### **Different Similarity Measures**

 $f^p, f^q: time series$ 

#### ▼ Manhattan

- Quantifies the absolute magnitude of the difference between time series
- · Easy to calculate

$$D_{Man} = (\sum_{t=1}^N |f_t^p - f_t^q|)$$

• Implementation: scipy.spatial.distance.cityblock

#### ▼ Euclidean

- Quantifies the Euclidean distance of the difference between time series
- · Easy to calculate
- · More sensitive to outliers, due to it's nonlinear character

$$D_E = (\sum_{t=1}^N |f_t^p - f_t^q|^2)^{rac{1}{2}}$$

• Implementation: scipy.spatial.distance.euclidean

#### ▼ Mahalanobis

 Quantifies the difference between time series but accounts for nonstationarity of variance and temporalcross-correlation

$$D_{Mah} = \sqrt{(f_t^p - f_t^q)^T \sum
olimits^{-1} (f_t^p - f_t^q)}$$

 $\sum: Covariance Matrix$ 

- Implementation: scipy.spatial.distance.mahalanobis
- ▼ Pearons's Correlation

Quantifies the degree of linear relationship between time series

$$D_{CC} = \frac{\sum_{t=0}^{N-1} \left[ \left( f_t^p - \overline{f}^p \right) * \left( f_{t-s}^q - \overline{f}^q \right) \right]}{\sqrt{\sum_{t=0}^{N-1} \left( f_t^p - \overline{f}^p \right)^2} * \sqrt{\sum_{t=0}^{N-1} \left( f_{t-s}^q - \overline{f}^q \right)^2}}$$

- Implementation: numpy.corrcoef
- ▼ Cosine Distance

$$ext{similarity} = \cos( heta) = rac{\mathbf{A} \cdot \mathbf{B}}{\|\mathbf{A}\| \|\mathbf{B}\|} = rac{\sum\limits_{i=1}^n A_i B_i}{\sqrt{\sum\limits_{i=1}^n A_i^2} \sqrt{\sum\limits_{i=1}^n B_i^2}},$$

- Implementation: scipy.spatial.distance.cosine
- ▼ Principal Component
  - Quantifies the difference between times PCs that explain the majority of the variance
  - Selecting m critical

$$D_{PCA} = \sqrt{\sum_{k=1}^{m} (PC_k^p - PC_k^q)^2}$$

- Implementation: sklearn.decomposition.PCA
- ▼ 3 Fourier Based Similarities
  - Fourier Transformation of series f(t)

$$f(t) = A_0 + \sum_{k=1}^{N-1} A_k \cos(2\pi kt + \phi_k)$$

with

$$A_k = \sqrt{F_k^{c2} + F_k^{s2}}$$

and

$$\phi_k = \arctan\left(\frac{F_k^c}{F_k^s}\right)$$

## Quantifies the combined effect of FT amplitude and phase differences

$$D_{FFT} = \sqrt{\sum_{k=0}^{m} (A_k^p - A_k^q)^2 + \sum_{k=1}^{m} (\phi_k^p - \phi_k^q)^2}$$

# Quantifies shape similarity based onderived FT amplitude and phase differences

$$D_{\xi} = 3\sqrt{\sum_{k=1}^{m} \left(\alpha_k^{ref} - \alpha_k\right)^2} + \sqrt{\sum_{k=1}^{m} \left(\theta_k^{ref} - \theta_k\right)^2}$$
 (9)

where  $\alpha_k$  and  $\theta_k$  are the relative amplitude and phase for each FT component:

$$\alpha_k = \frac{A_k}{A_1} \tag{10}$$

and

$$\theta_k = \left(\frac{A_k}{A_1}\right)_{ref} [2 + \cos(k\phi_1 - \phi_k)] \tag{11}$$

and  $\alpha_k$ ref and  $\theta_k$ ref are relative amplitude and phase for a reference class.  $D_\xi$  is zero if two time series, represented by their m Fourier components, have the same shape and increases as the differences between the shapes increases.

### Quantifies the FT of the difference between time series

$$A_k^{p-q} = \sqrt{(F_k^c(p) - F_k^c(q))^2 + (F_k^s(p) - F_k^s(q))^2}$$

$$= \sqrt{F_k^c(p-q)^2 + F_k^s(p-q)^2}$$
(12)

Based on the  $A_k^{p-q}$  of the selected m FT components,  $D_{Fk}$  can be calculated:

$$D_{Fk} = \sum_{k=0}^{N-1} w_k A_k^{p-q} \tag{13}$$

where A\_k^p-q is the F\_k-distance between the time series of p and q respectively, and w\_k is the weight of the kth frequency FT component. Modification of the weights allows to enhance (high w\_k) or diminish(low w\_k) the influence of each component on D\_Fk and to accentuate specific components in the similarity measure. As a result, these weights will determine the sensitivity to time series differences. For example, when w\_0=0 the D\_Fk will be insensitive to amplitude translations as the offset value in the y-axis is neglected in the D\_Fk calculation

- Implementation: numpy.fft
- ▼ Mutual Information

*Mutual Information.* Introduced by Shannon [26], the notion of *entropy* is a measure for the expected information from observing the value of a random variable X, noted as H(X). The expected information for observed values of two random variables X and Y is the natural extension *joint entropy* H(X,Y). This gives way to the notion of *Mutual Information* 

$$I(X;Y) = H(X) + H(Y) - H(X,Y),$$
(1)

which describes the information shared between both variables. Using the definition of entropy for continuous random variables in Equation 1 yields the differential definition of MI

$$I(X;Y) = \int_{Y} \int_{X} p(x,y) \log \left( \frac{p(x,y)}{p(x)p(y)} \right) dx dy$$
 (2)

where p(x), p(y) and p(x, y) are the marginal and joint probability density functions of X and Y, respectively [8]. Using the natural logarithm, MI is then measured in the *natural unit of information* (nat).

• Implementation: sklearn.feature\_selection.mutual\_info\_classif