## Speech Recognition Techniques for a Sign Language Recognition System

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### Introduction

- automatic sign language recognition system
- necessary for communication between deaf and hearing people
- continuous sign language recognition, several speakers, vision-based approach, no special hardware
- ► large vocabulary speech recognition (LVSR) system to obtain a textual representation of the signed sentences
- evaluation of speech recognition techniques on publicly available sign language corpus

### Automatic Sign Language Recognition (ASLR)

- similar to speech recognition: temporal sequences of images
- important features
- hand-shapes, facial expressions, lip-patterns
- orientation and movement of the hands, arms or body
- ► HMMs are used to compensate time and amplitude variations of the signers

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expre	esses	me ob:	servatio	n seq	uence

### **Experimental Setup**

### **Database**

- system evaluation on the RWTH-BOSTON-104 database
- ▶ 201 sentences (161 training and 40 test sequences)
- vocabulary size of 104 words
- ▶3 speakers (2 female, 1 male)
- corpus is annotated in glosses

### **Problems**

- ▶ 26% of the training data are singletons
- simple sentence structure
- one out-of-vocabulary (OOV) words with whole-word models

### Differences in Comparison to ASR

- simultaneousness
- signing space
- ▶ environment
- speakers and dialects
- coarticulation and movement epenthesis
- silence
- whole-word models and sub-word units

# System Overview Visual Modeling (VM)

- related to the acoustic model in ASR
- ► HMM based, with separate GMMs, globally pooled diag. covariance matrix
- monophone whole-word models
- pronunciation handling

### Language Modeling (LM)

- according to ASR: LM should have a greater weight than the VM
- ▶ trigram LM using the SRILM toolkit, with modified Kneser-Ney discounting with interpolation

### **Features**

- appearance-based image features: for baseline system
- thumbnails of video sequence frames (intensity images scaled to 32x32 pixels)
- give a global description of all (manual and non-manual) features proposed in linguistic research
- manual features:
- dominant hand tracking: hand position, hand velocity, and hand trajectory features

### Feature Selection and Model Combination

### Feature Selection

- concatenation of appearance-based and manual features
- sliding window for context modeling
- dimensionality reduction by PCA and/or LDA

### **Model Combination**

- log-linear combination of independently trained models
- profit from independent alignments (e.g. performing well for long and short words)
- profit from different feature extraction approaches

# Features frame intensity (w/o pronunciations) frame intensity (w/ pronunciations) frame intensity (w/ pronunciations) frame intensity (w/ pronunciations + tangent distance) fra

PCA-trame, nand-trajectory	112 23.6		
model-combination	2x100 17.9		
Example Results	RWTH-BOSTON-104		
Correct Examples  IX-1P FIND SOMETHING-ONE BOOK IX-1P FIND SOMETHING-ONE BOOK  JOHN FISH WONT EAT BUT CAN EAT CHICKEN JOHN FISH WONT EAT BUT CAN EAT CHICKEN LOVE JOHN WHO LOVE JOHN WHO JOHN BUY YESTERDAY WHAT BOOK JOHN BUY YESTERDAY WHAT BOOK	Corpus Statistics  Training Test sentences 161 40 running words 710 178 frames 12422 3324 vocabulary 103 65 singletons 27 9 OOV - 1		
Incorrect Examples  MARY VEGETABLE KNOW IX LIKE CORN MARY VEGETABLE KNOW IX LIKE MARY  JOHN IX GIVE MAN IX NEW COAT JOHN IX WOMAN NEW COAT  LIKE CHOCOLATE WHO  JOHN LIKE CHOCOLATE WHO  JOHN [UNKNOWN] BUY HOUSE  JOHN FUTURE NOT BUY HOUSE	LM Perplexities  LM type PF zerogram 106.0 unigram 36.8 bigram 6.7 trigram 4.7  Database is publicly available		

### Conclusion

- LVSR system is suitable for vision-based continuous sign language recognition
- many of the principles known from ASR can directly be transfered
- ▶ important for ASLR: temporal contexts, pronunciation handling, language modelling, and model combination
- outlook: connection of recognizer output to a statistical machine translation system achieved promising translation results