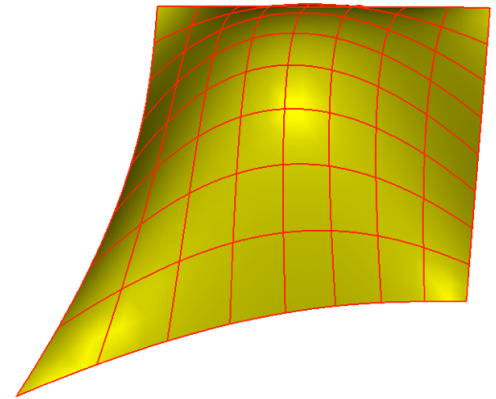
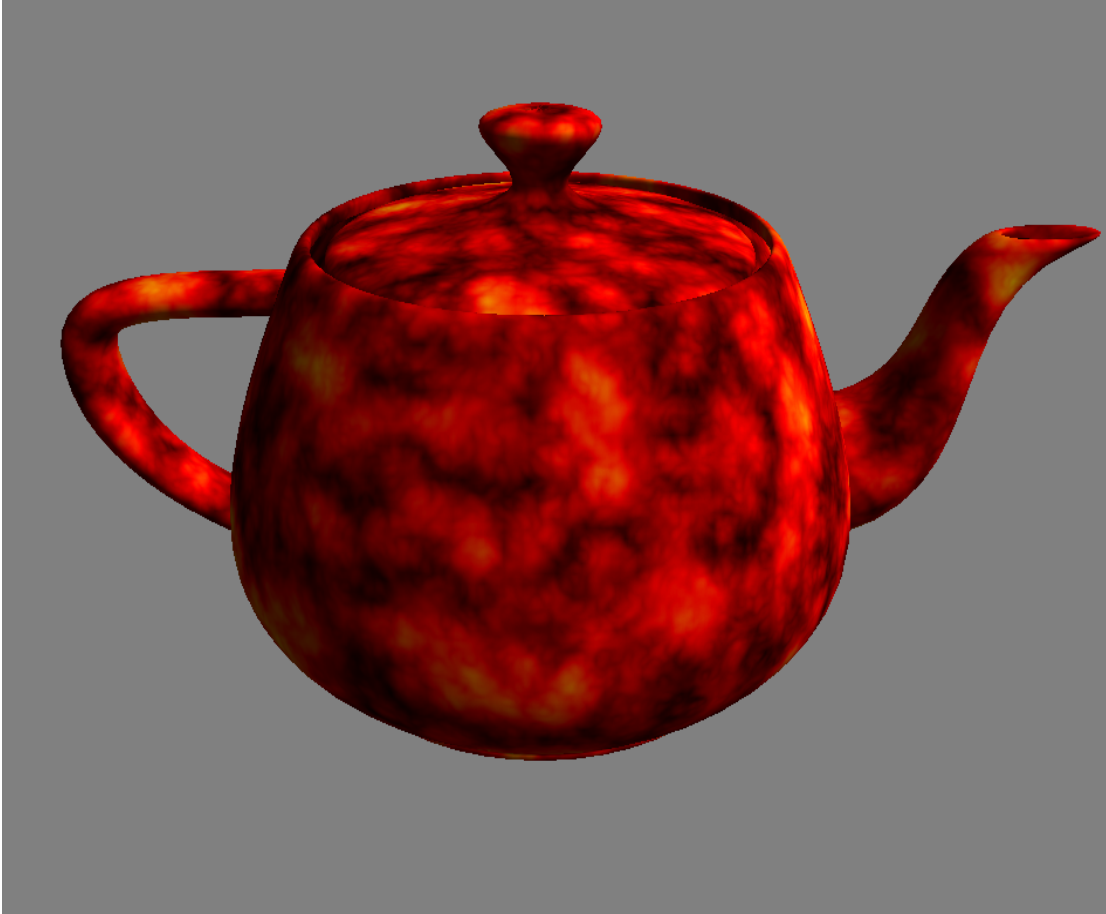


Surfaces



Formulations

***Implicit:** $f(x,y,z) = 0$*

Normal $\mathbf{n} = \nabla(f)$

***Explicit:** $z = f(x,y)$*

***Parametric:** $x = f_x(s,t), y = f_y(s,t), z = f_z(s,t)$*

Quadric surfaces

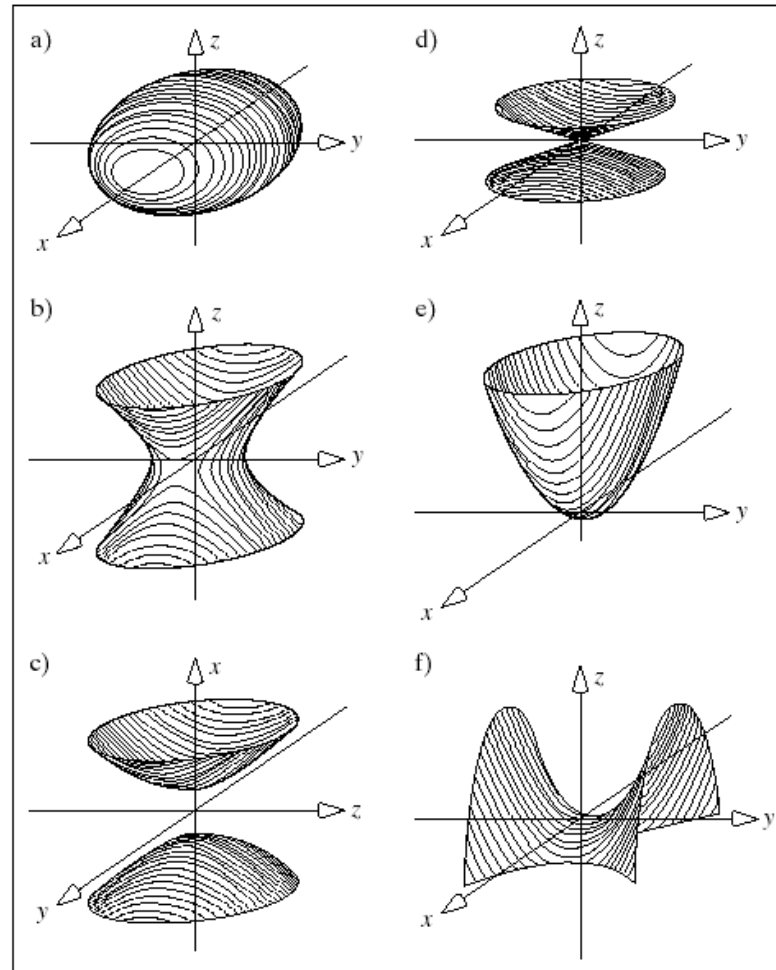


FIGURE 6.70 The six quadric surfaces: (a) Ellipsoid. (b) Hyperboloid of one sheet. (c) Hyperboloid of two sheets. (d) Elliptic cone. (e) Elliptic paraboloid. (f) Hyperbolic paraboloid.



Quadric surfaces

Sphere:

$$f(x, y, z) = (x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = R^2$$

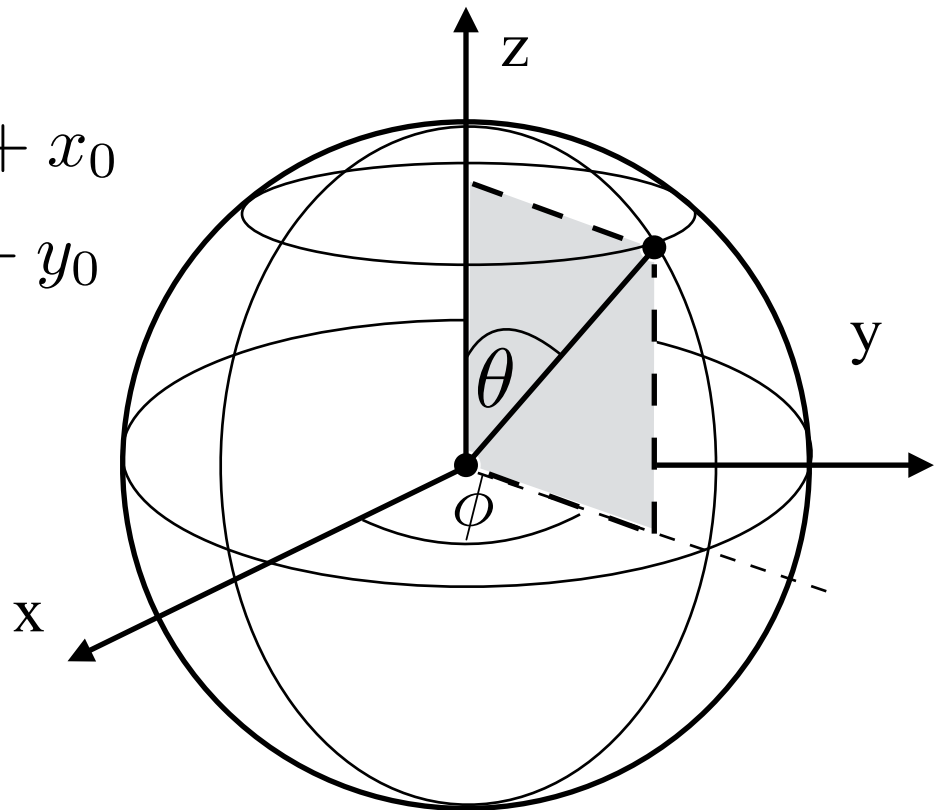
$$x(\phi, \theta) = R \sin(\theta) \cos(\phi) + x_0$$

$$y(\phi, \theta) = R \sin(\theta) \sin(\phi) + y_0$$

$$z(\phi, \theta) = R \cos(\theta) + z_0$$

$$0 \leq \phi \leq 2\pi$$

$$0 \leq \theta \leq \pi$$



Normal on Sphere

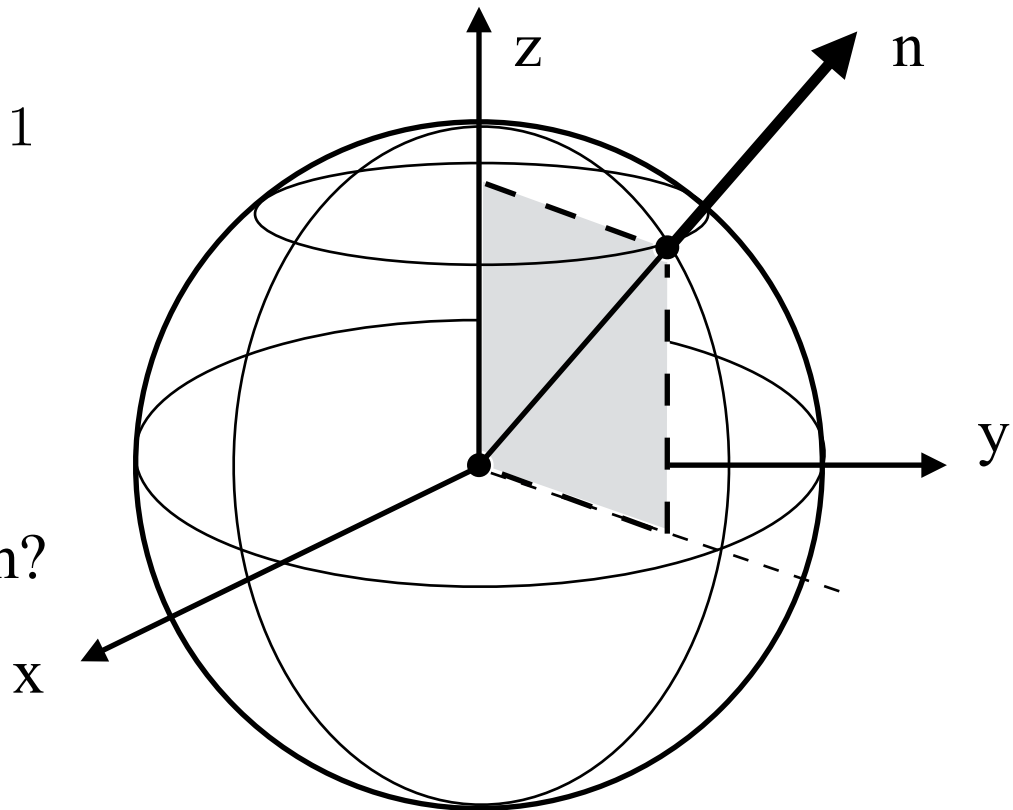
$$\mathbf{n}(x, y, z) = \nabla f(x, y, z) = \left(\frac{\partial f(x, y, z)}{\partial x}, \frac{\partial f(x, y, z)}{\partial y}, \frac{\partial f(x, y, z)}{\partial z} \right)$$

For $f(x, y, z) = x^2 + y^2 + z^2 - 1$

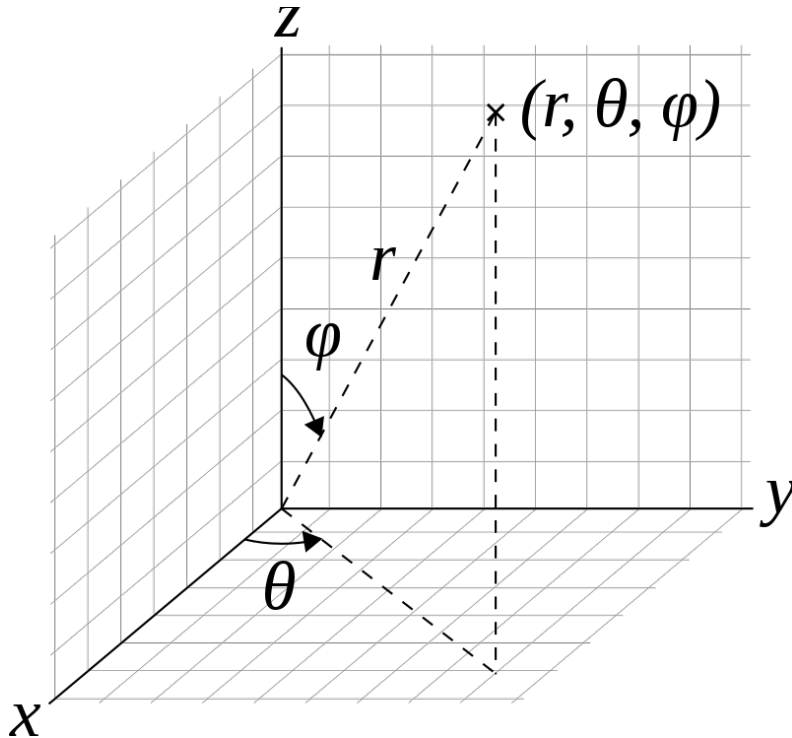
$$\mathbf{n}(x, y, z) = (2x, 2y, 2z)$$

Exercise:

- a) Unit normal?
- b) What about the general form?



Reminder: Spherical coordinates



r : radial distance
theta: azimuthal angle
phi: polar angle

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<https://creativecommons.org/licenses/by-sa/3.0>

Quadric surfaces

Ellipsoid

$$f(x, y, z) = \left(\frac{x - x_0}{R_x}\right)^2 + \left(\frac{y - y_0}{R_y}\right)^2 + \left(\frac{z - z_0}{R_z}\right)^2 - 1$$

$$f(x, y, z) = (x - x_0)^2 + (y - y_0)^2 + (z - z_0)^2 = R^2$$

$$x(\phi, \theta) = R_x \sin(\theta) \cos(\phi) + x_0$$

$$y(\phi, \theta) = R_y \sin(\theta) \sin(\phi) + y_0$$

$$z(\phi, \theta) = R_z \cos(\theta) + z_0$$

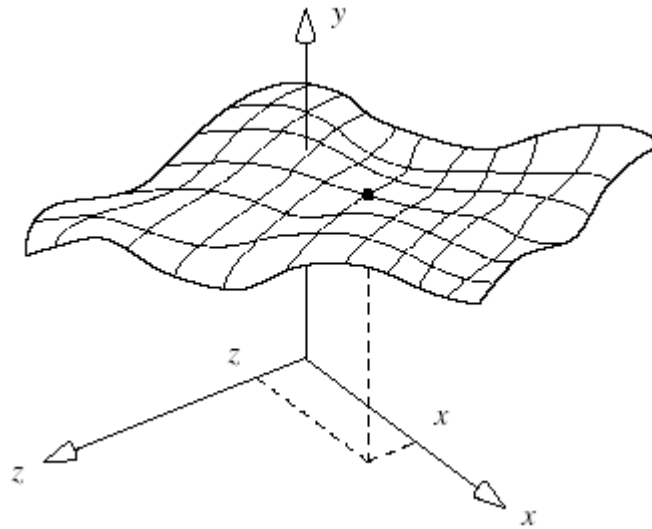
$$0 \leq \phi \leq 2\pi$$

$$0 \leq \theta \leq \pi$$

Normal vector?

Height fields

$$y=f(x,z)$$

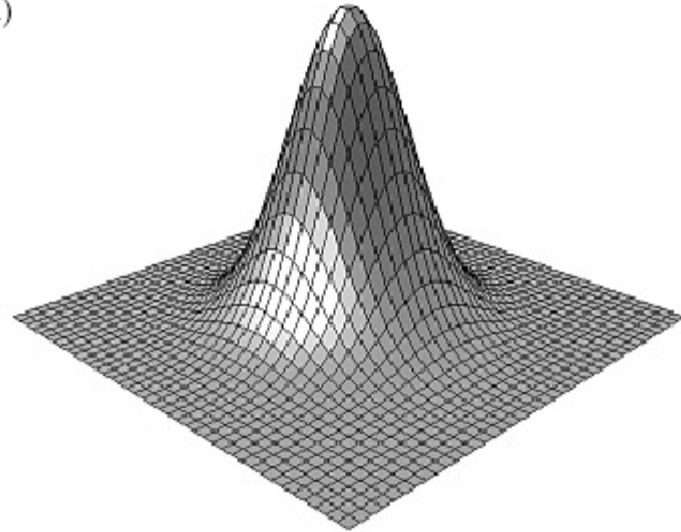


Typical height fields

Gaussian

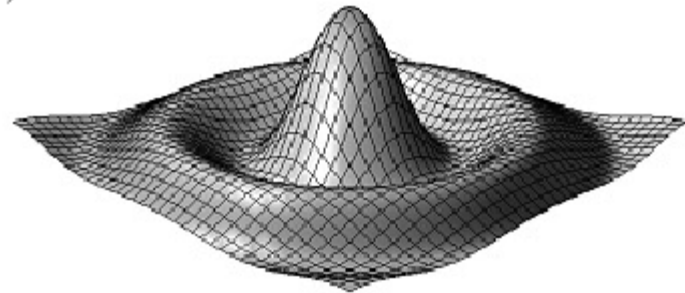
$$y = f(x, z) = e^{-ax^2 - bz^2}$$

a)



Sinc

$$y = f(x, z) = \frac{\sin(\sqrt{x^2 + z^2})}{\sqrt{x^2 + z^2}} \quad \text{b)}$$



Parametric formulations

Ruled surfaces:

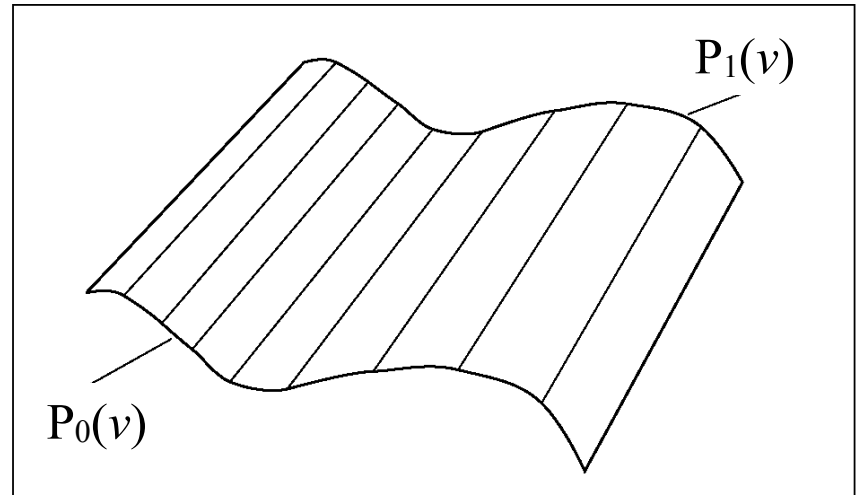
Linear combination of two curves

- Through every point on the surface there passes at least one line that lies on the surface

$$P(u) = (1 - u)P_0 + uP_1$$

Making P_0 and P_1 curves :

$$P(u, v) = (1 - u)P_0(v) + uP_1(v)$$

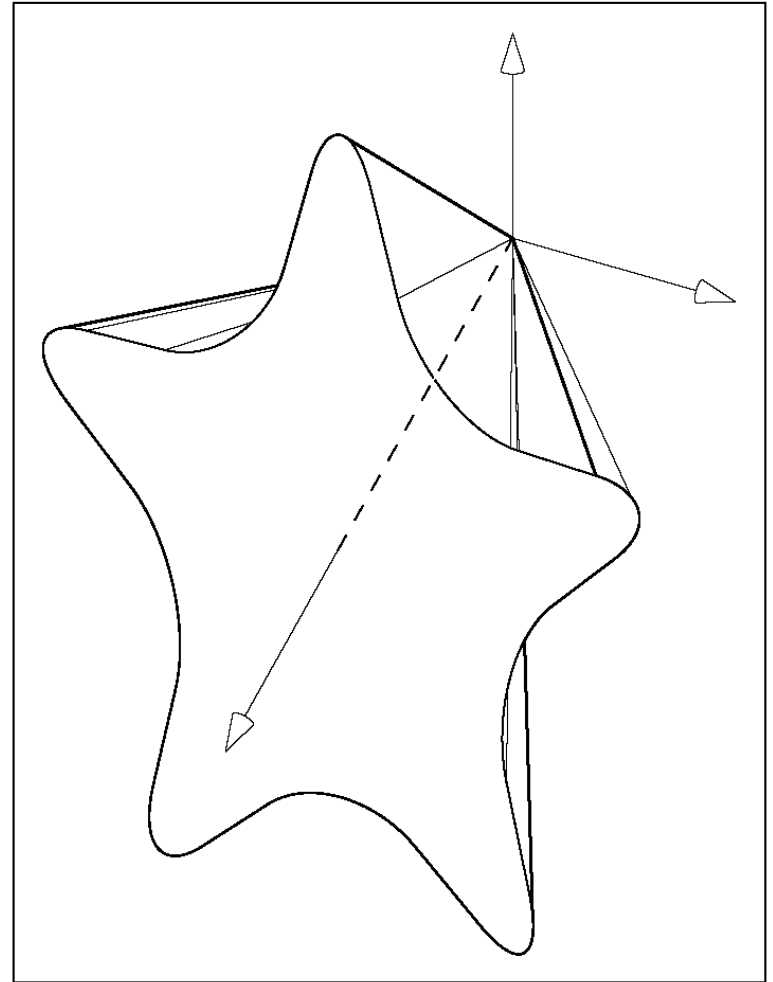


Special cases

General cone

$$P(u, v) = (1 - u)P_0 + uP_1(v)$$

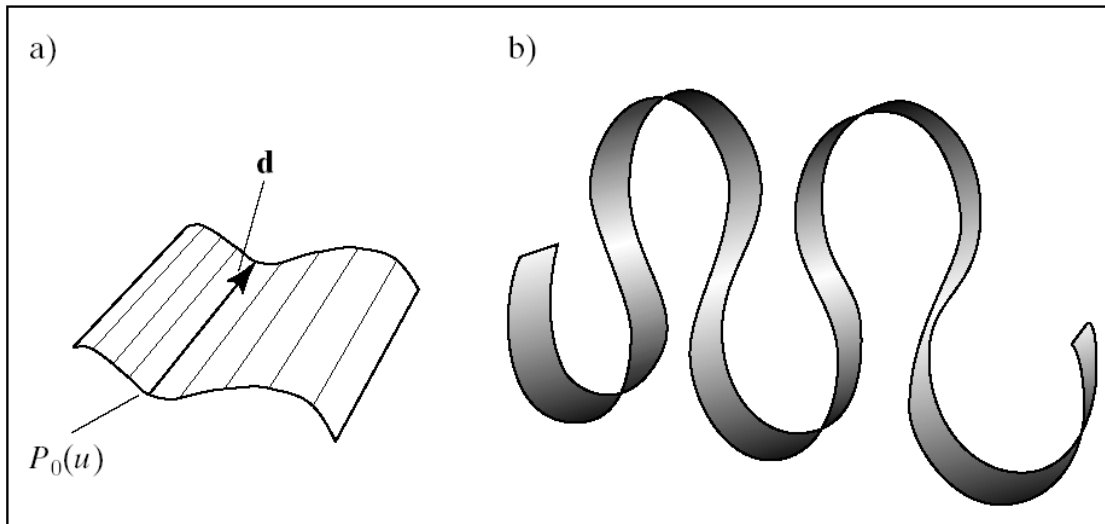
P_0 is the apex



General Cylinder

P_1 a translated version of P_0

$$P(u, v) = (1 - u)P_0(v) + u(P_0(v) + \mathbf{d}) \Rightarrow P(u, v) = P_0(v) + u\mathbf{d}$$



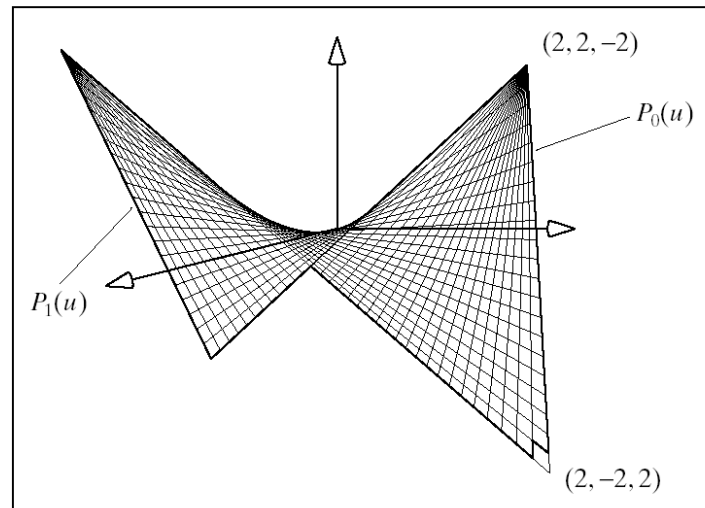
Bilinear patches

Both P_1 and P_0 are lines

$$P(u, v) = (1 - u)P_0(v) + uP_1(v) \Rightarrow$$

$$P(u, v) = (1 - u)[(1 - v)P_{00} + vP_{01}] + u[(1 - v)P_{10} + vP_{11}] \Rightarrow$$

$$P(u, v) = (1 - u)(1 - v)P_{00} + (1 - u)vP_{01} + u(1 - v)P_{10} + uvP_{11}$$



Surfaces of revolution

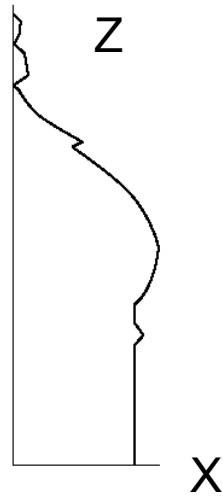
Sweep profile curve around an axis:

$$C(v) = (X(v), Z(v))$$

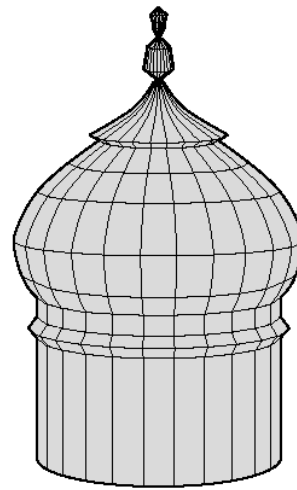
$$P(u, v) = (X(v)\cos(u), X(v)\sin(u), Z(v))$$



a)



b)



c)

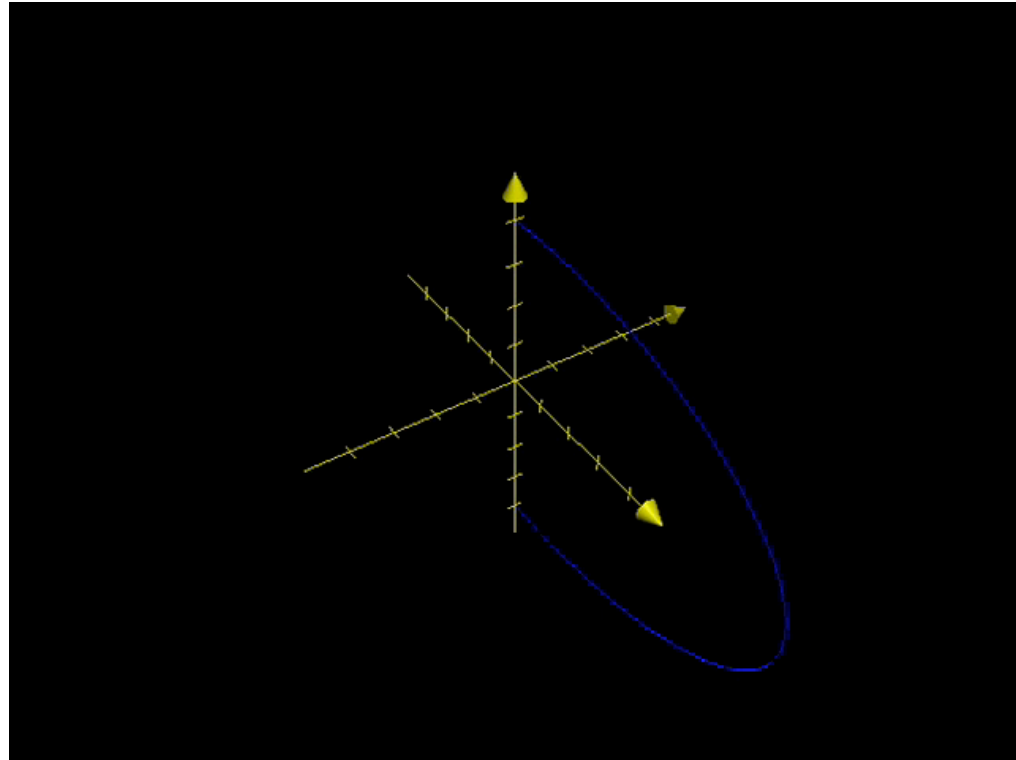
Example

Curve

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \cdot \cos(t) \\ 0 \\ 2 \cdot \sin(t) \end{bmatrix}, t = -\frac{\pi}{2} \dots \frac{\pi}{2}$$

Surface

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \cdot \cos(t) \cdot \cos(u) \\ 4 \cdot \cos(t) \cdot \sin(u) \\ 2 \cdot \sin(t) \end{bmatrix}, t = -\frac{\pi}{2} \dots \frac{\pi}{2}, u = 0 \dots a$$



Parametric surfaces from control points (constraints)

Extension of the curve form to two dimensions

- Focus on cubic patches

General form of a cubic patch

$$P(s, t) = \sum_{i=0}^{15} B_i(s, t) G_i, \quad (s, t) \in [0, 1] \times [0, 1]$$

where

$B_i(s, t)$: Cubic polynomials in two variables

G_i : Point or tangent constraints

Parametric surfaces from control points (constraints)

Extension of the curve form to two dimensions

Curve: $P(s) = SMG = [s^3 \ s^2 \ s \ 1]MG$ with s in $[0, 1]$

Surface: $P(s,t) = SMG(t)$ with s,t in $[0, 1]$

Example: Bezier curve $P(s)$ of four points P_1, P_2, P_3, P_4 :

$P(s) = SMG$, $s \in [0, 1]$ or

$$\begin{bmatrix} x(s) & y(s) & z(s) \end{bmatrix} = \begin{bmatrix} s^3 & s^2 & s & 1 \end{bmatrix} M \begin{bmatrix} G_x & G_y & G_z \end{bmatrix} \text{ or}$$

$$\begin{bmatrix} x(s) & y(s) & z(s) \end{bmatrix} = \begin{bmatrix} s^3 & s^2 & s & 1 \end{bmatrix} M \begin{bmatrix} P_{1,x} & P_{1,y} & P_{1,z} \\ P_{2,x} & P_{2,y} & P_{2,z} \\ P_{3,x} & P_{3,y} & P_{3,z} \\ P_{4,x} & P_{4,y} & P_{4,z} \end{bmatrix}$$

Bezier Surfaces

*Take a bezier curve $P(s)$
and let its control points
become bezier curves*

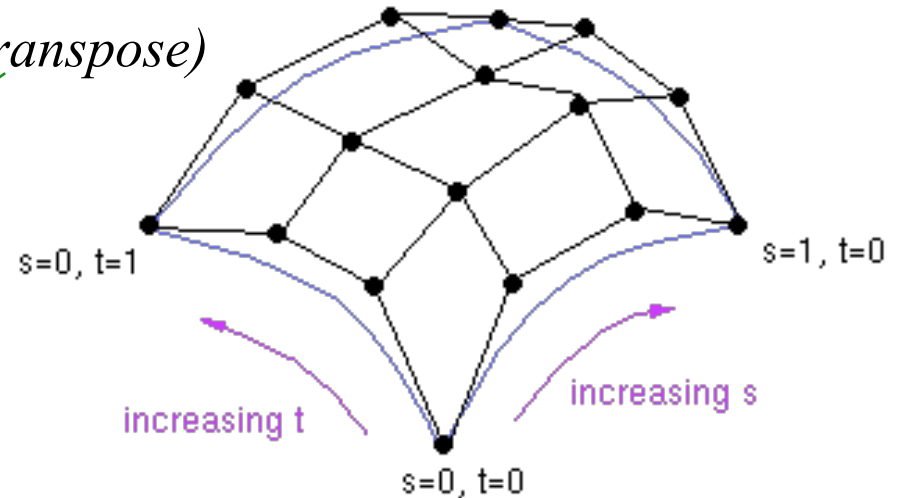
$$P(s) = S \mathbf{M} \mathbf{G}(t)$$

$$\mathbf{G}(t) = [P_1(t) \ P_2(t) \ P_3(t) \ P_4(t)]^T$$

(transpose)

Where:

$$P_i(t) = T \mathbf{M} \mathbf{G}_i = T \mathbf{M} [P_{i1} \ P_{i2} \ P_{i3} \ P_{i4}]^T$$



Total: $4 \times 4 = 16$ control points

$P_{ij}, i=1,2,3,4, j=1,2,3,4$

Tensor product representation (easier per dimension)

$$P_x(s, t) = \mathbf{S} \mathbf{M} G_x(t) = \mathbf{S} \mathbf{M} \begin{bmatrix} P_{1,x}(t) \\ P_{2,x}(t) \\ P_{3,x}(t) \\ P_{4,x}(t) \end{bmatrix}, \text{ where}$$

$$P_{i,x}(t) = \mathbf{T} \mathbf{M} G_{i,x} = G_{i,x}^T \mathbf{M}^T \mathbf{T}^T = \begin{bmatrix} P_{i1,x} & P_{i2,x} & P_{i3,x} & P_{i4,x} \end{bmatrix} \mathbf{M}^T \mathbf{T}^T$$

Tensor product representation (easier per dimension)

$$P_x(s, t) = \mathbf{S}\mathbf{M}\mathbf{G}_x(t) = \mathbf{S}\mathbf{M} \begin{bmatrix} P_{1,x}(t) \\ P_{2,x}(t) \\ P_{3,x}(t) \\ P_{4,x}(t) \end{bmatrix}, \text{ where}$$

$$P_{i,x}(t) = \mathbf{T}\mathbf{M}\mathbf{G}_{i,x} = \mathbf{G}_{i,x}^T \mathbf{M}^T \mathbf{T}^T = \begin{bmatrix} P_{i1,x} & P_{i2,x} & P_{i3,x} & P_{i4,x} \end{bmatrix} \mathbf{M}^T \mathbf{T}^T$$

Together they give:

$$P_x(s, t) = \mathbf{S}\mathbf{M}\mathbf{G}_x(t) = \mathbf{S}\mathbf{M} \begin{bmatrix} P_{1,x}(t) \\ P_{2,x}(t) \\ P_{3,x}(t) \\ P_{4,x}(t) \end{bmatrix} = \mathbf{S}\mathbf{M} \begin{bmatrix} \mathbf{G}_{1,x}^T \mathbf{M}^T \mathbf{T}^t \\ \mathbf{G}_{2,x}^T \mathbf{M}^T \mathbf{T}^t \\ \mathbf{G}_{3,x}^T \mathbf{M}^T \mathbf{T}^t \\ \mathbf{G}_{4,x}^T \mathbf{M}^T \mathbf{T}^t \end{bmatrix} \rightarrow$$

$$P_x(s, t) = \mathbf{S}\mathbf{M} \begin{bmatrix} P_{11,x} & P_{12,x} & P_{13,x} & P_{14,x} \\ P_{21,x} & P_{22,x} & P_{23,x} & P_{24,x} \\ P_{31,x} & P_{32,x} & P_{33,x} & P_{34,x} \\ P_{41,x} & P_{42,x} & P_{43,x} & P_{44,x} \end{bmatrix} \mathbf{M}^T \mathbf{T}^T$$

$$P_x(s, t) = \mathbf{S}\mathbf{M}\mathbf{G}_x \mathbf{M}^T \mathbf{T}^T, (s, t) \in [0, 1] \times [0, 1]$$

Tensor product representation (easier per dimension)

$$P_x(s, t) = \mathbf{S}\mathbf{M}\mathbf{G}_x(t) = \mathbf{S}\mathbf{M} \begin{bmatrix} P_{1,x}(t) \\ P_{2,x}(t) \\ P_{3,x}(t) \\ P_{4,x}(t) \end{bmatrix}, \text{ where}$$

$$P_{i,x}(t) = \mathbf{T}\mathbf{M}\mathbf{G}_{i,x} = \mathbf{G}_{i,x}^T \mathbf{M}^T \mathbf{T}^T = \begin{bmatrix} P_{i1,x} & P_{i2,x} & P_{i3,x} & P_{i4,x} \end{bmatrix} \mathbf{M}^T \mathbf{T}^T$$

Together they give:

$$P_x(s, t) = \mathbf{S}\mathbf{M}\mathbf{G}_x(t) = \mathbf{S}\mathbf{M} \begin{bmatrix} P_{1,x}(t) \\ P_{2,x}(t) \\ P_{3,x}(t) \\ P_{4,x}(t) \end{bmatrix} = \mathbf{S}\mathbf{M} \begin{bmatrix} \mathbf{G}_{1,x}^T \mathbf{M}^T \mathbf{T}^t \\ \mathbf{G}_{2,x}^T \mathbf{M}^T \mathbf{T}^t \\ \mathbf{G}_{3,x}^T \mathbf{M}^T \mathbf{T}^t \\ \mathbf{G}_{4,x}^T \mathbf{M}^T \mathbf{T}^t \end{bmatrix} \rightarrow$$

$$P_x(s, t) = \mathbf{S}\mathbf{M} \begin{bmatrix} P_{11,x} & P_{12,x} & P_{13,x} & P_{14,x} \\ P_{21,x} & P_{22,x} & P_{23,x} & P_{24,x} \\ P_{31,x} & P_{32,x} & P_{33,x} & P_{34,x} \\ P_{41,x} & P_{42,x} & P_{43,x} & P_{44,x} \end{bmatrix} \mathbf{M}^T \mathbf{T}^T$$

$$P_x(s, t) = \mathbf{S}\mathbf{M}\mathbf{G}_x \mathbf{M}^T \mathbf{T}^T, (s, t) \in [0, 1] \times [0, 1]$$

Tensor product representation (easier per dimension)

$$P_x(s, t) = S\mathbf{M} \begin{bmatrix} P_{11,x} & P_{12,x} & P_{13,x} & P_{14,x} \\ P_{21,x} & P_{22,x} & P_{23,x} & P_{24,x} \\ P_{31,x} & P_{32,x} & P_{33,x} & P_{34,x} \\ P_{41,x} & P_{42,x} & P_{43,x} & P_{44,x} \end{bmatrix} \mathbf{M}^T T^T$$

$$P_x(s, t) = S\mathbf{M}\mathbf{G}_x\mathbf{M}^T T^T, (s, t) \in [0, 1] \times [0, 1]$$

Similarly:

$$P_y(s, t) = S\mathbf{M}\mathbf{G}_y\mathbf{M}^T T^T, (s, t) \in [0, 1] \times [0, 1]$$

$$P_z(s, t) = S\mathbf{M}\mathbf{G}_z\mathbf{M}^T T^T, (s, t) \in [0, 1] \times [0, 1]$$

Tensor product representation

More compactly:

$$P(s, t) = S\mathbf{M}\mathbf{G}\mathbf{M}^T T^T, (s, t) \in [0, 1] \times [0, 1] \text{ or}$$

$$P(s, t) = \begin{bmatrix} s^3 & s^2 & s & 1 \end{bmatrix} \mathbf{M} \begin{bmatrix} P_{11} & P_{12} & P_{13} & P_{14} \\ P_{21} & P_{22} & P_{23} & P_{24} \\ P_{31} & P_{32} & P_{33} & P_{34} \\ P_{41} & P_{42} & P_{43} & P_{44} \end{bmatrix} \mathbf{M}^T \begin{bmatrix} t^3 \\ t^2 \\ t \\ 1 \end{bmatrix}$$

4x4x3 Tensor

Cubic Bezier patch forms

Pick the most convenient

a)
$$P(s, t) = \begin{bmatrix} s^3 & s^2 & s & 1 \end{bmatrix} MGM \begin{bmatrix} t^3 \\ t^2 \\ t \\ 1 \end{bmatrix} \quad (s, t) \in [0, 1] \times [0, 1]$$

b)
$$P(s, t) = \sum_{i=0}^3 B_i^3(s) \sum_{j=0}^3 B_j^3(t) P_{ij}, \quad (s, t) \in [0, 1] \times [0, 1]$$

where the Bernstein polynomials are

$$B_0^3(v) = (1 - v)^3, B_1^3(v) = 3(1 - v)^2 v,$$

$$B_2^3(v) = 3(1 - v) v^2, B_3^3(v) = v^3$$

Properties of Bezier surfaces

Affine Invariance

Convex Hull

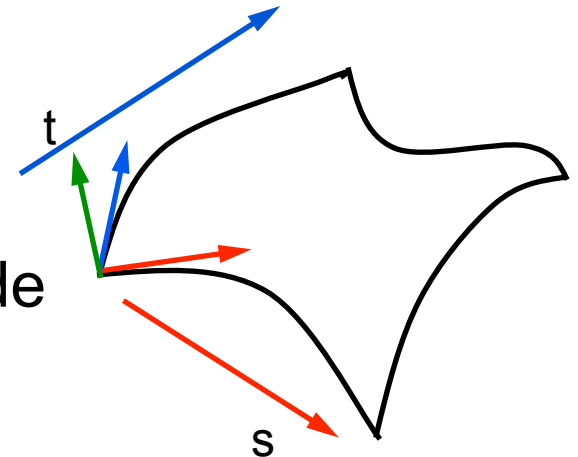
Plane precision

Variation diminishing

Hermite surfaces

Constraints at the four corners:

- Position, Tangent, Twist
- Same form, different basis matrix M_h
- Geometry vector in 4x4 form to fit in slide



$$G_x = \begin{bmatrix} \text{points} & \text{tangents} \\ \text{tangents} & \text{twist vectors} \end{bmatrix}$$

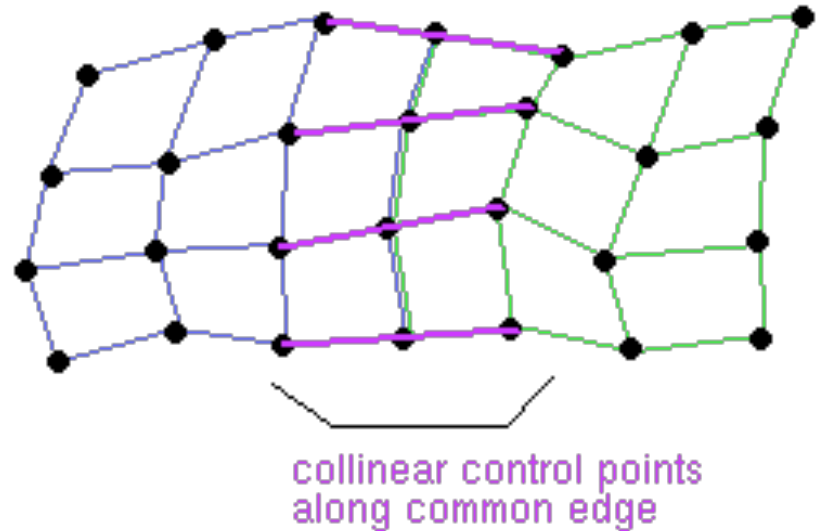
$x(0,0)$	$x(0,1)$	$\frac{\partial}{\partial t} x(0,0)$	$\frac{\partial}{\partial t} x(0,1)$
$x(1,0)$	$x(1,1)$	$\frac{\partial}{\partial t} x(1,0)$	$\frac{\partial}{\partial t} x(1,1)$
$\frac{\partial}{\partial s} x(0,0)$	$\frac{\partial}{\partial s} x(0,1)$	$\frac{\partial}{\partial s \partial t} x(0,0)$	$\frac{\partial}{\partial s \partial t} x(0,1)$
$\frac{\partial}{\partial s} x(1,0)$	$\frac{\partial}{\partial s} x(1,1)$	$\frac{\partial}{\partial s \partial t} x(1,0)$	$\frac{\partial}{\partial s \partial t} x(1,1)$

Piecewise cubic bezier surfaces

G1 continuity

Common edge

Make 2 sets of 4 control points collinear



Rendering parametric curves and surfaces

Transform into primitives we know how to handle

Curves

- Line segments

Surfaces

- Quadrilaterals
- Triangles

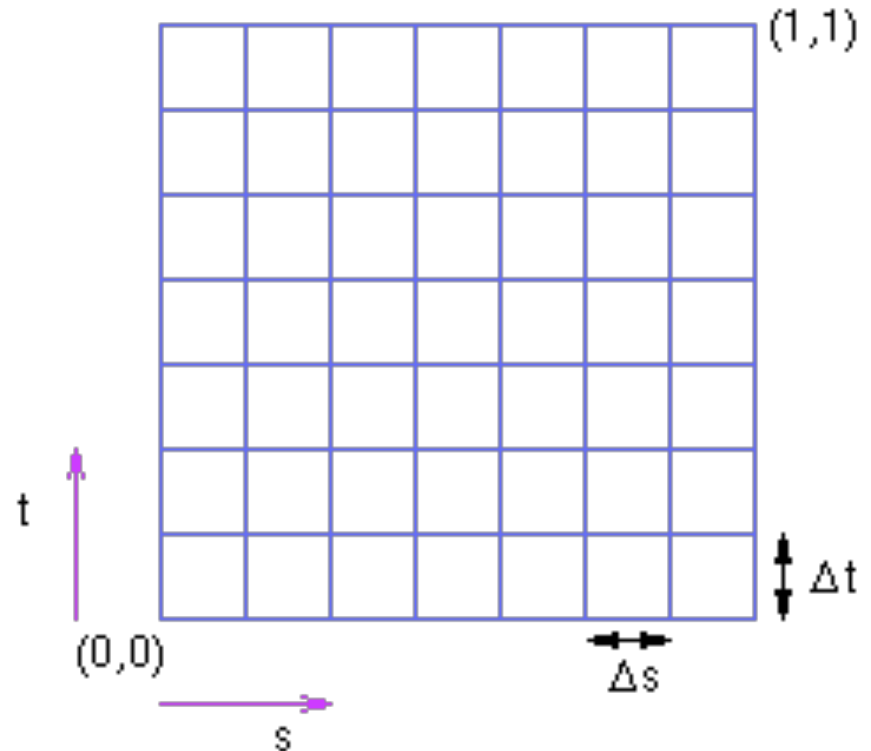
Converting to quadrilaterals

Straightforward

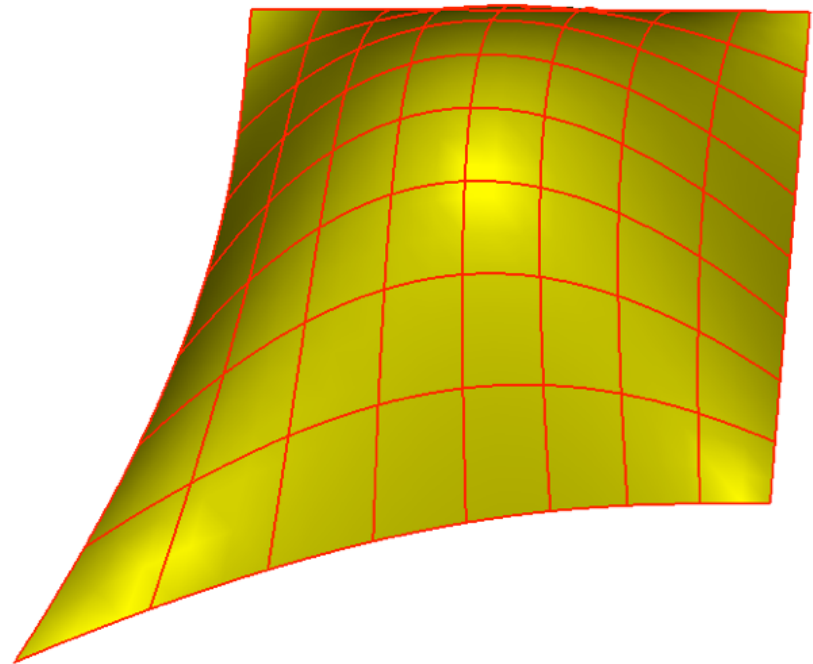
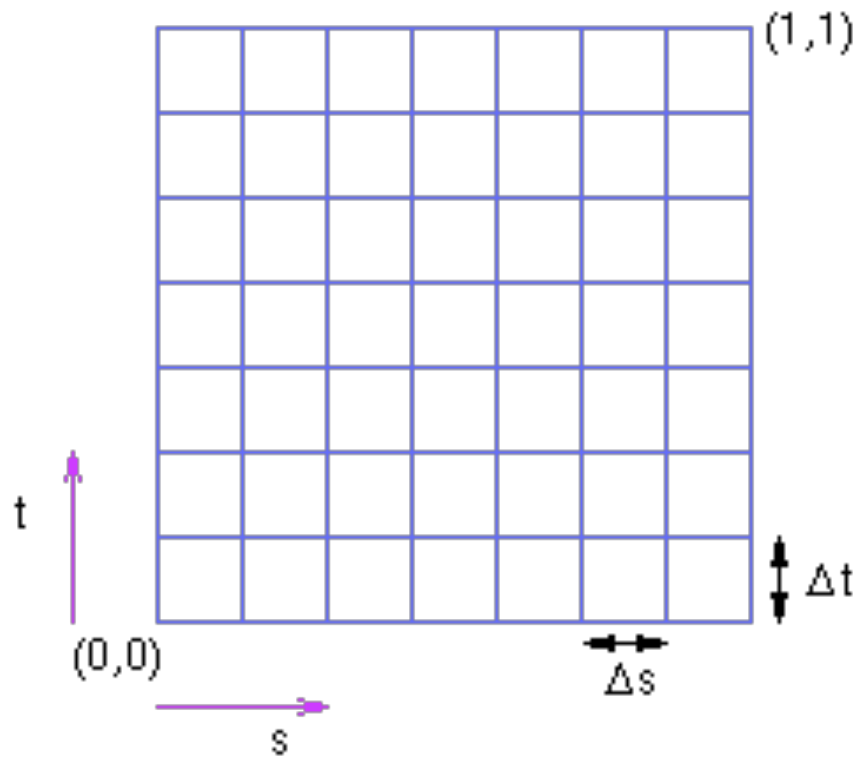
Uniform subdivision

Evaluation of $P(s,t)$ at each
grid point

Isoparametric lines (isolines)
become isoparametric
curves



Isolines



Optimizations

$$x(s,t) = S M G_x M^T T^T$$

- $M G M^T$ remains constant over patch: precompute
- $S M$ and $M^T T^T$ remain constant over all patches:
precompute $S M$ and store in $Q[s]$
 $Q[t] = Q^T[s]$ assuming equal subdivisions in s and t

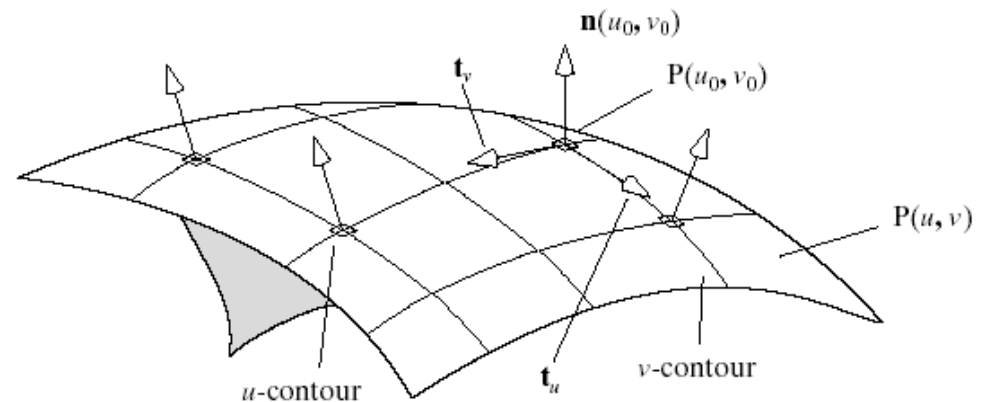
Computing surface normals

Parametric surface $P(u,v)$

$$P(u,v) = U M G M^T V^T$$

Normal Vector at u,v ?

$$\mathbf{N} = \frac{\partial P(u,v)}{\partial u} \times \frac{\partial P(u,v)}{\partial v}$$



Cubic Bezier patch forms (Again!)

Pick the most convenient

a)
$$P(s, t) = \begin{bmatrix} s^3 & s^2 & s & 1 \end{bmatrix} MGM \begin{bmatrix} t^3 \\ t^2 \\ t \\ 1 \end{bmatrix} \quad (s, t) \in [0, 1] \times [0, 1]$$

b)
$$P(s, t) = \sum_{i=0}^3 B_i^3(s) \sum_{j=0}^3 B_j^3(t) P_{ij}, \quad (s, t) \in [0, 1] \times [0, 1]$$

where the Bernstein polynomials are

$$B_0^3(v) = (1 - v)^3, B_1^3(v) = 3(1 - v)^2 v,$$

$$B_2^3(v) = 3(1 - v) v^2, B_3^3(v) = v^3$$

General form of a cubic patch

$$P(s, t) = \sum_{i=0}^{15} B_i(s, t) G_i, \quad (s, t) \in [0, 1] \times [0, 1]$$

where

$B_i(s, t)$: Cubic polynomials in two variables

G_i : Point or tangent constraints