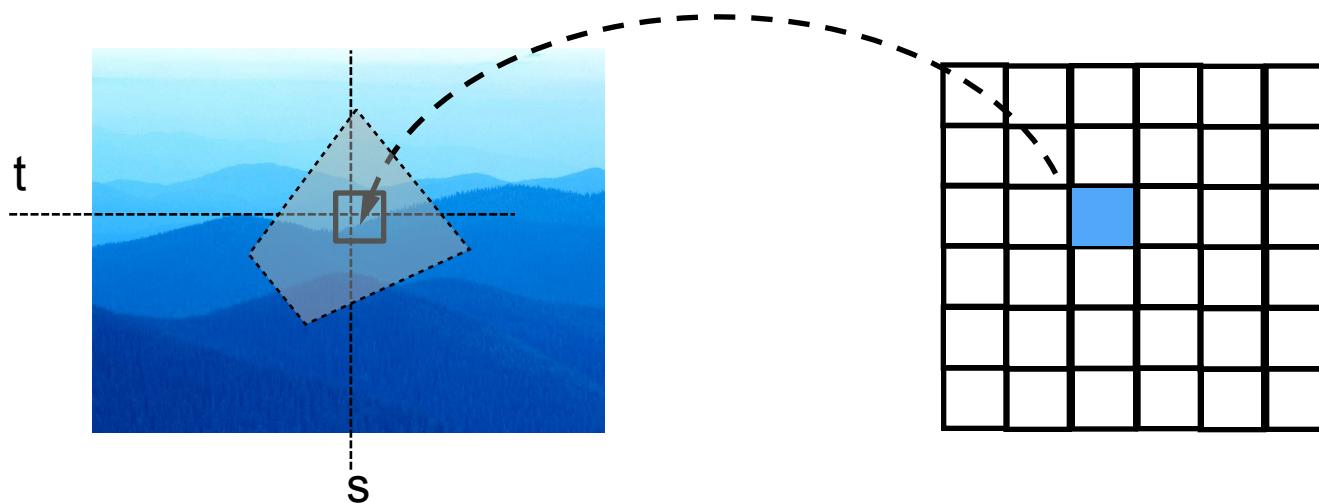
- `vec4 texColor = texture(s,t)` returns what really?

# FILTERING

- gl.NEAREST: no filtering, return the texture element closest ( in Manhattan distance) to the texture coordinates provided
- gl.LINEAR: Returns the weighted average of the four texture elements that are closest to the texture coordinates provided

# Filtering textures

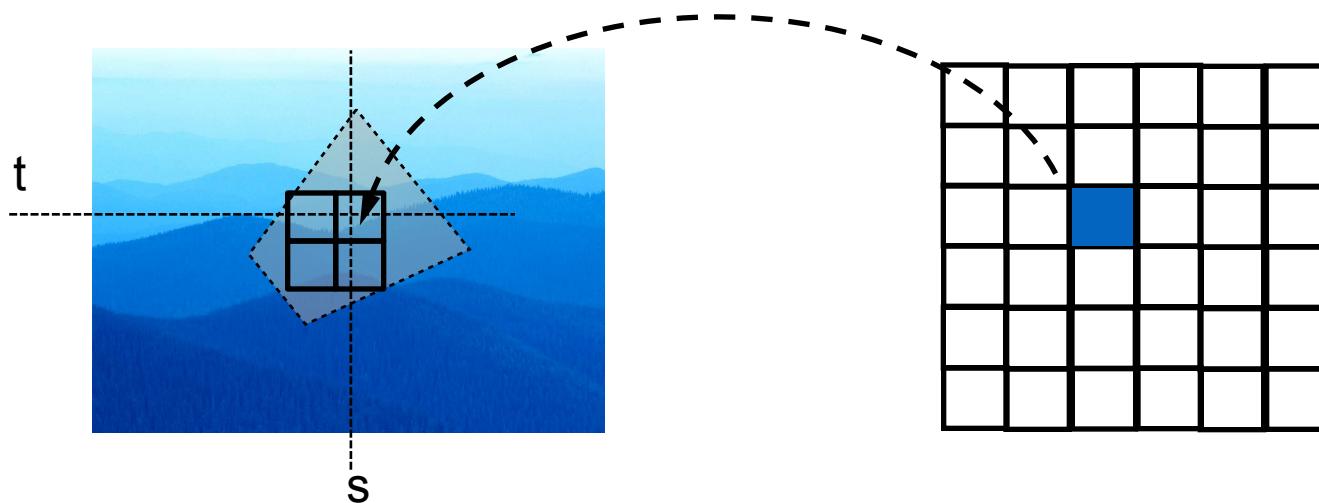
***Addresses texture minification,magnification***



- `vec4 texColor = texture(s,t)` returns what?
- Nearest: returns the color a single pixel square

# Filtering textures

***Addresses texture minification,magnification***



- `vec4 texColor = texture(s,t)` returns what ?
- Linear: returns the average of the nearest four texels
- They capture better how the pixel actually covers texels



The University of New Mexico

# Mipmapped Textures

---

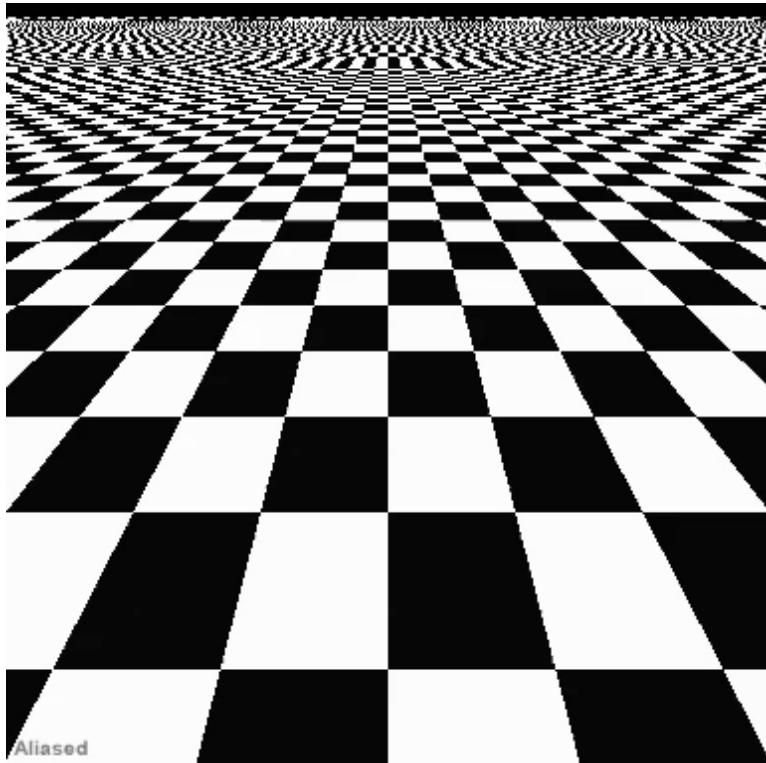
- *Mipmapping* allows for prefiltered texture maps of decreasing resolutions
- Lessens interpolation errors for smaller textured objects
- Declare mipmap level during texture definition  
`gl.texImage2D(gl.TEXTURE_2D, level, ...)`



The University of New Mexico

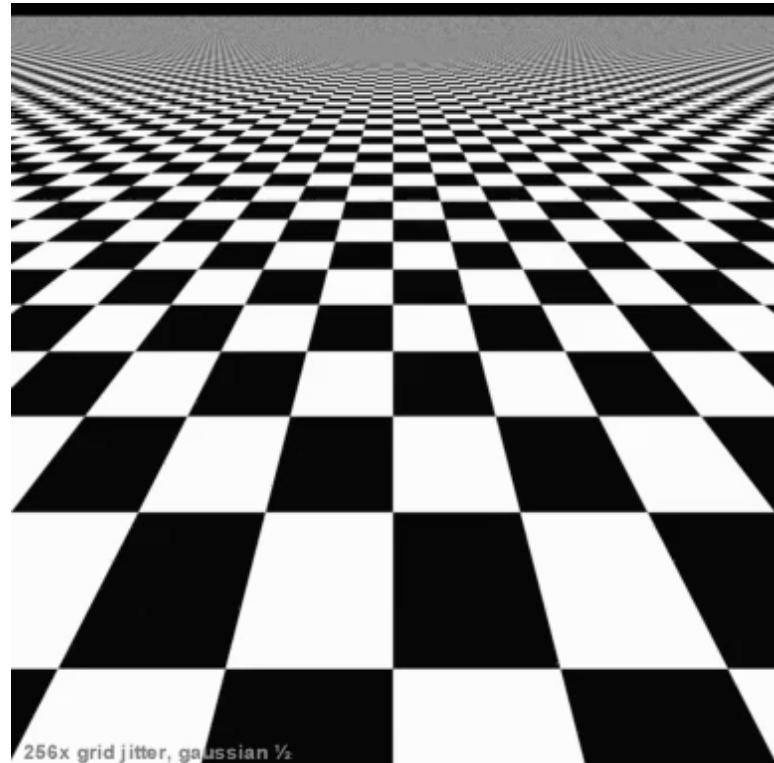
# Example

point sampling



Aliased

256 Grid jitter sampling



256x grid jitter, gaussian  $\frac{1}{2}$

# Texture Coordinate Transforms

*Texture coordinates are, in fact, 2D coordinates in texture space and they can be transformed with affine transformations*

# Texture Objects

***Copying an image from main memory to video memory is very expensive (`gl.texImage2D`) .***

- *Create texture names*
- *Bind (create) texture objects to texture data:*
  - **Image arrays + texture properties**
- *Bind and rebind texture objects.*

# Texture Object Creation

```
function loadFileTexture(tex, filename)
{
    tex.textureWebGL = gl.createTexture();
    tex.image = new Image();
    tex.image.src = filename ;
    tex.isTextureReady = false ;
    tex.image.onload = function()
        { handleTextureLoaded(tex);} ;
// The image is going to be loaded asynchronously (lazy) which
could be
// after the program continues to the next functions.
OUCH!
}
```

# Texture Object Creation

```
function handleTextureLoaded(textureObj) {  
    gl.bindTexture(gl.TEXTURE_2D, textureObj.textureWebGL);  
    gl.texImage2D(gl.TEXTURE_2D, 0, gl.RGBA, gl.RGBA,  
                 gl.UNSIGNED_BYTE, textureObj.image);  
    gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_MAG_FILTER,  
                    gl.LINEAR);  
    gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_MIN_FILTER,  
                    gl.LINEAR_MIPMAP_NEAREST);  
    gl.generateMipmap(gl.TEXTURE_2D);  
    gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_S,  
                    gl.CLAMP_TO_EDGE); //Prevents s-coordinate wrapping  
    gl.texParameteri(gl.TEXTURE_2D, gl.TEXTURE_WRAP_T,  
                    gl.CLAMP_TO_EDGE); //Prevents t-coordinate wrapping  
    gl.bindTexture(gl.TEXTURE_2D, null);  
}
```

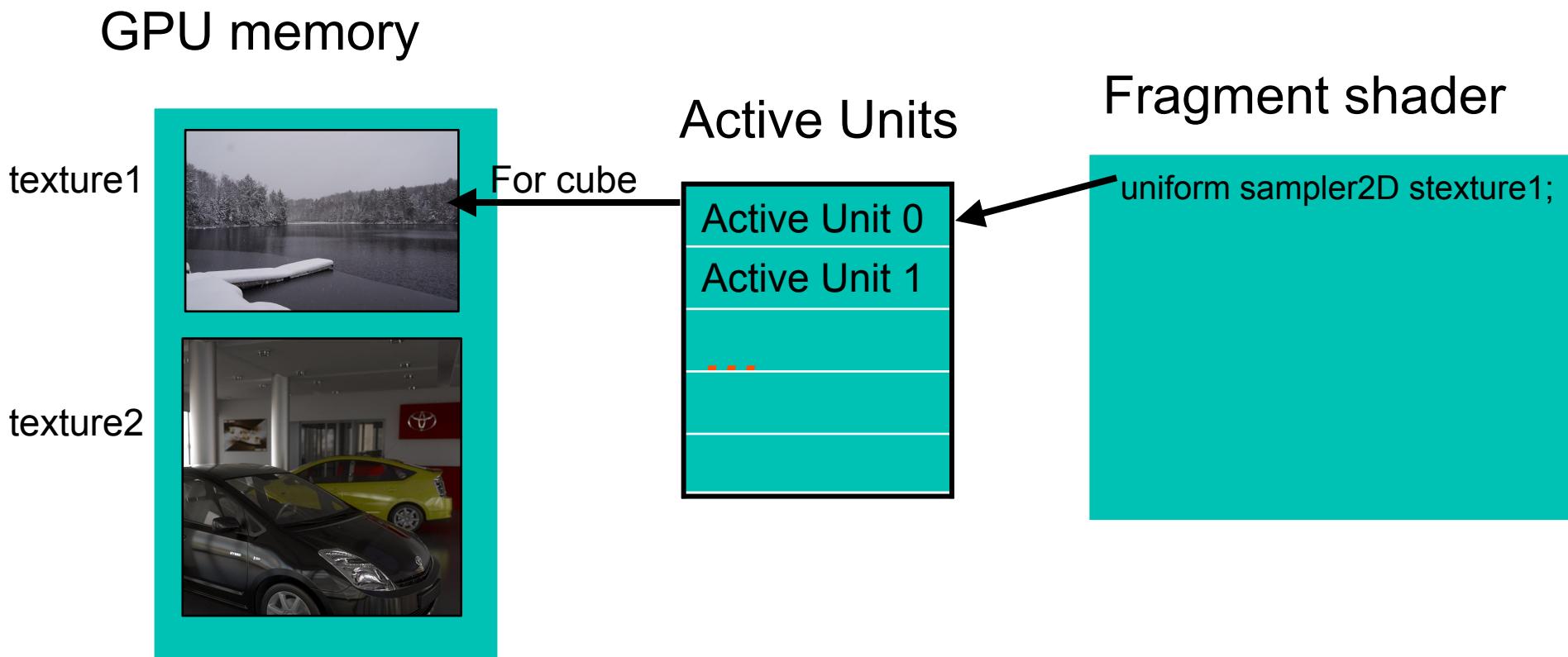
# Using Textures

```
gl.activeTexture(gl.TEXTURE0) ;  
gl.bindTexture(gl.TEXTURE_2D, texture1) ;  
gl.uniform1i(gl.getUniformLocation(program, "stexture1"), 0);  
  
drawCube() ; //  
  
gl.activeTexture(gl.TEXTURE0) ;  
gl.bindTexture(gl.TEXTURE_2D, texture2) ;  
gl.uniform1i(gl.getUniformLocation(program, "stexture1"), 0);  
  
drawSphere() ; // different texture for the sphere
```

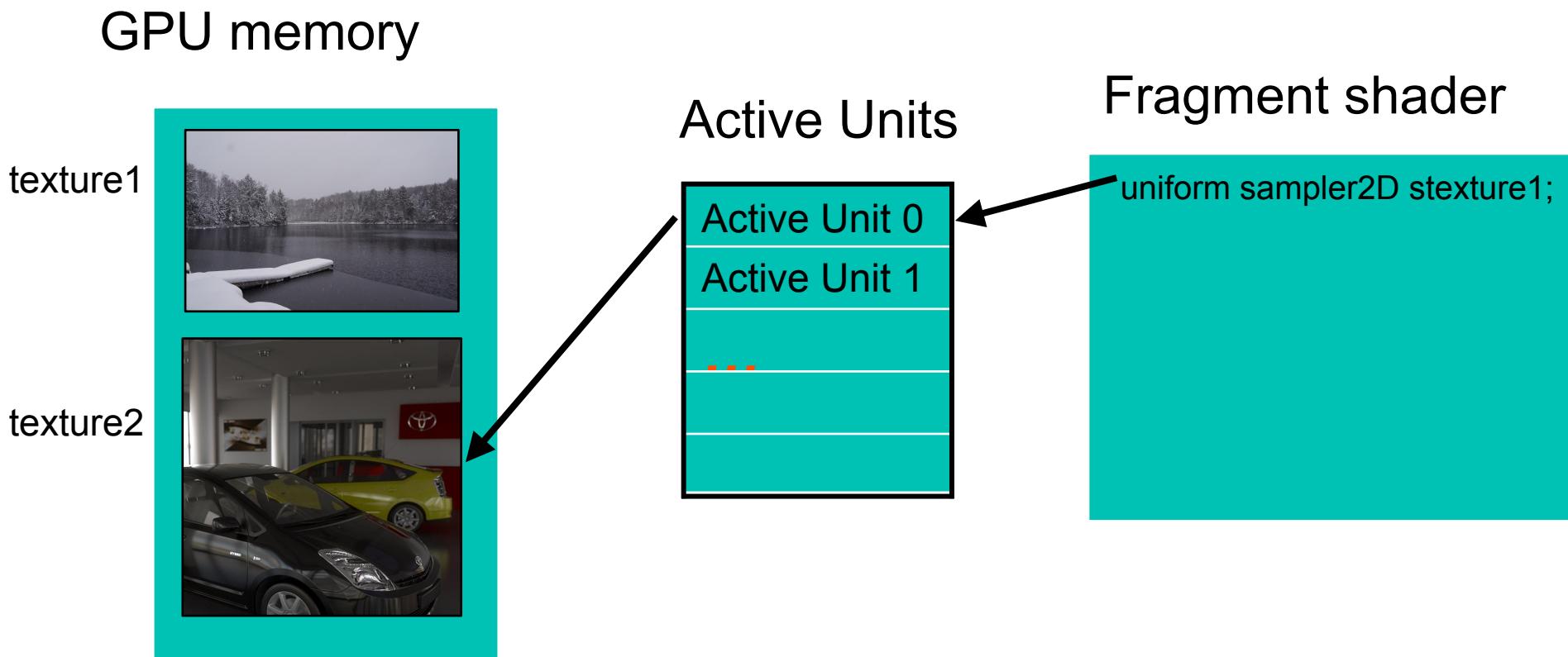
# Fragment shader

```
precision mediump float;  
  
uniform sampler2D stexture1;  
  
in vec4 fColor;  
in vec2 fTexCoord ;  
  
layout (location=0) out vec4 fragColor ;  
  
void  
main()  
{  
  
    //fragColor = vec4(fColor.rgb,1.0);  
    fragColor = texture( stexture1, fTexCoord );  
  
}
```

# Schematically: For cube



# Schematically: For sphere



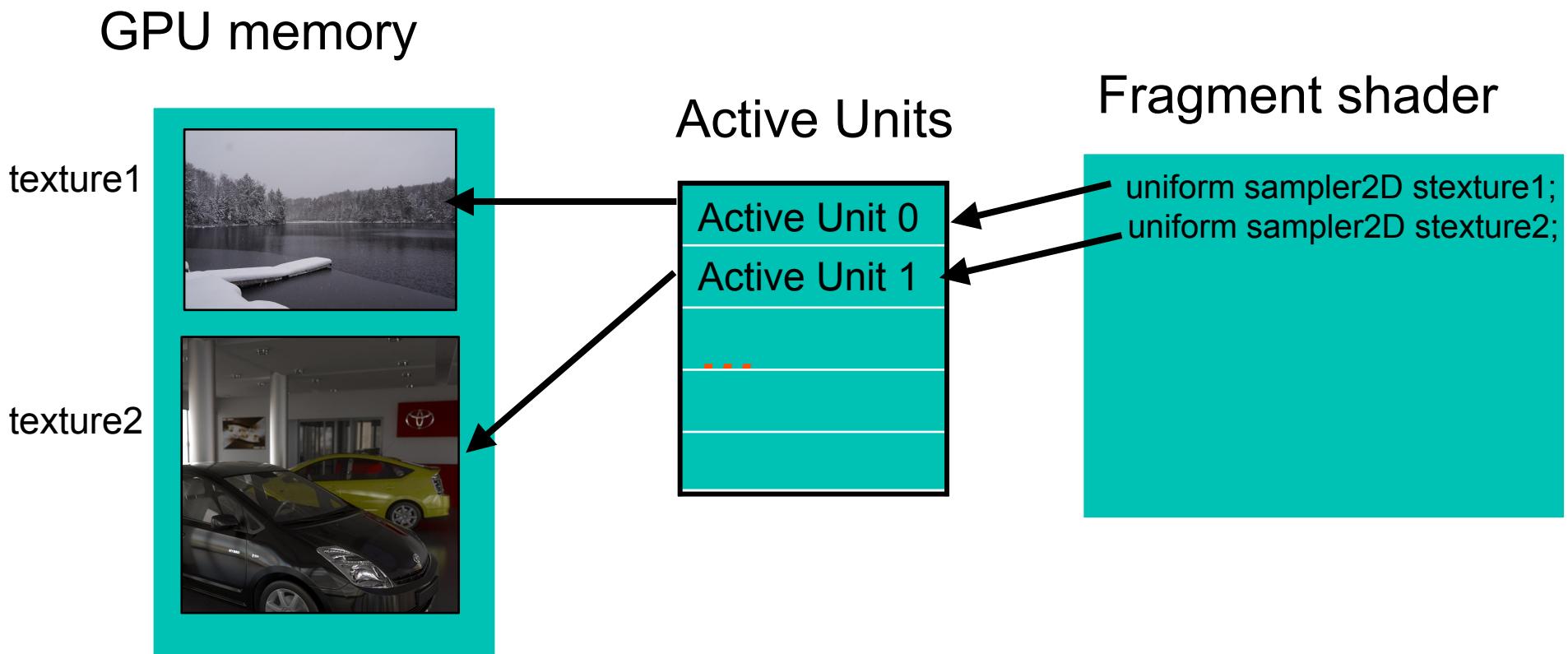
# Multiple Textures

```
gl.activeTexture(gl.TEXTURE0) ;  
gl.bindTexture(gl.TEXTURE_2D, texture1) ;  
gl.uniform1i(gl.getUniformLocation(program, "stexture1"), 0);  
  
gl.activeTexture(gl.TEXTURE1) ;  
gl.bindTexture(gl.TEXTURE_2D, texture2) ;  
gl.uniform1i(gl.getUniformLocation(program, "stexture2"), 1);  
  
drawSphere() ; // two active textures
```

The diagram illustrates the mapping of OpenGL texture units to uniforms. It consists of two main sections of code, each with a red circle highlighting a specific value. Arrows point from these highlighted values to their corresponding locations in a separate row of text.

- Top Section:** Shows the setup for the first texture.
  - A red circle highlights the value `0` in the line `gl.activeTexture(gl.TEXTURE0) ;`.
  - A red circle highlights the value `0` in the line `gl.uniform1i(gl.getUniformLocation(program, "stexture1"), 0);`.
  - An arrow points from the highlighted `0` in the uniform assignment to the highlighted `0` in the uniform location string.
- Bottom Section:** Shows the setup for the second texture.
  - A red circle highlights the value `1` in the line `gl.activeTexture(gl.TEXTURE1) ;`.
  - A red circle highlights the value `1` in the line `gl.uniform1i(gl.getUniformLocation(program, "stexture2"), 1);`.
  - An arrow points from the highlighted `1` in the uniform assignment to the highlighted `1` in the uniform location string.

# Schematically



# Fragment Shader

```
precision mediump float;

uniform sampler2D stexture1;
uniform sampler2D stexture2;

varying vec4 fColor;
varying vec2 fTexCoord ;

layout(location = 0 ) out vec4 fragColor ;

void
main()
{
    fragColor = vec4(fColor.rgb,1.0) ;
    vec4 c1 = texture( stexture1, fTexCoord );
    vec4 c2 = texture( stexture2, fTexCoord );
    fragColor = mix(c1,c2,0.5);

}
```

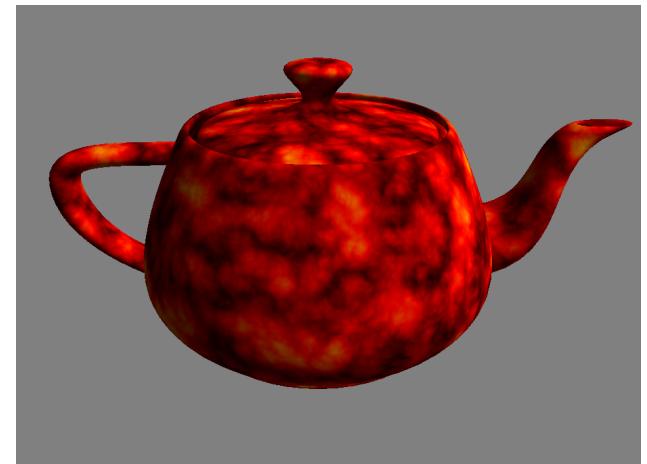
# Filters!

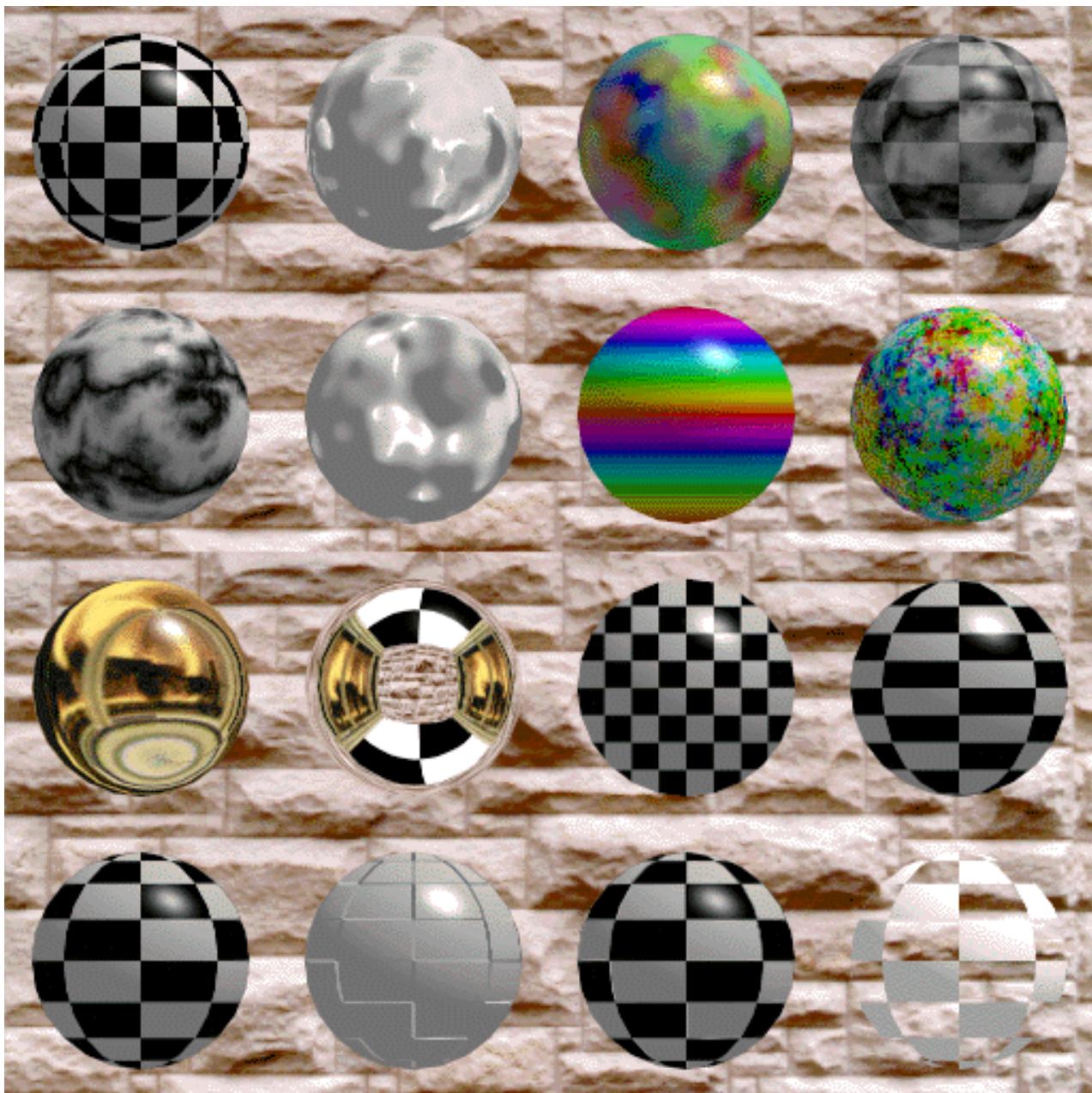
```
gl.texParameterf(gl.TEXTURE_2D, gl.TEXTURE_MAG_FILTER,  
                 gl.NEAREST);  
gl.texParameterf(gl.TEXTURE_2D, gl.TEXTURE_MIN_FILTER,  
                 gl.NEAREST);
```

DO NOT FORGET TO SET THE FILTERS!! You get black textures  
because of the default settings

# Texture Creation

- Photographs
- Procedural:  $T(s,t) = F(u,v,\dots)$ 
  - *Images generated by the CPU*
  - *Images generated by the GPU (render to texture)*
  - *Per pixel by the GPU*
    - ² Dynamic resolution
    - ² Computation vs memory
    - ² Dynamic





# Common use of Textures: Light maps

*For static objects we can simulate lighting  
by blending textures*

