SPECIFICATIONS

> Range: ±3g

> Bandwidth: 0-50Hz > Consumption: ~0.35mA

> Input Voltage Range: 1.8-3.6V

FEATURES

- > 3-axis sensing
- > MEMS technology
- > Pre-conditioned analog output
- > Small form factor
- > Raw data output
- > Easy-to-use

APPLICATIONS

- > Activity monitoring
- > Tilt detection
- > Vibration measurement
- > Human-Computer Interaction
- > Robotics & Cybernetics
- > Biomechanics
- > Biomedical devices prototyping

GENERAL DESCRIPTION

Motion produces accelerations that can be translated into numerical values. Our Accelerometer (ACC) has a limited bandwidth, especially designed to acquire data from kinematic and biomechanical events. The analog output of each axis can be accessed individually, extending its potential use. Typical applications include posture detection, range of motion estimation, step counting, actigraphy, fall detection, vibration analysis, and shock detection. By default only the Z-axis is connected, however the sensor has 3 axis, and the user can choose to connect the Xand Y-axis as well, by following a procedure similar to the one found in:

https://www.youtube.com/watch?v=RaJQ3hcdJqUhhttps://www.youtube.com/watch?v=rh8y_NsVLI4h

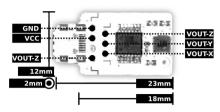


Fig. 1. Pin-out and physical dimensions.

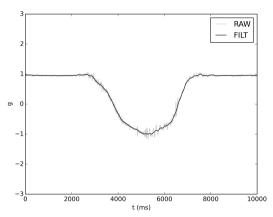


Fig. 2. Raw and filtered ACC data (acquired with BITalino (r)evolution) for a full rotation around the Z-axis.



PLUX – Wireless Biosignals, S.A. Av. 5 de Outubro, n. 70 – 8. 1050-059 Lisbon, Portugal bitalino@plux.info http://bitalino.com/

REV A



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Accelerometer (ACC) Sensor Data Sheet

TRANSFER FUNCTION

[-3g, 3g]

$$ACC(g) = \frac{ADC - C_{min}}{C_{max} - C_{min}}.2 - 1$$

ACC(g) – ACC value in g-force (g)

ADC - Value sampled from the channel

 C_{min} – Minimum calibration value¹

 C_{max} – Maximum calibration value¹

ORDERING GUIDE

Part #	Description
SENS-ACC-NC	Accelerometer (ACC) without connectors
SENS-ACC-UCE6	Accelerometer (ACC) with UC-E6 socket for seamless plug & play
	connection to a BITalino (r)evolution Plugged or Core
SENS-ACC-SHER4	Accelerometer (ACC) with a Molex Sherlock 4-pin socket for easy
	power and signal cable connection or pin breakout using PCB wires

 $^{^1}$ Calibration values are determined by performing a very slow 360° rotation of the sensor board to force the accelerometer to cross the gravity-imposed -1g and 1g in each axis. It is recommended that filtering or averaging of the data is performed to remove natural tremors (e.g. shaky hands) as illustrated in Fig. 2.

