

Class 16 Metric compatible Covariant derivative (Chap 15)

In weeks 7-8

$$\textcircled{1} \quad d : \Omega^k \rightarrow \Omega^{k+1} \quad \Omega^k = C^\infty(M; \Lambda^k T^*M)$$

$$d^2 = 0 \quad \boxed{1 - dR} \quad \text{Space } k\text{-forms}$$

$$\textcircled{2} \quad \nabla : C^\infty(M; E) \rightarrow C^\infty(M; E \otimes T^*M)$$

↑
vector bundle

pick $v \in TM$ then $\nabla_v : C^\infty(M; E) \hookrightarrow$

$$\begin{aligned} \textcircled{3} \quad d_\nabla : C^\infty(M; E \otimes \Lambda^k T^*M) \\ \rightarrow C^\infty(M; E \otimes \Lambda^{k+1} T^*M) \end{aligned}$$

$$d_\nabla s \otimes w \quad d_\nabla (\sum s_i \otimes w) = \sum d_\nabla s_i \otimes w$$

Weeks 5-6 we studied metrics on \bar{E} .

g is section of $\bar{E}^* \otimes \bar{E}^*$

and at each fiber it is positive def.

Symmetric matrix.

This two weeks. study
metric compatible cov. der

Leibniz rule.

$$\underline{d(w, \lambda w) = dw, \lambda w + (-)^{\dim u} w, \lambda d\omega}$$

u, v sections of \bar{E} .

$g(u, v) : M \rightarrow \mathbb{R}$ $dg(u, v)$ 1-form

$$dg(u, v) = g(\nabla u, v) + g(u, \nabla v)$$

1-form (metric compatible condition)

M, E, g, ∇

the space of g is convex contractible }

the space of ∇ is affine over }

$$C^\infty(\text{End}(E) \otimes \Lambda^1 T^* M)$$

$$\nabla^0, \nabla - \nabla^0$$

$$g(\nabla u, v) \quad \forall u \in C^\infty(E \otimes T^* M)$$

$$g \in E^* \otimes E^* \quad \forall \in C^\infty(E)$$

$$\nabla u = \sum_i dx^i$$

$$g(\nabla u, v) = \sum_i g(S_i, v) dx^i$$

$$1\text{-form: } E \otimes E^*$$



In local chart U , we have two choices of bases of sections of E .

① Because of the existence of g ,

we can choose an orthonormal basis of E

$$e_1, \dots, e_n$$

$$g(e_i, e_j) = \delta_{ij}$$

$$\text{no } \frac{\partial}{\partial x^i}$$

② In general, $\underline{E} = TM$, dx

there is another basis $\left(\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n} \right)$

$\underline{\phi_U}: U \rightarrow \mathbb{R}^n$ $\dim M = n$.

$\underline{\psi_U}: TM|_U \rightarrow U \times \mathbb{R}^n \xrightarrow{\phi_U \times \text{Id}} \mathbb{R}^n \times \mathbb{R}^n$

depends on the choice of $(x^1, \dots, x^n, \frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n})$

ϕ_U but has no relation with g .

In general $g(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j}) \neq \delta_{ij}$

we will use $g_{ij} = g(\frac{\partial}{\partial x^i}, \frac{\partial}{\partial x^j})$

$\underline{g_{ij}}: U \rightarrow \overline{\mathbb{R}}$ $g_{ij} = g_{ji}$

In weeks we write s_1, \dots, s_n

for basis of E . but now replace by

e_1, \dots, e_n . $v_1, \dots, v_n: U \rightarrow \mathbb{R}$

Now we change the notation

$s \in C^\infty(E)$

$\nabla s \in C^\infty(E \otimes T^*U)$

$$\nabla s = \sum_{i,j} (ds_i + \underline{\alpha_i^j s_j}) e_i$$

$\overbrace{\qquad\qquad\qquad}^{\nabla^0 s = ds} \quad \overbrace{\qquad\qquad\qquad}^{\alpha^j_i}$

$(\text{local } \alpha \text{ depends on } U)$

$$\nabla - \nabla^0 = \underline{\alpha} \in C^\infty(\text{End}(E) \otimes T^*U)$$

$\text{matrix valued 1-form.}$

α_i^j is 1-form.

$\alpha = \{\alpha_i^j\}$ is a matrix of 2-form.

In particular -

$$\begin{aligned}\nabla e_i &= \sum \alpha_i^j e_j \\ &= \underline{\alpha_i^j e_j} \quad \text{Q}\end{aligned}$$

(previously I used $\underline{\alpha_{ij}}$).

$$(\nabla e_i = 0)$$

$$\boxed{dg(u, v) = g(\nabla u, v) + g(u, \nabla v)}$$

$$g(e_i, e_j) = \delta_{ij} \leftarrow \text{constant}$$

$$dg(e_i, e_j) = 0 \quad \text{functions on } U$$

$$g(\underline{\nabla e_i}, e_j) + g(e_i, \underline{\nabla e_j})$$

$$= g(\alpha_i^k e_k, e_j) + g(e_i, \alpha_j^l e_l)$$

\downarrow I-f-

$$= \alpha_i^k g(e_k, e_j) + \alpha_j^l g(e_i, e_l)$$

$$= \alpha_i^k \cdot \delta_{kj} + \alpha_j^l \delta_{il}$$

$$= \alpha_i^j + \alpha_j^i$$

$$\alpha = \{\alpha_{ij}^i\}_{ij}$$

$$\underbrace{\alpha^T + \alpha = 0}_{\alpha \in C^\infty(\text{End}(E) \otimes \mathcal{U})}$$

Clear metric compatible iff $\underline{\nabla}g = 0$

$$\nabla: C^0(E) \rightarrow C^0(E^* \otimes T^{1,0})$$

we want to extend ∇ to $\underline{\underline{E^*}}, \underline{\underline{E^* \otimes E}}$

for $s^* \in C^0(E^*)$ $s \in C^\infty(E)$

$$\boxed{d \langle s, s^* \rangle = \langle \nabla s, s^* \rangle}$$

$\xrightarrow{\text{of}} + \langle s, \nabla s^* \rangle$

↑

this is a def of ∇s^*

∇ on $\underline{\underline{E^* \otimes E}}$.

$$\nabla(s_1 \otimes s_2) = (\nabla s_1) \otimes s_2 + s_1 \otimes (\nabla s_2).$$

Then we can combine these def's. $\nabla g \Rightarrow$
to get $\underline{\nabla}$ on $\underline{\underline{E^* \otimes E^*}}$ $\underline{\underline{g \in C^\infty(E^* \otimes E)}}$

$$\begin{array}{c}
 \frac{dg(u,v)}{u,v \in C^{\infty}(E)} \\
 u \otimes v \in C^{\infty}(E \otimes E) \\
 g \in C^{\infty}(E^* \otimes E^*) \\
 C^{\infty}((E \otimes E)^*) \\
 \langle u \otimes v, g \rangle : M \rightarrow \mathbb{R}
 \end{array}$$

$$\begin{aligned}
 d\langle u \otimes v, g \rangle &= \underbrace{\langle \nabla(u \otimes v), g \rangle}_{+ \langle u \otimes v, \nabla g \rangle} \\
 &= \underbrace{\langle (\nabla u) \otimes v, g \rangle}_{+ \langle u \otimes \nabla v, g \rangle} + \langle u \otimes \nabla v, g \rangle \\
 &= \underbrace{g(\nabla u, v) + g(u, \nabla v)}_{+ \langle u \otimes v, \nabla g \rangle} \quad \text{for any } u, v.
 \end{aligned}$$

$$\nabla g \in C^{\infty}(E^* \otimes E^* \otimes T^*M)$$

$$\nabla g(u, v) \neq (\nabla g)(u, v)$$

$$\nabla g = 0 \not\Rightarrow \nabla g(u, v) = 0 \text{ for } \forall u, v$$

Next. torsion free condition

(only for ∇ on $T(M)$)

(because we use d .)

$$\begin{array}{l} \nabla \\ \hline E = TM \end{array} \quad \begin{array}{l} \nabla \\ \hline E^* = T^*M \end{array}$$

$$\nabla : C^{\infty}(M; T^*M) \rightarrow C^{\infty}(M; \underline{T^*M \otimes T^*M})$$

$$A : C^\infty(M; T^*M \otimes T^*M) \rightarrow C^\infty(\Lambda^2 T^*M)$$

↑
antisymmetrization map.

$$\text{by } A(w_1 \otimes w_2) = w_1 \wedge w_2$$

$$:= \frac{1}{2} \underbrace{(w_1 \otimes w_2 - w_2 \otimes w_1)}_{}$$

(In general, we can define

$$A : C^\infty(T^*M \otimes \underbrace{\Lambda^k T^*M})$$

$$\rightarrow C^\infty(\underbrace{\Lambda^{k+1} T^*M})$$

For a 1-form w

we can define dw 2-form. $C^\infty(\Lambda^2 T^*M)$

$$dw = Jw \in C^\infty(\underbrace{T^*M \otimes T^*M})$$

$$\text{IA}(\text{d}_\nabla \omega) \in C^\infty(\Lambda^2 T^* M)$$

$$\text{d}\omega \quad \hookrightarrow$$

Def the torsion tensor T_∇ :

$$C^\infty(T^* M) \rightarrow C^\infty(\Lambda^2 T^* M)$$

$$T_\nabla \omega = \underbrace{\text{IA}(\text{d}_\nabla \omega)}_{\text{d}\omega}$$

∇ (on $T M$ or $T^* M$) is called

torsion free $\Leftrightarrow T_\nabla = 0$. i.e.

$$\text{IA}(\text{d}_\nabla \omega) = \text{d}\omega.$$

Rem. In Cloff's book - he wrote

$$d_\nabla \text{ for } \text{IA} d_\nabla$$

Then Given a Riemannian metric on
 M (i.e. on T^*M), \exists unique
 metric compatible, torsion-free
 covariant derivative, which we
 call as Levi-Civita connection

∇_{LC}

Rem: we can extend ∇ to
 a map: $C^\infty(\bigwedge^k T^*M) \rightarrow C^\infty(\bigwedge^{k+1} T^*M)$
 $d\omega \in C^\infty(\bigwedge^k T^*M \otimes T^*M)$
 $Ad\omega \in C^\infty(\bigwedge^{k+1} T^*M)$

$$\bar{\nabla} \omega = A d_{\bar{\nabla}} \omega - d \omega$$

Claim: If $\bar{\nabla} \omega = 0$ for

1-form ω , then it vanishes for all
k-form ω .

$$d(w_1 \wedge w_2) = dw_1 \wedge w_2 + (-)^{\deg w_1} w_1 \wedge dw_2$$

$$\begin{aligned} \overline{Ad_{\bar{\nabla}}(w_1 \wedge w_2)} &= \overline{Ad_{\bar{\nabla}} w_1 \wedge w_2} \\ &\quad + (-)^{\deg w_1} \overline{w_1 \wedge Ad_{\bar{\nabla}} w_2} \end{aligned}$$

d only depends on Ω^k (only for M)

$d_{\bar{\nabla}}$ depends on $\bar{\nabla}$ /A

$$A \nabla w = dw$$

↑ ↑
f - M + \nabla Only for M

the metric compatible condition

We start with M with a metric
 g on $\tilde{E} = TM$.

(M, g) is called a Riemannian manifold

Then $\{\nabla g = 0, T\partial = 0\}$
 can be regarded as equations on the
 space of ∇ . $C^\infty(\text{End}(E) \otimes T^*M)$

Later. (The final goal of this course)

is to understand the Yang-Mills equation

$$\overbrace{F_\nabla^f}^{\leftarrow \text{introduced later}} = 0$$

This is also an equation on the space
of \mathcal{J} .

\mathcal{J}_{LC} depends uniquely by (M, g)

Sketch the ideas for the next class.

There are two proofs

- ① using orthonormal basis $\overline{g(e_i, e_j) = \delta_{ij}}$
- ② using coordinate basis $\overline{\frac{\partial}{\partial x^1}, \dots, \frac{\partial}{\partial x^n}}$

Warm-up computation (everything locally)

$$\nabla e_i = \sum_j e_j \otimes \alpha_j^i.$$

e_1, \dots, e_n is orthonormal basis of

$$\overline{E} = \overline{T\mathcal{M}}$$

Quesn: What is the formula for

$$\nabla \text{ on } T^*\mathcal{M} (= \overline{E}^*)$$

e^i as dual basis on \overline{E}^*

$$\langle e_i, e^j \rangle = \delta_{ij}$$

$$\nabla e^i = \sum_j e^j \otimes \underline{\beta_j^i}$$

$$0 = \underbrace{d\langle e_i, e_j \rangle}_{S_{ij}} = \langle \nabla e_i, e_j \rangle + \langle e_i, \nabla e_j \rangle$$

$$\begin{aligned} &= \underbrace{\langle \alpha_i^k e_k, e_j \rangle}_{-\alpha_i^j + \beta_i^j} + \underbrace{\langle e_i, e_j \otimes \beta_i^j \rangle}_{\beta_i^j = -\alpha_i^j} \\ &= -\alpha_i^j + \beta_i^j \end{aligned}$$

$$\nabla g = 0 \Rightarrow \alpha_i^j + \alpha_j^i = 0$$

$$\Rightarrow \beta_i^j + \beta_j^i = 0$$

$$d(w_1, w_2) = \dots$$